Algorithms & Models of Computation CS/ECE 374, Spring 2019

Non-deterministic Finite Automata (NFAs)

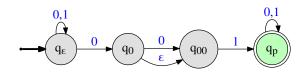
Lecture 4 Thursday, January 24, 2019

LATEXed: January 27, 2019 12:59

Part I

NFA Introduction

Non-deterministic Finite State Automata (NFAs)



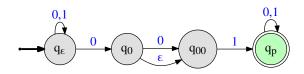
Differences from DFA

- From state q on same letter $a \in \Sigma$ multiple possible states
- No transitions from q on some letters
- ε -transitions!

Questions:

- Is this a "real" machine?
- What does it do?

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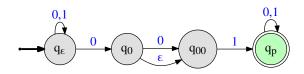
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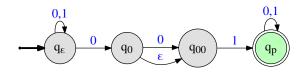


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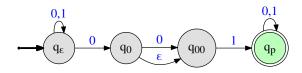
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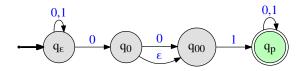
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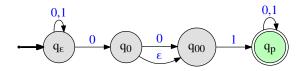
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- ullet From q_0 on arepsilon
- From q_{ε} on 01
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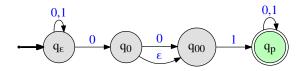
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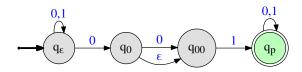
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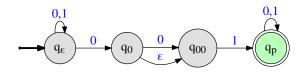


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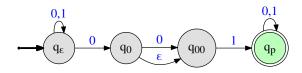
NFA acceptance: informal



Informal definition: An NFA N accepts a string w iff some accepting state is reached by N from the start state on input w.

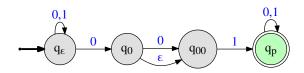
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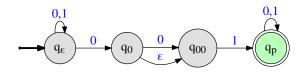


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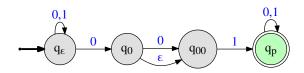
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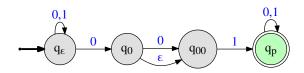
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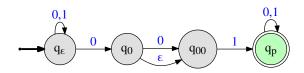
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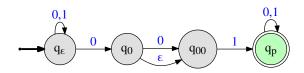
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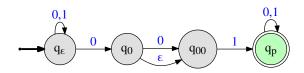
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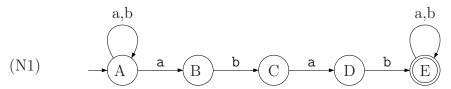


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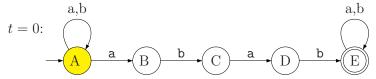
Example the first



Run it on input ababa.

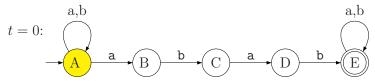
Idea: Keep track of the states where the NFA might be at any given time.

Example the first

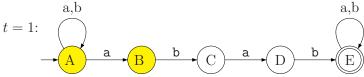


Remaining input: ababa.

Example the first

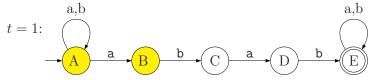


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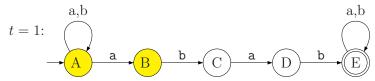
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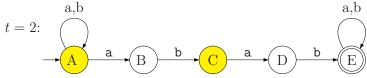


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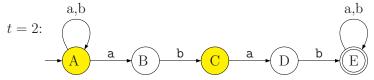


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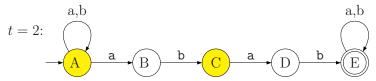
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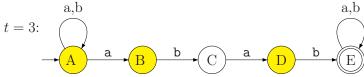


Remaining input: aba.

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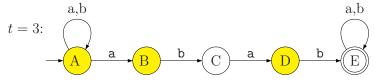


Remaining input: aba.



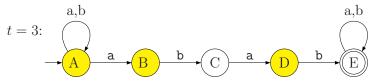
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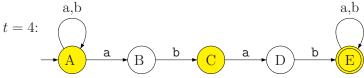


Remaining input: ba.

