CS 425 / ECE 428 Distributed Systems Fall 2018

Indranil Gupta (Indy) Lecture 18: Mutual Exclusion

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#### Why Mutual Exclusion?

- Bank's Servers in the Cloud: Two of your customers make simultaneous deposits of \$10,000 into your bank account, each from a separate ATM.
  - Both ATMs read initial amount of \$1000 concurrently from the bank's cloud server
  - Both ATMs add \$10,000 to this amount (locally at the ATM)
  - Both write the final amount to the server
  - What's wrong?

#### Why Mutual Exclusion?

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  - Both ATMs read initial amount of \$1000 concurrently from the bank's cloud server
  - Both ATMs add \$10,000 to this amount (locally at the ATM)
  - Both write the final amount to the server
  - You lost \$10,000!
- The ATMs need *mutually exclusive* access to your account entry at the server
  - or, mutually exclusive access to executing the code that modifies the account entry

## More Uses of Mutual Exclusion

- Distributed File systems
  - Locking of files and directories
- Accessing objects in a safe and consistent way
  - Ensure at most one server has access to object at any point of time
- Server coordination
  - Work partitioned across servers
  - Servers coordinate using locks
- In industry
  - Chubby is Google's locking service
  - Many cloud stacks use Apache Zookeeper for coordination among servers

### **Problem Statement for Mutual Exclusion**

- *Critical Section* Problem: Piece of code (at all processes) for which we need to ensure there is <u>at most one process</u> executing it at any point of time.
- Each process can call three functions
  - enter() to enter the critical section (CS)
  - AccessResource() to run the critical section code
  - exit() to exit the critical section

### Our Bank Example

ATM1:

enter(S); // AccessResource() obtain bank amount; add in deposit; update bank amount; // AccessResource() end exit(S); // exit

¦ATM2:

enter(S); // AccessResource() obtain bank amount; add in deposit; update bank amount; // AccessResource() end exit(S); // exit

### Approaches to Solve Mutual Exclusion

#### • Single OS:

- If all processes are running in one OS on a machine (or VM), then
- Semaphores, mutexes, condition variables, monitors, etc.

## Approaches to Solve Mutual Exclusion (2)

- Distributed system:
  - Processes communicating by passing messages
- Need to guarantee 3 properties:
  - Safety (essential) At most one process executes in CS (Critical Section) at any time
  - Liveness (essential) Every request for a CS is granted eventually
  - Ordering (desirable) Requests are granted in the order they were made

### Processes Sharing an OS: Semaphores

- Semaphore == an integer that can only be accessed via two special functions
- Semaphore S=1; // Max number of allowed accessors

```
1. wait(S) (or P(S) or down(S)):
```

```
enter() while(1) { // each execution of the while loop is atomic
if (S > 0) {
S--;
break;
}
```

Each while loop execution and S++ are each atomic operations – supported via hardware instructions such as compare-and-swap, test-and-set, etc.

```
exit() 2. signal(S) (or V(S) or up(s)):
```

S++; // <u>atomic</u>

#### Our Bank Example Using Semaphores

Semaphore S=1; // shared ATM1:

wait(S);
// AccessResource()
obtain bank amount;
add in deposit;
update bank amount;
// AccessResource() end
signal(S); // exit

Semaphore S=1; // shared ATM2: wait(S); // AccessResource() obtain bank amount; add in deposit; update bank amount; // AccessResource() end signal(S); // exit

- In a distributed system, cannot share variables like semaphores
- So how do we support mutual exclusion in a distributed system?

## System Model

- Before solving any problem, specify its System Model:
  - Each pair of processes is connected by reliable channels (such as TCP).
  - Messages are eventually delivered to recipient, and in FIFO (First In First Out) order.
  - Processes do not fail.
    - Fault-tolerant variants exist in literature.

