

Polynomial Time Reductions

Lecture 22

April 18

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Part I

(Polynomial Time) Reductions

Reductions

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Using Reductions

- ① We use reductions to find algorithms to solve problems.
- ② We also use reductions to show that we **can't** find algorithms for some problems. (We say that these problems are **hard**.)

Reductions for decision problems/languages

For languages L_X, L_Y , a **reduction from L_X to L_Y** is:

- 1 An algorithm ...
- 2 Input: $w \in \Sigma^*$
- 3 Output: $w' \in \Sigma^*$
- 4 Such that:

$$\boxed{w \in L_Y} \iff \boxed{w' \in L_X}$$

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(Actually, this is only one type of reduction, but this is the one we'll use most often.) There are other kinds of reductions.

Reductions for decision problems/languages

For decision problems X , Y , a **reduction from X to Y** is:

- 1 An algorithm ...
- 2 Input: I_X , an instance of X .
- 3 Output: I_Y an instance of Y .
- 4 Such that:

$$\boxed{I_Y \text{ is YES instance of } Y} \iff \boxed{I_X \text{ is YES instance of } X}$$

Using reductions to solve problems

- ① \mathcal{R} : Reduction $X \rightarrow Y$
- ② \mathcal{A}_Y : algorithm for Y :

Using reductions to solve problems

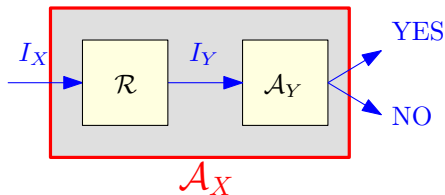
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- 3 \implies New algorithm for X :

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     $I_Y \leftarrow \mathcal{R}(I_X)$   
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If \mathcal{R} and \mathcal{A}_Y polynomial-time $\implies \mathcal{A}_X$ polynomial-time.

Comparing Problems

- ① “Problem X is no harder to solve than Problem Y ”.
- ② If Problem X reduces to Problem Y (we write $X \leq Y$), then X cannot be harder to solve than Y .
- ③ $X \leq Y$:
 - ① X is no harder than Y , or
 - ② Y is at least as hard as X .

Part II

Examples of Reductions

Independent Sets and Cliques

Given a graph G , a set of vertices V' is:

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- 1 **independent set**: no two vertices of V' connected by an edge.

Independent Sets and Cliques

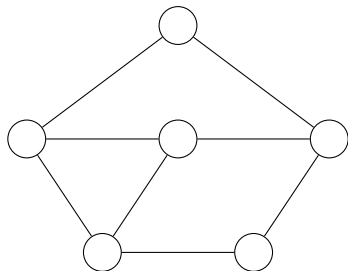
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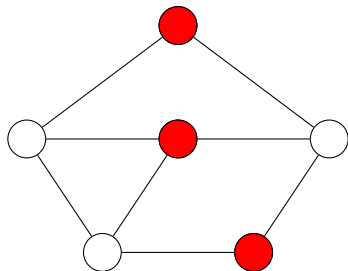
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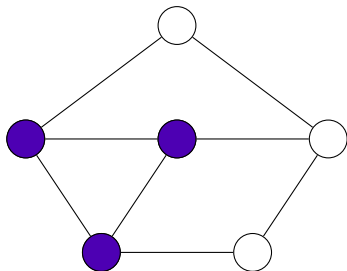
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The **Independent Set** and **Clique** Problems

Problem: **Independent Set**

Instance: A graph G and an integer k .

Question: Does G has an independent set of size $\geq k$?

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Problem: **Clique**

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Recall

For decision problems X , Y , a reduction from X to Y is:

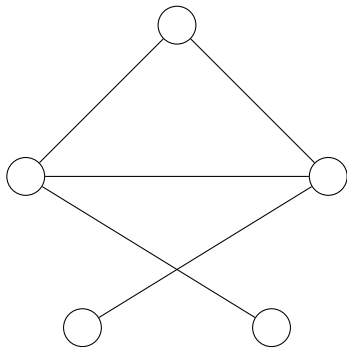
- 1 An algorithm ...
- 2 that takes I_X , an instance of X as input ...
- 3 and returns I_Y , an instance of Y as output ...
- 4 such that the solution (YES/NO) to I_Y is the same as the solution to I_X .

Reducing **Independent Set** to **Clique**

An instance of **Independent Set** is a graph G and an integer k .

