



Data Reliability

Interpreting Sensor Data



Reminders:

- HW1 due now.
- HW2 out this evening.



Analogy

- System reliability challenge:
 - Building reliable systems from less reliable components
- Data reliability challenge:
 - Making reliable conclusions from less reliable (sensor) data



Making Conclusions from Probabilistic Data

- Cyber-physical systems obtain data about their environment via sensors
- Sensors (or data sources in general) are often imperfect
- The challenge is: how to correctly compute the “state of the environment” given sensor readings?



Review: Things You Should Know About Probabilities

- Probability of multiple simultaneous events
 - What are the odds that it rains and my basement floods? Say $P(\text{rains}) = 0.2$. $P(\text{flood}) = 0.1$



Review: Things You Should Know About Probabilities

- Probability of multiple simultaneous events
 - What are the odds that it rains and my basement floods?
 - Answer: It is the odds that “it rains”, times the odds that “my basement floods given that it rains”:

$$P(\text{rain, flood}) = P(\text{rain}) P(\text{flood}|\text{rain})$$

Note: $P(\text{flood}|\text{rain})$ is larger than $P(\text{flood})$



Review: Things You Should Know About Probabilities

- $P(A,B) = P(A|B).P(B)$
- Corollary: If events A and B are independent, the odds of them happening together is the product of their individual probabilities.
- $P(A,B) = P(A).P(B)$

Note: This is because $P(A|B) = P(A)$



Review: Probability versus Conditional Probability

- Probability: the odds that something, say X , happens, $P(X)$.
- Conditional probability: the odds that X happens *given* that a certain condition, C , has occurred, $P(X|C)$.
 - This condition may affect the odds.



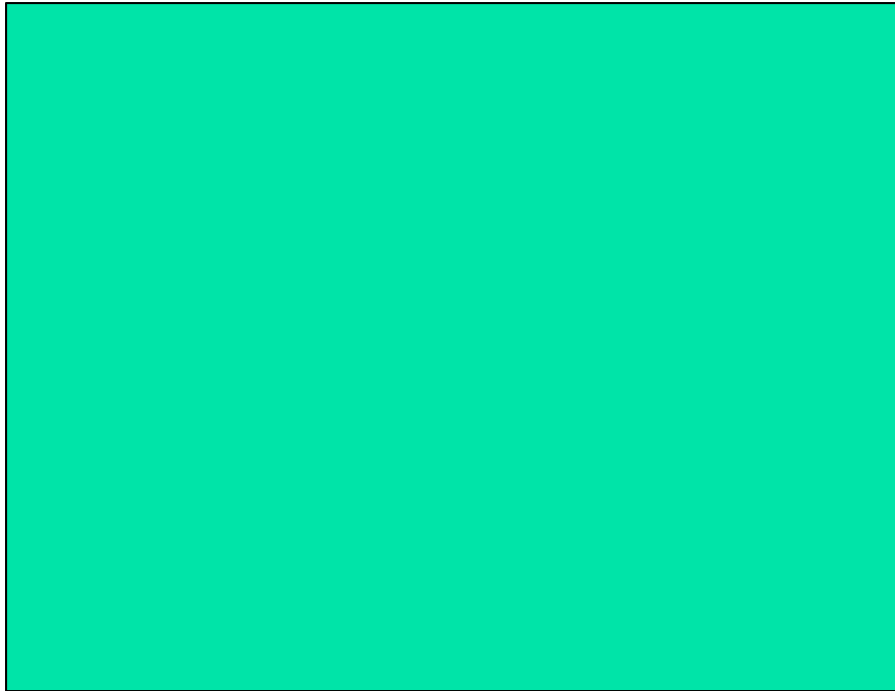
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 - This condition may affect the odds.
- Traffic example:
 - $P(\text{Accident})$ may be low
 - $P(\text{Accident}|\text{Black ice})$ is a lot higher!