### **Central Solution**

- Elect a central master (or leader)
  - Use one of our election algorithms!
- Master keeps
  - A **queue** of waiting requests from processes who wish to access the CS
  - A special **token** which allows its holder to access CS
- Actions of any process in group:
  - enter()
    - Send a request to master
    - Wait for token from master
  - exit()
    - Send back token to master

### **Central Solution**

- Master Actions:
  - On receiving a request from process Pi
     if (master has token)
     Send token to Pi
    - else
- Add Pi to queue
- On receiving a token from process Pi
  - if (queue is not empty)
    - Dequeue head of queue (say P*j*), send that process the token
  - else
- Retain token

## Analysis of Central Algorithm

- Safety at most one process in CS
  - Exactly one token
- Liveness every request for CS granted eventually
  - With *N* processes in system, queue has at most *N* processes
  - If each process exits CS eventually and no failures, liveness guaranteed
- FIFO Ordering is guaranteed, in order of requests received at master

### **Analyzing Performance**

Efficient mutual exclusion algorithms use fewer messages, and make processes wait for shorter durations to access resources. Three metrics:

- *Bandwidth*: the total number of messages sent in each *enter* and *exit* operation.
- *Client delay*: the delay incurred by a process at each enter and exit operation (when *no* other process is in, or waiting)

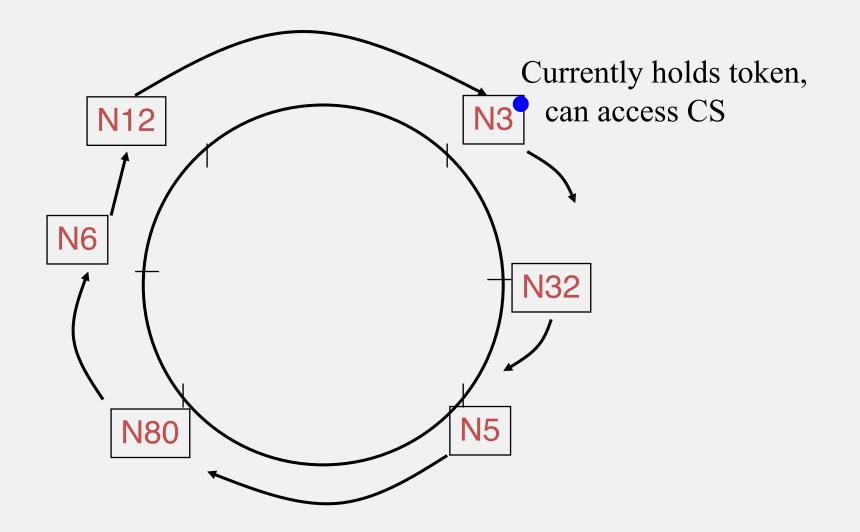
(We will prefer mostly the enter operation.)

• *Synchronization delay*: the time interval between one process exiting the critical section and the next process entering it (when there is *only one* process waiting)

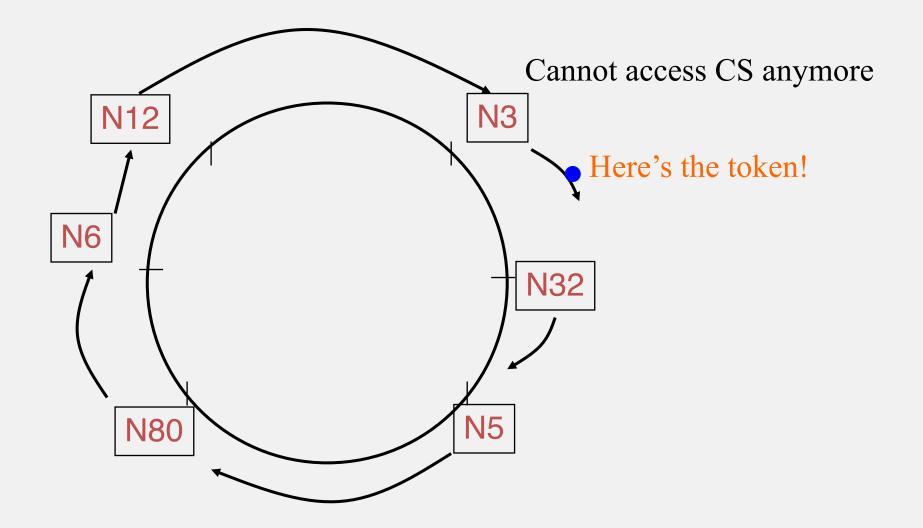
### Analysis of Central Algorithm

- *Bandwidth*: the total number of messages sent in each *enter* and *exit* operation.
  - 2 messages for enter
  - 1 message for exit
- *Client delay*: the delay incurred by a process at each enter and exit operation (when *no* other process is in, or waiting)
  - 2 message latencies (request + grant)
- *Synchronization delay*: the time interval between one process exiting the critical section and the next process entering it (when there is *only one* process waiting)
  - 2 message latencies (release + grant)

