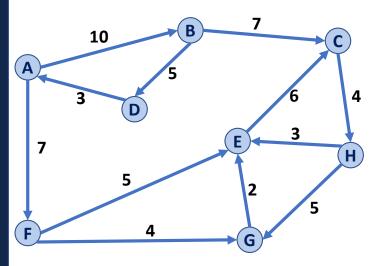
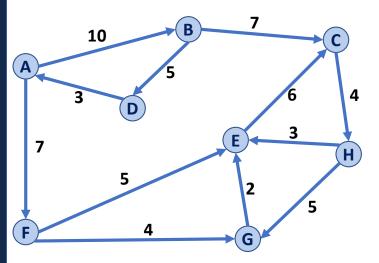
CS 225

Data Structures

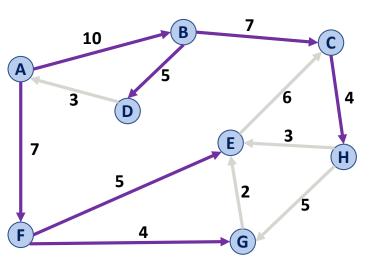
November 29 – Dijkstra's Algorithm Analysis G Carl Evans



```
PrimMST(G, s):
     foreach (Vertex v : G):
       d[v] = +inf
       p[v] = NULL
     d[s] = 0
10
     PriorityQueue Q // min distance, defined by d[v]
11
12
     Q.buildHeap(G.vertices())
13
     Graph T
                      // "labeled set"
14
15
     repeat n times:
16
       Vertex u = Q.removeMin()
17
       T.add(u)
       foreach (Vertex v : neighbors of u not in T):
18
19
         if cost(v, m) < d[v]:
20
           d[v] = cost(v, m)
21
           p[v] = m
```

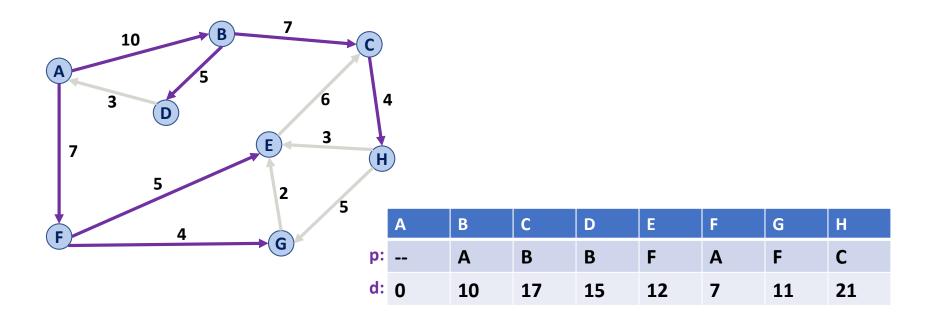


```
DijkstraSSSP(G, s):
     foreach (Vertex v : G):
       d[v] = +inf
       p[v] = NULL
     d[s] = 0
10
     PriorityQueue Q // min distance, defined by d[v]
11
12
     Q.buildHeap(G.vertices())
13
     Graph T
                      // "labeled set"
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       T.add(u)
       foreach (Vertex v : neighbors of u not in T):
18
19
         if
                             < d[v]:
20
           d[v] =
21
           p[v] = m
```

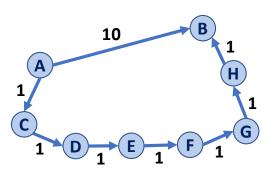


```
DijkstraSSSP(G, s):
     foreach (Vertex v : G):
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       p[v] = NULL
     d[s] = 0
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     PriorityQueue Q // min distance, defined by d[v]
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       Vertex u = Q.removeMin()
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       T.add(u)
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       foreach (Vertex v : neighbors of u not in T):
19
         if cost(u, v) + d[u] < d[v]:
20
           d[v] = cost(u, v) + d[u]
21
           p[v] = m
```

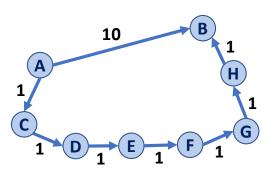
Dijkstra gives us the shortest path from our path (single source) to **every** connected vertex!



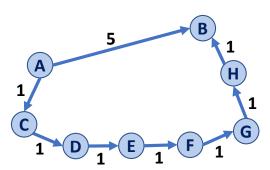
Q: How does Dijkstra handle a single heavy-weight path vs. many light-weight paths?



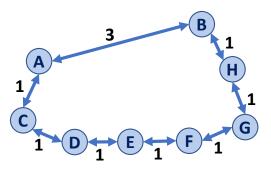
Q: How does Dijkstra handle a single heavy-weight path vs. many light-weight paths?



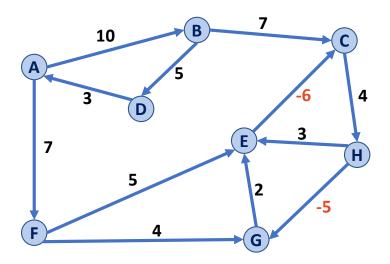
Q: How does Dijkstra handle a single heavy-weight path vs. many light-weight paths?



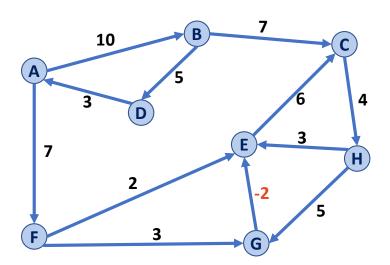
Q: How does Dijkstra handle undirected graphs?



