

# Optimization

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**Goal:** Find the **minimizer**  $\mathbf{x}^*$  that minimizes the **objective (cost) function**  $f(\mathbf{x}): \mathcal{R}^n \rightarrow \mathcal{R}$

Unconstrained Optimization

Constrained Optimization

# Optimization

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## Constrained Optimization

# Optimization

$$f(\mathbf{x}^*) = \min_x f(\mathbf{x})$$

$$\text{s.t. } \mathbf{g}(\mathbf{x}) = \mathbf{0}$$

$$\mathbf{h}(\mathbf{x}) \leq \mathbf{0}$$

- What if we are looking for a maximizer  $\mathbf{x}^*$ ?

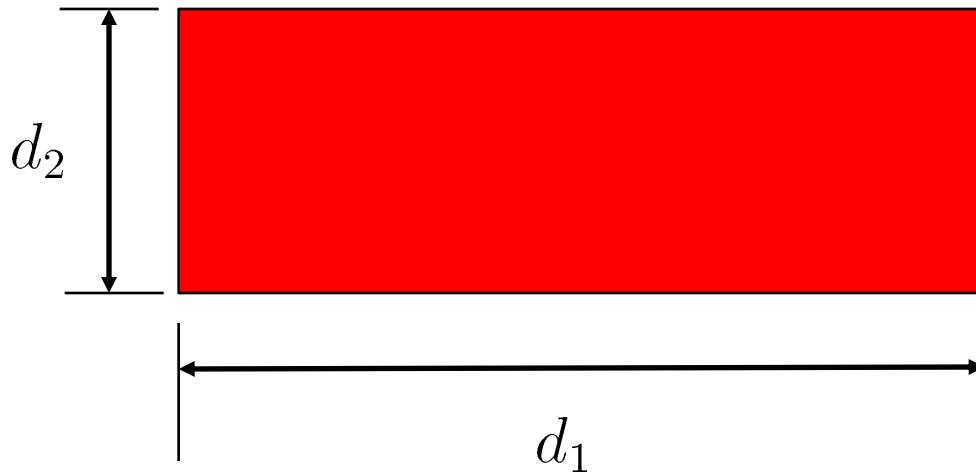
$$f(\mathbf{x}^*) = \max_x f(\mathbf{x})$$

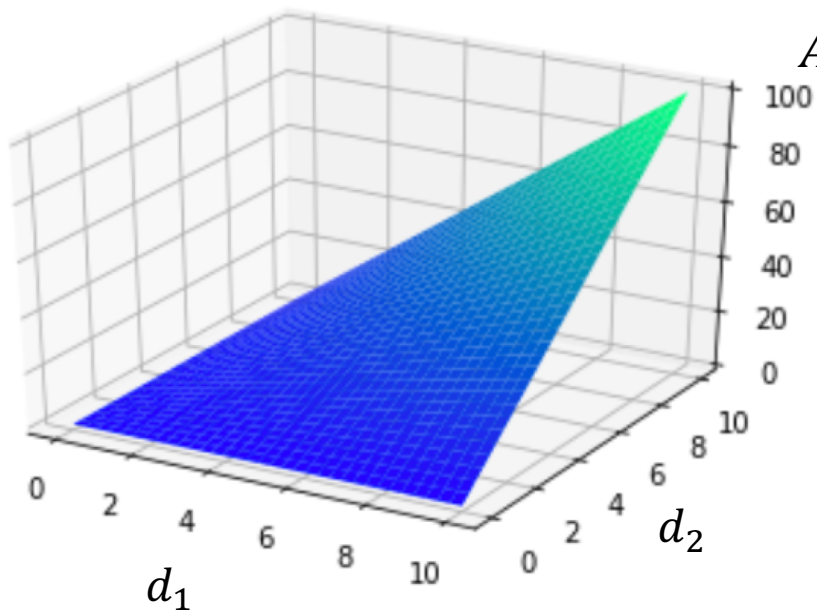
- What if constraint is  $\mathbf{h}(\mathbf{x}) > \mathbf{0}$ ?
- What if method only has inequality constraints?

# Calculus problem: maximize the rectangle area subject to perimeter constraint

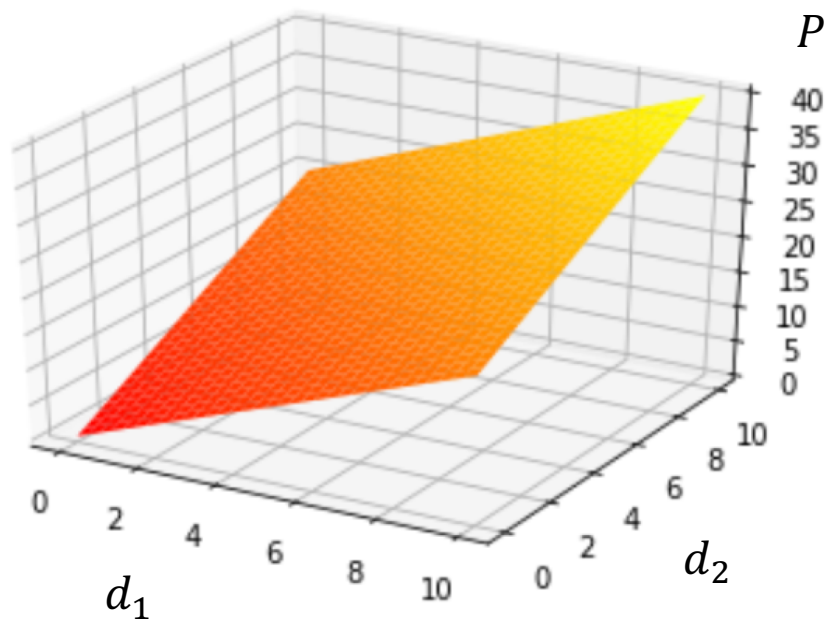
$$\max_{\mathbf{d} \in \mathcal{R}^2} \quad f(d_1, d_2) = d_1 \times d_2$$

