Chapter 5: Thread-Level Parallelism – Part 1

Introduction

- What is a parallel or multiprocessor system?
- Why parallel architecture?
- Performance potential
- Flynn classification
- Communication models
- Architectures
- Centralized shared-memory
- Distributed shared-memory
- Parallel programming
- Synchronization
- Memory consistency models

What is a parallel or multiprocessor system?

Multiple processor units working together to solve the same problem Key architectural issue: Communication model

Why parallel architectures?

Absolute performance

Technology and architecture trends

- Dennard scaling, ILP wall, Moore's law
- \Rightarrow Multicore chips

Connect multicore together for even more parallelism

Performance Potential

Amdahl's Law is pessimistic Let s be the serial part Let p be the part that can be parallelized n ways Serial: SSPPPPP 6 processors: SSP Ρ Ρ Ρ Ρ Ρ Speedup = 8/3 = 2.67 $T(n) = \frac{1}{s+p/n}$ As $n \to \infty$, $T(n) \to \frac{1}{s}$ Pessimistic

Gustafson's Corollary

Amdahl's law holds if run same problem size on larger machines But in practice, we run larger problems and "wait" the same time

Performance Potential (Cont.)

Gustafson's Corollary (Cont.)

Assume for larger problem sizes

Serial time fixed (at s)

Parallel time proportional to problem size (truth more complicated)

Hypothetical Serial:

SSPPPPPP PPPPPP PPPPPP PPPPPP PPPPPP

Speedup = $(8+5^{*}6)/8 = 4.75$ T'(n) = s + n*p; T'(∞) $\rightarrow \infty$!!!!

How does your algorithm "scale up"?

Flynn classification

Single-Instruction Single-Data (SISD)

Single-Instruction Multiple-Data (SIMD)

Multiple-Instruction Single-Data (MISD)

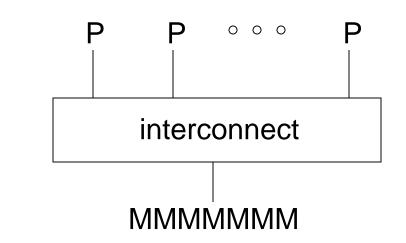
Multiple-Instruction Multiple-Data (MIMD)

Communication models

Shared-memory

- Message passing
- Data parallel

Communication Models: Shared-Memory



Each node a processor that runs a process

One shared memory

Accessible by any processor

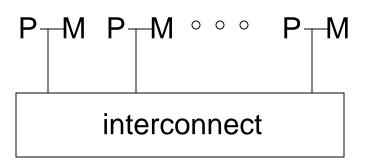
The same address on two different processors refers to the same datum

Therefore, write and read memory to

Store and recall data

Communicate, Synchronize (coordinate)

Communication Models: Message Passing



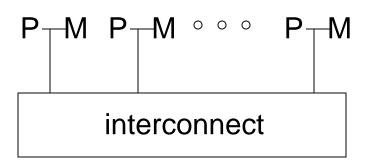
Each node a computer

Processor – runs its own program (like SM)

Memory – local to that node, unrelated to other memory

Add messages for internode communication, send and receive like mail

Communication Models: Data Parallel



Virtual processor per datum

Write sequential programs with "conceptual PC" and let parallelism be within the data (e.g., matrices)

 $\mathsf{C}=\mathsf{A}+\mathsf{B}$

Typically SIMD architecture, but MIMD can be as effective

All mechanisms can usually be synthesized by all hardware Key: which communication model does hardware support best? Virtually all small-scale systems, multicores are shared-memory

Which is Best Communication Model to Support?

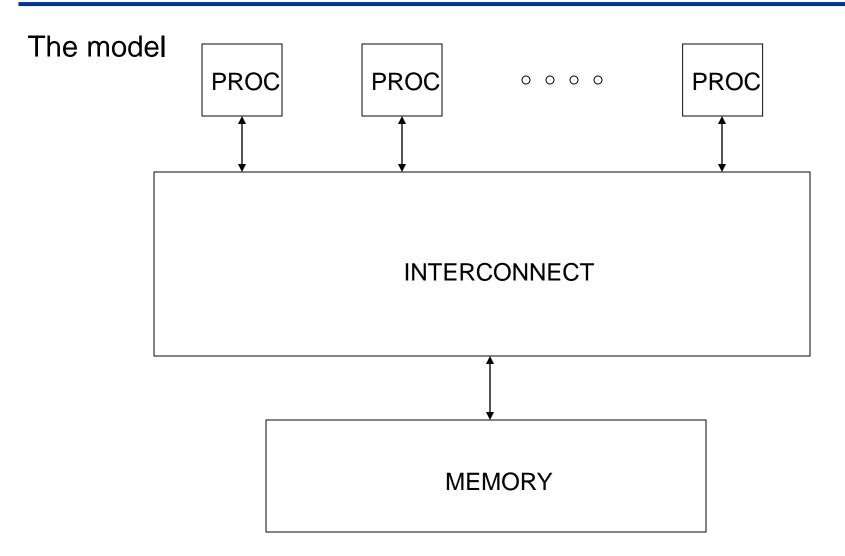
Shared-memory

Used in small-scale systems Easier to program for dynamic data structures Lower overhead communication for small data Implicit movement of data with caching Hard to build?

