

# Backtracking and Memoization

Lecture 12

February 28, 2017

# Recursion

## Reduction:

Reduce one problem to another

## Recursion

A special case of reduction

- 1 reduce problem to a *smaller* instance of *itself*
- 2 self-reduction

- 1 Problem instance of size **n** is reduced to one or more instances of size **n - 1** or less.
- 2 For termination, problem instances of small size are solved by some other method as **base cases**.

# Recursion in Algorithm Design

- 1 **Tail Recursion**: problem reduced to a *single* recursive call after some work. Easy to convert algorithm into iterative or greedy algorithms. Examples: Interval scheduling, MST algorithms, etc.
- 2 **Divide and Conquer**: Problem reduced to multiple **independent** sub-problems that are solved separately. Conquer step puts together solution for bigger problem.  
Examples: Closest pair, deterministic median selection, quick sort.
- 3 **Backtracking**: Refinement of brute force search. Build solution incrementally by invoking recursion to try all possibilities for the decision in each step.
- 4 **Dynamic Programming**: problem reduced to multiple (typically) *dependent or overlapping* sub-problems. Use **memoization** to avoid recomputation of common solutions leading to *iterative bottom-up* algorithm.

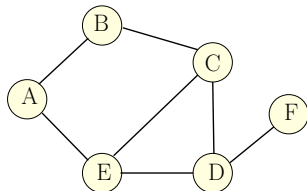
# Part I

## Brute Force Search, Recursion and Backtracking

# Maximum Independent Set in a Graph

## Definition

Given undirected graph  $G = (V, E)$  a subset of nodes  $S \subseteq V$  is an **independent set** (also called a stable set) if for there are no edges between nodes in  $S$ . That is, if  $u, v \in S$  then  $(u, v) \notin E$ .

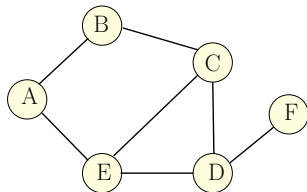


Some independent sets in graph above:  $\{D\}$ ,  $\{A, C\}$ ,  $\{B, E, F\}$

# Maximum Independent Set Problem

Input Graph  $G = (V, E)$

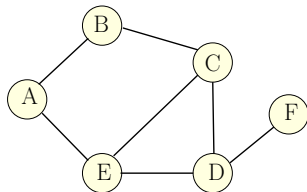
Goal Find maximum sized independent set in  $G$



# Maximum Weight Independent Set Problem

Input Graph  $\mathbf{G} = (\mathbf{V}, \mathbf{E})$ , weights  $\mathbf{w}(v) \geq 0$  for  $\mathbf{v} \in \mathbf{V}$

Goal Find maximum weight independent set in  $\mathbf{G}$



# Maximum Weight Independent Set Problem

- 1 No one knows an *efficient* (polynomial time) algorithm for this problem
- 2 Problem is **NP-Complete** and it is *believed* that there is no polynomial time algorithm

Brute-force algorithm:

Try all subsets of vertices.



# Brute-force enumeration

Algorithm to find the size of the maximum weight independent set.

```
MaxIndSet( $G = (V, E)$ ):
```

```
  max = 0
```

```
  for each subset  $S \subseteq V$  do
```

```
    check if  $S$  is an independent set
```

```
    if  $S$  is an independent set and  $w(S) > \mathbf{max}$  then
```

```
      max =  $w(S)$ 
```

```
  Output max
```