such that  $g(d_1, d_2) = 2(d_1 + d_2) - 20 \leq 0$

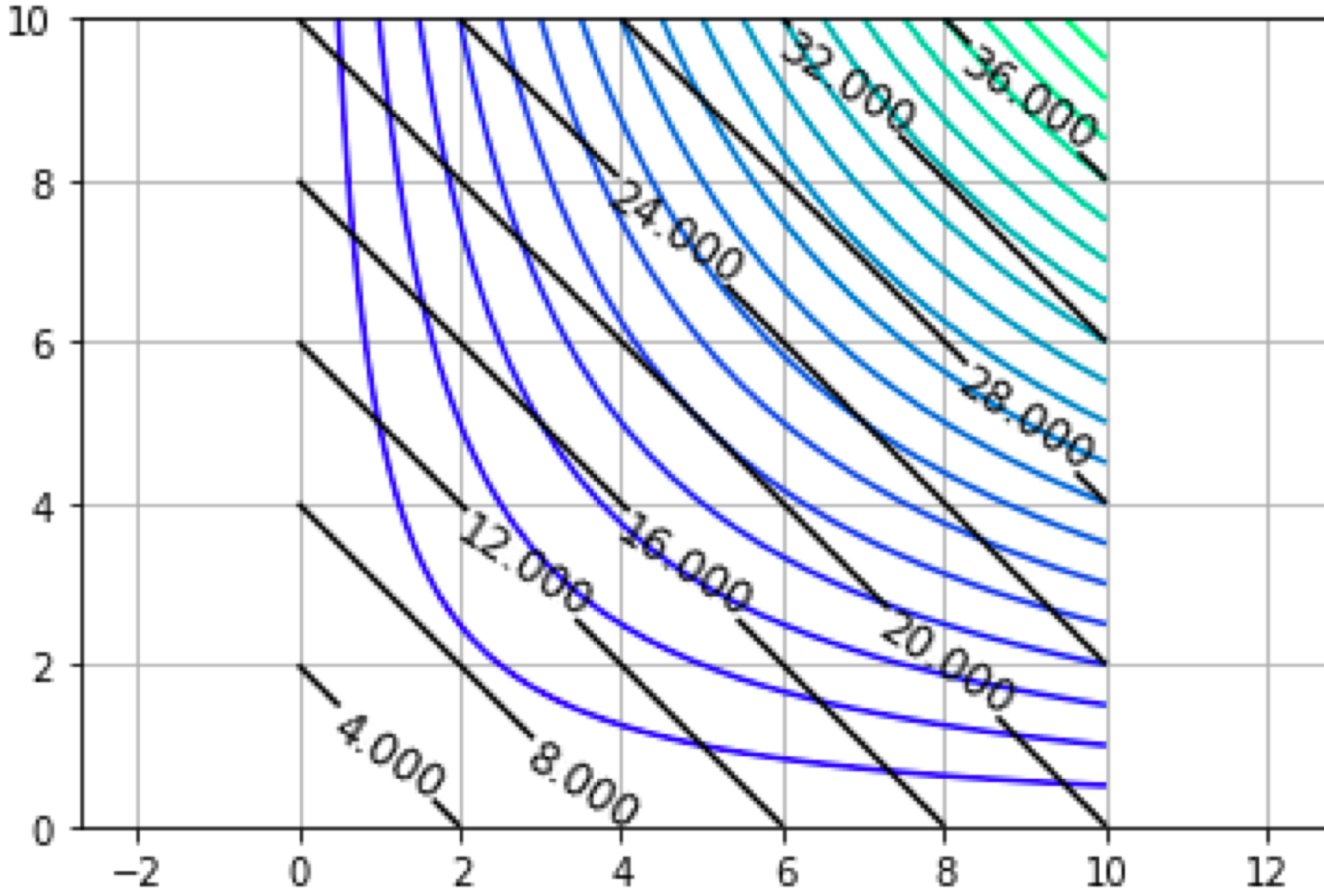




$$\text{Area} = d_1 d_2$$



$$\text{Perimeter} = 2(d_1 + d_2)$$



Does the solution exist? Local or global solution?



# Types of optimization problems

$$f(\mathbf{x}^*) = \min_{\mathbf{x}} f(\mathbf{x})$$

$f$ : nonlinear, continuous  
and smooth

## Gradient-free methods

Evaluate  $f(\mathbf{x})$

## Gradient (first-derivative) methods

Evaluate  $f(\mathbf{x}), \nabla f(\mathbf{x})$

## Second-derivative methods

Evaluate  $f(\mathbf{x}), \nabla f(\mathbf{x}), \nabla^2 f(\mathbf{x})$

Taking derivatives...

# What is the optimal solution?

$$f(\mathbf{x}^*) = \min_{\mathbf{x}} f(\mathbf{x})$$

**(First-order) Necessary condition**

**(Second-order) Sufficient condition**

$$\min_{\underline{x}} f(\underline{x})$$

First-order necessary condition

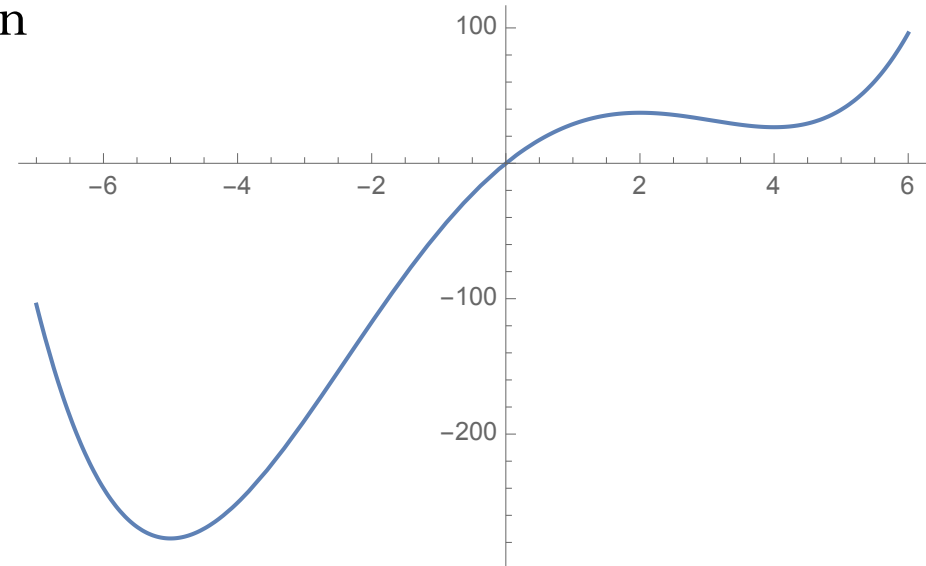
$$\rightarrow \nabla f(\underline{x}) = \underline{0}$$

Second-order sufficient condition

$\rightarrow \underline{\underline{H}}_f$  is positive definite

# Example (1D)

Consider the function  $f(x) = \frac{x^4}{4} - \frac{x^3}{3} - 11x^2 + 40x$ . Find the stationary point and check the sufficient condition



