



# Personal Sensing

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# Review:

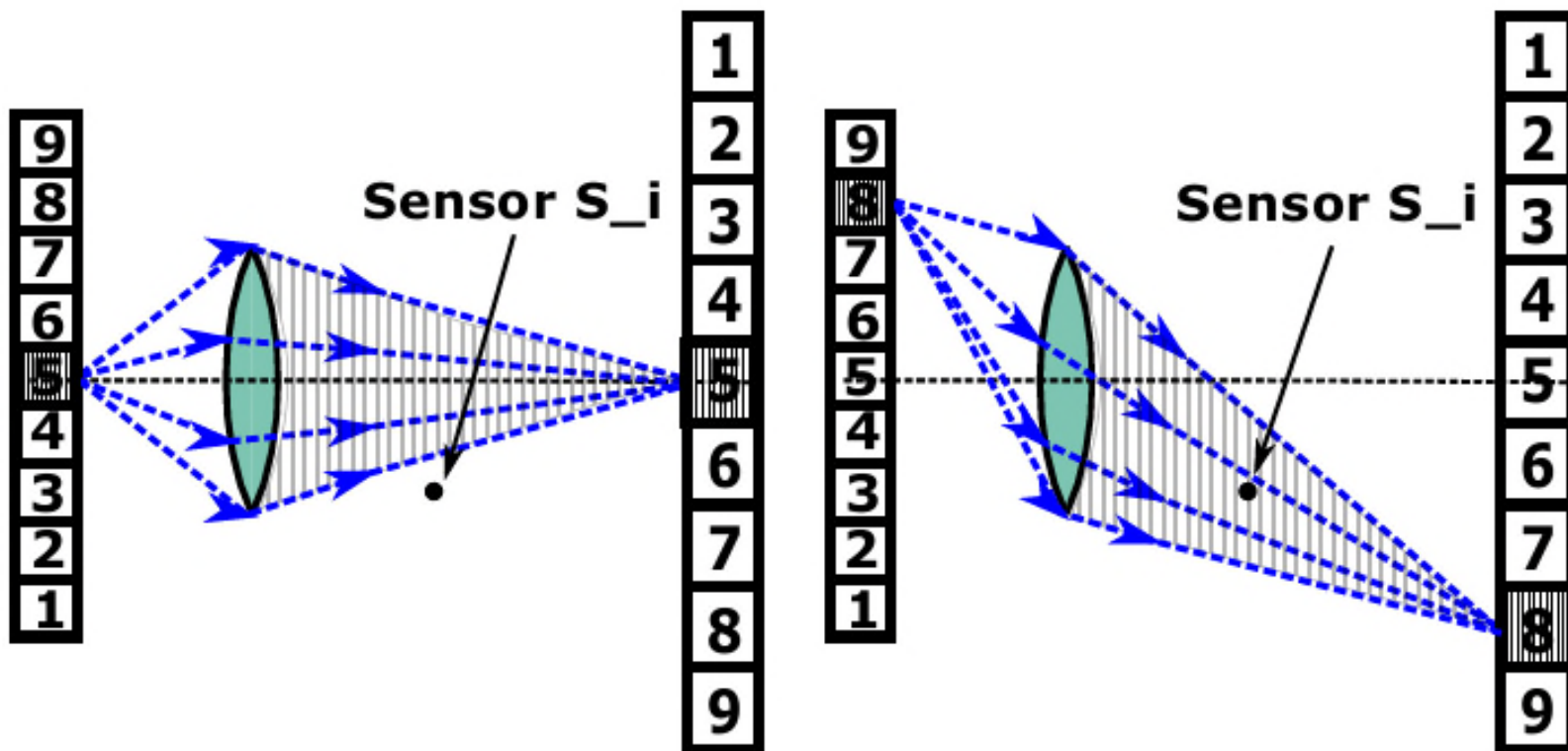
## Localization with a Single LED

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- Can you simultaneously localize a large number of optical receivers using a single “smart” LED?