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```
  Output max
```

Running time: suppose  $G$  has  $n$  vertices and  $m$  edges

- 1  $2^n$  subsets of  $V$
- 2 checking each subset  $S$  takes  $O(m)$  time
- 3 total time is  $O(m2^n)$

# A Recursive Algorithm

Let  $\mathbf{V} = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$ .

For a vertex  $\mathbf{u}$  let  $\mathbf{N}(\mathbf{u})$  be its neighbors.

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## Observation

$\mathbf{v}_1$ : vertex in the graph.

One of the following two cases is true

Case 1  $\mathbf{v}_1$  is in some maximum independent set.

Case 2  $\mathbf{v}_1$  is in no maximum independent set.

We can try both cases to “reduce” the size of the problem

# A Recursive Algorithm

Let  $\mathbf{V} = \{v_1, v_2, \dots, v_n\}$ .

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One of the following two cases is true

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$\mathbf{G}_1 = \mathbf{G} - v_1$  obtained by removing  $v_1$  and incident edges from  $\mathbf{G}$

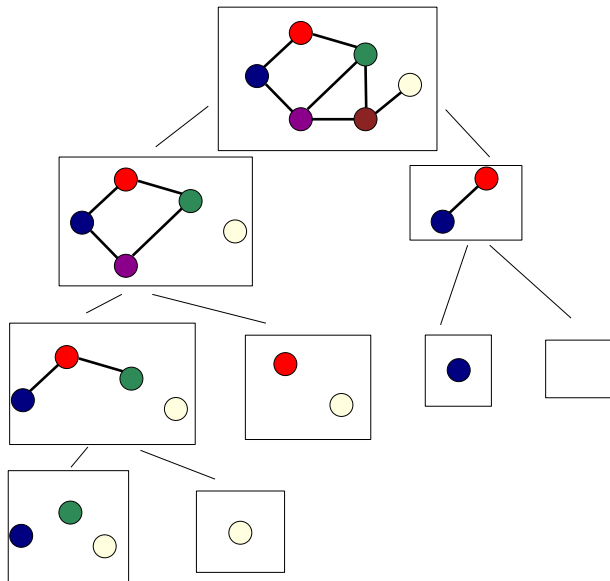
$\mathbf{G}_2 = \mathbf{G} - v_1 - \mathbf{N}(v_1)$  obtained by removing  $\mathbf{N}(v_1) \cup v_1$  from  $\mathbf{G}$

$$\text{MIS}(\mathbf{G}) = \max\{\text{MIS}(\mathbf{G}_1), \text{MIS}(\mathbf{G}_2) + w(v_1)\}$$

# A Recursive Algorithm

```
RecursiveMIS(G):  
  if G is empty then Output 0  
  a = RecursiveMIS(G - v1)  
  b = w(v1) + RecursiveMIS(G - v1 - N(v1))  
  Output max(a, b)
```

# Example



# Recursive Algorithms

..for Maximum Independent Set

Running time:

$$T(n) = T(n - 1) + T(n - 1 - \text{deg}(v_1)) + O(1 + \text{deg}(v_1))$$

where  $\text{deg}(v_1)$  is the degree of  $v_1$ .  $T(0) = T(1) = 1$  is base case.

Worst case is when  $\text{deg}(v_1) = 0$  when the recurrence becomes

$$T(n) = 2T(n - 1) + O(1)$$

Solution to this is  $T(n) = O(2^n)$ .



# Backtrack Search via Recursion

- 1 Recursive algorithm generates a tree of computation where each node is a smaller problem (subproblem)
- 2 Simple recursive algorithm computes/explores the whole tree blindly in some order.
- 3 Backtrack search is a way to explore the tree intelligently to prune the search space
  - 1 Some subproblems may be so simple that we can stop the recursive algorithm and solve it directly by some other method
  - 2 Memoization to avoid recomputing same problem
  - 3 Stop the recursion at a subproblem if it is clear that there is no need to explore further.
  - 4 Leads to a number of heuristics that are widely used in practice although the worst case running time may still be exponential.

# Sequences

## Definition

**Sequence:** an ordered list  $a_1, a_2, \dots, a_n$ . **Length** of a sequence is number of elements in the list.

## Definition

$a_{i_1}, \dots, a_{i_k}$  is a **subsequence** of  $a_1, \dots, a_n$  if  
 $1 \leq i_1 < i_2 < \dots < i_k \leq n$ .

## Definition

A sequence is **increasing** if  $a_1 < a_2 < \dots < a_n$ . It is **non-decreasing** if  $a_1 \leq a_2 \leq \dots \leq a_n$ . Similarly **decreasing** and **non-increasing**.

# Sequences

Example...

## Example

- 1 Sequence: **6, 3, 5, 2, 7, 8, 1, 9**
- 2 Subsequence of above sequence: **5, 2, 1**
- 3 Increasing sequence: **3, 5, 9, 17, 54**
- 4 Decreasing sequence: **34, 21, 7, 5, 1**
- 5 Increasing subsequence of the first sequence: **2, 7, 9.**

# Longest Increasing Subsequence Problem

**Input** A sequence of numbers  $a_1, a_2, \dots, a_n$

**Goal** Find an **increasing subsequence**  $a_{i_1}, a_{i_2}, \dots, a_{i_k}$  of maximum length

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## Example

- 1 Sequence: 6, 3, 5, 2, 7, 8, 1
- 2 Increasing subsequences: 6, 7, 8 and 3, 5, 7, 8 and 2, 7 etc
- 3 Longest increasing subsequence: 3, 5, 7, 8

8, 5, 7, 1

5, 6, 7, 8, 1, 2

# Naïve Enumeration

Assume  $a_1, a_2, \dots, a_n$  is contained in an array  $A$