Message-passing

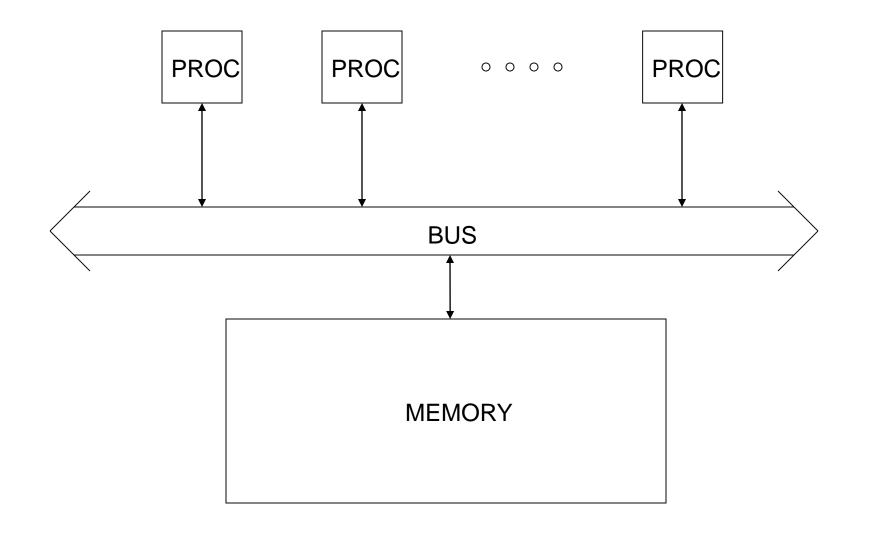
Communication explicit harder to program? Larger overheads in communication OS intervention? Easier to build?

Shared-Memory Architecture



For now, assume interconnect is a bus - centralized architecture

Centralized Shared-Memory Architecture



Centralized Shared-Memory Architecture (Cont.)

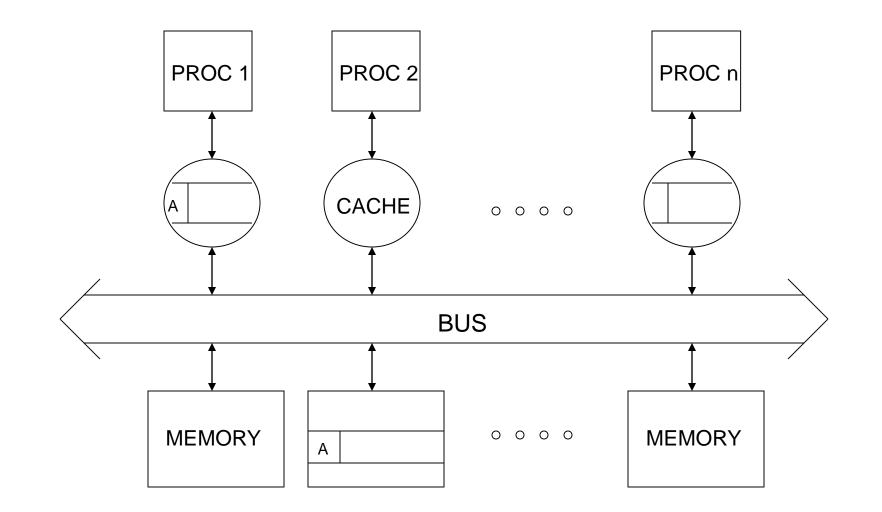
For higher bandwidth (throughput)