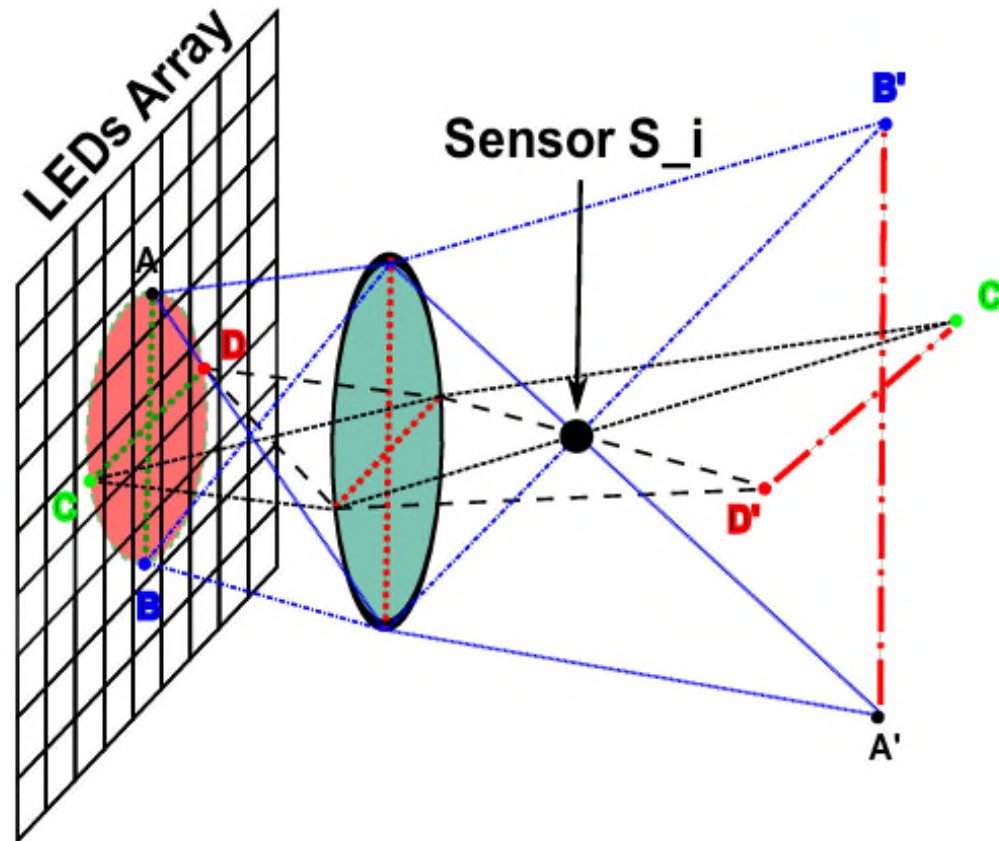
# Idea #1

- Your location determines what you see:

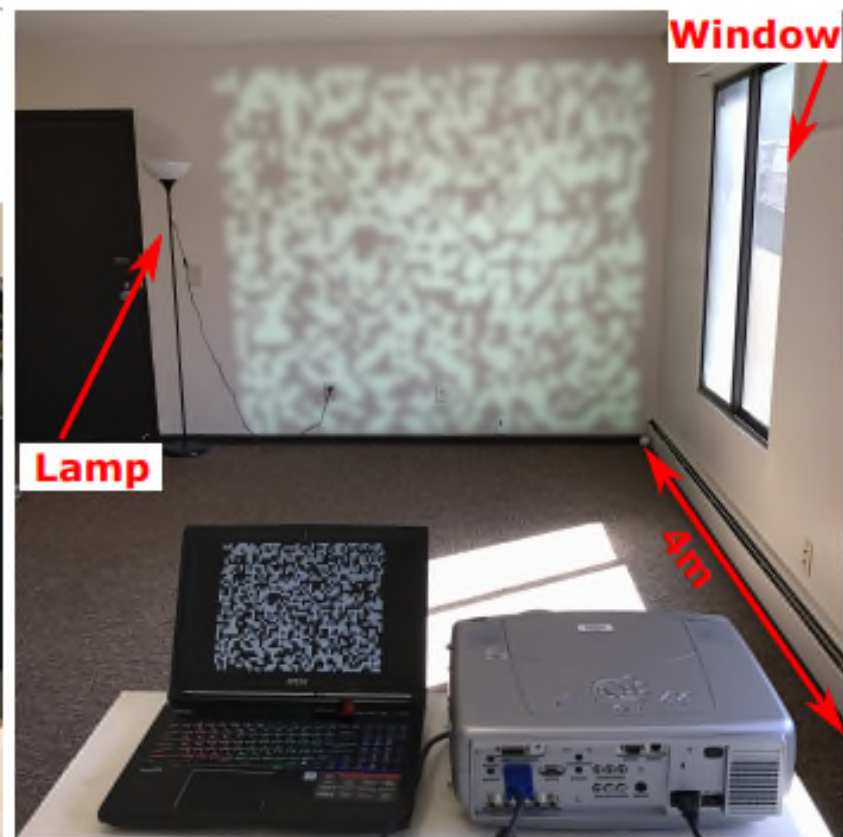
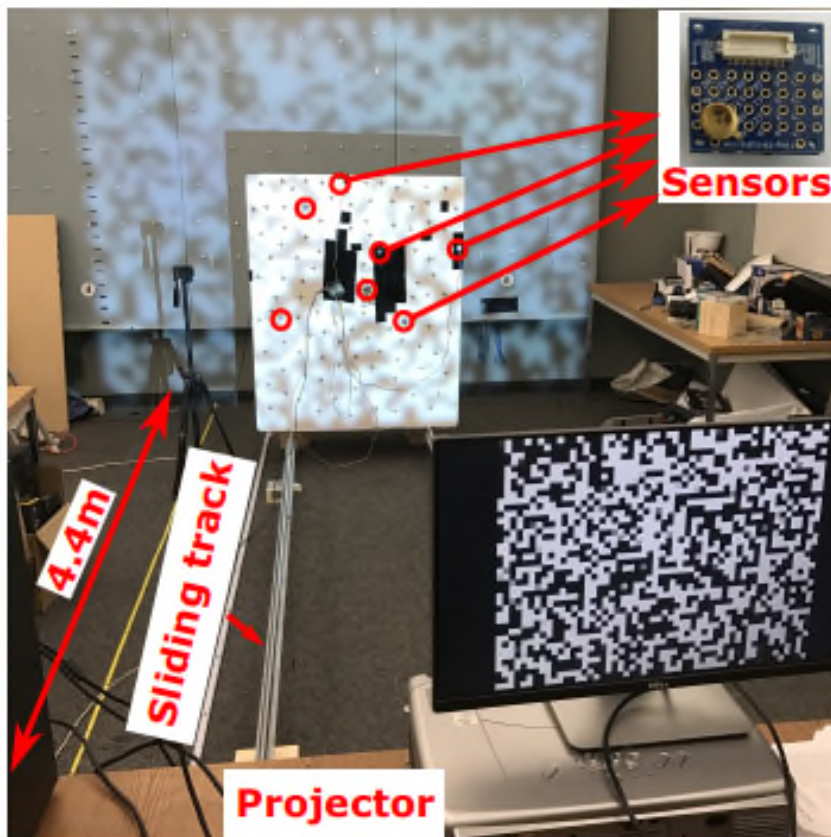