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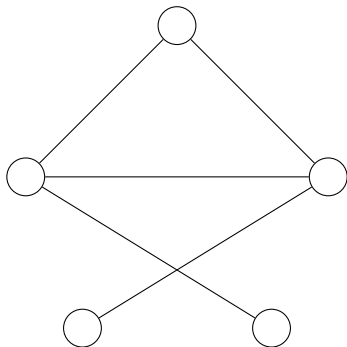
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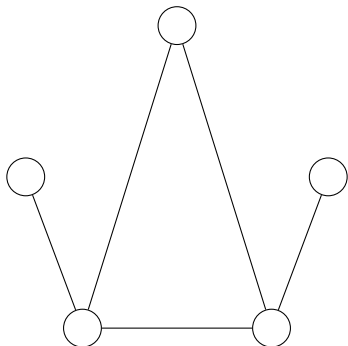
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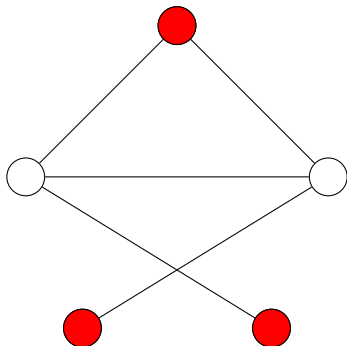
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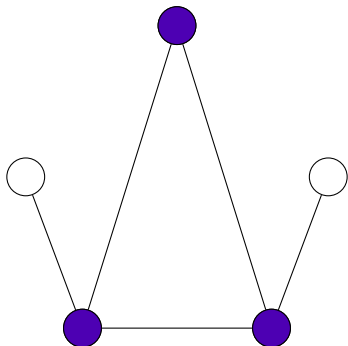
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Correctness of reduction

Lemma

G has an independent set of size k if and only if \overline{G} has a clique of size k .

Proof.

Need to prove two facts:

G has independent set of size at least k implies that \overline{G} has a clique of size at least k .

\overline{G} has a clique of size at least k implies that G has an independent set of size at least k .

Easy to see both from the fact that $S \subseteq V$ is an independent set in G if and only if S is a clique in \overline{G} . □

Independent Set and Clique

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What does this mean?

② If we have an algorithm for **Clique**, then we have an algorithm for **Independent Set**.

③ **Clique** is *at least as hard as* **Independent Set**.

④ Also... **Clique** \leq **Independent Set**. Why? Thus **Clique** and **Independent Set** are polynomial-time equivalent.

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We check if M has *any* reachable non-final state.

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Given an **NFA** N , convert it to an equivalent **DFA** M , and use the **DFA Universality** Algorithm.

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Given an **NFA** N , convert it to an equivalent **DFA** M , and use the **DFA Universality** Algorithm.

The reduction takes **exponential time**!

NFA Universality is known to be PSPACE-Complete and we do not expect a polynomial-time algorithm.

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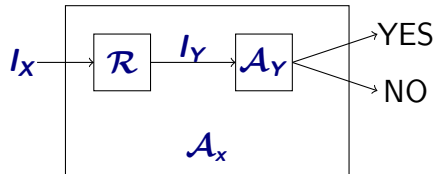
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Polynomial-time Reduction

A polynomial time reduction from a *decision* problem X to a *decision* problem Y is an *algorithm* \mathcal{A} that has the following properties:

- 1 given an instance I_X of X , \mathcal{A} produces an instance I_Y of Y
- 2 \mathcal{A} runs in time polynomial in $|I_X|$.
- 3 Answer to I_X YES *iff* answer to I_Y is YES.

Proposition

If $X \leq_P Y$ then a polynomial time algorithm for Y implies a polynomial time algorithm for X .

Such a reduction is called a **Karp reduction**. Most reductions we will need are Karp reductions. Karp reductions are the same as mapping reductions when specialized to polynomial time for the reduction step.

Reductions again...

Let X and Y be two decision problems, such that X can be solved in polynomial time, and $X \leq_P Y$. Then

- (A) Y can be solved in polynomial time.
- (B) Y can NOT be solved in polynomial time.
- (C) If Y is hard then X is also hard.
- (D) None of the above.
- (E) All of the above.

Polynomial-time reductions and hardness

For decision problems X and Y , if $X \leq_P Y$, and Y has an efficient algorithm, X has an efficient algorithm.

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Because we showed **Independent Set** \leq_P **Clique**. If **Clique** had an efficient algorithm, so would **Independent Set**!

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If $X \leq_P Y$ and X does not have an efficient algorithm, Y cannot have an efficient algorithm!

Polynomial-time reductions and instance sizes

Proposition

Let \mathcal{R} be a polynomial-time reduction from X to Y . Then for any instance I_X of X , the size of the instance I_Y of Y produced from I_X by \mathcal{R} is polynomial in the size of I_X .

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Proof.

\mathcal{R} is a polynomial-time algorithm and hence on input I_X of size $|I_X|$ it runs in time $p(|I_X|)$ for some polynomial $p()$.

I_Y is the output of \mathcal{R} on input I_X .

\mathcal{R} can write at most $p(|I_X|)$ bits and hence $|I_Y| \leq p(|I_X|)$. □

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Note: Converse is not true. A reduction need not be polynomial-time even if output of reduction is of size polynomial in its input.

Polynomial-time Reduction

A polynomial time reduction from a *decision* problem X to a *decision* problem Y is an *algorithm* \mathcal{A} that has the following properties:

- ① Given an instance I_X of X , \mathcal{A} produces an instance I_Y of Y .
- ② \mathcal{A} runs in time polynomial in $|I_X|$. This implies that $|I_Y|$ (size of I_Y) is polynomial in $|I_X|$.
- ③ Answer to I_X YES *iff* answer to I_Y is YES.