A Visual Interpretation

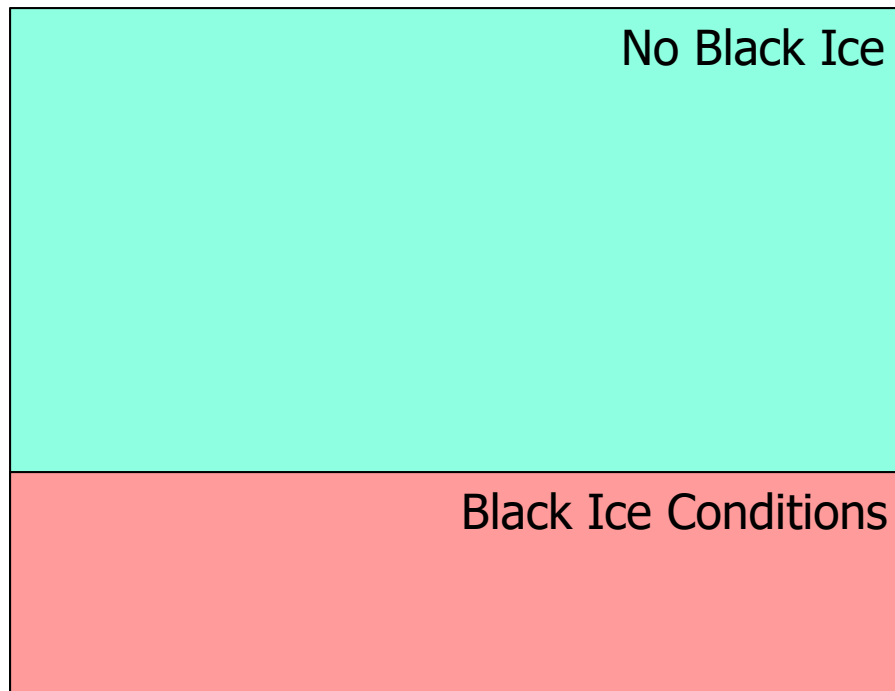
The universe of all possibilities





A Visual Interpretation

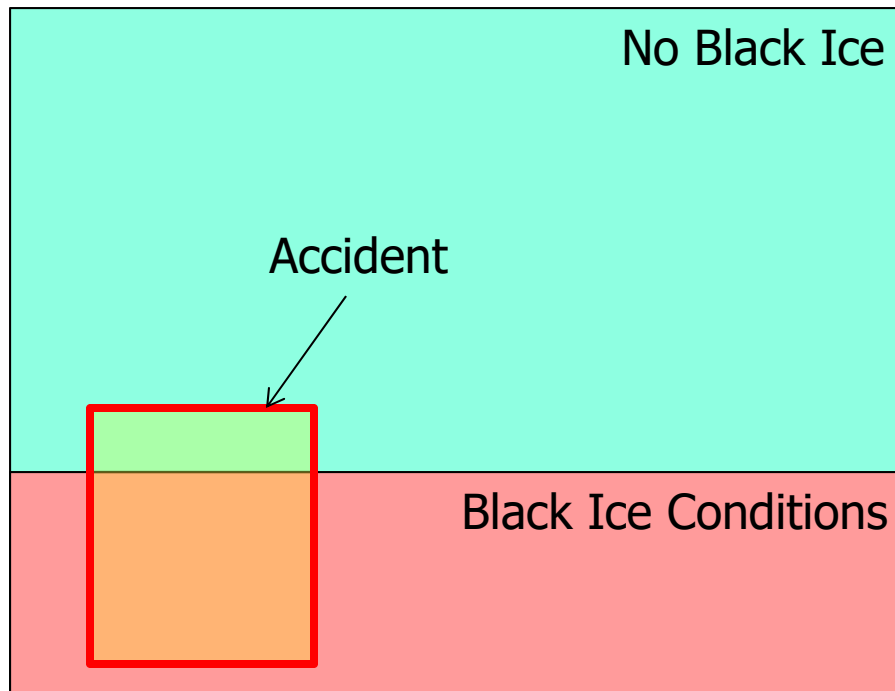
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Consider a graphical visualization of probabilities where area represents probability