## Idea #2

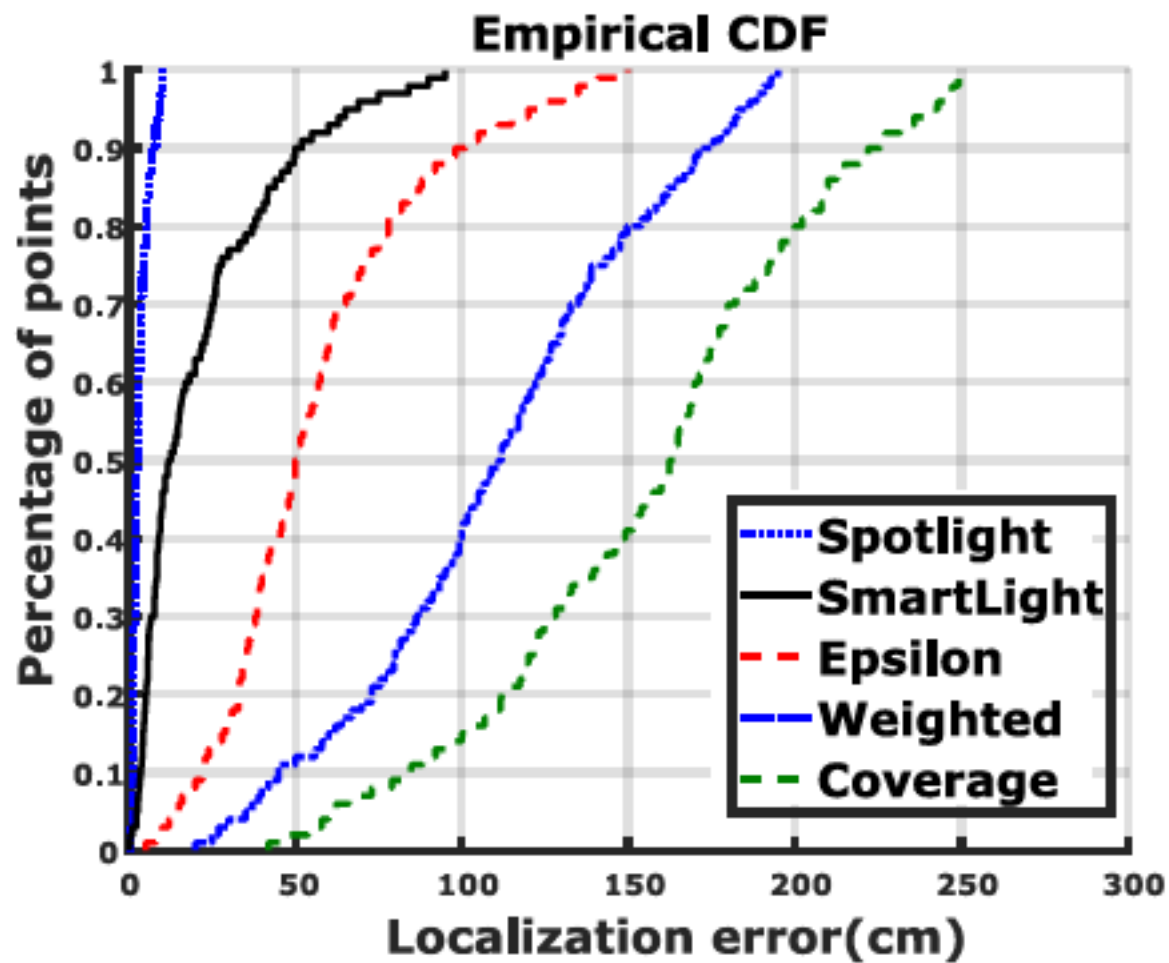
- Distance determines size of visible area