Proposition

If $X \leq_P Y$ then a polynomial time algorithm for Y implies a polynomial time algorithm for X .

Transitivity of Reductions

Proposition

$X \leq_P Y$ and $Y \leq_P Z$ implies that $X \leq_P Z$.

Note: $X \leq_P Y$ does not imply that $Y \leq_P X$ and hence it is very important to know the FROM and TO in a reduction.

To prove $X \leq_P Y$ you need to show a reduction FROM X TO Y . That is, show that an algorithm for Y implies an algorithm for X .

Vertex Cover

Given a graph $G = (V, E)$, a set of vertices S is:

Vertex Cover

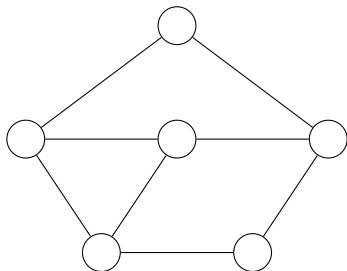
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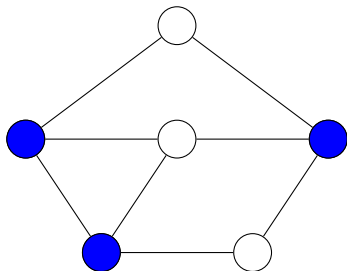
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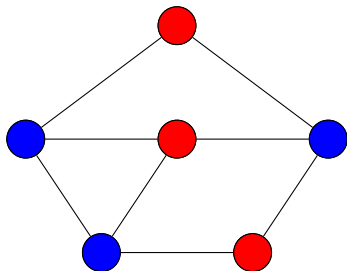
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The **Vertex Cover** Problem

Problem (**Vertex Cover**)

Input: *A graph G and integer k .*

Goal: *Is there a vertex cover of size $\leq k$ in G ?*

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Can we relate **Independent Set** and **Vertex Cover**?

Relationship between...

Vertex Cover and Independent Set

Proposition

Let $G = (V, E)$ be a graph. S is an independent set if and only if $V \setminus S$ is a vertex cover.

Proof.

(\Rightarrow) Let S be an independent set

- 1 Consider any edge $uv \in E$.
- 2 Since S is an independent set, either $u \notin S$ or $v \notin S$.
- 3 Thus, either $u \in V \setminus S$ or $v \in V \setminus S$.
- 4 $V \setminus S$ is a vertex cover.

(\Leftarrow) Let $V \setminus S$ be some vertex cover:

- 1 Consider $u, v \in S$
- 2 uv is not an edge of G , as otherwise $V \setminus S$ does not cover uv .
- 3 $\implies S$ is thus an independent set. □

Independent Set \leq_P Vertex Cover

- 1 G : graph with n vertices, and an integer k be an instance of the **Independent Set** problem.

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- 2 G has an independent set of size $\geq k$ iff G has a vertex cover of size $\leq n - k$
- 3 (G, k) is an instance of **Independent Set**, and $(G, n - k)$ is an instance of **Vertex Cover** with the same answer.
- 4 Therefore, **Independent Set** \leq_P **Vertex Cover**. Also **Vertex Cover** \leq_P **Independent Set**.

Proving Correctness of Reductions

To prove that $X \leq_P Y$ you need to give an algorithm \mathcal{A} that:

- 1 Transforms an instance I_X of X into an instance I_Y of Y .
- 2 Satisfies the property that answer to I_X is YES iff I_Y is YES.
 - 1 typical easy direction to prove: answer to I_Y is YES if answer to I_X is YES
 - 2 **typical difficult direction to prove**: answer to I_X is YES if answer to I_Y is YES (equivalently answer to I_X is NO if answer to I_Y is NO).
- 3 Runs in **polynomial** time.

Part III

The Satisfiability Problem (SAT)

Propositional Formulas

Definition

Consider a set of boolean variables x_1, x_2, \dots, x_n .

- 1 A **literal** is either a boolean variable x_j or its negation $\neg x_j$.
- 2 A **clause** is a disjunction of literals.
For example, $x_1 \vee x_2 \vee \neg x_4$ is a clause.
- 3 A **formula in conjunctive normal form (CNF)** is propositional formula which is a conjunction of clauses
 - 1 $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$ is a **CNF** formula.

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 - 1 $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$ is a **CNF** formula.
- 4 A formula φ is a **3CNF**:
A **CNF** formula such that every clause has **exactly** 3 literals.
 - 1 $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3 \vee x_1)$ is a **3CNF** formula, but $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$ is not.

Problem: SAT

Instance: A CNF formula φ .

Question: Is there a truth assignment to the variables of φ such that φ evaluates to true?

Problem: 3SAT

Instance: A 3CNF formula φ .

Question: Is there a truth assignment to the variables of φ such that φ evaluates to true?

Satisfiability

SAT

Given a **CNF** formula φ , is there a truth assignment to variables such that φ evaluates to true?

Example

- 1 $(x_1 \vee x_2 \vee \neg x_4) \wedge (x_2 \vee \neg x_3) \wedge x_5$ is satisfiable; take x_1, x_2, \dots, x_5 to be all true
- 2 $(x_1 \vee \neg x_2) \wedge (\neg x_1 \vee x_2) \wedge (\neg x_1 \vee \neg x_2) \wedge (x_1 \vee x_2)$ is not satisfiable.