# Example (ND)

Consider the function  $f(x_1, x_2) = 2x_1^3 + 4x_2^2 + 2x_2 - 24x_1$

Find the stationary point and check the sufficient condition

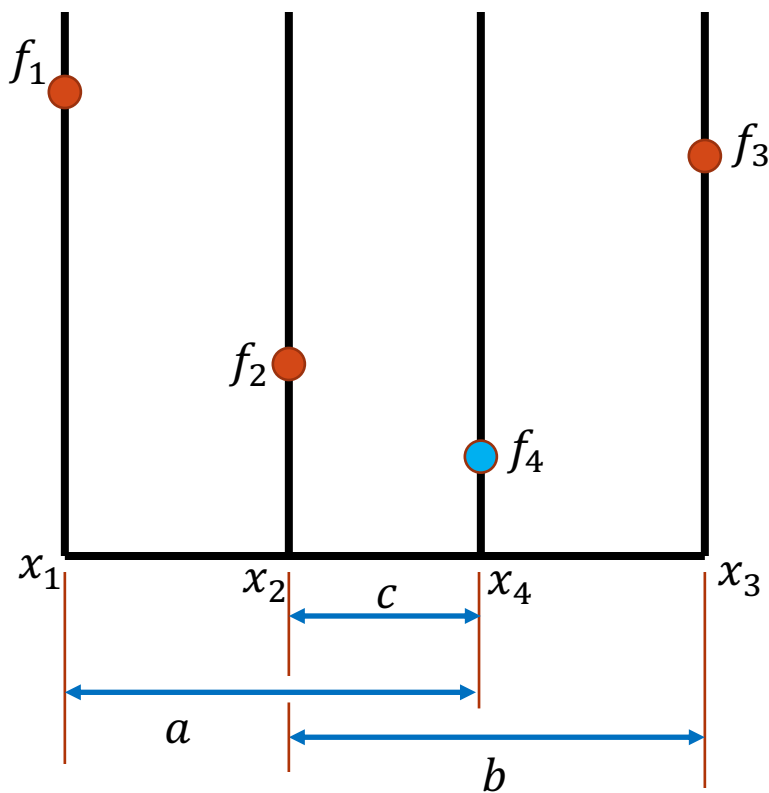
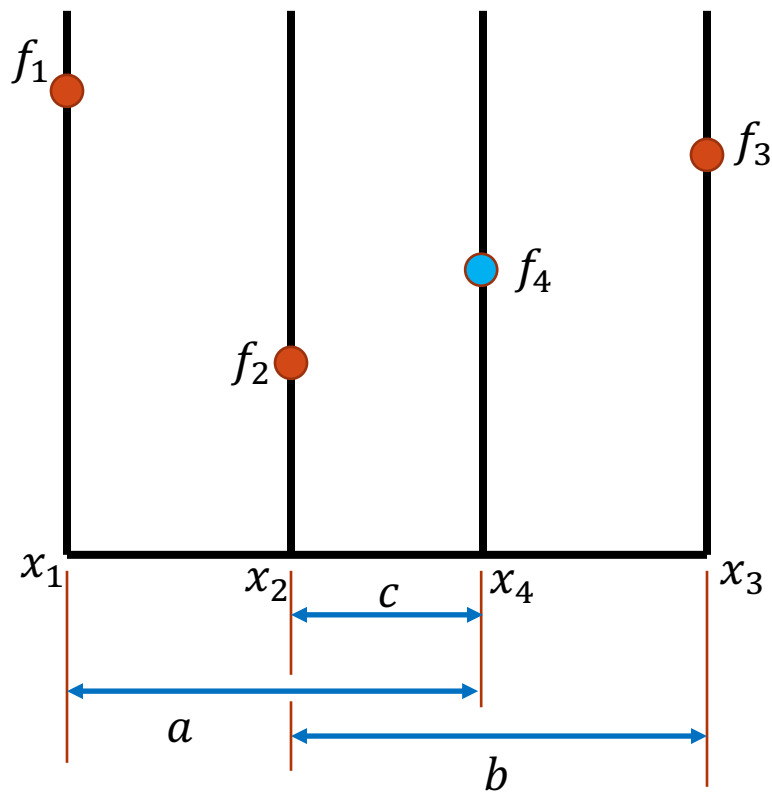
# Optimization in 1D:

## Golden Section Search

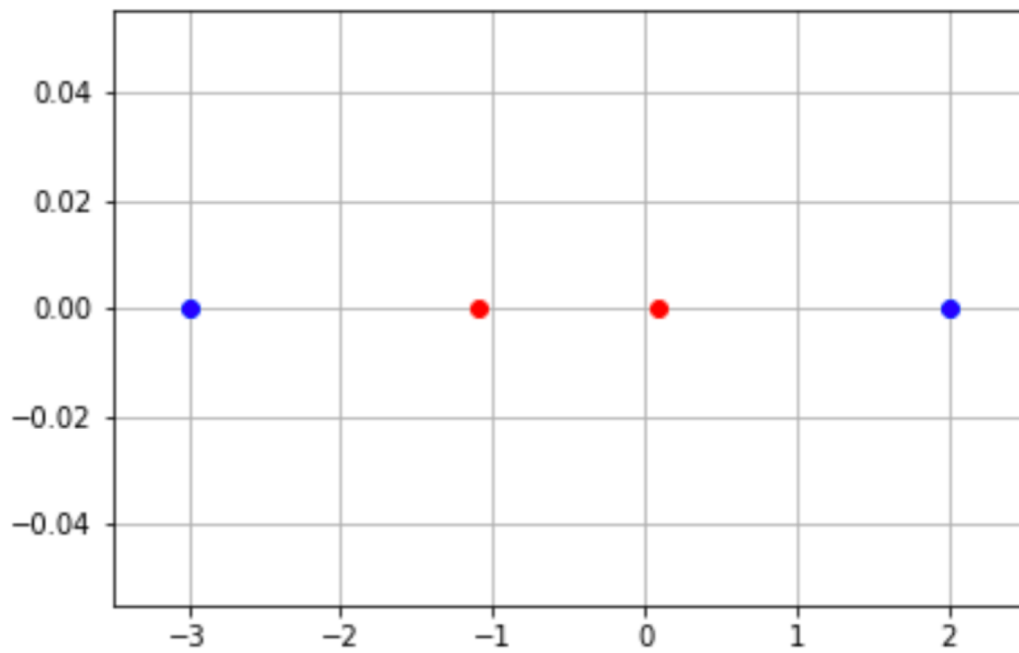
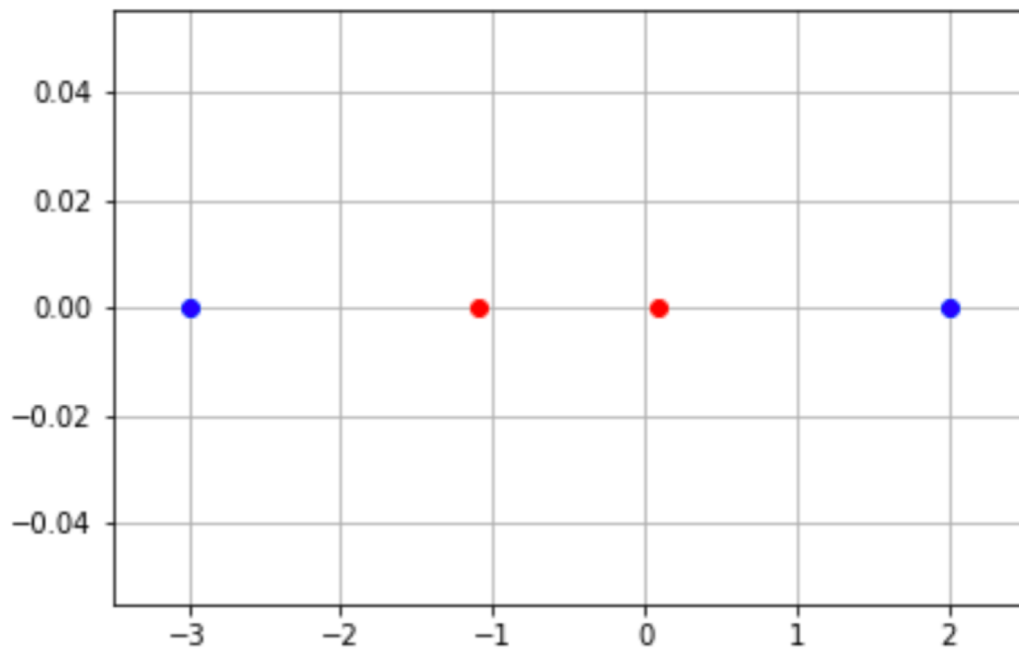
- Similar idea of bisection method for root finding
- Needs to bracket the minimum inside an interval
- Required the function to be unimodal