# Testbed



# Evaluation



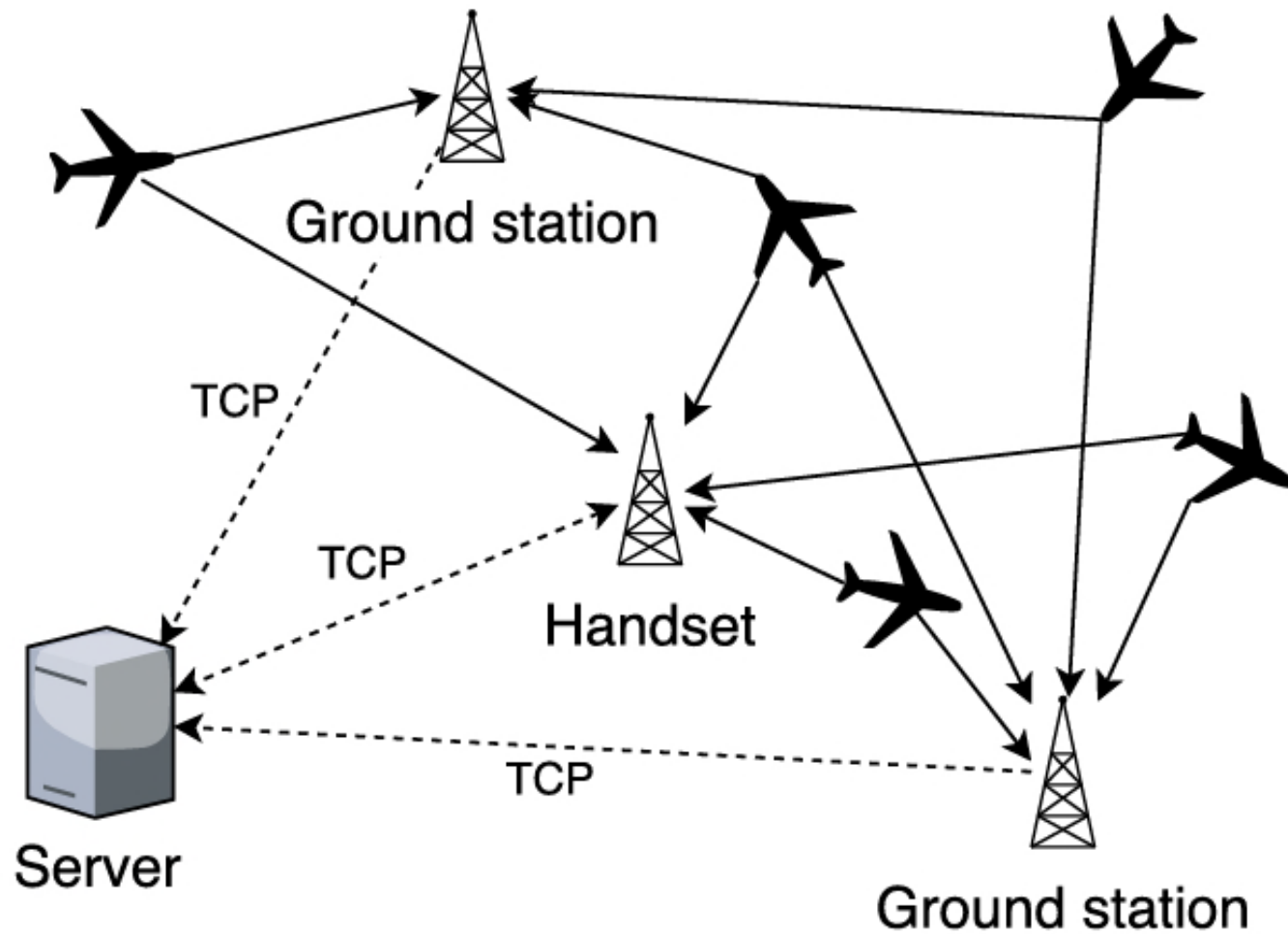
# Localization with Aircraft Signals



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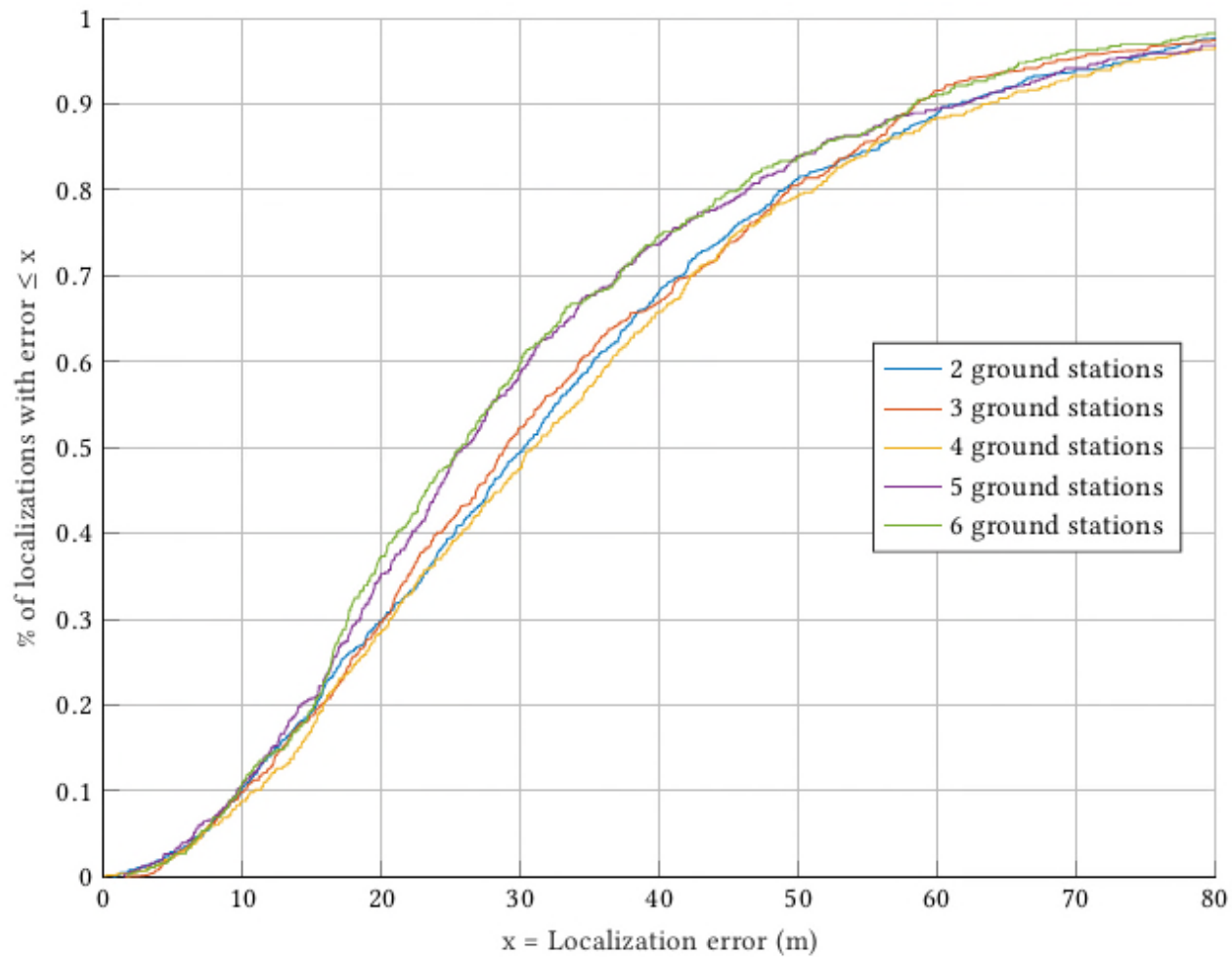
- Can we use aircraft signals to localize mobile devices even in-doors (where there is no GPS)?