A Visual Interpretation

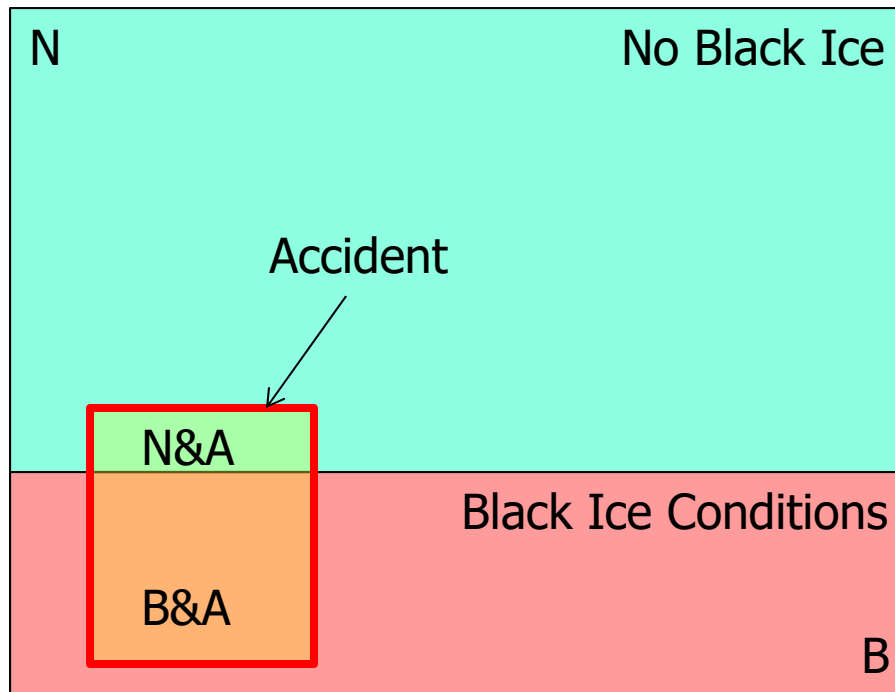
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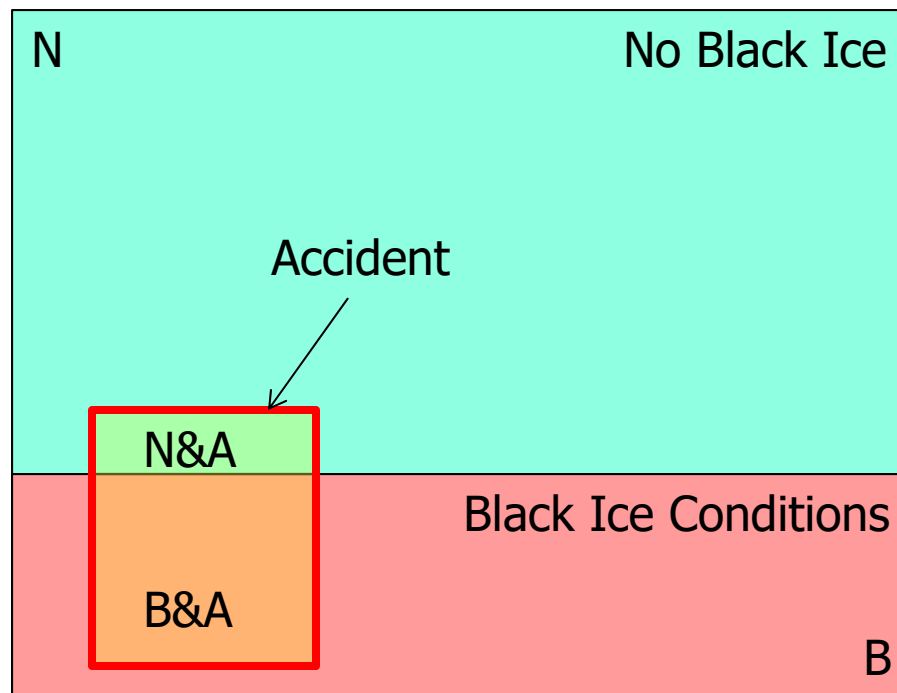
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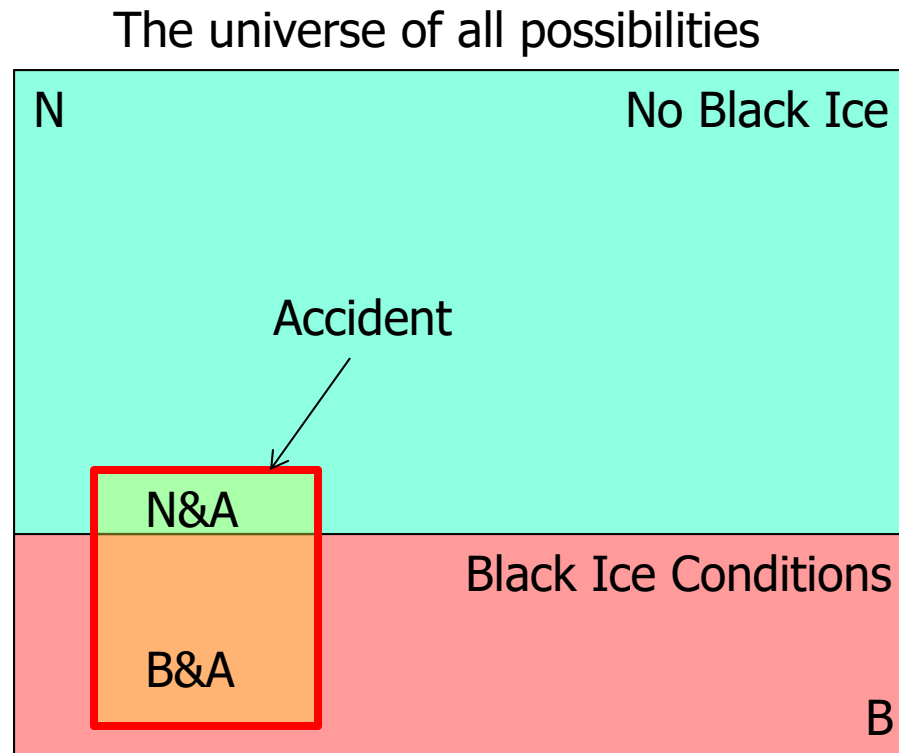
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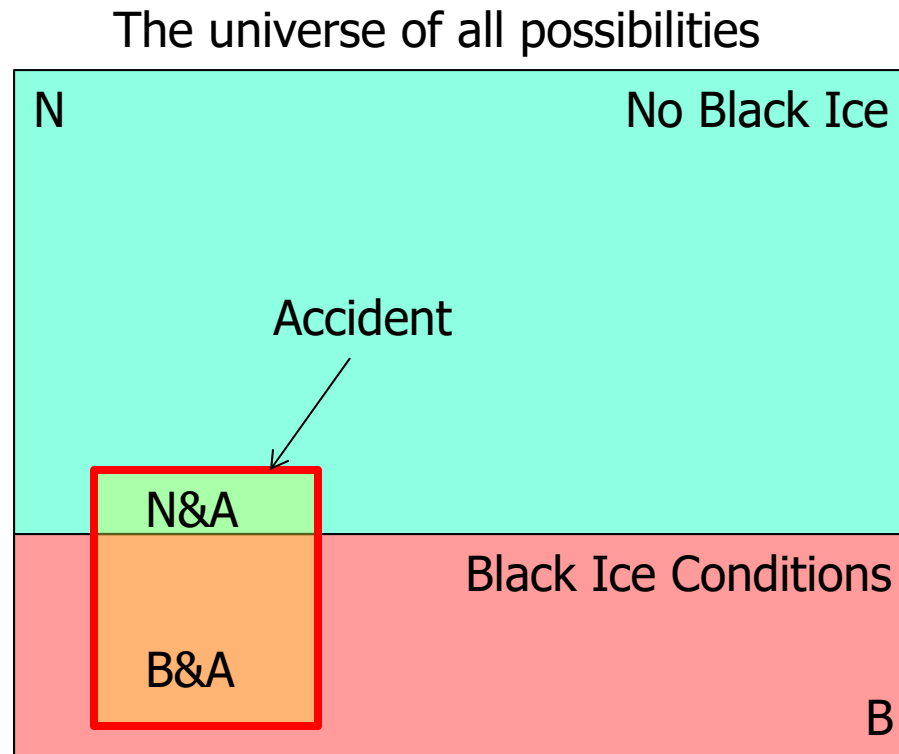
- $P(\text{Accident}) = \frac{(N\&A + B\&A)}{(N + B)}$