```
algLISNaive(A[1..n]):  
  max = 0  
  for each subsequence B of A do  
    if B is increasing and |B| > max then  
      max = |B|  
  
  Output max
```

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  Output  $\mathbf{max}$ 
```

Running time:

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Running time:  $O(n2^n)$ .

$2^n$  subsequences of a sequence of length  $n$  and  $O(n)$  time to check if a given sequence is increasing.



# Recursive Approach: Take 1

LIS: Longest increasing subsequence

Can we find a recursive algorithm for LIS?

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 $LIS(A[1..n]) = LIS(A[1..(n - 1)])$
- 2 **Case 2:** contains  $A[n]$  in which case LIS( $A[1..n]$ ) is

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- 2 **Case 2:** contains  $A[n]$  in which case  $LIS(A[1..n])$  is not so clear.

## Observation

*For second case we want to find a subsequence in  $A[1..(n-1)]$  that is restricted to numbers less than  $A[n]$ . This suggests that a more general problem is  $LIS\_smaller(A[1..n], x)$  which gives the longest increasing subsequence in  $A$  where each number in the sequence is less than  $x$ .*

# Recursive Approach

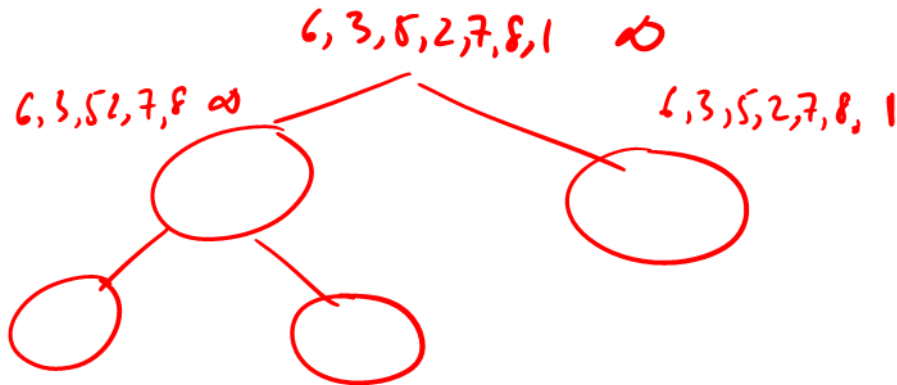
**LIS\_smaller**( $A[1..n]$ ,  $x$ ) : length of longest increasing subsequence in  $A[1..n]$  with all numbers in subsequence less than  $x$

```
LIS_smaller( $A[1..n]$ ,  $x$ ) :  
  if ( $n = 0$ ) then return 0  
   $m = \text{LIS\_smaller}(A[1..(n - 1)], x)$   
  if ( $A[n] < x$ ) then  
     $m = \max(m, 1 + \text{LIS\_smaller}(A[1..(n - 1)], A[n]))$   
  Output  $m$ 
```

```
LIS( $A[1..n]$ ) :  
  return LIS_smaller( $A[1..n]$ ,  $\infty$ )
```