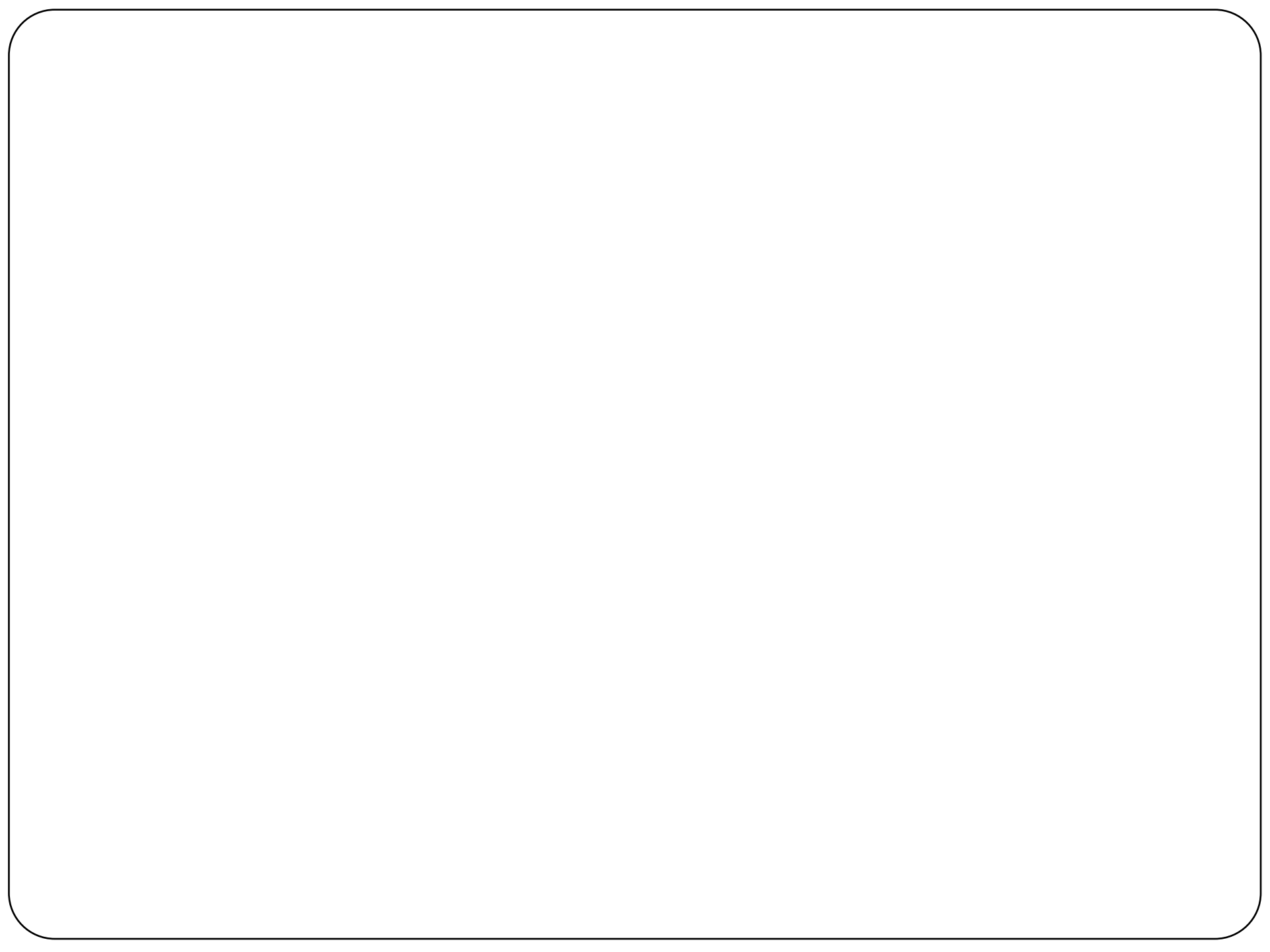
A function  $f: \mathcal{R} \rightarrow \mathcal{R}$  is unimodal on an interval  $[a, b]$

- ✓ There is a unique  $\mathbf{x}^* \in [a, b]$  such that  $f(\mathbf{x}^*)$  is the minimum in  $[a, b]$
- ✓ For any  $x_1, x_2 \in [a, b]$  with  $x_1 < x_2$ 
  - $x_2 < \mathbf{x}^* \implies f(x_1) > f(x_2)$
  - $x_1 > \mathbf{x}^* \implies f(x_1) < f(x_2)$

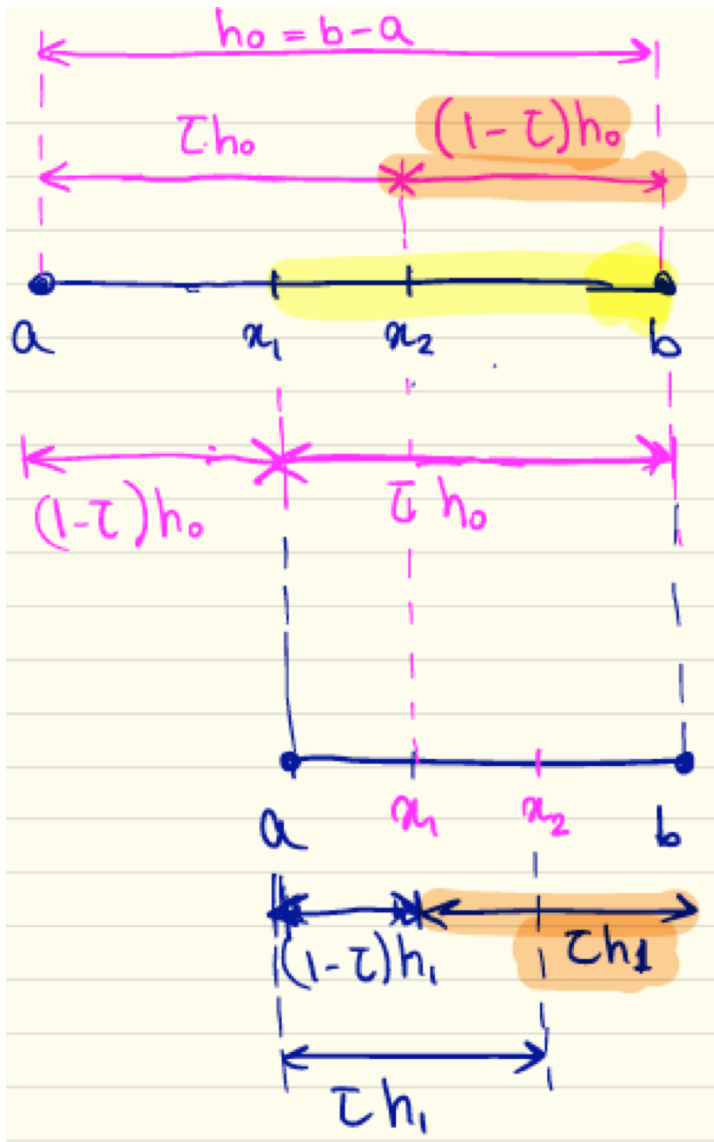








# Golden Section Search



Propose:

$$x_1 = a + (1 - \tau) h_0$$

$$x_2 = a + \tau h_0$$

Evaluate  $f_1 = f(x_1)$

$$f_2 = f(x_2)$$

if ( $f_1 > f_2$ ):

$$a = x_1$$

$x_1 = x_2 \rightarrow$  already have func. value!

$$h_1 = b - a$$

$$x_2 = a + \tau h_1$$

$$f_2 = f(x_2) \rightarrow \text{only one}$$

if ( $f_1 < f_2$ ):

$$b = x_2$$

$$x_2 = x_1$$

$$x_1 = a + (1 - \tau) h_1$$

$$f_1 = f(x_1)$$

# Golden Section Search

What happens with the length of the interval after one iteration?

$$h_1 = \tau h_0$$

Or in general:  $h_{k+1} = \tau h_k$

**Hence the interval gets reduced by  $\tau$**

(for bisection method to solve nonlinear equations,  $\tau=0.5$ )

For recursion:

$$\begin{aligned}\tau h_1 &= (1 - \tau) h_0 \\ \tau \tau h_0 &= (1 - \tau) h_0 \\ \tau^2 &= (1 - \tau) \\ \tau &= \mathbf{0.618}\end{aligned}$$

# Golden Section Search

- Derivative free method!
- Slow convergence:

$$\lim_{k \rightarrow \infty} \frac{|e_{k+1}|}{|e_k|} = 0.618 \quad r = 1 \text{ (linear convergence)}$$

- Only one function evaluation per iteration

# Iclicker question

Consider running golden section search on a function that is unimodal. If golden section search is started with an initial bracket of  $[-10, 10]$ , what is the length of the new bracket after 1 iteration?