3SAT

Given a **3CNF** formula φ , is there a truth assignment to variables such that φ evaluates to true?

(More on **2SAT** in a bit...)

Importance of **SAT** and **3SAT**

- ① **SAT** and **3SAT** are basic constraint satisfaction problems.
- ② Many different problems can be reduced to them because of the simple yet powerful expressiveness of logical constraints.
- ③ Arise naturally in many applications involving hardware and software verification and correctness.
- ④ As we will see, it is a fundamental problem in theory of **NP-Completeness**.

$$z = \bar{x}$$

Given two bits x, z which of the following **SAT** formulas is equivalent to the formula $z = \bar{x}$:

(A) $(\bar{z} \vee x) \wedge (z \vee \bar{x})$.

(B) $(z \vee x) \wedge (\bar{z} \vee \bar{x})$.

(C) $(\bar{z} \vee x) \wedge (\bar{z} \vee \bar{x}) \wedge (\bar{z} \vee \bar{x})$.

(D) $z \oplus x$.

(E) $(z \vee x) \wedge (\bar{z} \vee \bar{x}) \wedge (z \vee \bar{x}) \wedge (\bar{z} \vee x)$.

$$z = x \wedge y$$

Given three bits x, y, z which of the following **SAT** formulas is equivalent to the formula $z = x \wedge y$:

(A) $(\bar{z} \vee x \vee y) \wedge (z \vee \bar{x} \vee \bar{y})$.

(B) $(\bar{z} \vee x \vee y) \wedge (\bar{z} \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y})$.

(C) $(\bar{z} \vee x \vee y) \wedge (\bar{z} \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y})$.

(D) $(z \vee x \vee y) \wedge (\bar{z} \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y})$.

(E) $(z \vee x \vee y) \wedge (z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y}) \wedge$
 $(\bar{z} \vee x \vee y) \wedge (\bar{z} \vee x \vee \bar{y}) \wedge (\bar{z} \vee \bar{x} \vee y) \wedge (\bar{z} \vee \bar{x} \vee \bar{y})$.

Converting $z = x \wedge y$ to 3SAT

z	x	y					
0	0	0					
0	0	1					
0	1	0					
0	1	1					
1	0	0					
1	0	1					
1	1	0					
1	1	1					

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$				
0	0	0	1				
0	0	1	1				
0	1	0	1				
0	1	1	0				
1	0	0	0				
1	0	1	0				
1	1	0	0				
1	1	1	1				

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$				
0	0	0	1	1	1	1	1
0	0	1	1	1	1	1	1
0	1	0	1	1	1	1	1
0	1	1	0	0	1	1	1
1	0	0	0	1	0	1	1
1	0	1	0	1	1	0	1
1	1	0	0	1	1	1	0
1	1	1	1	1	1	1	1

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$	$z \vee \bar{x} \vee \bar{y}$			
0	0	0	1	1	1	1	1
0	0	1	1	1	1	1	1
0	1	0	1	1	1	1	1
0	1	1	0	0	1	1	1
1	0	0	0	1	0	1	1
1	0	1	0	1	1	0	1
1	1	0	0	1	1	1	0
1	1	1	1	1	1	1	1

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$	$z \vee \bar{x} \vee \bar{y}$	$\bar{z} \vee x \vee y$		
0	0	0	1	1	1	1	1
0	0	1	1	1	1	1	1
0	1	0	1	1	1	1	1
0	1	1	0	0	1	1	1
1	0	0	0	1	0	1	1
1	0	1	0	1	1	0	1
1	1	0	0	1	1	1	0
1	1	1	1	1	1	1	1

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$	$z \vee \bar{x} \vee \bar{y}$	$\bar{z} \vee x \vee y$	$\bar{z} \vee x \vee \bar{y}$	
0	0	0	1	1	1	1	1
0	0	1	1	1	1	1	1
0	1	0	1	1	1	1	1
0	1	1	0	0	1	1	1
1	0	0	0	1	0	1	1
1	0	1	0	1	1	0	1
1	1	0	0	1	1	1	0
1	1	1	1	1	1	1	1

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$	$z \vee \bar{x} \vee \bar{y}$	$\bar{z} \vee x \vee y$	$\bar{z} \vee x \vee \bar{y}$	$\bar{z} \vee \bar{x} \vee y$
0	0	0	1	1	1	1	1
0	0	1	1	1	1	1	1
0	1	0	1	1	1	1	1
0	1	1	0	0	1	1	1
1	0	0	0	1	0	1	1
1	0	1	0	1	1	0	1
1	1	0	0	1	1	1	0
1	1	1	1	1	1	1	1

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$	$z \vee \bar{x} \vee \bar{y}$	$\bar{z} \vee x \vee y$	$\bar{z} \vee x \vee \bar{y}$	$\bar{z} \vee \bar{x} \vee y$
0	0	0	1	1	1	1	1
0	0	1	1	1	1	1	1
0	1	0	1	1	1	1	1
0	1	1	0	0	1	1	1
1	0	0	0	1	0	1	1
1	0	1	0	1	1	0	1
1	1	0	0	1	1	1	0
1	1	1	1	1	1	1	1