A Visual Interpretation



- $P(\text{Accident}) = \frac{(N\&A + B\&A)}{(N + B)}$
- $P(\text{Accident}|\text{Ice}) = \frac{(B\&A)}{B}$
- $P(\text{Accident}|\text{No Ice}) = \frac{(N\&A)}{N}$

A Visual Interpretation

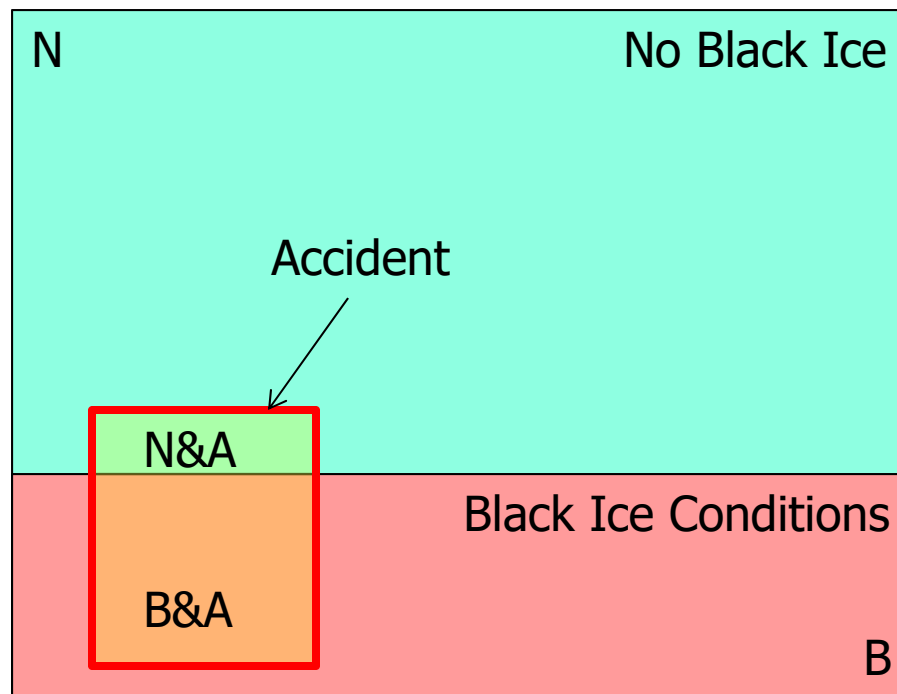


- $P(\text{Accident}) = \frac{(N\&A + B\&A)}{(N + B)}$
- $P(\text{Accident}|\text{Ice}) = \frac{(B\&A)}{B}$
- $P(\text{Accident}|\text{No Ice}) = \frac{(N\&A)}{N}$

Question: If $P(\text{Accident}|\text{Ice}) = 0.1$, $P(\text{Accident}|\text{No-Ice}) = 0.02$, $P(\text{Ice}) = 0.2$, what are the odds of accidents in general, $P(\text{Accident})$?

A Visual Interpretation

The universe of all possibilities



- $(B\&A)/B = 0.1$
- $(N\&A)/N = 0.02$
- $B/(B+N) = 0.2$
- $(N\&A+B\&A)/(N+B)?$

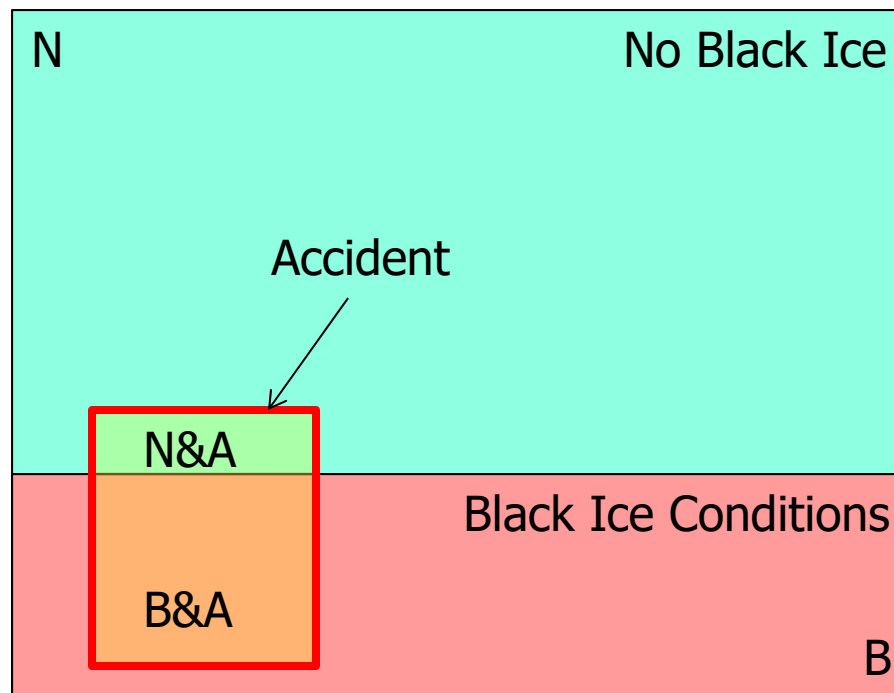
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Review:

Total Probability Theorem

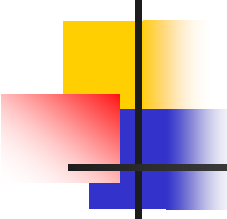
$$P(\text{Something}) = P(\text{Something}|X) P(X) + P(\text{Something}|\bar{X}) P(\bar{X})$$

The universe of all possibilities



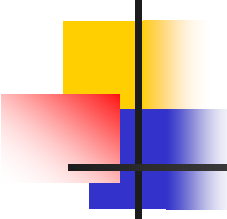
- $P(\text{Accident}) =$
 $0.1 * 0.2$
 $+ 0.02 * 0.8$
 $= 0.032$

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Example: Probability versus Conditional Probability

- A father is accused of murdering his abused child. The lawyer says that only 2% of men who abuse their children actually end up killing them, so the odds that this is a murder are very low.
- Is this argument statistically valid? If so, explain why (mathematically). If not, why not?



Example: Probability versus Conditional Probability

- A father is accused of murdering his abused child. The lawyer says that only 2% of men who abuse their children actually end up killing them, so the odds that this is a murder are very low.
- The relevant statistic is: *given that* an abused child is murdered, what are the odds that the father did it? (This happens to be 50%)

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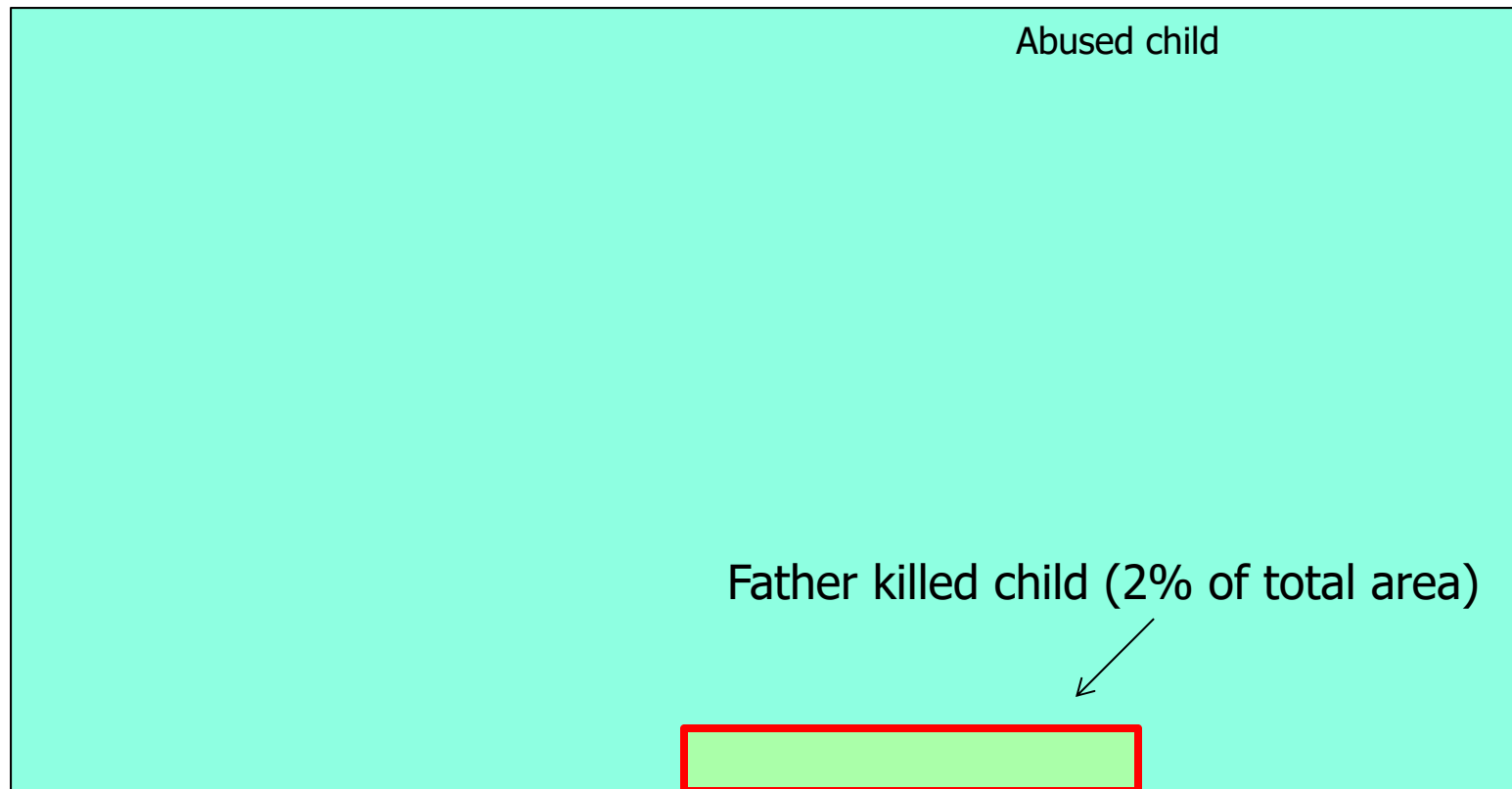
Conditional probability