- A) 20
- B) 10
- C) 12.36
- D) 7.64

# Newton's Method

Using Taylor Expansion, we can approximate the function  $f$  with a quadratic function about  $x_0$

$$f(x) \approx f(x_0) + f'(x_0)(x - x_0) + \frac{1}{2}f''(x_0)(x - x_0)^2$$

And we want to find the minimum of the quadratic function using the first-order necessary condition

# Newton's Method

- **Algorithm:**

$x_0 =$  starting guess

$$x_{k+1} = x_k - f'(x_k)/f''(x_k)$$

- **Convergence:**

- Typical quadratic convergence
- Local convergence (start guess close to solution)
- May fail to converge, or converge to a maximum or point of inflection

Demo: "Newton's method in 1D"  
And "Newton's method Initial Guess"



# Newton's Method (Graphical Representation)

# Example

Consider the function  $f(x) = 4x^3 + 2x^2 + 5x + 40$

If we use the initial guess  $x_0 = 2$ , what would be the value of  $x$  after one iteration of the Newton's method?

# Optimization in ND: Steepest Descent Method

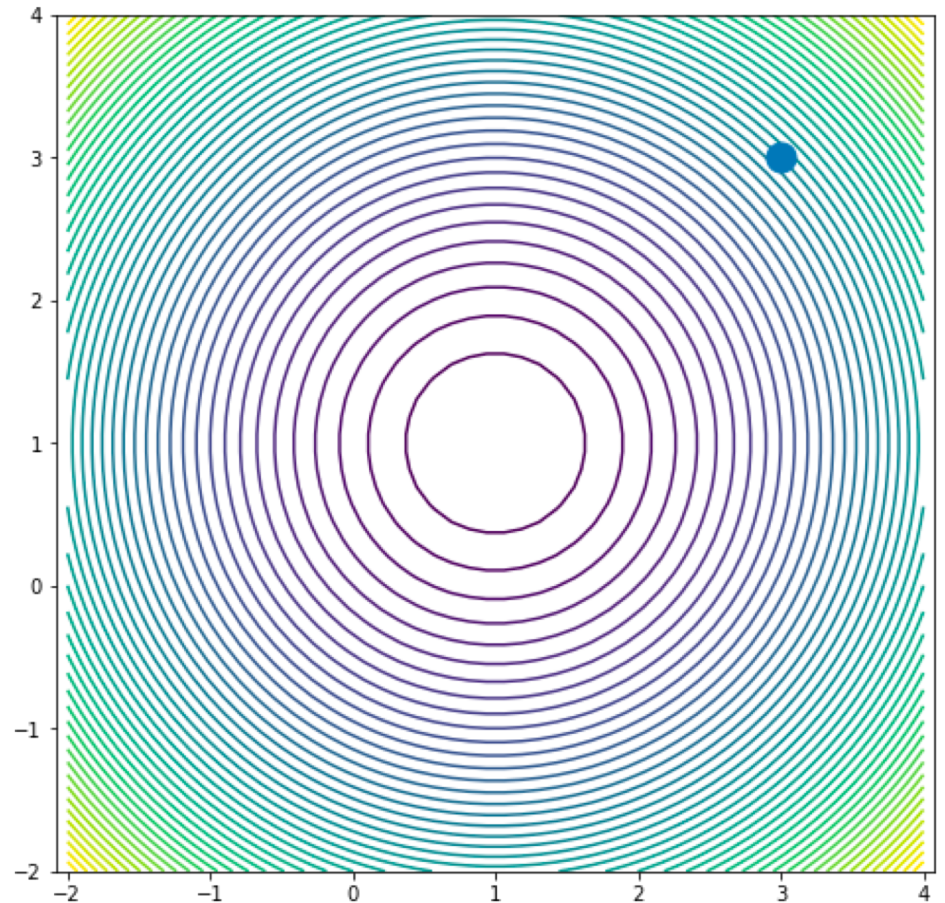
Given a function

$f(\mathbf{x}): \mathcal{R}^n \rightarrow \mathcal{R}$  at a point  $\mathbf{x}$ , the function will decrease its value in the direction of steepest descent:  $-\nabla f(\mathbf{x})$

*Clicker question:*

What is the steepest descent direction?

$$f(x_1, x_2) = (x_1 - 1)^2 + (x_2 - 1)^2$$



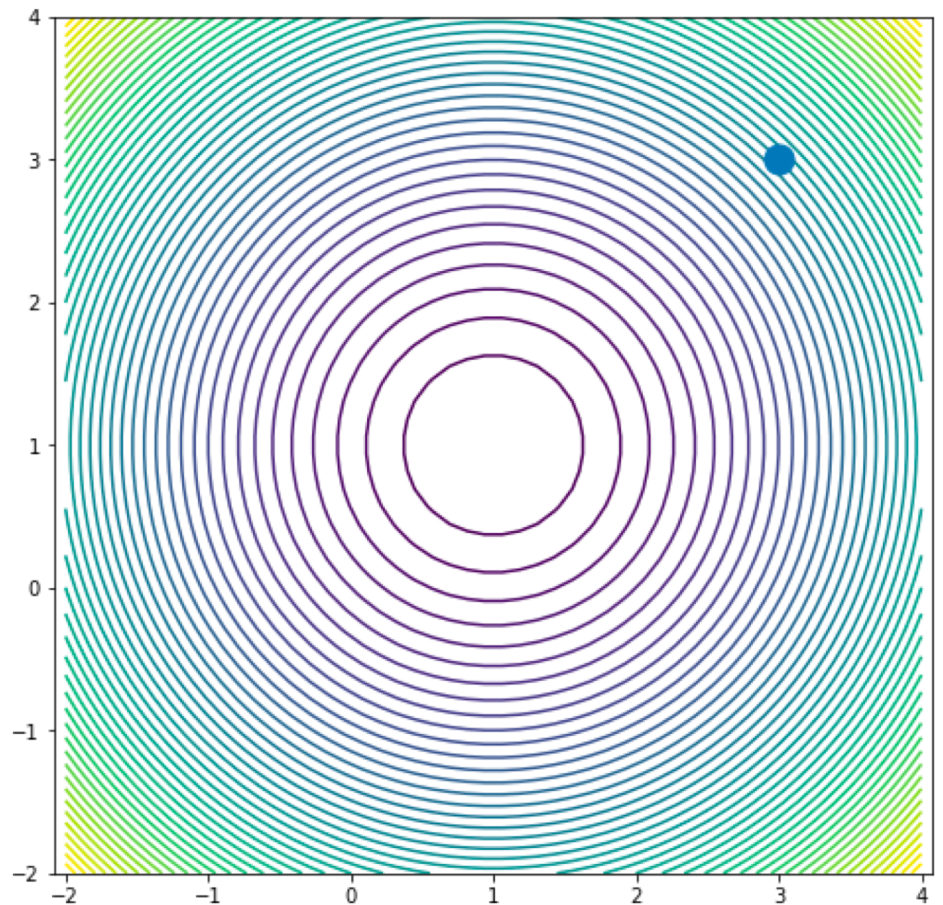
# Steepest Descent Method

Start with initial guess:

$$\mathbf{x}_0 = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$$

Check the update:

$$f(x_1, x_2) = (x_1 - 1)^2 + (x_2 - 1)^2$$



# Steepest Descent Method

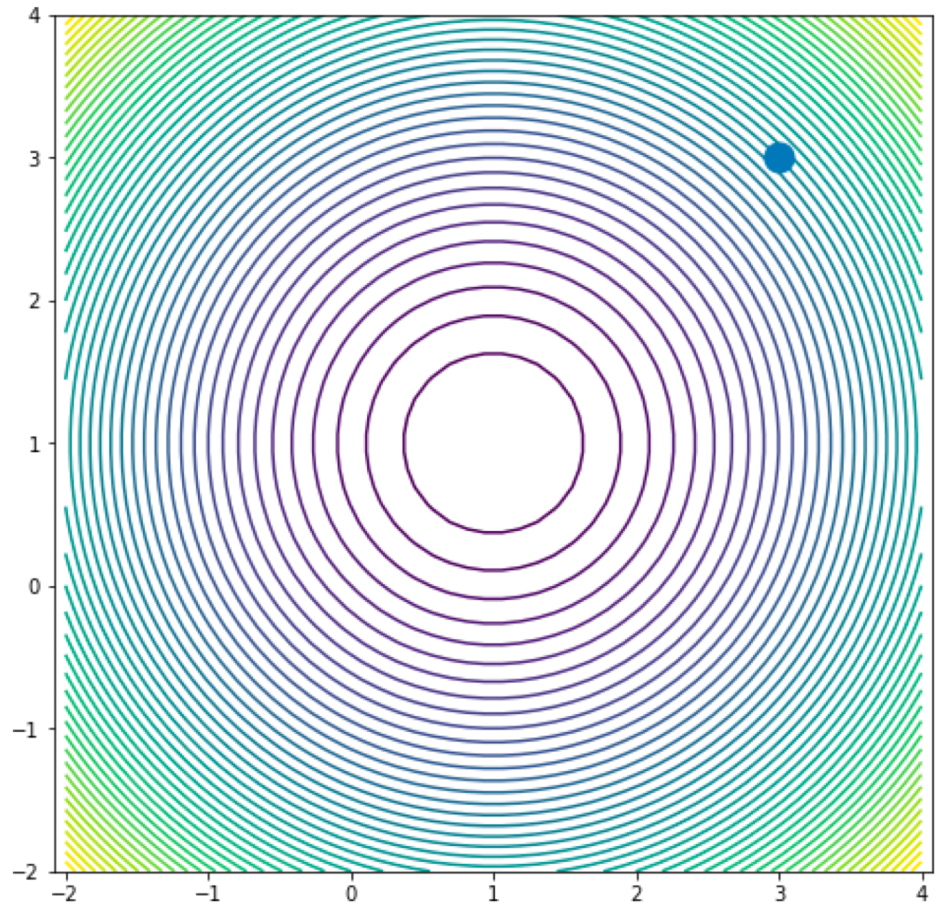
Update the variable with:

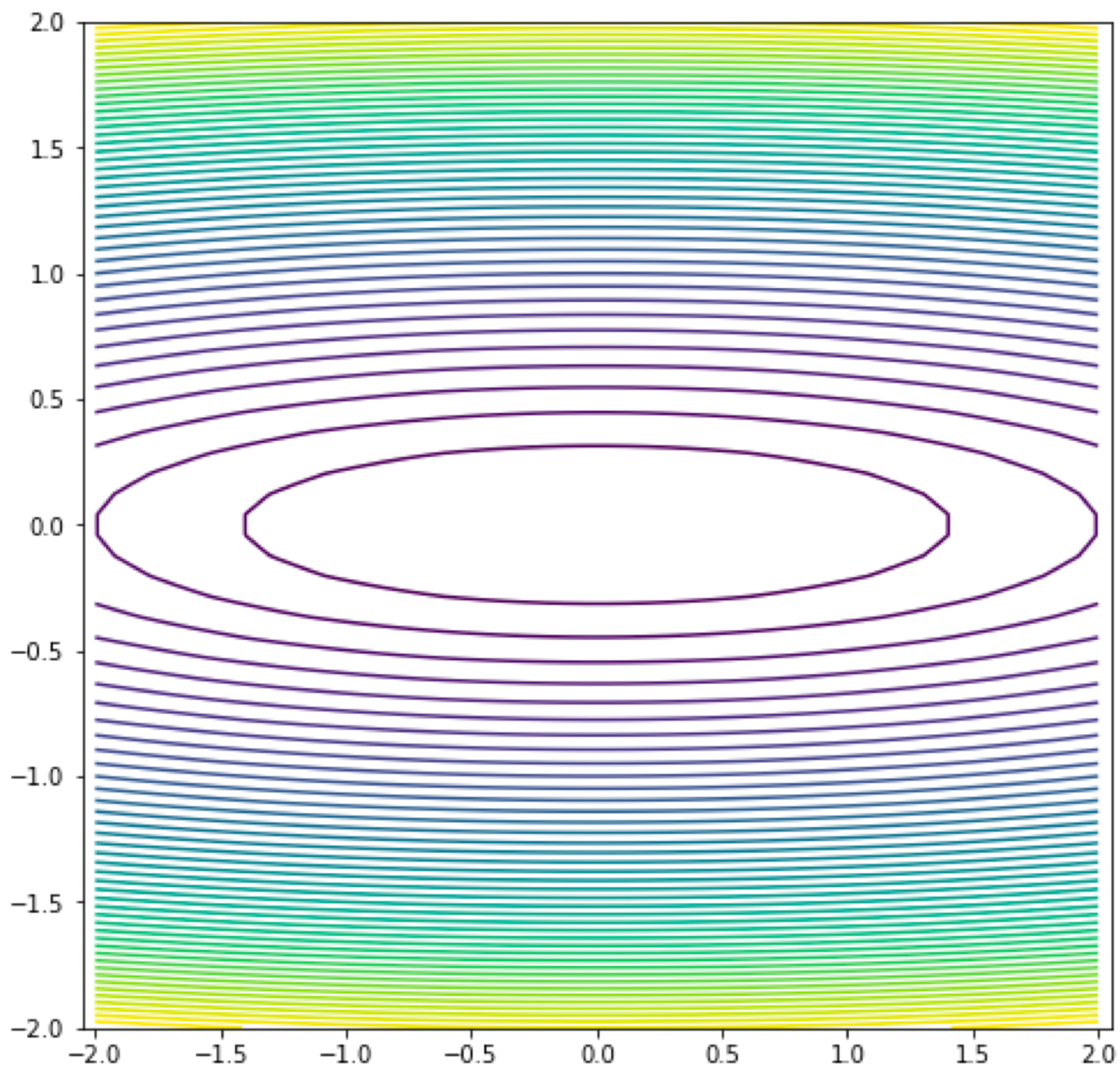
$$\mathbf{x}_{k+1} = \mathbf{x}_k - \alpha_k \nabla f(\mathbf{x}_k)$$

How far along the gradient should we go? What is the “best size” for  $\alpha_k$ ?