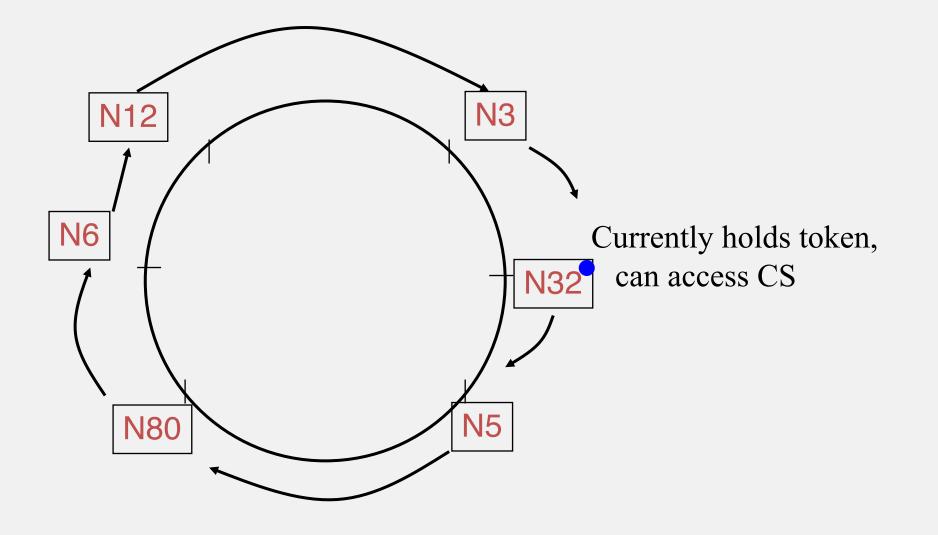
• The master is the performance bottleneck and SPoF (single point of failure)













- N Processes organized in a virtual ring
- Each process can send message to its successor in ring
- Exactly 1 token
- enter()
  - Wait until you get token
- exit() // already have token
  - Pass on token to ring successor
- If receive token, and not currently in enter(), just pass on token to ring successor

## Analysis of Ring-based Mutual Exclusion

- Safety
  - Exactly one token
- Liveness
  - Token eventually loops around ring and reaches requesting process (no failures)
- Bandwidth
  - Per enter(), 1 message by requesting process but up to *N* messages throughout system
  - 1 message sent per exit()

# Analysis of Ring-Based Mutual Exclusion (2)

- Client delay: 0 to *N* message transmissions after entering enter()
  - Best case: already have token
  - Worst case: just sent token to neighbor
- Synchronization delay between one process' exit() from the CS and the next process' enter():
  - Between 1 and (*N*-1) message transmissions.
  - <u>Best case</u>: process in enter() is successor of process in exit()
  - <u>Worst case</u>: process in enter() is predecessor of process in exit()



- Client/Synchronization delay to access CS still O(*N*) in Ring-Based approach.
- Can we make this faster?

### System Model

- Before solving any problem, specify its System Model:
  - Each pair of processes is connected by reliable channels (such as TCP).
  - Messages are eventually delivered to recipient, and in FIFO (First In First Out) order.
  - Processes do not fail.

## Ricart-Agrawala's Algorithm

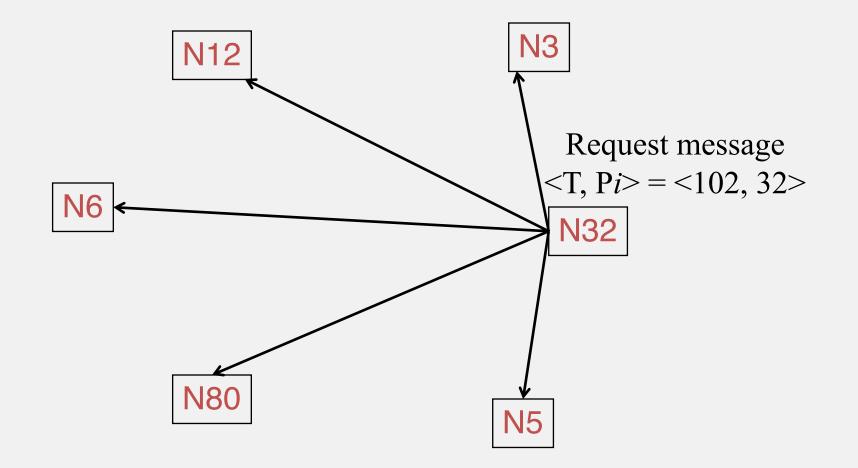
- Classical algorithm from 1981
- Invented by Glenn Ricart (NIH) and Ashok Agrawala (U. Maryland)
- No token
- Uses the notion of causality and multicast
- Has lower waiting time to enter CS than Ring-Based approach