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$	$z \vee \bar{x} \vee \bar{y}$	$\bar{z} \vee x \vee y$	$\bar{z} \vee x \vee \bar{y}$	$\bar{z} \vee \bar{x} \vee y$
0	0	0	1	1	1	1	1
0	0	1	1	1	1	1	1
0	1	0	1	1	1	1	1
0	1	1	0	0	1	1	1
1	0	0	0	1	0	1	1
1	0	1	0	1	1	0	1
1	1	0	0	1	1	1	0
1	1	1	1	1	1	1	1

$$(z = x \wedge y)$$

$$\equiv$$

$$(z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x \vee y) \wedge (\bar{z} \vee x \vee \bar{y}) \wedge (\bar{z} \vee \bar{x} \vee y)$$

Converting $z = x \wedge y$ to 3SAT

z	x	y			
0	0	0			
0	0	1			
0	1	0			
0	1	1			
1	0	0			
1	0	1			
1	1	0			
1	1	1			

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$		
0	0	0	1		
0	0	1	1		
0	1	0	1		
0	1	1	0		
1	0	0	0		
1	0	1	0		
1	1	0	0		
1	1	1	1		

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$	clauses
0	0	0	1	
0	0	1	1	
0	1	0	1	
0	1	1	0	
1	0	0	0	
1	0	1	0	
1	1	0	0	
1	1	1	1	

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$	clauses
0	0	0	1	
0	0	1	1	
0	1	0	1	
0	1	1	0	$z \vee \bar{x} \vee \bar{y}$
1	0	0	0	$\bar{z} \vee x \vee y$
1	0	1	0	$\bar{z} \vee x \vee y$
1	1	0	0	$\bar{z} \vee x \vee y$
1	1	1	1	

Converting $z = x \wedge y$ to 3SAT

z	x	y	$z = x \wedge y$	clauses
0	0	0	1	
0	0	1	1	
0	1	0	1	
0	1	1	0	$z \vee \bar{x} \vee \bar{y}$
1	0	0	0	$\bar{z} \vee x \vee y$
1	0	1	0	$\bar{z} \vee x \vee y$
1	1	0	0	$\bar{z} \vee x \vee y$
1	1	1	1	

$$(z = x \wedge y)$$

\equiv

$$(z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x \vee y) \wedge (\bar{z} \vee x \vee \bar{y}) \wedge (\bar{z} \vee \bar{x} \vee y)$$

Converting $z = x \wedge y$ to 3SAT

Simplify further if you want to

- 1 Using that $(x \vee y) \wedge (x \vee \bar{y}) = x$, we have that:

Converting $z = x \wedge y$ to 3SAT

Simplify further if you want to

① Using that $(x \vee y) \wedge (x \vee \bar{y}) = x$, we have that:

$$\textcircled{1} (\bar{z} \vee x \vee u) \wedge (\bar{z} \vee x \vee \bar{y}) = (\bar{z} \vee x)$$

$$\textcircled{2} (\bar{z} \vee x \vee y) \wedge (\bar{z} \vee \bar{x} \vee y) = (\bar{z} \vee y)$$

Converting $z = x \wedge y$ to 3SAT

Simplify further if you want to

① Using that $(x \vee y) \wedge (x \vee \bar{y}) = x$, we have that:

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② $(\bar{z} \vee x \vee y) \wedge (\bar{z} \vee \bar{x} \vee y) = (\bar{z} \vee y)$

② Using the above two observations, we have that our formula

$$\psi \equiv (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x \vee y) \wedge (\bar{z} \vee x \vee \bar{y}) \wedge (\bar{z} \vee \bar{x} \vee y)$$

Converting $z = x \wedge y$ to 3SAT

Simplify further if you want to

① Using that $(x \vee y) \wedge (x \vee \bar{y}) = x$, we have that:

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$$\textcircled{2} (\bar{z} \vee x \vee y) \wedge (\bar{z} \vee \bar{x} \vee y) = (\bar{z} \vee y)$$

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$$\psi \equiv (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x \vee y) \wedge (\bar{z} \vee x \vee \bar{y}) \wedge (\bar{z} \vee \bar{x} \vee y)$$

$$\text{is equivalent to } \psi \equiv (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x) \wedge (\bar{z} \vee y)$$

Converting $z = x \wedge y$ to 3SAT

Simplify further if you want to

① Using that $(x \vee y) \wedge (x \vee \bar{y}) = x$, we have that:

$$\textcircled{1} (\bar{z} \vee x \vee u) \wedge (\bar{z} \vee x \vee \bar{y}) = (\bar{z} \vee x)$$

$$\textcircled{2} (\bar{z} \vee x \vee y) \wedge (\bar{z} \vee \bar{x} \vee y) = (\bar{z} \vee y)$$

② Using the above two observations, we have that our formula

$$\psi \equiv (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x \vee y) \wedge (\bar{z} \vee x \vee \bar{y}) \wedge (\bar{z} \vee \bar{x} \vee y)$$

$$\text{is equivalent to } \psi \equiv (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x) \wedge (\bar{z} \vee y)$$

Lemma

$$(z = x \wedge y) \equiv (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x) \wedge (\bar{z} \vee y)$$

$$z = x \vee y$$

Given three bits x, y, z which of the following **SAT** formulas is equivalent to the formula $z = x \vee y$:

(A) $(\bar{z} \vee x \vee y) \wedge (\bar{z} \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y})$.