- A) 0
- B) 0.5
- C) 1
- D) 2
- E) Cannot be determined

$$f(x_1, x_2) = (x_1 - 1)^2 + (x_2 - 1)^2$$





# Steepest Descent Method

## Algorithm:

Initial guess:  $\mathbf{x}_0$

Evaluate:  $\mathbf{s}_k = -\nabla f(\mathbf{x}_k)$

Perform a line search to obtain  $\alpha_k$  (for example, Golden Section Search)

$$\alpha_k = \operatorname{argmin}_{\alpha} f(\mathbf{x}_k + \alpha \mathbf{s}_k)$$

Update:  $\mathbf{x}_{k+1} = \mathbf{x}_k + \alpha_k \mathbf{s}_k$

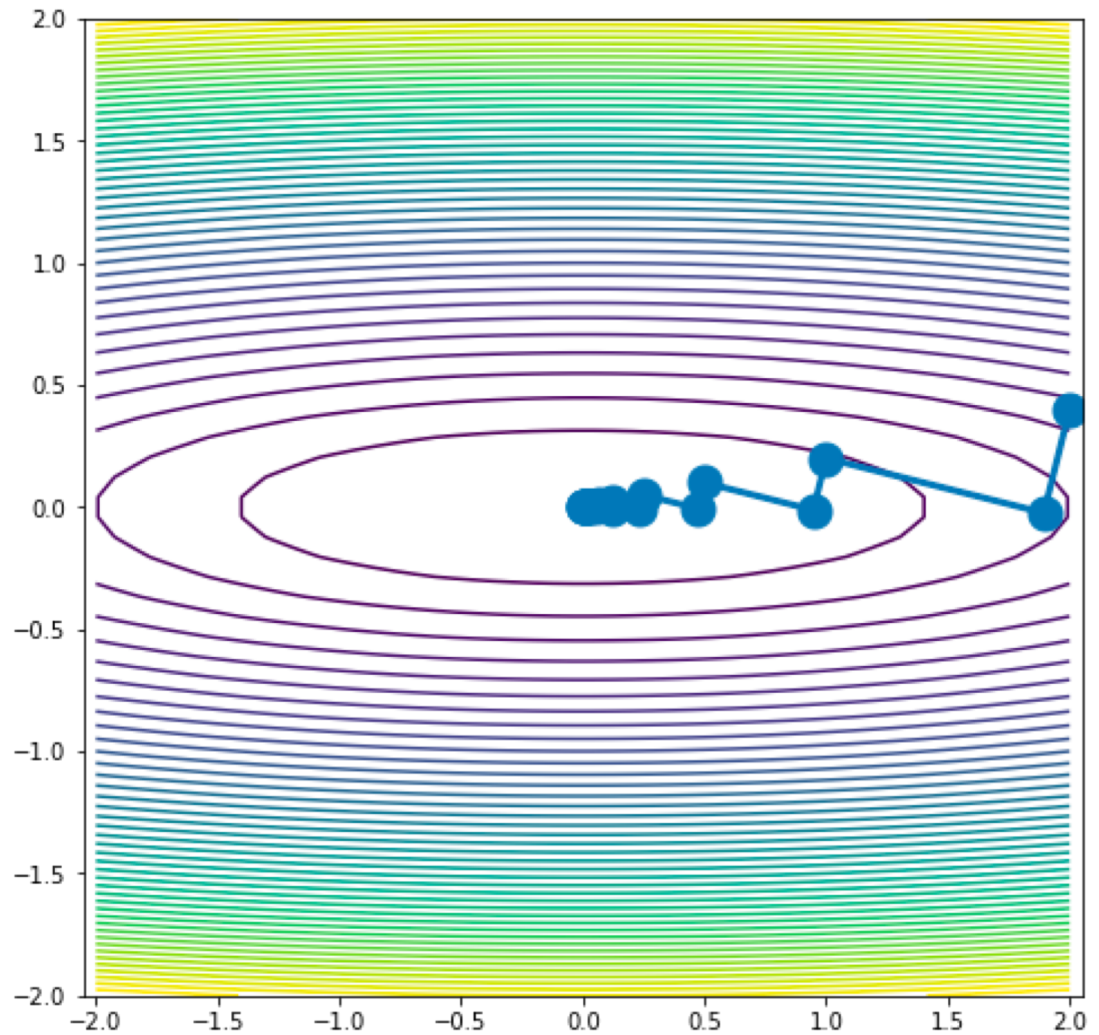
# Line Search



# Steepest Descent Method

**Demo:** Steepest Descent

**Convergence:** linear



Demo: "Steepest Descent"

# Iclicker question:

Consider minimizing the function

$$f(x_1, x_2) = 10(x_1)^3 - (x_2)^2 + x_1 - 1$$

Given the initial guess

$$x_1 = 2, x_2 = 2$$

what is the direction of the first step of gradient descent?

# Newton's Method

Using Taylor Expansion, we build the approximation:

$$f(\mathbf{x} + \mathbf{s}) \approx f(\mathbf{x}) + \nabla f(\mathbf{x})^T \mathbf{s} + \frac{1}{2} \mathbf{s}^T \mathbf{H}_f(\mathbf{x}) \mathbf{s} = \hat{f}(\mathbf{s})$$

And we want to find the minimum  $\hat{f}(\mathbf{s})$ , so we enforce the first-order necessary condition