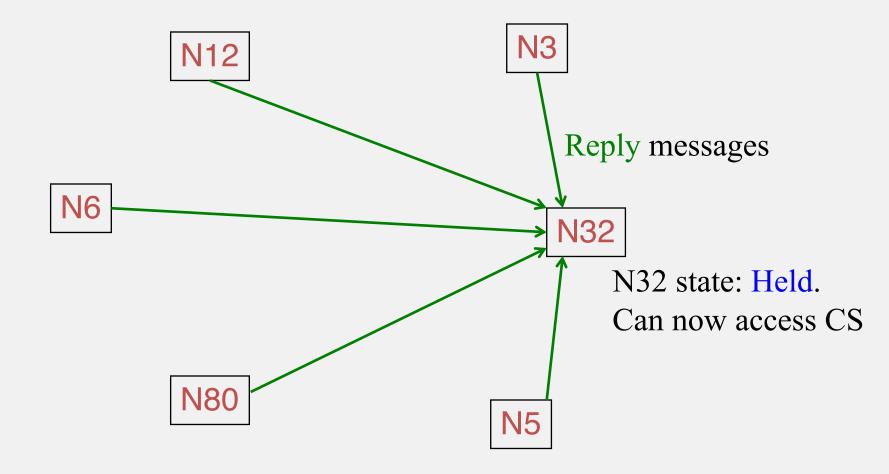
### Key Idea: Ricart-Agrawala Algorithm

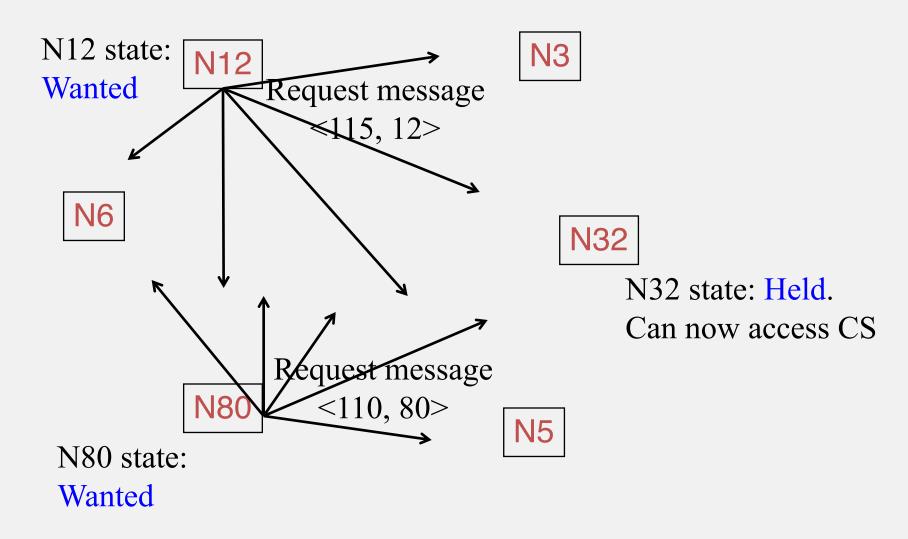
- enter() at process Pi
  - <u>multicast</u> a request to all processes
    - Request: <T, P*i*>, where T = current Lamport timestamp at P*i*
  - Wait until *all* other processes have responded positively to request
- Requests are granted in order of causality
- <T, P*i*> is used lexicographically: P*i* in request <T,</li>
   P*i*> is used to break ties (since Lamport timestamps are not unique for concurrent events)