(B) $(\bar{z} \vee x \vee y) \wedge (\bar{z} \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y})$.

(C) $(z \vee x \vee y) \wedge (\bar{z} \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y})$.

(D) $(z \vee x \vee y) \wedge (z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y}) \wedge$
 $(\bar{z} \vee x \vee y) \wedge (\bar{z} \vee x \vee \bar{y}) \wedge (\bar{z} \vee \bar{x} \vee y) \wedge (\bar{z} \vee \bar{x} \vee \bar{y})$.

(E) $(\bar{z} \vee x \vee y) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee \bar{y})$.

Converting $z = x \vee y$ to 3SAT

z	x	y			
0	0	0			
0	0	1			
0	1	0			
0	1	1			
1	0	0			
1	0	1			
1	1	0			
1	1	1			

Converting $z = x \vee y$ to 3SAT

z	x	y	$z = x \vee y$		
0	0	0	1		
0	0	1	0		
0	1	0	0		
0	1	1	0		
1	0	0	0		
1	0	1	1		
1	1	0	1		
1	1	1	1		

Converting $z = x \vee y$ to 3SAT

z	x	y	$z = x \vee y$	clauses
0	0	0	1	
0	0	1	0	
0	1	0	0	
0	1	1	0	
1	0	0	0	
1	0	1	1	
1	1	0	1	
1	1	1	1	

Converting $z = x \vee y$ to 3SAT

z	x	y	$z = x \vee y$	clauses
0	0	0	1	
0	0	1	0	$z \vee x \vee \bar{y}$
0	1	0	0	$z \vee \bar{x} \vee y$
0	1	1	0	$z \vee \bar{x} \vee \bar{y}$
1	0	0	0	$\bar{z} \vee x \vee y$
1	0	1	1	
1	1	0	1	
1	1	1	1	

Converting $z = x \vee y$ to 3SAT

z	x	y	$z = x \vee y$	clauses
0	0	0	1	
0	0	1	0	$z \vee x \vee \bar{y}$
0	1	0	0	$z \vee \bar{x} \vee y$
0	1	1	0	$z \vee \bar{x} \vee \bar{y}$
1	0	0	0	$\bar{z} \vee x \vee y$
1	0	1	1	
1	1	0	1	
1	1	1	1	

$$(z = x \vee y)$$

$$\equiv$$

$$(z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x \vee y)$$

Converting $z = x \vee y$ to 3SAT

Simplify further if you want to

$$(z = x \vee y) \equiv (z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x \vee y)$$

① Using that $(x \vee y) \wedge (x \vee \bar{y}) = x$, we have that:

Converting $z = x \vee y$ to 3SAT

Simplify further if you want to

$$(z = x \vee y) \equiv (z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x \vee y)$$

① Using that $(x \vee y) \wedge (x \vee \bar{y}) = x$, we have that:

① $(z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee \bar{y}) = z \vee \bar{y}.$

② $(z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y}) = z \vee \bar{x}$

Converting $z = x \vee y$ to 3SAT

Simplify further if you want to

$$(z = x \vee y) \equiv (z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x \vee y)$$

① Using that $(x \vee y) \wedge (x \vee \bar{y}) = x$, we have that:

① $(z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee \bar{y}) = z \vee \bar{y}.$

② $(z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y}) = z \vee \bar{x}$

② Using the above two observations, we have the following.

Converting $z = x \vee y$ to 3SAT

Simplify further if you want to

$$(z = x \vee y) \equiv (z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y}) \wedge (\bar{z} \vee x \vee y)$$

① Using that $(x \vee y) \wedge (x \vee \bar{y}) = x$, we have that:

① $(z \vee x \vee \bar{y}) \wedge (z \vee \bar{x} \vee \bar{y}) = z \vee \bar{y}.$

② $(z \vee \bar{x} \vee y) \wedge (z \vee \bar{x} \vee \bar{y}) = z \vee \bar{x}$

② Using the above two observations, we have the following.

Lemma

The formula $z = x \vee y$ is equivalent to the CNF formula

$$(z = x \vee y) \equiv (z \vee \bar{y}) \wedge (z \vee \bar{x}) \wedge (\bar{z} \vee x \vee y)$$

SAT \leq_p 3SAT

How **SAT** is different from **3SAT**?

In **SAT** clauses might have arbitrary length: **1, 2, 3, ...** variables:

$$(x \vee y \vee z \vee w \vee u) \wedge (\neg x \vee \neg y \vee \neg z \vee w \vee u) \wedge (\neg x)$$

In **3SAT** every clause must have **exactly 3** different literals.