# Newton's Method

## Algorithm:

Initial guess:  $\mathbf{x}_0$

Solve:  $\mathbf{H}_f(\mathbf{x}_k) \mathbf{s}_k = -\nabla f(\mathbf{x}_k)$

Update:  $\mathbf{x}_{k+1} = \mathbf{x}_k + \mathbf{s}_k$

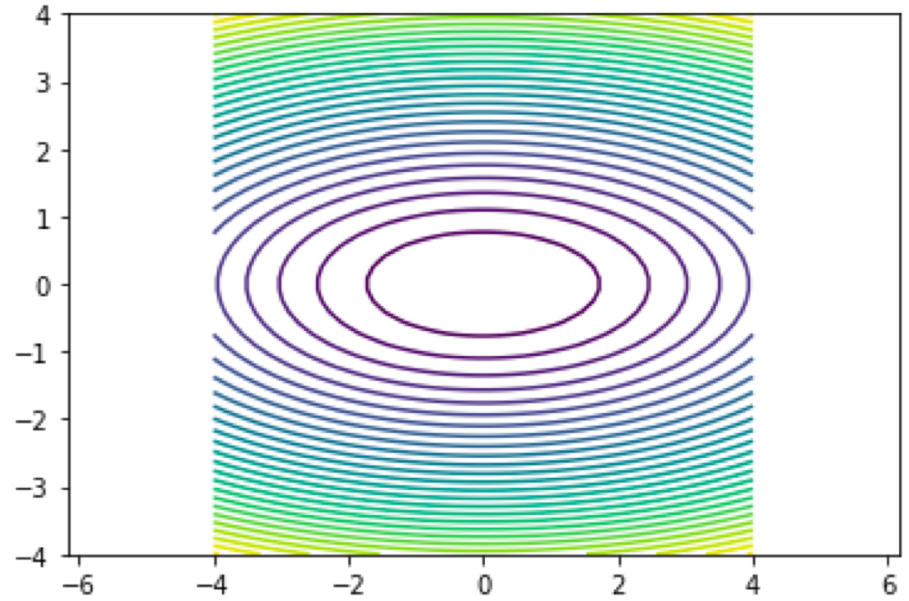
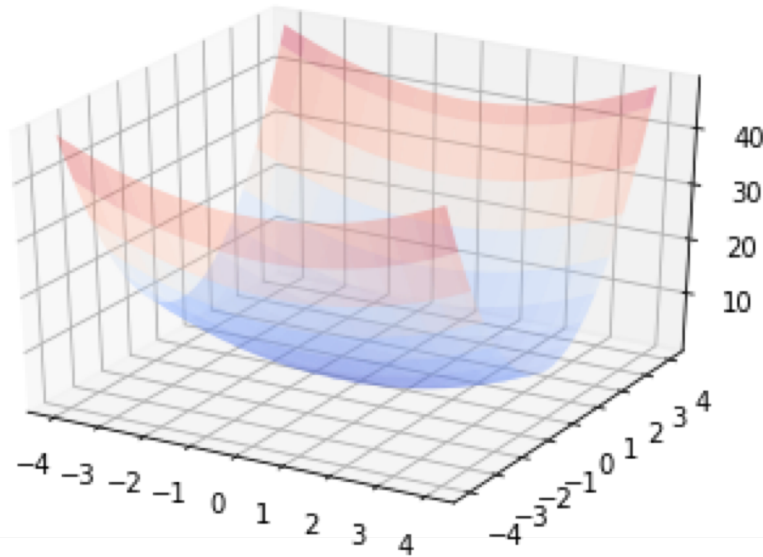
Note that the Hessian is related to the curvature and therefore contains the information about how large the step should be.

# Example

You want to find the optimal solution of  $f(x, y) = 3x^2 + 2y^2$ .  
Write the algorithm to find an optimal solution using the Newton's method.

# Iclicker question:

$$f(x, y) = 0.5x^2 + 2.5y^2$$



When using the Newton's Method to find the minimizer of this function, estimate the number of iterations it would take for convergence?

- A) 1    B) 2-5    C) 5-10    D) More than 10    E) Depends on the initial guess

# Newton's Method Summary

## Algorithm:

Initial guess:  $\mathbf{x}_0$

Solve:  $\mathbf{H}_f(\mathbf{x}_k) \mathbf{s}_k = -\nabla f(\mathbf{x}_k)$

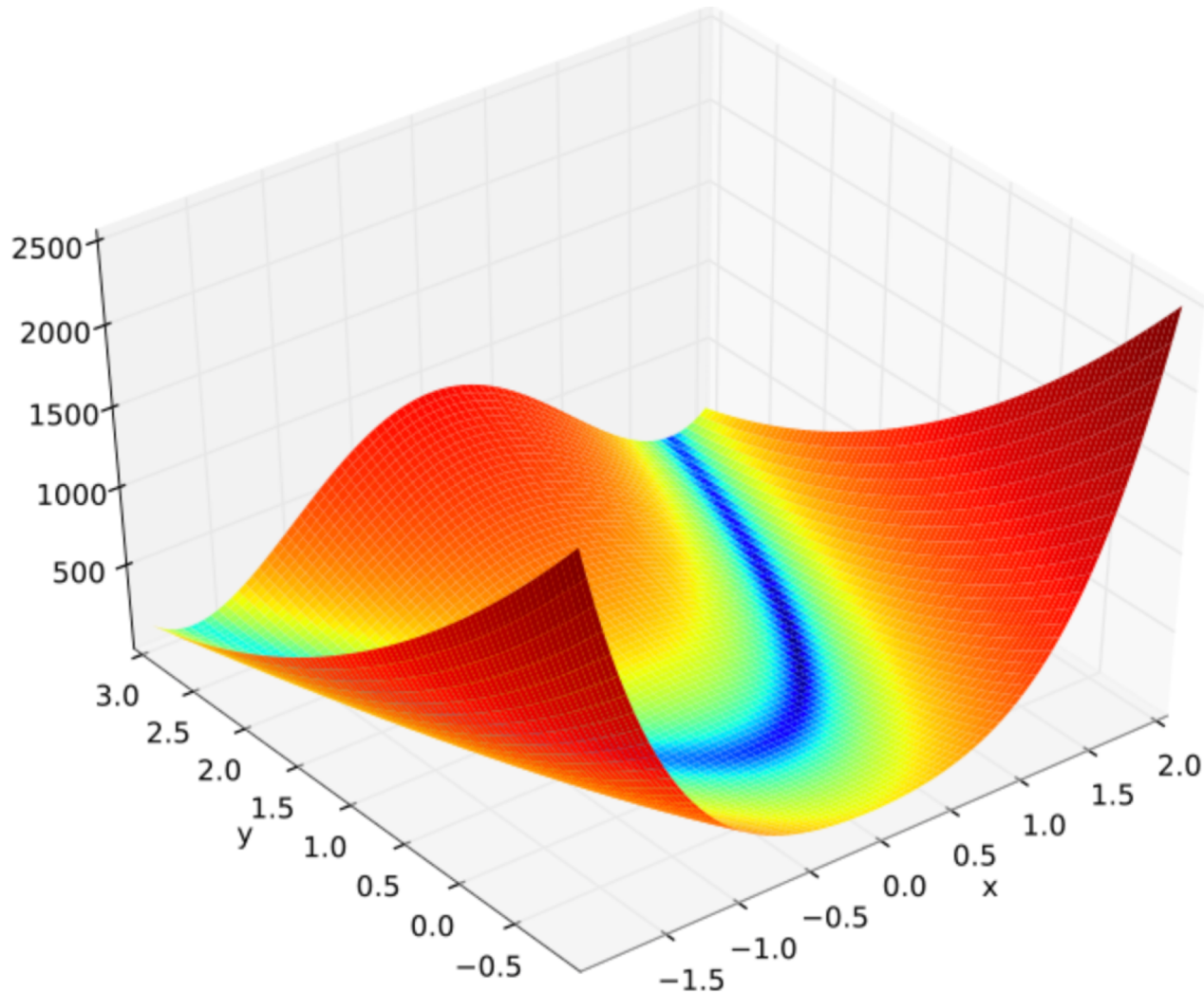
Update:  $\mathbf{x}_{k+1} = \mathbf{x}_k + \mathbf{s}_k$

## About the method...

- Typical quadratic convergence 😊
- Need second derivatives 😞
- Local convergence (start guess close to solution)
- Works poorly when Hessian is nearly indefinite
- Cost per iteration:  $O(n^3)$

# Example:

[https://en.wikipedia.org/wiki/Rosenbrock\\_function](https://en.wikipedia.org/wiki/Rosenbrock_function)





# Iclicker question:

Recall Newton's method and the steepest descent method for minimizing a function  $f(\mathbf{x}): \mathcal{R}^n \rightarrow \mathcal{R}$ . How many statements below describe the Newton Method's only (not both)?

1. Convergence is linear
2. Requires a line search at each iteration
3. Evaluates the Gradient of  $f(\mathbf{x})$  at each iteration
4. Evaluates the Hessian of  $f(\mathbf{x})$  at each iteration
5. Computational cost per iteration is  $O(n^3)$

A) 1    B) 2    C) 3    D) 4    E) 5