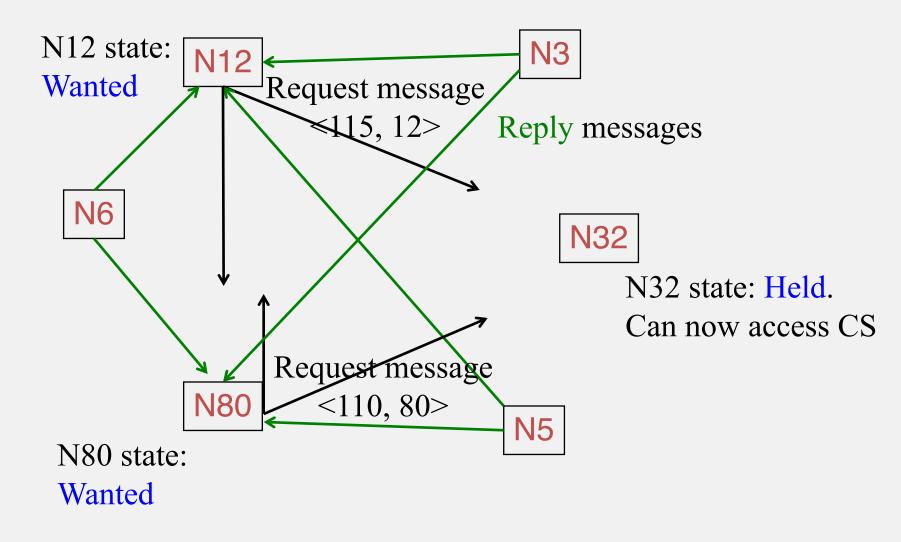
### Messages in RA Algorithm

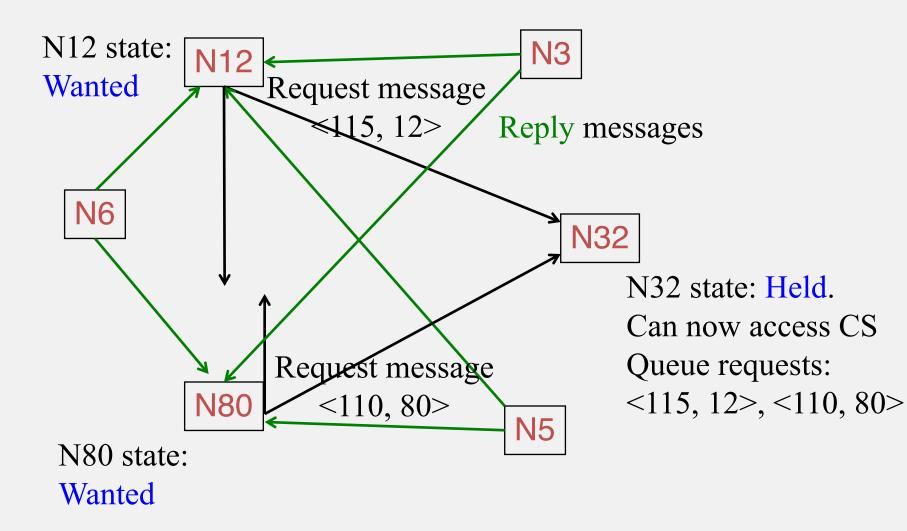
- enter() at process Pi
  - set state to <u>Wanted</u>
  - multicast "Request" <T*i*, P*i*> to all processes, where T*i* = current Lamport timestamp at P*i*
  - wait until <u>all</u> processes send back "Reply"
  - change state to <u>Held</u> and enter the CS
- On receipt of a Request  $\langle Tj, Pj \rangle$  at  $Pi (i \neq j)$ :
  - if (state = <u>Held</u>) or (state = <u>Wanted</u> & (T*i*, *i*) < (T*j*, *j*))
     // lexicographic ordering in (T*j*, P*j*)
     add request to local queue (of waiting requests)
     else send "Reply" to P*j*
- exit() at process Pi
  - change state to <u>Released</u> and "Reply" to <u>all</u> queued requests.