SAT \leq_p 3SAT

How SAT is different from 3SAT?

In SAT clauses might have arbitrary length: 1, 2, 3, ... variables:

$$(x \vee y \vee z \vee w \vee u) \wedge (\neg x \vee \neg y \vee \neg z \vee w \vee u) \wedge (\neg x)$$

In 3SAT every clause must have **exactly 3** different literals.

To reduce from an instance of SAT to an instance of 3SAT, we must make all clauses to have exactly 3 variables...

Basic idea

- 1 Pad short clauses so they have 3 literals.
- 2 Break long clauses into shorter clauses.
- 3 Repeat the above till we have a 3CNF.

3SAT \leq_P SAT

① 3SAT \leq_P SAT.

② Because...

A 3SAT instance is also an instance of SAT.

$SAT \leq_p 3SAT$

Claim

$SAT \leq_p 3SAT$.

SAT \leq_P 3SAT

Claim

SAT \leq_P 3SAT.

Given φ a SAT formula we create a 3SAT formula φ' such that

- 1 φ is satisfiable iff φ' is satisfiable.
- 2 φ' can be constructed from φ in time polynomial in $|\varphi|$.

SAT \leq_P 3SAT

Claim

SAT \leq_P 3SAT.

Given φ a SAT formula we create a 3SAT formula φ' such that

- 1 φ is satisfiable iff φ' is satisfiable.
- 2 φ' can be constructed from φ in time polynomial in $|\varphi|$.

Idea: if a clause of φ is not of length 3, replace it with several clauses of length exactly 3.

SAT \leq_p 3SAT

A clause with two literals

Reduction Ideas: clause with 2 literals

- 1 **Case clause with 2 literals:** Let $c = l_1 \vee l_2$. Let u be a new variable. Consider

$$c' = (l_1 \vee l_2 \vee u) \wedge (l_1 \vee l_2 \vee \neg u).$$

- 2 Suppose $\varphi = \psi \wedge c$. Then $\varphi' = \psi \wedge c'$ is satisfiable iff φ is satisfiable.

SAT \leq_p 3SAT

A clause with a single literal

Reduction Ideas: clause with 1 literal

- 1 **Case clause with one literal:** Let c be a clause with a single literal (i.e., $c = \ell$). Let u, v be new variables. Consider

$$c' = (\ell \vee u \vee v) \wedge (\ell \vee u \vee \neg v) \\ \wedge (\ell \vee \neg u \vee v) \wedge (\ell \vee \neg u \vee \neg v).$$

- 2 Suppose $\varphi = \psi \wedge c$. Then $\varphi' = \psi \wedge c'$ is satisfiable iff φ is satisfiable.

SAT \leq_p 3SAT

A clause with more than 3 literals

Reduction Ideas: clause with more than 3 literals

- 1 **Case clause with five literals:** Let $c = l_1 \vee l_2 \vee l_3 \vee l_4 \vee l_5$. Let u be a new variable. Consider

$$c' = (l_1 \vee l_2 \vee l_3 \vee u) \wedge (l_4 \vee l_5 \vee \neg u).$$

- 2 Suppose $\varphi = \psi \wedge c$. Then $\varphi' = \psi \wedge c'$ is satisfiable iff φ is satisfiable.

SAT \leq_p 3SAT

A clause with more than 3 literals

Reduction Ideas: clause with more than 3 literals

- 1 **Case clause with $k > 3$ literals:** Let $c = l_1 \vee l_2 \vee \dots \vee l_k$. Let u be a new variable. Consider

$$c' = (l_1 \vee l_2 \dots l_{k-2} \vee u) \wedge (l_{k-1} \vee l_k \vee \neg u).$$

- 2 Suppose $\varphi = \psi \wedge c$. Then $\varphi' = \psi \wedge c'$ is satisfiable iff φ is satisfiable.

Breaking a clause

Lemma

For any boolean formulas X and Y and z a new boolean variable.
Then

$X \vee Y$ is satisfiable

if and only if, z can be assigned a value such that

$(X \vee z) \wedge (Y \vee \neg z)$ is satisfiable

(with the same assignment to the variables appearing in X and Y).

$SAT \leq_p 3SAT$ (contd)

Clauses with more than 3 literals

Let $c = \ell_1 \vee \dots \vee \ell_k$. Let u_1, \dots, u_{k-3} be new variables. Consider

$$\begin{aligned} c' = & (\ell_1 \vee \ell_2 \vee u_1) \wedge (\ell_3 \vee \neg u_1 \vee u_2) \\ & \wedge (\ell_4 \vee \neg u_2 \vee u_3) \wedge \\ & \dots \wedge (\ell_{k-2} \vee \neg u_{k-4} \vee u_{k-3}) \wedge (\ell_{k-1} \vee \ell_k \vee \neg u_{k-3}). \end{aligned}$$

Claim

$\varphi = \psi \wedge c$ is satisfiable iff $\varphi' = \psi \wedge c'$ is satisfiable.

