**System** = mass in uniform gravity, 1D vertical motion **Endpoints** = (y, t) from (0,  $-\tau$ )  $\rightarrow$  (0,  $+\tau$ ) **Lagrangian**  $L(y, \dot{y}, t) \frac{2}{m} = \dot{y}^2 - 2gy$ 

Path Class #1 : constant speed going up & coming down → vary H = max height

• Paths  

$$y(t) = H\left(1 - \frac{|t|}{\tau}\right) \rightarrow \dot{y} = \pm \frac{H}{\tau}$$
• Lagrangian  $L(t) \frac{2}{m} = \left(\frac{H}{\tau}\right)^2 - 2gH\left(1 - \frac{|t|}{\tau}\right) \rightarrow L(t) \frac{2}{m(g\tau)^2} = \left(\frac{H}{g\tau^2}\right)^2 - 2\frac{H}{g\tau^2}\left(1 - \frac{|t|}{\tau}\right)$ 
Define  $b = \frac{H}{g\tau^2}$  and vary that ... true path has  $H = \frac{g\tau^2}{2} \therefore \left(b_{\text{true}} = \frac{1}{2}\right)$ 
Drop  $\frac{2}{m(g\tau)^2} \rightarrow L(t) = b^2 - 2b\left(1 - \frac{|t|}{\tau}\right)$  ... vary *b* and see what happens !  
plot b^2-2b(1-Abs[t]) for b={0.1,0.25,0.5,0.75,1} from t=-1 to 1

• Action 
$$S = \int_{-\tau}^{+\tau} L dt = 2\tau b(b-1)$$
 plot b(b-1) from b=0 to 1.5

• Least Action 
$$\frac{1}{2\tau} \frac{dS}{db}\Big|_{b^*} = 0 = 2b^* - 1 \rightarrow \text{min action at} \left(b^* = \frac{1}{2}\right) = b_{\text{true}} \odot \rightarrow \left(S_{\text{min}} = -\frac{\tau}{2}\right)$$

Path Class #2 : constant acceleration up & down → vary a = acceleration

- Paths  $y(t) = v_0(t+\tau) \frac{1}{2}a(t+\tau)^2 \text{ and } y(\pm\tau) = 0 \quad \therefore \quad v_0 = a\tau \quad \rightarrow \quad y(t) = \frac{a}{2}(\tau^2 t^2)$
- Lagrangian  $L(t) \frac{2}{m} = a^2 t^2 + ga(t^2 \tau^2) \rightarrow L(t) \frac{2}{m(g\tau)^2} = \frac{a}{g} \left[ \frac{t^2}{\tau^2} \left( \frac{a}{g} + 1 \right) 1 \right]$ Define  $b \equiv \frac{a}{g}$  and vary that ... true path has  $a = g \therefore b_{\text{true}} = 1$   $\text{Drop} \frac{2}{m(g\tau)^2} \rightarrow \left[ L(t) = b \left[ \frac{t^2}{\tau^2} (b+1) - 1 \right] \dots \text{ vary } b \text{ and see what happens } !$ plot  $b(t^2(b+1)-1)$  for  $b = \{0.4, 0.7, 1, 1.3, 1.6\}$  from t = -1 to 1

• Action 
$$S = \int_{-\tau}^{+\tau} L \, dt = \frac{2\tau b}{3} (b-2)$$

plot b(b-2) from b=0 to 1.5

• Least Action 
$$\frac{3}{2\tau} \frac{dS}{db}\Big|_{b^*} = 0 = 2b^* - 2 \rightarrow \text{min action at } (b^* = 1) = b_{\text{true}} \rightarrow (S_{\text{min}} = -\frac{2\tau}{3}) < -\frac{\tau}{2} \odot$$