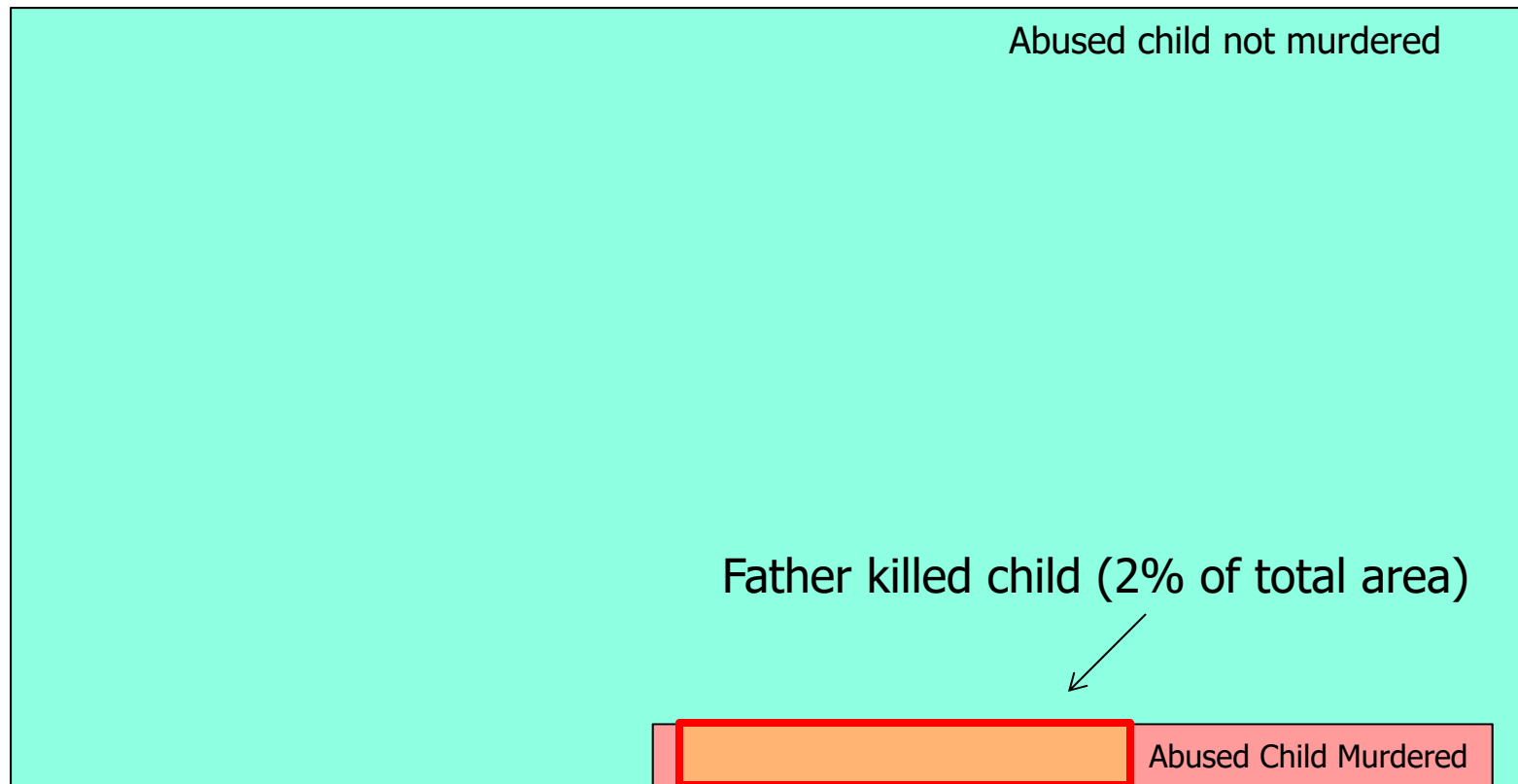
A Visual Interpretation

The universe of all possibilities



A Visual Interpretation

The universe of all possibilities



Father did it given abused child was murdered is 50%



Example: Intrusion Detection

- A motion alarm is used to detect unauthorized access to a warehouse after hours. The motion sensor is mounted near the only entrance to the warehouse. If a burglar enters the building, there is a 99% chance that the burglar triggers the motion alarm.
- At 9pm, on September 16th, 2013, the alarm was set off. What are the odds that a burglar is in the building?

Example: Asteroid Collision with Earth



- If a major Asteroid collides with Earth in St. Louis, traffic on I-74 will be backed up.
- On Feb 10th, 2014, there was a big back-up on I-74. What are the odds that a major Asteroid collided with Earth?

Example: Asteroid Collision with Earth



- If a major Asteroid collides with Earth in St. Louis (**A**), traffic on I-74 will be backed up (**B**).
 - $P(B|A) = P(\text{Backup given Asteroid}) = 1$
- On Feb 10th, 2014, there was a big back-up on I-74 (**B**). What are the odds that a major Asteroid collided with Earth in St. Louis (**A**)?
 - $P(A|B) = P(\text{Asteroid given Backup}) = ?$



Factors to Consider

P (Asteroid given Backup) ?



Factors to Consider

P (Asteroid given Backup) ?

- How often do major asteroids hit earth?
 - $P(A) = P(\text{Asteroid}) = ?$
 - The less often it happens, the less likely it is that a traffic jam is attributed to an asteroid.
- How often traffic backs up on I-74
 - $P(B) = P(\text{Backup}) = ?$
 - The more often this happens the less likely it is to be an indicator of asteroid collision

Factors to Consider

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 - $P(B) = P(\text{Backup}) = ?$
 - The more often this happens the less likely it is to be an indicator of asteroid collision
- $P(A|B) = P(B|A) \cdot P(A)/P(B)$ ← Bayes Theorem



Factors to Consider

P (Asteroid given Backup) ?