Another way to see it — reduce size of clause by one:

$$c' = (\ell_1 \vee \ell_2 \dots \vee \ell_{k-2} \vee u_{k-3}) \wedge (\ell_{k-1} \vee \ell_k \vee \neg u_{k-3}).$$

An Example

Example

$$\begin{aligned}\varphi = & (\neg x_1 \vee \neg x_4) \wedge (x_1 \vee \neg x_2 \vee \neg x_3) \\ & \wedge (\neg x_2 \vee \neg x_3 \vee x_4 \vee x_1) \wedge (x_1).\end{aligned}$$

Equivalent form:

$$\psi = (\neg x_1 \vee \neg x_4 \vee z) \wedge (\neg x_1 \vee \neg x_4 \vee \neg z)$$

An Example

Example

$$\begin{aligned}\varphi = & (\neg x_1 \vee \neg x_4) \wedge (x_1 \vee \neg x_2 \vee \neg x_3) \\ & \wedge (\neg x_2 \vee \neg x_3 \vee x_4 \vee x_1) \wedge (x_1).\end{aligned}$$

Equivalent form:

$$\begin{aligned}\psi = & (\neg x_1 \vee \neg x_4 \vee z) \wedge (\neg x_1 \vee \neg x_4 \vee \neg z) \\ & \wedge (x_1 \vee \neg x_2 \vee \neg x_3)\end{aligned}$$

An Example

Example

$$\begin{aligned}\varphi = & (\neg x_1 \vee \neg x_4) \wedge (x_1 \vee \neg x_2 \vee \neg x_3) \\ & \wedge (\neg x_2 \vee \neg x_3 \vee x_4 \vee x_1) \wedge (x_1).\end{aligned}$$

Equivalent form:

$$\begin{aligned}\psi = & (\neg x_1 \vee \neg x_4 \vee z) \wedge (\neg x_1 \vee \neg x_4 \vee \neg z) \\ & \wedge (x_1 \vee \neg x_2 \vee \neg x_3) \\ & \wedge (\neg x_2 \vee \neg x_3 \vee y_1) \wedge (x_4 \vee x_1 \vee \neg y_1)\end{aligned}$$

An Example

Example

$$\begin{aligned}\varphi = & \left(\neg x_1 \vee \neg x_4 \right) \wedge \left(x_1 \vee \neg x_2 \vee \neg x_3 \right) \\ & \wedge \left(\neg x_2 \vee \neg x_3 \vee x_4 \vee x_1 \right) \wedge \left(x_1 \right).\end{aligned}$$

Equivalent form:

$$\begin{aligned}\psi = & \left(\neg x_1 \vee \neg x_4 \vee z \right) \wedge \left(\neg x_1 \vee \neg x_4 \vee \neg z \right) \\ & \wedge \left(x_1 \vee \neg x_2 \vee \neg x_3 \right) \\ & \wedge \left(\neg x_2 \vee \neg x_3 \vee y_1 \right) \wedge \left(x_4 \vee x_1 \vee \neg y_1 \right) \\ & \wedge \left(x_1 \vee u \vee v \right) \wedge \left(x_1 \vee u \vee \neg v \right) \\ & \wedge \left(x_1 \vee \neg u \vee v \right) \wedge \left(x_1 \vee \neg u \vee \neg v \right).\end{aligned}$$

Overall Reduction Algorithm

Reduction from SAT to 3SAT

```
ReduceSATto3SAT( $\varphi$ ):
```

```
  //  $\varphi$ : CNF formula.
```

```
  for each clause  $c$  of  $\varphi$  do
```

```
    if  $c$  does not have exactly 3 literals then  
      construct  $c'$  as before
```

```
    else
```

```
       $c' = c$ 
```

```
   $\psi$  is conjunction of all  $c'$  constructed in loop
```

```
  return Solver3SAT( $\psi$ )
```

Correctness (informal)

φ is satisfiable iff ψ is satisfiable because for each clause c , the new 3CNF formula c' is logically equivalent to c .

What about **2SAT**?

2SAT can be solved in polynomial time! (specifically, linear time!)

No known polynomial time reduction from **SAT** (or **3SAT**) to **2SAT**. If there was, then **SAT** and **3SAT** would be solvable in polynomial time.

Why the reduction from **3SAT** to **2SAT** fails?

Consider a clause $(x \vee y \vee z)$. We need to reduce it to a collection of **2CNF** clauses. Introduce a fresh variable α , and rewrite this as

$$\begin{array}{ll} (x \vee y \vee \alpha) \wedge (\neg\alpha \vee z) & \text{(bad! clause with 3 vars)} \\ \text{or } (x \vee \alpha) \wedge (\neg\alpha \vee y \vee z) & \text{(bad! clause with 3 vars).} \end{array}$$

(In animal farm language: **2SAT** good, **3SAT** bad.)

What about **2SAT**?

A challenging exercise: Given a **2SAT** formula show to compute its satisfying assignment...

(Hint: Create a graph with two vertices for each variable (for a variable x there would be two vertices with labels $x = 0$ and $x = 1$). For every **2CNF** clause add two directed edges in the graph. The edges are implication edges: They state that if you decide to assign a certain value to a variable, then you must assign a certain value to some other variable.

Now compute the strong connected components in this graph, and continue from there...)