

no discussion sessions tomorrow

Dynamic Prog. (Cont'd)

Last Ex: Parsing

Given CFG  $G = (V, T, P, S)$  &  
 String  $x = a_1 a_2 \dots a_n \in T^*$ ,  
 decide whether  $x \in L(G)$

**Note:** may assume that all productions in  $P$   
 are of the form

$$A \rightarrow BC \quad (A, B, C \in V)$$

$$\text{or } A \rightarrow a \quad (A \in V, a \in T)$$

Chomsky Normal Form (CNF)

e.g.  $S \rightarrow AS \mid AB$   
 $A \rightarrow BC$   
 $B \rightarrow SA \mid AC \mid \epsilon$   
 $C \rightarrow AB \mid CC \mid \epsilon$

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 $\in L(G)?$   
      

(e.g.  $A \rightarrow BCDE$  can be converted to  
 $A \rightarrow XY, X \rightarrow BC, Y \rightarrow DE$ )

CYK Alg'm (Cocke-Younger-Kasami '70)

Dynamic subproblems:  $(1 \leq i \leq j \leq n, A \in V)$

Define subproblems:  $(1 \leq i \leq j \leq n, A \in V)$

$f(i, j, A) = \text{true}$  iff  
the substring  $a_i a_{i+1} \dots a_j$   
can be generated by  $A$ .

Final Ans:  $f(1, n, S)$

Base cases:  $f(i, i, A) = \text{true}$  iff  
 $A \rightarrow a_i$  is in  $P$ .

Recursive formula:

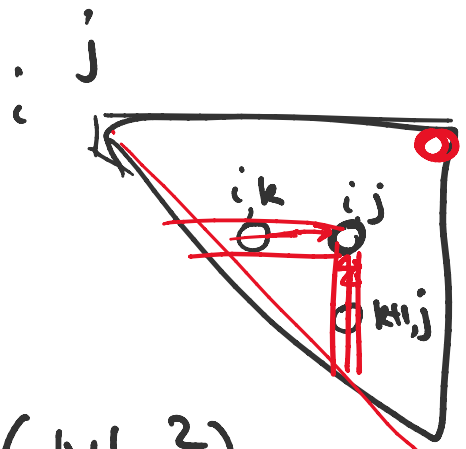
choices for 1<sup>st</sup> deriv. step in opt sol'n for  $f(i, j, A)$ :

- which production  $A \rightarrow BC$
- split  $a_i \dots a_k a_{k+1} \dots a_j$

$$f(i, j, A) = \bigvee_{\substack{A \rightarrow BC \\ \text{in } P}} \bigvee_{k=i}^{j-1} (f(i, k, B) \wedge f(k+1, j, C))$$

Evaluation order:

increas. order of  
 $j-i$



Runtime:

$$\# \text{ subproblems} = O(N^3)$$

$$\text{time per subproblems} = O(|P|n)$$

$$\Rightarrow O(N^3 |P| n) \text{ total time}$$

$[n^3 |P| n] \text{ time}$

more carefully,  $O(|P|n^3)$  time  
 (Since each production  $A \rightarrow BC$  is considered once)

**Rmk:** can be improved to  $O(|P|n^{2.373})$   
 (Valiant '75)  
 for most PL, there are faster linear-time alg's ...

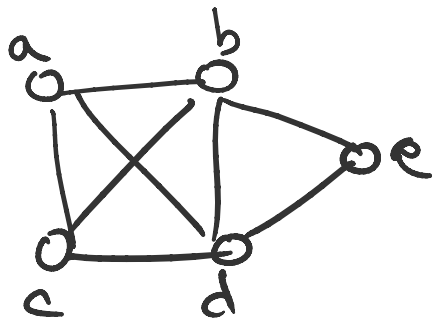
## Graph Alg's

**Def** A graph  $G$  is  $(V, E)$ ,  
 $V =$  set of vertices  
 $E =$  set of edges of form  $(u, v)$   
 or  $uv$  with  $u, v \in V$

$n = |V|$   
 $m = |E|$

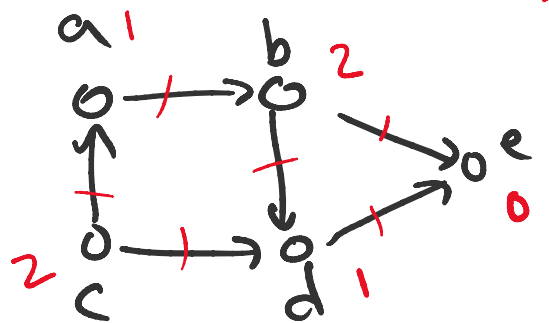
if directed

if undirected  
 (or  $\{u, v\}$ )



undirected

$G = (\{a, b, c, d, e\}, \{ab, ad, ac, bc, \dots\})$



directed

$G = (\{a, b, c, d, e\}, \{(a, b), (b, d), \dots\})$

**Basic concepts:** adjacency, incidence, paths, connectedness, cycles, trees, ...

Ex: road networks, social networks, ...

(applns: road networks, social networks, web page links, ...)

Note:  $n-1 \leq m \leq n^2$   
if connected

## Representation

- adjacency matrix

$$A[u,v] = \begin{cases} 1 & \text{if } (u,v) \in E \\ 0 & \text{else} \end{cases}$$

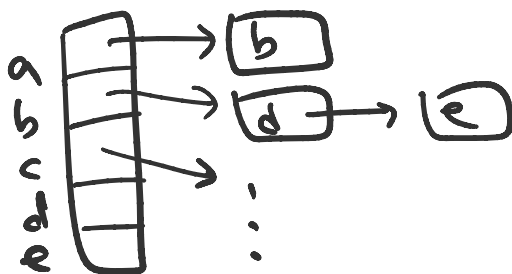
$\Theta(n^2)$  space

(good for dense graphs when  $m$  close to  $n^2$ )

- adjacency lists

for each  $u \in V$ ,

store linked list  $Adj[u] = \{v : (u,v) \in E\}$



$$\text{Space } O\left(n + \sum_{u \in V} |Adj[u]|\right)$$

$$= O\left(n + \sum_{u \in V} \text{out-deg}(u)\right)$$

$$= O(n + m)$$

(good for sparse graphs when  $m$  close to  $n$ )

## Basic Problems:

is there a path from  $s$  to  $t$ ?

Basic Questions

- is there a path from  $s$  to  $t$ ?
- find all vertices reachable from  $s$ ?
- is graph connected?
- find all connected components } directed?
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