- $P(A) = P(\text{Asteroid}) = 0.00001$
- $P(B) = P(\text{Backup}) = 0.01$
- $P(B|A) = 1$

- $P(A|B) = P(B|A) \cdot P(A)/P(B) = 0.001$

Review of Important Theorems



- Total Probability Theorem:

$$P(A) = P(A|C_1) P(C_1) + \dots + P(A|C_n) P(C_n)$$

where C_1, \dots, C_n cover the space of all possibilities

- Bayes Theorem:

$$P(A|B) = P(B|A) \cdot P(A)/P(B)$$

- Other: $P(A,B) = P(A|B) P(B)$



Intrusion Detection, Again

- A motion alarm is used to detect unauthorized access to a warehouse after hours. The motion sensor is mounted near the only entrance to the warehouse. If a burglar enters the building, there is a 99% chance that the burglar triggers the motion alarm.
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- Assume the alarm goes off about 3 days a year and burglaries happen about once a year



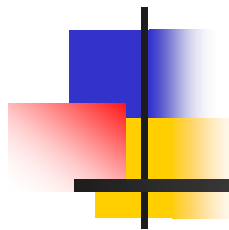
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- $P(A) = P(\text{Alarm}) = 3/365$
 - $P(B) = P(\text{Burglar}) = 1/365$
 - $P(A|B) = 0.99$



Intrusion Detection, Again

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- $P(A) = P(\text{Alarm}) = 3/365$
 - $P(B) = P(\text{Burglar}) = 1/365$
 - $P(A|B) = 0.99$
 - $P(B|A) = P(A|B).P(B)/P(A) = 0.33$ (i.e., if alarm sounds, there is a 33% chance it is a burglar)



Multisensor Data Fusion



A Second Sensor

- In the intrusion detection example, assume that there is a vibration sensor on the floor that detects footsteps. If a burglar enters the building, there is a 90% chance that the vibration sensor will fire. If the vibration sensor fires, what are the odds that there is a burglar? Assume that the vibration sensor fires 10 times a year



A Second Sensor

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 - $P(\text{Burg}|\text{vib}) = P(\text{Vib}|\text{Burg}) \cdot P(\text{Burg}) / P(\text{Vib})$
 $= 0.9 * (1/365) / (10/365) = 0.09$



Two Sensor Example

- In the intrusion detection example, what are the odds of burglary if both sensors fire?
- $P(\text{Burg}|A, \text{Vib}) = ?$

Remember: If burglar enters, motion alarm fires 99% of the time and vibration alarm fires 90% of the time. Burglaries occur once a year, motion alarm fires 3 times a year, and vibration alarm fires 10 times a year.



Two Sensor Example

- In the intrusion detection example, what are the odds of burglary if both sensors fire?
- $P(\text{Burg}|A, \text{Vib}) = ?$
- $P(B|A,V) = P(A,V|B) P(B)/P(A,V)$

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Now what?

Is it OK to say $P(A,V|B) = P(A|B)P(V|B)$?

Is it OK to say $P(A,V) = P(A)P(V)$?



Independence versus Conditional Independence

- John and Sally follow Mike on Twitter.
- When Mike tweets something, John re-tweets it with a 50% probability. Sally re-tweets it with a 30% probability.
- Are John's and Sally's tweets independent?



Independence versus Conditional Independence

- John and Sally follow Mike on Twitter.
- When Mike tweets something, John re-tweets it with a 50% probability. Sally re-tweets it with a 30% probability.
- Are John's and Sally's tweets independent?
 - No. However, given that Mike says something, their decisions to re-tweet it are independent (conditional independence)

Remember: If burglar enters, motion alarm fires 99% of the time and vibration alarm fires 90% of the time. Burglaries occur once a year, motion alarm fires 3 times a year, and vibration alarm fires 10 times a year.

Two Sensor Example

- In the intrusion detection example, what are the odds of burglary if both sensors fire?
- $P(\text{Burg}|A, \text{Vib}) = ?$
- $P(B|A,V) = P(A,V|B) P(B)/P(A,V)$

Now what?

OK to say $P(A,V|B) = P(A|B)P(V|B)$

~~$P(A,V) = P(A)P(V)?$~~

Remember: If burglar enters, motion alarm fires 99% of the time and vibration alarm fires 90% of the time. Burglaries occur once a year, motion alarm fires 3 times a year, and vibration alarm fires 10 times a year.



Two Sensor Example

- In the intrusion detection example, what are the odds of burglary if both sensors fire?
- $P(\text{Burg}|A, \text{Vib}) = ?$
- $P(B|A,V) = \frac{P(A,V|B) P(B)}{P(A,V)}$ where
 $P(A,V) = P(A,V|B) P(B) + P(A,V|\bar{B}) P(\bar{B})$
and $P(A,V|B) = P(A|B)P(V|B)$

Remember: If burglar enters, motion alarm fires 99% of the time and vibration alarm fires 90% of the time. Burglaries occur once a year, motion alarm fires 3 times a year, and vibration alarm fires 10 times a year.