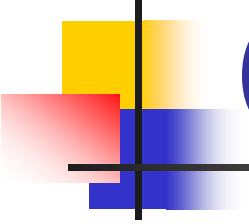
# Localization with Aircraft Signals





# Evaluation





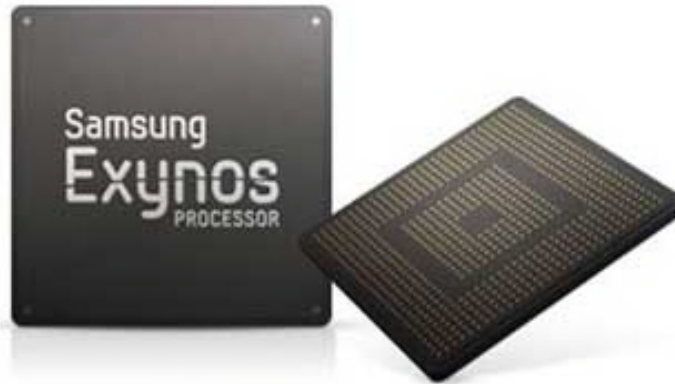
# What Can Smart Phones Do (In Personal Sensing)?

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What's next in personal/context sensing?

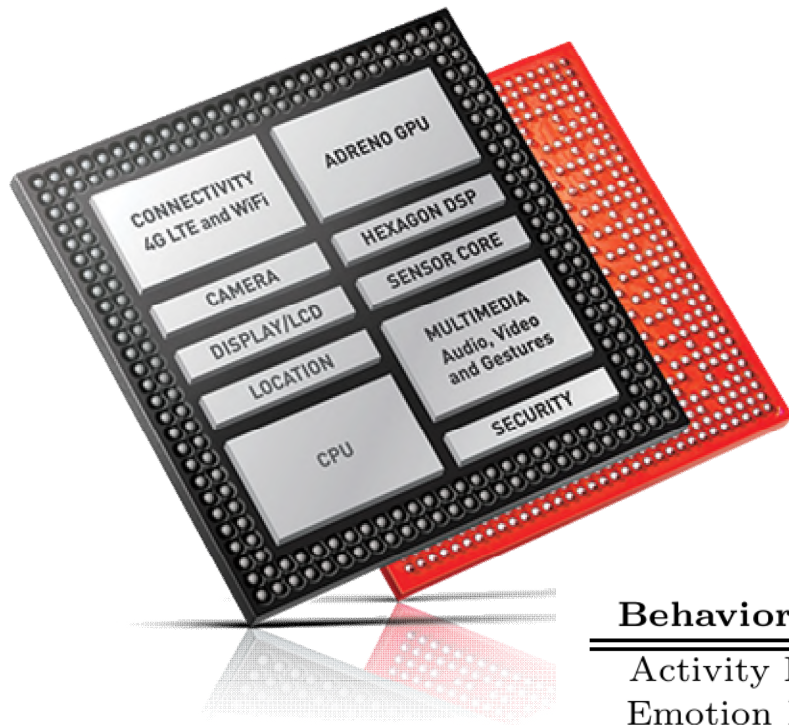
- Deep learning?
- Augmented reality?
- Virtual Reality?