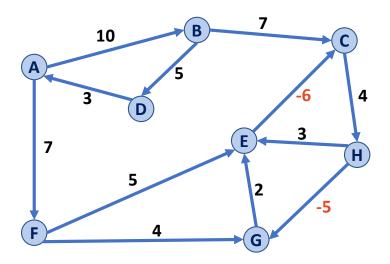
Q: How does Dijkstra handle negative weight cycles?



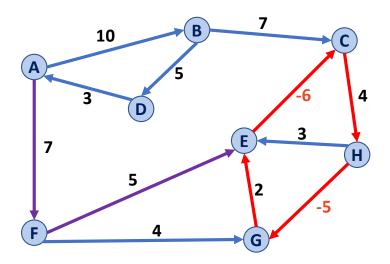
Q: How does Dijkstra handle negative weight edges, without a negative weight cycle?



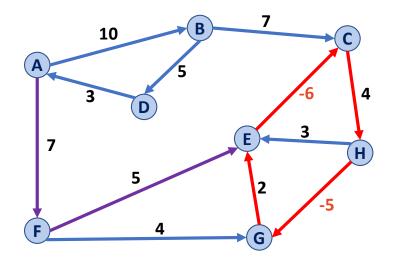
Q: How does Dijkstra handle negative weight cycles?



Q: How does Dijkstra handle negative weight cycles?



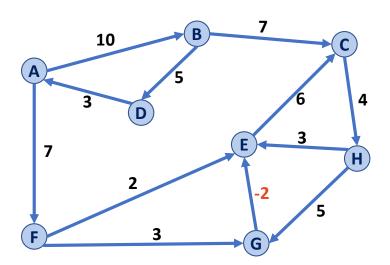
Q: How does Dijkstra handle negative weight cycles?



Shortest Path (A \rightarrow E): A \rightarrow F \rightarrow E \rightarrow (C \rightarrow H \rightarrow G \rightarrow E)*

Length: 12 Length: -5 (repeatable)

Q: How does Dijkstra handle negative weight edges, without a negative weight cycle?



What is Dijkstra's running time?

```
DijkstraSSSP(G, s):
     foreach (Vertex v : G):
       d[v] = +inf
       p[v] = NULL
     d[s] = 0
10
     PriorityQueue Q // min distance, defined by d[v]
11
12
     Q.buildHeap(G.vertices())
     Graph T
                      // "labeled set"
13
14
15
     repeat n times:
16
       Vertex u = Q.removeMin()
17
       T.add(u)
       foreach (Vertex v : neighbors of u not in T):
18
19
         if cost(u, v) + d[u] < d[v]:
20
           d[v] = cost(u, v) + d[u]
21
           p[v] = m
22
23
     return T
```

Suppose I have a new heap:

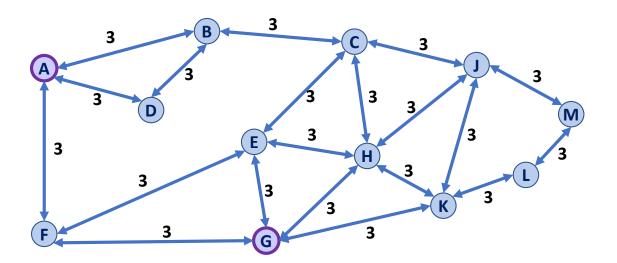
	Binary Heap	Fibonacci Heap
Remove Min	O(lg(n))	O(lg(n))
Decrease Key	O(lg(n))	O(1)*

What's the updated running time?

```
DijkstraSSSP(G, s):
     foreach (Vertex v : G):
       d[v] = +inf
       p[v] = NULL
     d[s] = 0
10
     PriorityQueue Q // min distance, defined by d[v]
11
     Q.buildHeap(G.vertices())
12
     Graph T
                      // "labeled set"
13
14
15
     repeat n times:
16
       Vertex u = 0.removeMin()
17
       T.add(u)
18
       foreach (Vertex v : neighbors of u not in T):
19
          if cost(u, v) + d[u] < d[v]:
20
           d[v] = cost(u, v) + d[u]
21
           p[v] = m
```

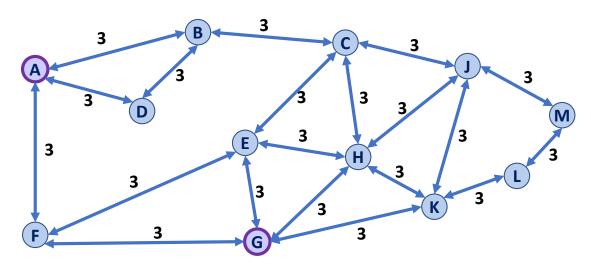
Suppose you want to travel from **A** to **G**.

Q1: What is the shortest path from A to G?



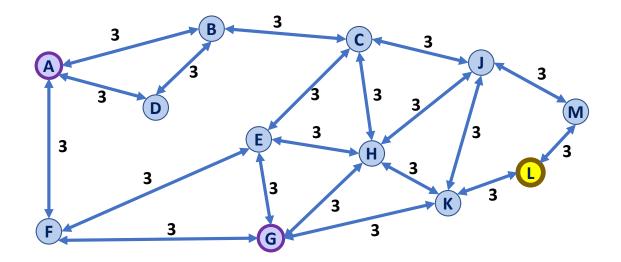
Suppose you want to travel from A to G.

Q2: What is the fastest algorithm to use to find the shortest path?



In your journey between **A** and **G**, you also want to visit the landmark **L**.

Q3: What is the shortest path from A to G that visits L?



In your journey between **A** and **G**, you also want to visit the landmark **L**.

Q4: What is the fastest algorithm to find this path?

Q5: What are the specific call(s) to this algorithm?