Two Sensor Example

- In the intrusion detection example, what are the odds of burglary if both sensors fire?
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Remember: If burglar enters, motion alarm fires 99% of the time and vibration alarm fires 90% of the time. Burglaries occur once a year, motion alarm fires 3 times a year, and vibration alarm fires 10 times a year.

Two Sensor Example

- $P(\text{Burg}|A, \text{Vib})$ Solution steps:
 - Find the probability of false alarms from:
$$P(A) = P(A|B) P(B) + P(A|\bar{B}) P(\bar{B})$$
$$P(V) = P(V|B) P(B) + P(V|\bar{B}) P(\bar{B})$$
 - Find the probability of both sensors firing:
$$P(A, V) = P(A, V|B) P(B) + P(A, V|\bar{B}) P(\bar{B})$$

where $P(A, V|B) = P(A|B)P(V|B)$
 $P(A, V|\bar{B}) = P(A|\bar{B})P(V|\bar{B})$
 - $P(B|A, V) = P(A, V|B) P(B)/P(A, V) = 94.62\%$



Key Things to Remember

- Total Probability Theorem:
 - $P(A) = P(A|C_1) P(C_1) + \dots + P(A|C_n) P(C_n)$
where C_1, \dots, C_n cover the space of all possibilities
- Bayes Theorem: $P(A|B) = P(B|A) \cdot P(A)/P(B)$
- Other: $P(A,B) = P(A|B) P(B)$



Practice and Review: Conditional Probabilities

- A driver with a history of substance abuse is severely injured when his car spins out of control hitting a stop sign. Police and ambulance vehicles are dispatched. A police officer at the scene suggests to a paramedic that the driver must have been intoxicated. The paramedic answers: "Statistically, only 10% of individuals with substance abuse problems end up in severe car crashes, so it may well have been something else".
 - Is the argument valid?



Practice and Review: Conditional Probabilities

- A driver with a history of substance abuse is severely injured when his car spins out of control hitting a stop sign. Police and ambulance vehicles are dispatched. A police officer at the scene suggests to a paramedic that the driver must have been intoxicated. The paramedic answers: "Statistically, only 10% of individuals with substance abuse problems end up in severe car crashes, so it may well have been something else".
 - Is the argument valid?
 - No. The relevant statistic here is: Given that a person with a history of substance abuse ends up in a severe car crash, what are the odds that there were under influence? (These odds are very high.)



Practice and Review: Conditional Probabilities

- An obstacle sensor on a robot is used to detect nearby obstacles on the path. When an obstacle is present, it is detected with a 99.9% probability. When the sensor fires, what is the probability that an obstacle lies in the robot's path?



Practice and Review: Conditional Probabilities

- An obstacle sensor on a robot is used to detect nearby obstacles on the path. When an obstacle is present, it is detected with a 99.9% probability. When the sensor fires, what is the probability that an obstacle lies in the robot's path?
 - Not clear; we do not know the rate of false positives (instances when the sensor fires in the absence of obstacles).



Conditional Independence

- Two obstacle sensors are mounted near each other on the front of a robot. The probability that one of them fires in a particular time interval is 5%. What is the probability that both fire simultaneously?



Conditional Independence

- Two obstacle sensors are mounted near each other on the front of a robot. The probability that one of them fires in a particular time interval is 5%. What is the probability that both fire simultaneously?
 - We cannot compute the numeric answer because the sensors are not independent. We need more information.



Conditional Independence

- Two obstacle sensors are mounted near each other on the front of a robot. *When an obstacle appears in front of the robot, the probability that one of them fires is 75%. What is the probability that both fire at that time?*



Conditional Independence

- Two obstacle sensors are mounted near each other on the front of a robot. *When an obstacle appears in front of the robot*, the probability that one of them fires is 75%. What is the probability that both fire at that time?
 - $(0.75)^2$



Multisensor Fusion

- A defense sensor (radar) is used to detect incoming missiles. The probability of a missile being fired in the vicinity of the sensor is 1%. When a missile is fired, the sensor detects it with 98% probability. The sensor also has a 20% false positive rate. Three sensors are deployed. When all three sensors indicate a missile, what is the probability that an actual missile is fired?



Three Sensor Example

- $P(M|S1,S2,S3) = 54.3\%$
- $P(M|S1,S2,S3) = P(S1,S2,S3|M) P(M)/P(S1,S2,S3)$, where:
 $P(S1,S2,S3) = P(S1,S2,S3|M) P(M) + P(S1,S2,S3|no M) P(no M)$
and
 $P(S1,S2,S3|M) = P(S1|M)P(S2|M)P(S3|M)$
 $P(S1,S2,S3|no M) = P(S1|no M)P(S2|no M)P(S3|no M)$



Multisensor Fusion

- In the preceding example, how many sensors do you need in order to raise the probability of there being a target (when all sensors fire) to over 95%?



Robot Example:

- A robot has a camera that detects obstacles with probability 70%, a bump sensor that detects imminent collisions with a probability of 99.9% (when an obstacle is 1 inch away), and a cliff sensor that detects imminent falls off a cliff with a probability of 99.9% (when the cliff is 1 inch away). The robot has breaks that can stop it within 0.1 second. The mission is to deliver supplies from point A to point B, safely.
 - What are safety-critical requirements?
 - What are mission-critical (i.e., performance) requirements?
 - What is a safe state?
 - How to ensure well-formed dependencies?
 - What is a safe speed for the robot?
 - Is the algorithm that computes speed based on preferred arrival time and route safety-critical or mission-critical?