# Processors in the Smartphone Market



# Platform and Datasets

- Snapdragon 800 SoC



## Behavioral Context

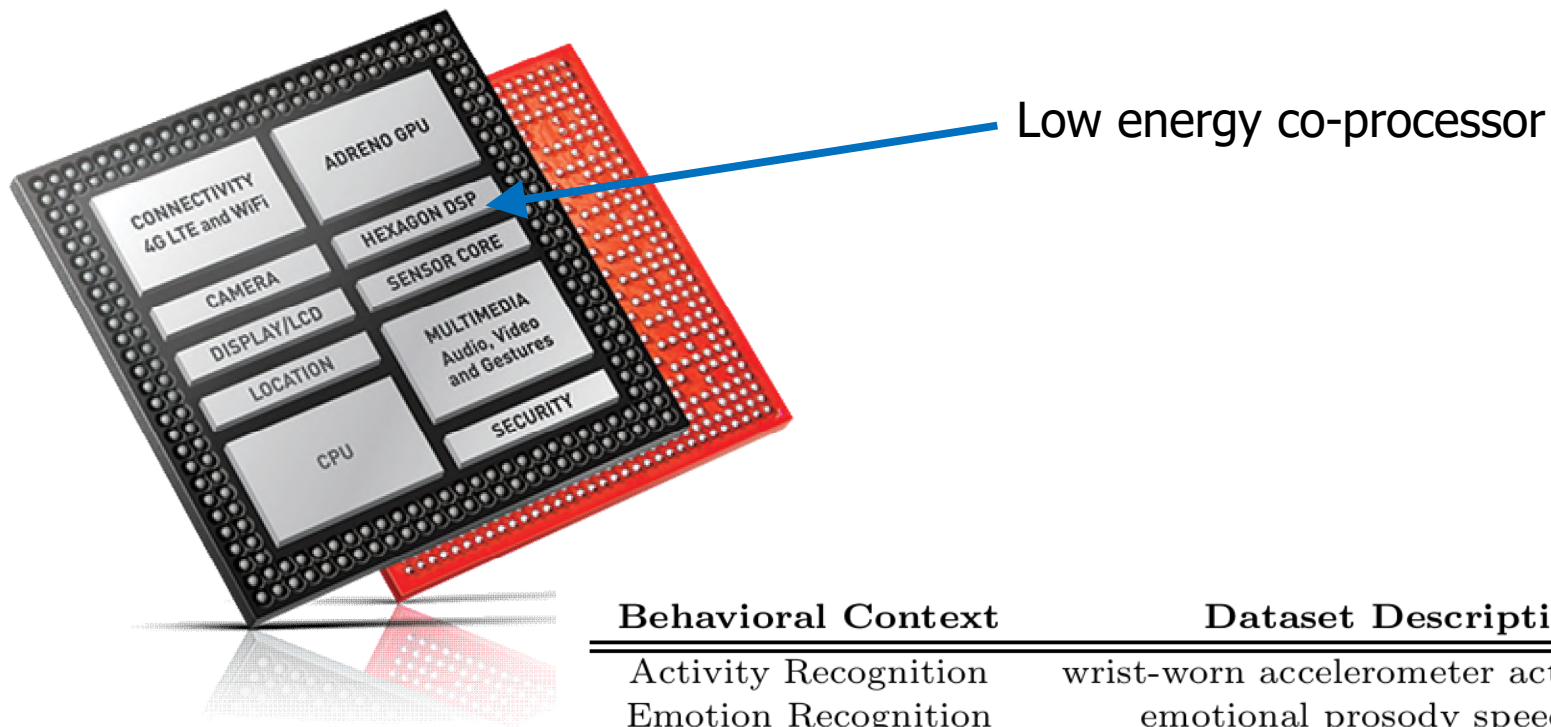
Activity Recognition  
Emotion Recognition  
Speaker Identification

## Dataset Description

wrist-worn accelerometer activities [10]  
emotional prosody speech [19]  
10-minute speech from 23 speakers each

# Platform and Datasets

- Snapdragon 800 SoC



<u>Behavioral Context</u>	<u>Dataset Description</u>
Activity Recognition	wrist-worn accelerometer activities [10]
Emotion Recognition	emotional prosody speech [19]
Speaker Identification	10-minute speech from 23 speakers each