# Example

Sequence:  $A[1..7] = 6, 3, 5, 2, 7, 8, 1$



# Part II

## Recursion and Memoization

# Fibonacci Numbers

Fibonacci numbers defined by recurrence:

$$\mathbf{F(n) = F(n - 1) + F(n - 2) \text{ and } F(0) = 0, F(1) = 1.}$$

These numbers have many interesting and amazing properties.  
A journal *The Fibonacci Quarterly!*

- ①  $\mathbf{F(n) = (\phi^n - (1 - \phi)^n) / \sqrt{5}}$  where  $\phi$  is the golden ratio  $\mathbf{(1 + \sqrt{5}) / 2 \simeq 1.618.}$
- ②  $\lim_{n \rightarrow \infty} \mathbf{F(n + 1) / F(n) = \phi}$



# How many bits?

Consider the  $n$ th Fibonacci number  $F(n)$ . Writing the number  $F(n)$  in base 2 requires

- (A)  $\Theta(n^2)$  bits.
- (B)  $\Theta(n)$  bits.
- (C)  $\Theta(\log n)$  bits.
- (D)  $\Theta(\log \log n)$  bits.

# Recursive Algorithm for Fibonacci Numbers

**Question:** Given  $n$ , compute  $F(n)$ .

```
Fib( $n$ ):  
  if ( $n = 0$ )  
    return 0  
  else if ( $n = 1$ )  
    return 1  
  else  
    return Fib( $n - 1$ ) + Fib( $n - 2$ )
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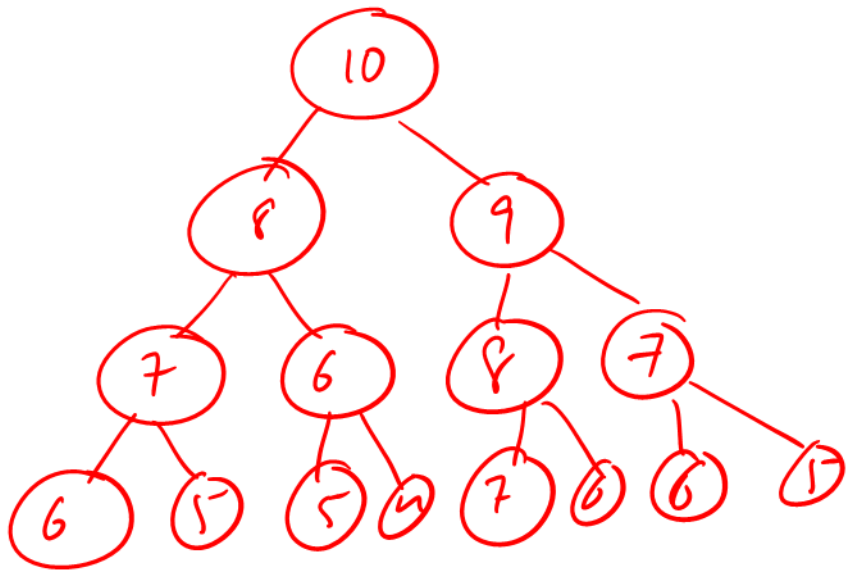
Roughly same as  $F(n)$

$$T(n) = \Theta(\phi^n)$$

The number of additions is exponential in  $n$ . Can we do better?

# An iterative algorithm for Fibonacci numbers

```
FibIter(n):  
  if (n = 0) then  
    return 0  
  if (n = 1) then  
    return 1  
  F[0] = 0  
  F[1] = 1  
  for i = 2 to n do  
    F[i] = F[i - 1] + F[i - 2]  
  return F[n]
```



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```

What is the running time of the algorithm?  $O(n)$  additions.

# What is the difference?

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## Dynamic Programming:

Finding a recursion that can be *effectively/efficiently* memoized.

Leads to polynomial time algorithm if number of sub-problems is polynomial in input size.

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Can we convert recursive algorithm into an efficient algorithm without explicitly doing an iterative algorithm?

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    return 1  
  if (Fib(n) was previously computed)  
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    return Fib(n - 1) + Fib(n - 2)
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How do we keep track of previously computed values?

Two methods: explicitly and implicitly (via data structure)



# Automatic explicit memoization

Initialize table/array  $\mathbf{M}$  of size  $\mathbf{n}$  such that  $\mathbf{M}[i] = -1$  for  $i = 0, \dots, \mathbf{n}$ .

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Initialize table/array **M** of size **n** such that **M[i] = -1** for **i = 0, ..., n**.