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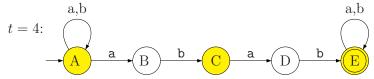


Remaining input: ba.



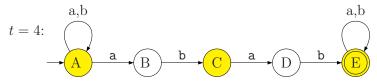
Remaining input: a.

Example the first

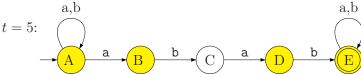


Remaining input: a.

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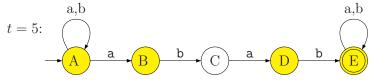


Remaining input: a.



Remaining input: ε .

Example the first



Remaining input: ε .

Accepts: ababa.

Formal Tuple Notation

Definition

A non-deterministic finite automata (NFA) $N = (Q, \Sigma, \delta, s, A)$ is a five tuple where

- Q is a finite set whose elements are called states,
- Σ is a finite set called the input alphabet,
- $\delta: Q \times \Sigma \cup \{\varepsilon\} \to \mathcal{P}(Q)$ is the transition function (here $\mathcal{P}(Q)$ is the power set of Q),
- $s \in Q$ is the start state,
- $A \subseteq Q$ is the set of accepting/final states.

 $\delta(q,a)$ for $a \in \Sigma \cup \{\varepsilon\}$ is a subset of Q — a set of states.

Reminder: Power set

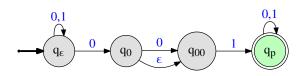
For a set Q its power set is: $\mathcal{P}(Q) = 2^Q = \{X \mid X \subseteq Q\}$ is the set of all subsets of Q.

Example

$$Q = \{1, 2, 3, 4\}$$

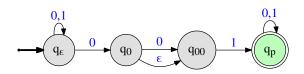
$$\mathcal{P}(Q) = \left\{ \begin{array}{c} \{1, 2, 3, 4\}, \\ \{2, 3, 4\}, \{1, 3, 4\}, \{1, 2, 4\}, \{1, 2, 3\}, \\ \{1, 2\}, \{1, 3\}, \{1, 4\}, \{2, 3\}, \{2, 4\}, \{3, 4\}, \\ \{1\}, \{2\}, \{3\}, \{4\}, \\ \{\} \end{array} \right\}$$

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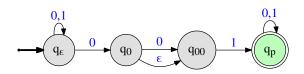


- $Q = \{q_{\varepsilon}, q_0, q_{00}, q_p\}$
- $\Sigma = \{0, 1\}$
- δ
- $s = q_{\varepsilon}$
- $\bullet \ A = \{q_p\}$

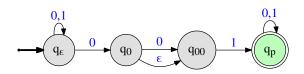
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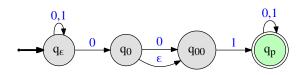
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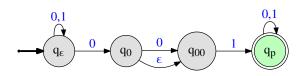
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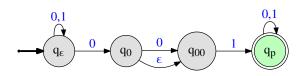
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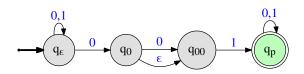
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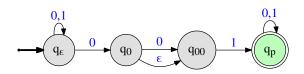
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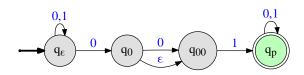


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Transition function in detail...



$$egin{aligned} \delta(q_{arepsilon},arepsilon) &= \{q_{arepsilon}\} \ \delta(q_{arepsilon},arepsilon) &= \{q_{arepsilon},q_{00}\} \ \delta(q_{arepsilon},0) &= \{q_{arepsilon},q_{00}\} \ \delta(q_{arepsilon},1) &= \{q_{arepsilon}\} \ \delta(q_{00},arepsilon) &= \{q_{00}\} \ \delta(q_{00},arepsilon) &= \{q_{00}\} \ \delta(q_{00},arepsilon) &= \{q_{p}\} \ \delta(q_{00},0) &= \{q_{p}\} \ \delta(q_{00},1) &= \{q_{p}\} \end{aligned}$$

- ② $\delta(q, a)$: set of states that N can go to from q on reading $a \in \Sigma \cup \{\varepsilon\}$.
- $exttt{0}$ Want transition function $\delta^*: Q imes \mathbf{\Sigma}^* o \mathcal{P}(Q)$
- $\delta^*(q, w)$: set of states reachable on input w starting in state q.