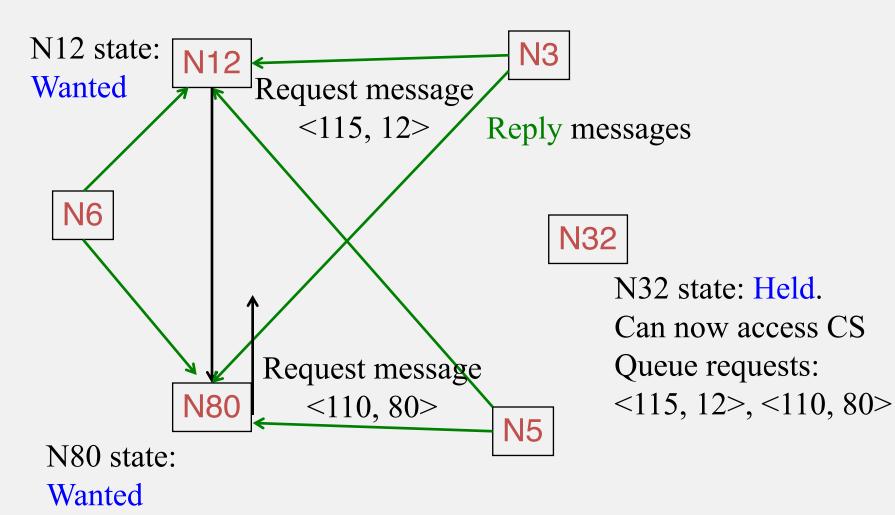




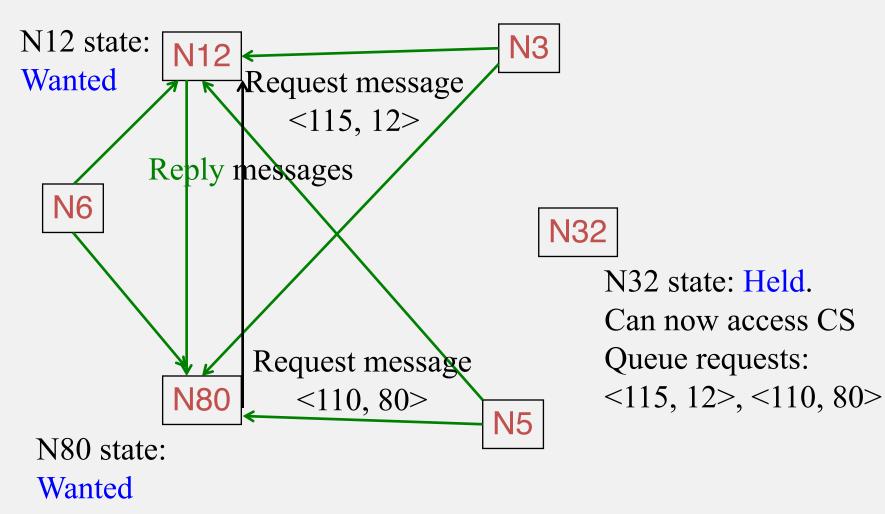






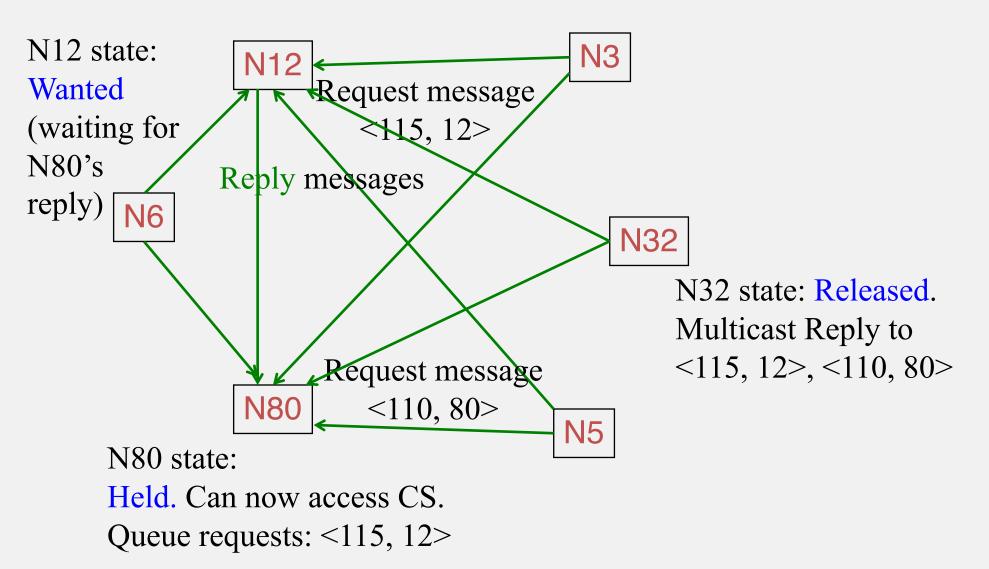


Queue requests: <115, 12> (since > (110, 80))



