

## 21.2

### (Polynomial Time) Reductions: Overview

# Reductions

A reduction from Problem **X** to Problem **Y** means (informally) that if we have an algorithm for Problem **Y**, we can use it to find an algorithm for Problem **X**.

## Using Reductions

① We use reductions to find algorithms to solve problems.

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## Using Reductions

- ① We use reductions to find algorithms to solve problems.
- ② We also use reductions to show that we **can't** find algorithms for some problems. (We say that these problems are **hard**.)

# Reductions for decision problems/languages

For languages  $L_X, L_Y$ , a reduction from  $L_X$  to  $L_Y$  is:

- 1 An algorithm ...
- 2 Input:  $w \in \Sigma^*$
- 3 Output:  $w' \in \Sigma^*$
- 4 Such that:

$$\boxed{w \in L_X} \iff \boxed{w' \in L_Y}$$

(Actually, this is only one type of reduction, but this is the one we'll use most often.)  
There are other kinds of reductions.

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# Reductions for decision problems/languages

For decision problems  $X, Y$ , a reduction from  $X$  to  $Y$  is:

- 1 An algorithm ...
- 2 Input:  $I_X$ , an instance of  $X$ .
- 3 Output:  $I_Y$  an instance of  $Y$ .
- 4 Such that:

$$\boxed{I_Y \text{ is YES instance of } Y} \iff \boxed{I_X \text{ is YES instance of } X}$$

# Using reductions to solve problems

- 1  $\mathcal{R}$ : Reduction  $X \rightarrow Y$
- 2  $\mathcal{A}_Y$ : algorithm for  $Y$ :
- 3  $\implies$  New algorithm for  $X$ :

```
 $\mathcal{A}_X(I_X)$ :  
    //  $I_X$ : instance of  $X$ .  
     $I_Y \leftarrow \mathcal{R}(I_X)$   
    return  $\mathcal{A}_Y(I_Y)$ 
```

If  $\mathcal{R}$  and  $\mathcal{A}_Y$  polynomial-time  $\implies \mathcal{A}_X$  polynomial-time.



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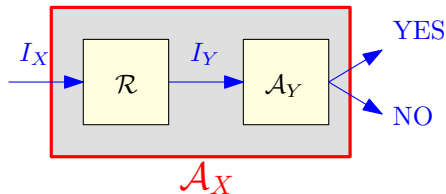
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# Comparing Problems

- ① “Problem  $X$  is no harder to solve than Problem  $Y$ ”.
- ② If Problem  $X$  reduces to Problem  $Y$  (we write  $X \leq Y$ ), then  $X$  cannot be harder to solve than  $Y$ .
- ③  $X \leq Y$ :
  - ①  $X$  is no harder than  $Y$ , or
  - ②  $Y$  is at least as hard as  $X$ .

**THE END**

...

**(for now)**