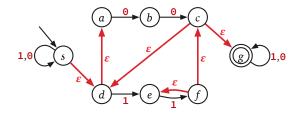
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For NFA $N = (Q, \Sigma, \delta, s, A)$ and $q \in Q$ the ϵ -reach(q) is the set of all states that q can reach using only ϵ -transitions.



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Inductive definition of $\delta^*: Q \times \Sigma^* \to \mathcal{P}(Q)$:

- if $w = \varepsilon$, $\delta^*(q, w) = \epsilon \operatorname{reach}(q)$
- if w = a where $a \in \Sigma$ $\delta^*(q, a) = \bigcup_{p \in \epsilon \text{reach}(q)} (\bigcup_{r \in \delta(p, a)} \epsilon \text{reach}(r))$
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Formal definition of language accepted by N

Definition

A string w is accepted by NFA N if $\delta_N^*(s, w) \cap A \neq \emptyset$.

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The language L(N) accepted by a NFA $N = (Q, \Sigma, \delta, s, A)$ is

$$\{w \in \mathbf{\Sigma}^* \mid \delta^*(s, w) \cap A \neq \emptyset\}.$$

Important: Formal definition of the language of NFA above uses δ^* and not δ . As such, one does not need to include ε -transitions closure when specifying δ , since δ^* takes care of that.

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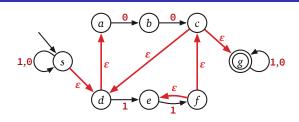
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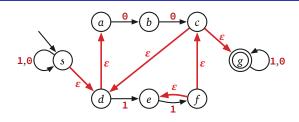
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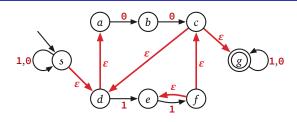
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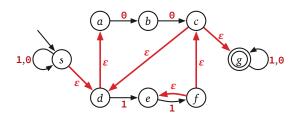
- $\delta^*(s,\epsilon)$
- \bullet $\delta^*(s,0)$
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- $\delta^*(s,\epsilon)$
- $\delta^*(s,0)$
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Another definition of computation

Definition

 $q \xrightarrow{w}_{N} p$: State p of NFA N is **reachable** from q on $w \iff$ there exists a sequence of states r_0, r_1, \ldots, r_k and a sequence x_1, x_2, \ldots, x_k where $x_i \in \Sigma \cup \{\varepsilon\}$, for each i, such that:

- \bullet $r_0 = q$
- for each i, $r_{i+1} \in \delta(r_i, x_{i+1})$,
- \bullet $r_k = p$, and
- $\bullet \ \ w = x_1 x_2 x_3 \cdots x_k.$

Definition

$$\delta^* N(q, w) = \left\{ p \in Q \mid q \xrightarrow{w}_N p \right\}.$$

Why non-determinism?

- Non-determinism adds power to the model; richer programming language and hence (much) easier to "design" programs
- Fundamental in **theory** to prove many theorems
- Very important in practice directly and indirectly
- Many deep connections to various fields in Computer Science and Mathematics

Many interpretations of non-determinism. Hard to understand at the outset. Get used to it and then you will appreciate it slowly.

Part II

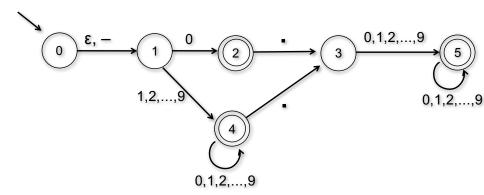
Constructing NFAs

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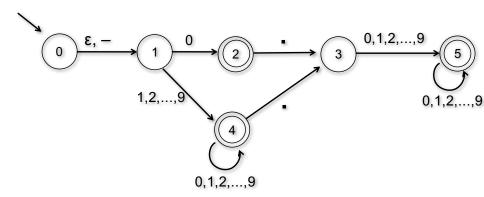
DFAs and NFAs

- Every DFA is a NFA so NFAs are at least as powerful as DFAs.
- NFAs prove ability to "guess and verify" which simplifies design and reduces number of states
- Easy proofs of some closure properties

Strings that represent decimal numbers.