```
Fib(n) :  
  if (n = 0)  
    return 0  
  if (n = 1)  
    return 1  
  if (M[n] ≠ -1) (* M[n] has stored value of Fib(n) *)  
    return M[n]  
  M[n] ← Fib(n - 1) + Fib(n - 2)  
  return M[n]
```

To allocate memory need to know upfront the number of subproblems for a given input size **n**

# Automatic implicit memoization

Initialize a (dynamic) dictionary data structure **D** to empty

```
Fib(n):  
  if (n = 0)  
    return 0  
  if (n = 1)  
    return 1  
  if (n is already in D)  
    return value stored with n in D  
    val  $\leftarrow$  Fib(n - 1) + Fib(n - 2)  
  Store (n, val) in D  
  return val
```

# Explicit vs Implicit Memoization

- 1 Explicit memoization or iterative algorithm preferred if one can analyze problem ahead of time. Allows for efficient memory allocation and access.
- 2 Implicit and automatic memoization used when problem structure or algorithm is either not well understood or in fact unknown to the underlying system.
  - 1 Need to pay overhead of data-structure.
  - 2 Functional languages such as LISP automatically do memoization, usually via hashing based dictionaries.

# How many distinct calls?

```
binom(t, b)    // computes  $\binom{t}{b}$   
  if t = 0 then return 0  
  if b = t or b = 0 then return 1  
  return binom(t - 1, b - 1) + binom(t - 1, b).
```

How many distinct calls does **binom**(n,  $\lfloor n/2 \rfloor$ ) makes during its recursive execution?

- (A)  $\Theta(1)$ .
- (B)  $\Theta(n)$ .
- (C)  $\Theta(n \log n)$ .
- (D)  $\Theta(n^2)$ .
- (E)  $\Theta\left(\binom{n}{\lfloor n/2 \rfloor}\right)$ .

That is, if the algorithm calls recursively **binom**(17, 5) about 5000 times during the computation, we count this as a single distinct call.

# Running time of memoized binom?

```
D: Initially an empty dictionary.  
binomM(t, b) // computes  $\binom{t}{b}$   
  if b = t then return 1  
  if b = 0 then return 0  
  if D[t, b] is defined then return D[t, b]  
  D[t, b]  $\leftarrow$  binomM(t - 1, b - 1) + binomM(t - 1, b).  
  return D[t, b]
```

Assuming that every arithmetic operation takes  $O(1)$  time, What is the running time of **binomM**(n,  $\lfloor n/2 \rfloor$ )?

- (A)  $\Theta(1)$ .
- (B)  $\Theta(n)$ .
- (C)  $\Theta(n^2)$ .
- (D)  $\Theta(n^3)$ .
- (E)  $\Theta\left(\binom{n}{\lfloor n/2 \rfloor}\right)$ .

# Back to Fibonacci Numbers

Is the iterative algorithm a *polynomial* time algorithm? Does it take  **$O(n)$**  time?

# Back to Fibonacci Numbers

Is the iterative algorithm a *polynomial* time algorithm? Does it take  $O(n)$  time?

- ① input is  $n$  and hence input size is  $\Theta(\log n)$
- ② output is  $F(n)$  and output size is  $\Theta(n)$ . Why?
- ③ Hence output size is exponential in input size so no polynomial time algorithm possible!
- ④ Running time of iterative algorithm:  $\Theta(n)$  additions but number sizes are  $O(n)$  bits long! Hence total time is  $O(n^2)$ , in fact  $\Theta(n^2)$ . Why?



# Back to Fibonacci Numbers

Saving space. Do we need an array of  $n$  numbers? Not really.

```
FibIter(n) :  
    if (n = 0) then  
        return 0  
    if (n = 1) then  
        return 1  
    prev2 = 0  
    prev1 = 1  
    for i = 2 to n do  
        temp = prev1 + prev2  
        prev2 = prev1  
        prev1 = temp  
  
    return prev1
```