Queue requests: <115, 12>

#### Example: Ricart-Agrawala Algorithm



### Analysis: Ricart-Agrawala's Algorithm

- Safety
  - Two processes Pi and Pj cannot both have access to CS
    - If they did, then both would have sent Reply to each other
    - Thus, (Ti, i) < (Tj, j) and (Tj, j) < (Ti, i), which are together not possible
    - What if  $(T_i, i) < (T_j, j)$  and P*i* replied to P*j*'s request before it created its own request?
      - Then it seems like both P*i* and P*j* would approve each others' requests
      - But then, causality and Lamport timestamps at  $P_i$  implies that  $T_i > T_j$ , which is a contradiction
      - So this situation cannot arise

## Analysis: Ricart-Agrawala's Algorithm (2)

- Liveness
  - Worst-case: wait for all other (*N-1*) processes to send Reply
- Ordering
  - Requests with lower Lamport timestamps are granted earlier

### Performance: Ricart-Agrawala's Algorithm

- Bandwidth: 2\*(*N*-1) messages per enter() operation
  - *N-1* unicasts for the multicast request + *N-1* replies
  - *N* messages if the underlying network supports multicast (1 multicast + *N*-1 unicast replies)
  - *N-1* unicast messages per exit operation
    - 1 multicast if the underlying network supports multicast
- Client delay: one round-trip time
- Synchronization delay: one message transmission time

# Ok, but ...

- Compared to Ring-Based approach, in Ricart-Agrawala approach
  - Client/synchronization delay has now gone down to O(1)
  - But bandwidth has gone up to O(N)
- Can we get *both* down?

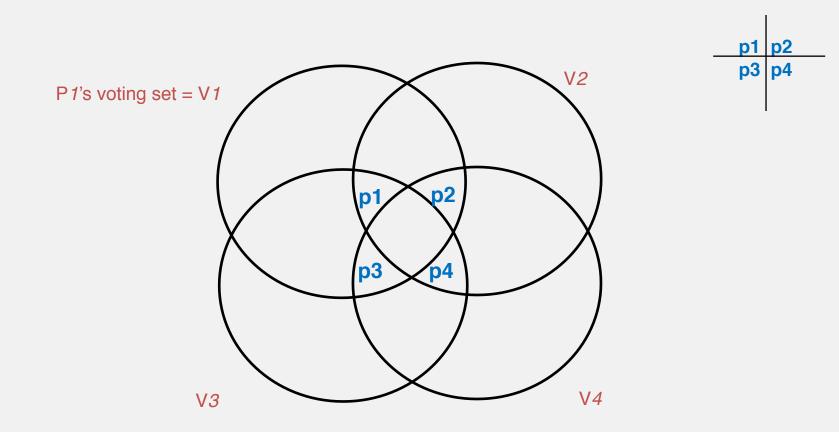
## Maekawa's Algorithm: Key Idea

- Ricart-Agrawala requires replies from *all* processes in group
- Instead, get replies from only *some* processes in group
- But ensure that only process one is given access to CS (Critical Section) at a time

### Maekawa's Voting Sets

- Each process P*i* is associated with a *voting set* V*i* (of processes)
- Each process belongs to its own voting set
- The intersection of any two voting sets must be non-empty
  - Same concept as *Quorums*!
- Each voting set is of size *K*
- Each process belongs to *M* other voting sets
- Maekawa showed that  $K=M=\sqrt{N}$  works best
- One way of doing this is to put N processes in a  $\sqrt{N}$  by  $\sqrt{N}$  matrix and for each P*i*, its voting set V*i* = row containing P*i* + column containing P*i*. Size of voting set = 2\* $\sqrt{N}$ -1

#### Example: Voting Sets with N=4



### Maekawa: Key Differences From Ricart-Agrawala

- Each process requests permission from only its voting set members
  - Not from all
- Each process (in a voting set) gives permission to at most one process at a time
  - Not to all

#### Actions

- state =  $\underline{\text{Released}}$ , voted = false
- enter() at process Pi:
  - state =  $\underline{Wanted}$
  - Multicast Request message to all processes in V*i*
  - Wait for Reply (vote) messages from all processes in V*i* (including vote from self)
  - state =  $\underline{\text{Held}}$
- exit() at process Pi:
  - state =  $\underline{\text{Released}}$
  - Multicast Release to all processes in V*i*

