When to Use Energy

Proof of (T+U) conservation used $\vec{F} = m\vec{a}$... so

 $\dot{T} + \dot{U} = 0$ always **gives you back a force-based EOM**. It's often a more <u>efficient</u> way to obtain the EOM than using forces or torques, but more strategy tips are needed:

When do we NEED to use d(T+U) = 0?

When *force* details are *unknown*.

• Elastic Collisions

All we know about the forces is that "elastic" \equiv **T** is conserved in the collision.

Known ΔE added / subtracted from system
 e.g. particle explodes, releasing known ΔE
 → must use energy analysis to include this info.

When can we NOT use d(T+U) = 0?

When it's not true OR can't be calculated.

- $U(\vec{r},t)$ with explicit *t*-dependence
- Forces that **can't be described** by $U(\vec{r})$ but **do work**
 - e.g. kinetic friction (depends on normal force), drag force (depends on velocity), force fields with $\vec{\nabla} \times \vec{F} \neq 0$
- Energy leaves / enters system in non-calculable way e.g. inelastic collisions where $\Delta U^{INT} \neq 0$
- System is losing mass, e.g. rocket motion

When details of interaction force <u>not known</u>, some <u>other</u> <u>info</u> must be provided.

Collisions

Elastic Collision : total T is conserved

- Collision takes place in infinitesimal time interval $\Delta t \approx 0$ \therefore impulse collision force : $F_{\text{impulse}} \cdot \Delta t = \Delta P$ $\infty \quad \cdot \quad 0 = \text{finite}$
- $\Delta \mathbf{U}^{\text{EXT}}(\vec{r}) = \mathbf{0} :: \Delta \vec{r} = 0$ (particles have no time to move!)
- Particle structure unchanged by collision ∴ ΔU^{INT} = 0

 i.e. no energy can escape into deforming / heating /
 <u>fragmenting</u> the particles
- "Elastic" also implies that energy **cannot escape** to **surrounding medium**, e.g. via sound waves

Inelastic Collision : total T+U^{EXT} *not* **conserved**

- Total Mass is conserved (non-relativistic systems)
- Classic example : Fusion / Fission of N ↔ 1 particles When particles fuse, KE of incoming particles converted into <u>heat</u> of fused particle ∵ ΔU^{INT} ≠ 0
 - Solution Often useful : go to CM Frame
- Abrupt ΔT_{total} , i.e. that occurs over $\Delta t \approx 0$, is a <u>signature</u> of an <u>inelastic process</u>

 $U^{EXT}(\vec{r}) = 0$ can't change over $\Delta t \approx 0 :: \Delta \vec{r} \approx 0$

 $\therefore \Delta(T + U^{\text{EXT}}) = \Delta T \neq 0 \rightarrow \text{inelastic}$