For lower latency

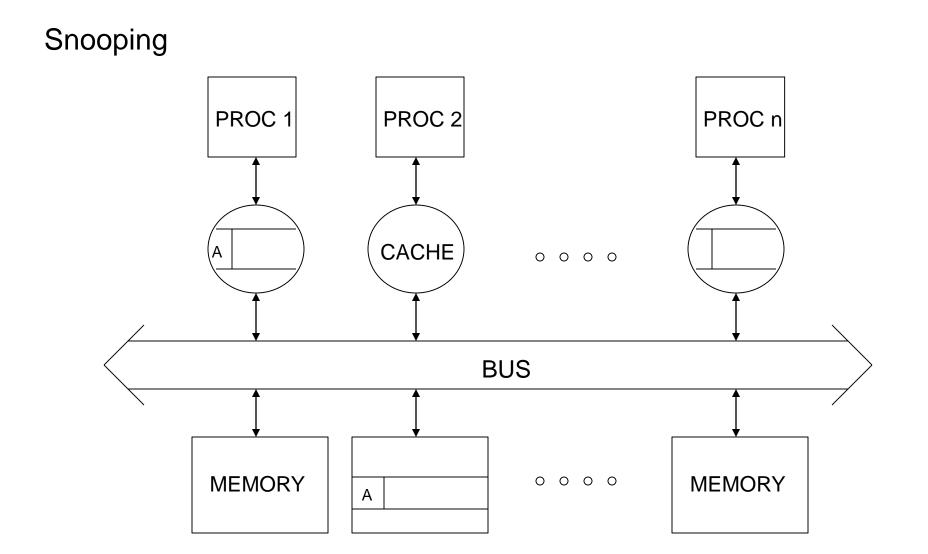




Cache Coherence Problem



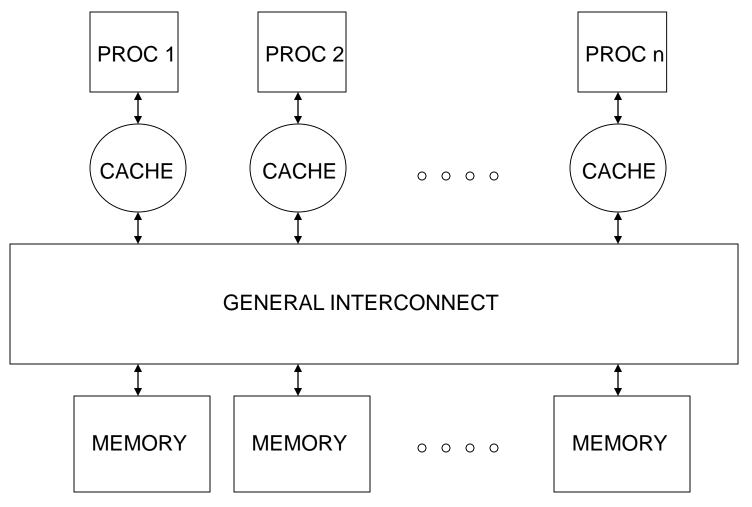
Cache Coherence Solutions



Problem with centralized architecture

Distributed Shared-Memory (DSM) Architecture

Use a higher bandwidth interconnection network



Uniform memory access architecture (UMA)

Distributed Shared-Memory (DSM) - Cont.

For lower latency: Non-Uniform Memory Access architecture (NUMA)

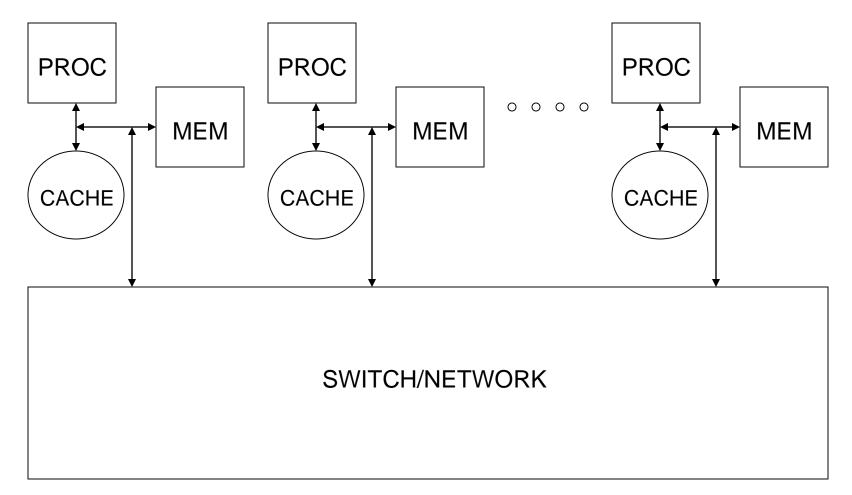


Non-Bus Interconnection Networks

Example interconnection networks

Distributed Shared-Memory - Coherence Problem

Directory scheme



Level of indirection!



Parallel Programming Example

```
Add two matrices: C = A + B
```

Sequential Program

Parallel Program Example (Cont.)



The Parallel Programming Process



Synchronization

Communication – Exchange data

Synchronization – Exchange data to order events

Mutual exclusion or atomicity

Event ordering or Producer/consumer

Point to Point

Flags

Global

Barriers

Mutual Exclusion

Example

Each processor needs to occasionally update a counter

Processor 1 Processor 2

Load reg1, Counter reg1 = reg1 + tmp1 Store Counter, reg1 Load reg2, Counter reg2 = reg2 + tmp2 Store Counter, reg2 Hardware instructions

Test&Set

```
Atomically tests for 0 and sets to 1
Unset is simply a store of 0
```

```
while (Test&Set(L) != 0) {;}
Critical Section
Unset(L)
```

Problem?

Mutual Exclusion Primitives – Alternative?

Test&Test&Set

Mutual Exclusion Primitives – Fetch&Add

```
Fetch&Add(var, data)
   { /* atomic action */
   temp = var
   var = temp + data
   }
   return temp
E.g., let X = 57
   P1: a = Fetch&Add(X,3)
   P2: b = Fetch&Add(X,5)
      If P1 before P2, ?
       If P2 before P1, ?
       If P1, P2 concurrent?
```

Point to Point Event Ordering

Example

Producer wants to indicate to consumer that data is ready

Processor 1	Processor 2
A[1] =	= A[1]
A[2] =	= A[2]
•	•
A[n] =	= A[n]

Global Event Ordering – Barriers

Example

- All processors produce some data
- Want to tell all processors that it is ready
- In next phase, all processors consume data produced previously

Use barriers