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- {strings that contain CS374 as a substring}
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 $L_k = \{ \text{bitstrings that have a 1 } k \text{ positions from the end} \}$

A simple transformation

Theorem

For every NFA N there is another NFA N' such that L(N) = L(N') and such that N' has the following two properties:

- ullet N' has single final state f that has no outgoing transitions
- The start state **s** of **N** is different from **f**

Part III

Closure Properties of NFAs

Spring 2019

Closure properties of NFAs

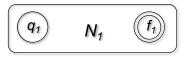
Are the class of languages accepted by NFAs closed under the following operations?

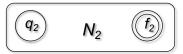
- union
- intersection
- concatenation
- Kleene star
- complement

Closure under union

Theorem

For any two NFAs N_1 and N_2 there is a NFA N such that $L(N) = L(N_1) \cup L(N_2)$.

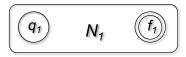


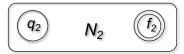


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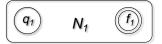


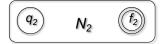


Closure under concatenation

Theorem

For any two NFAs N_1 and N_2 there is a NFA N such that $L(N) = L(N_1) \cdot L(N_2)$.

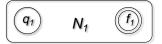


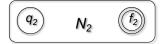


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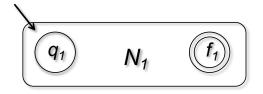
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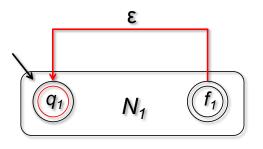
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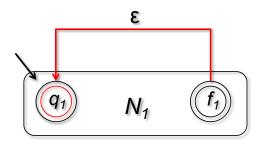
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Does not work! Why?

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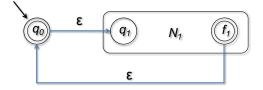
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Part IV

NFAs capture Regular Languages

Regular Languages Recap

Regular Languages

```
\emptyset regular \{\epsilon\} regular \{a\} regular for a \in \Sigma R_1 \cup R_2 regular if both are R_1R_2 regular if both are R^* is regular if R is
```

Regular Expressions

```
\emptyset denotes \emptyset
\epsilon denotes \{\epsilon\}
a denote \{a\}
r_1 + r_2 denotes R_1 \cup R_2
r_1r_2 denotes R_1R_2
r^* denote R^*
```

Regular expressions denote regular languages — they explicitly show the operations that were used to form the language

Theorem

For every regular language L there is an NFA N such that L = L(N).

Proof strategy:

- For every regular expression r show that there is a NFA N such that L(r) = L(N)
- Induction on length of r

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Base cases: \emptyset , $\{\varepsilon\}$, $\{a\}$ for $a \in \Sigma$.

- For every regular expression r show that there is a NFA N such that L(r) = L(N)
- Induction on length of r

- r_1 , r_2 regular expressions and $r = r_1 + r_2$. By induction there are NFAs N_1 , N_2 s.t $L(N_1) = L(r_1)$ and $L(N_2) = L(r_2)$. We have already seen that there is NFA N s.t $L(N) = L(N_1) \cup L(N_2)$, hence
- $r = r_1 \cdot r_2$. Use closure of NFA languages under concatenation
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Example

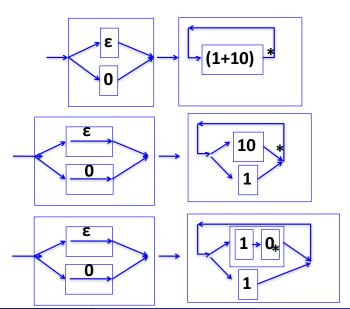
$$(\epsilon+0)(1+10)^*$$

$$\rightarrow (\epsilon+0) \rightarrow (1+10)^*$$

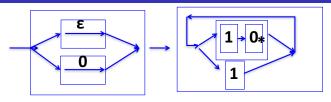
$$\downarrow 0$$

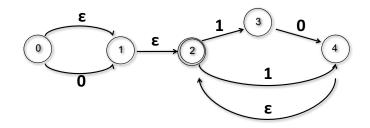
$$\downarrow (1+10)$$

Example



Example





Final NFA simplified slightly to reduce states