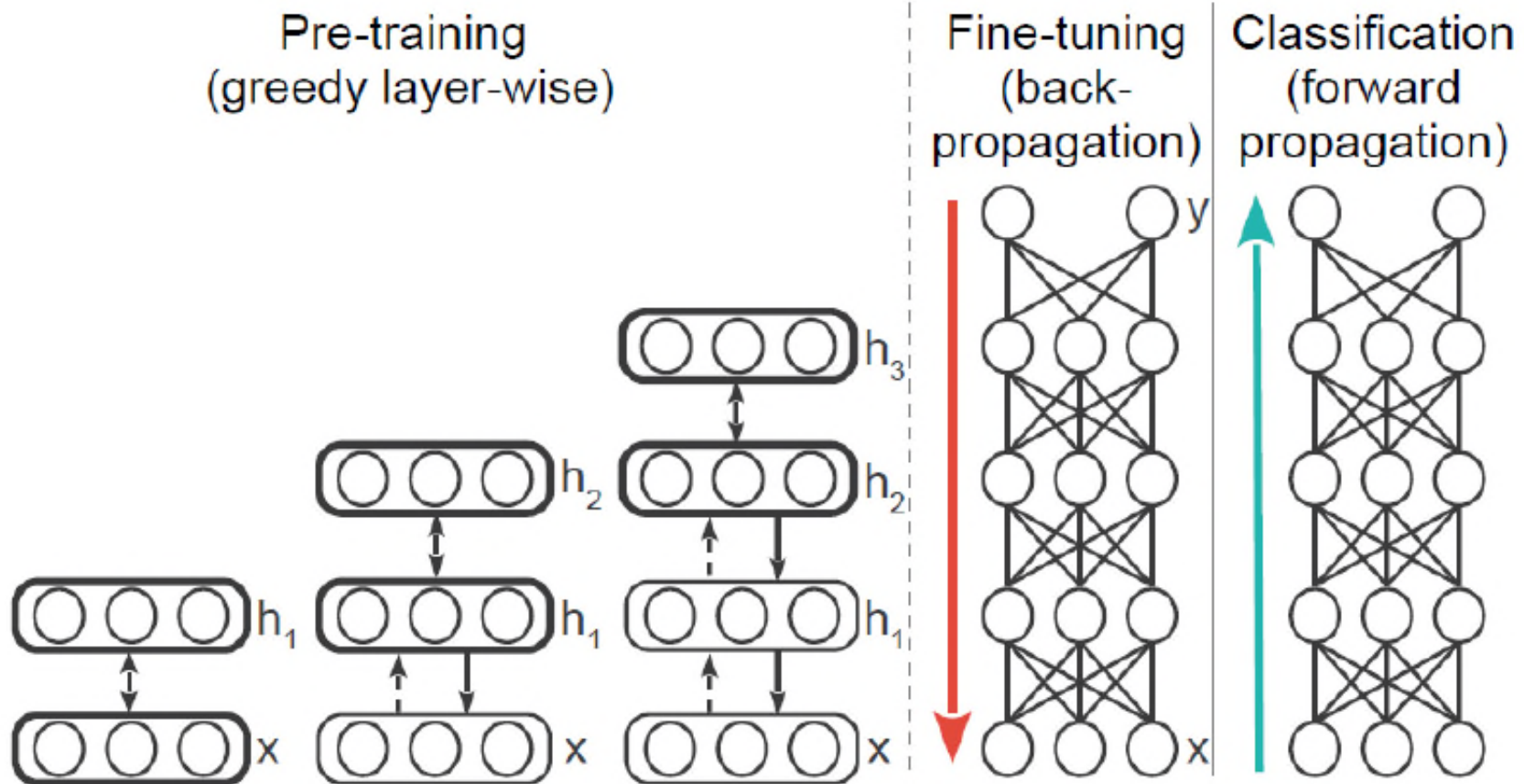


# Question

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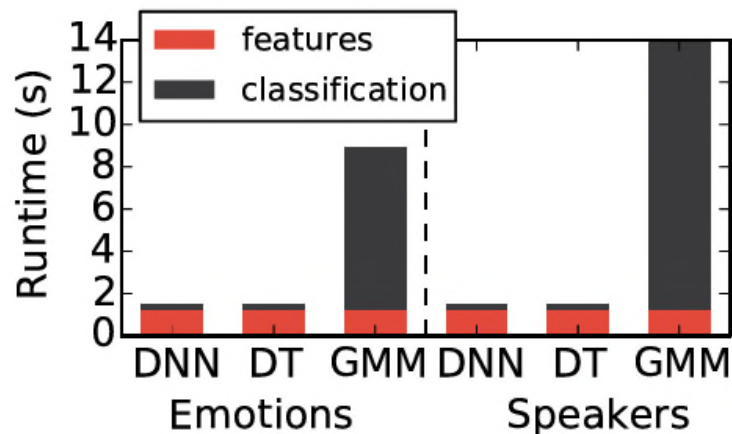
- Can deep-learning-based classification be run on cell phones?