# Actions (2)

```
• When Pi receives a Request from Pj:

if (state == <u>Held</u> OR voted = true)

queue Request
```

else

send **Reply** to P*j* and set voted = true

```
• When Pi receives a Release from Pj:
if (queue empty)
```

voted = false

else

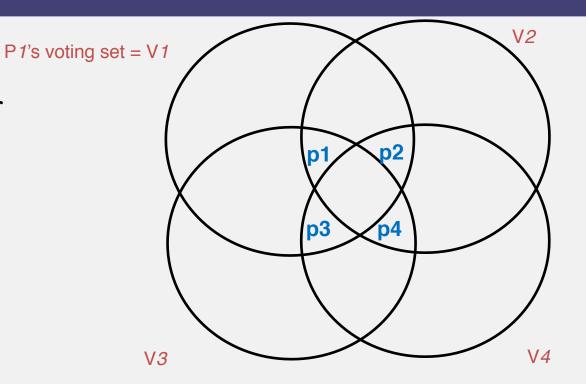
```
dequeue head of queue, say Pk
Send Reply only to Pk
voted = true
```



- When a process P*i* receives replies from all its voting set V*i* members, no other process P*j* could have received replies from all its voting set members V*j* 
  - V*i* and V*j* intersect in at least one process say P*k*
  - But Pk sends only one Reply (vote) at a time, so it could not have voted for both Pi and Pj

#### Liveness

- A process needs to wait for at most (*N-1*) other processes to finish CS
- But does not guarantee liveness
- Since can have a *deadlock*
- Example: all 4 processes need access
  - P1 is waiting for P3
  - P3 is waiting for P4
  - P4 is waiting for P2
  - P2 is waiting for P1
  - No progress in the system!
- There are deadlock-free versions



### Performance

- Bandwidth
  - $2\sqrt{N}$  messages per enter()
  - $\sqrt{N}$  messages per exit()
  - Better than Ricart and Agrawala's (2\*(*N*-1) and *N*-1 messages)
  - $\sqrt{N}$  quite small.  $N \sim 1$  million =>  $\sqrt{N} = 1$ K
- Client delay: One round trip time
- Synchronization delay: 2 message transmission times

# Why $\sqrt{N}$ ?

- Each voting set is of size *K*
- Each process belongs to *M* other voting sets
- Total number of voting set members (processes may be repeated) = *K\*N*
- But since each process is in *M* voting sets
  - K\*N/M = N => K = M (1)
- Consider a process Pi
  - Total number of voting sets = members present in P*i*'s voting set and all their voting sets = (M-1)\*K + 1
  - All processes in group must be in above
  - To minimize the overhead at each process (*K*), need each of the above members to be unique, i.e.,
    - N = (M-1)\*K + 1
    - N = (K-1)\*K + 1 (due to (1))
    - $K \sim \sqrt{N}$

### Failures?

- There are fault-tolerant versions of the algorithms we've discussed
  - E.g., Maekawa
- One other way to handle failures: Use Paxoslike approaches!

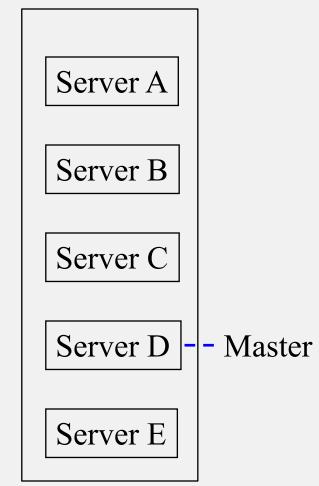
# Chubby

- Google's system for locking
- Used underneath Google's systems like BigTable, Megastore, etc.
- Not open-sourced but published
- Chubby provides *Advisory* locks only
  - Doesn't guarantee mutual exclusion unless every client checks lock before accessing resource

Reference: http://research.google.com/archive/chubby.html

# Chubby (2)

- Can use not only for locking but also writing small configuration files
- Relies on Paxos-like (consensus) protocol
- Group of servers with one elected as Master
  - All servers replicate same information
- Clients send read requests to Master, which serves it locally
- Clients send write requests to Master, which sends it to all servers, gets majority (quorum) among servers, and then responds to client
- On master failure, run election protocol
- On replica failure, just replace it and have it catch up



### Summary

- Mutual exclusion important problem in cloud computing systems
- Classical algorithms
  - Central
  - Ring-based
  - Ricart-Agrawala
  - Maekawa
- Industry systems
  - Chubby: a coordination service
  - Similarly, Apache Zookeeper for coordination

#### Announcements

- HW3, MP3 out, due soon.
- You should have started on both by now.