# Deep Learning

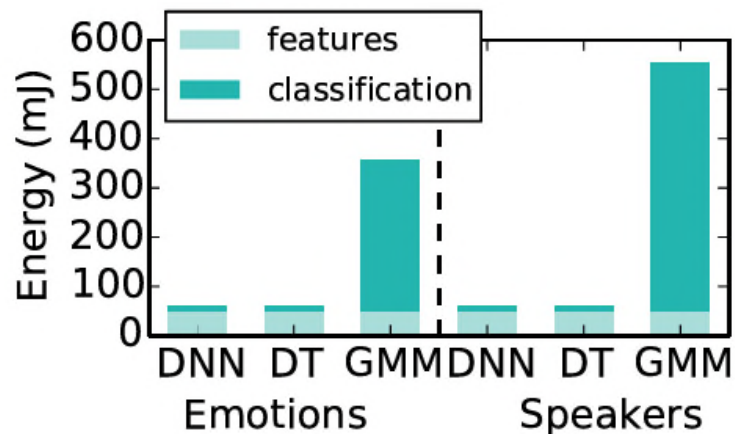


# Approaches: Energy and Latency Comparison

- DNN: Deep learning
- GMM: Gaussian mixture models
- DT: Decision trees



(a) Latency



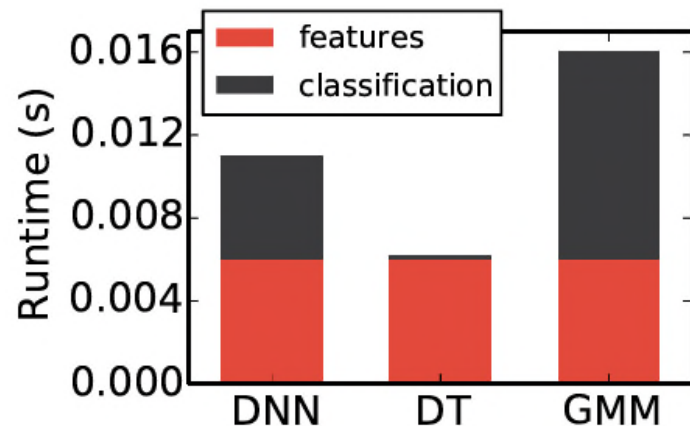
(b) Energy

Using the Microphone

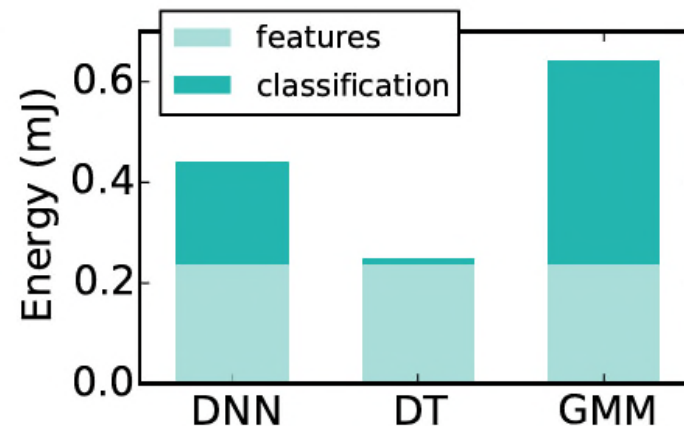


# Approaches: Energy and Latency Comparison

- DNN: Deep learning
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(a) Activity latency

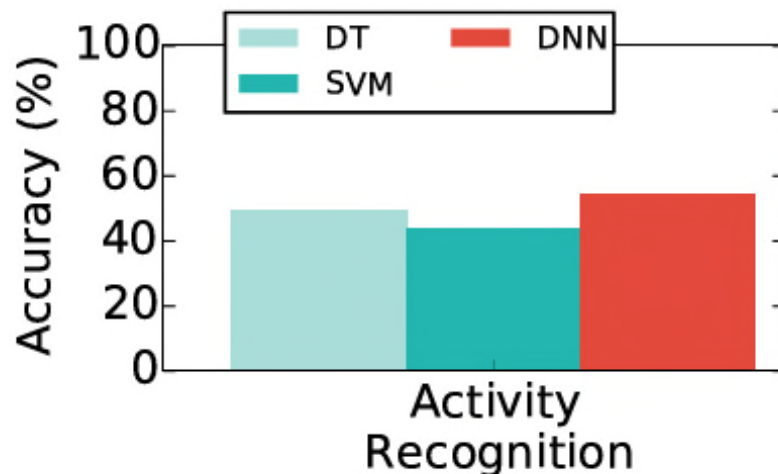


(b) Activity energy

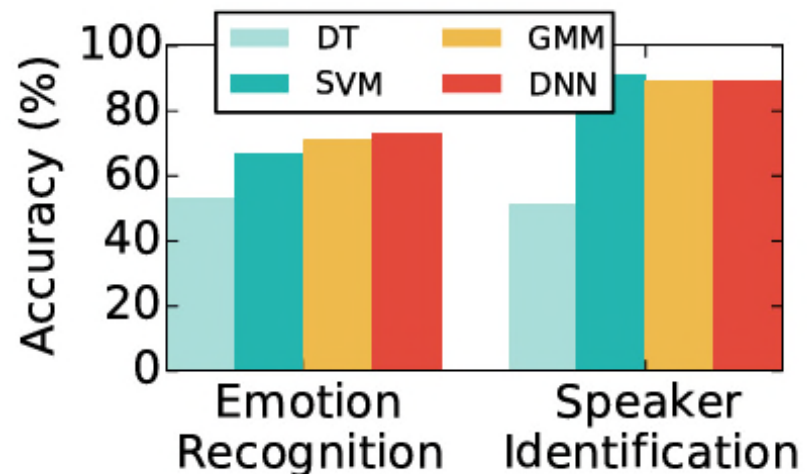
Using the Accelerometer/Gyro

# Approaches: Accuracy Comparison

- DNN: Deep learning
- GMM: Gaussian mixture models
- DT: Decision trees



(a) Activity



(b) Sound

# Can Augmented Reality Applications Run on Cell Phones?

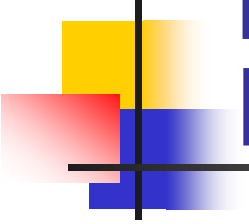


# Can Augmented Reality

## Applications Run on Cell Phones?

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- Prediction: Augmented reality market will grow from \$500 million in 2016 to \$5.7 billion in 2021
- Majority of revenue from subscription and license fee model
- Dominated by Tablets and Smart Glasses



Is the problem addressed in this paper already solved (e.g., see PokemonGo)?

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- Why? Why not?
- Same? Different? How different?

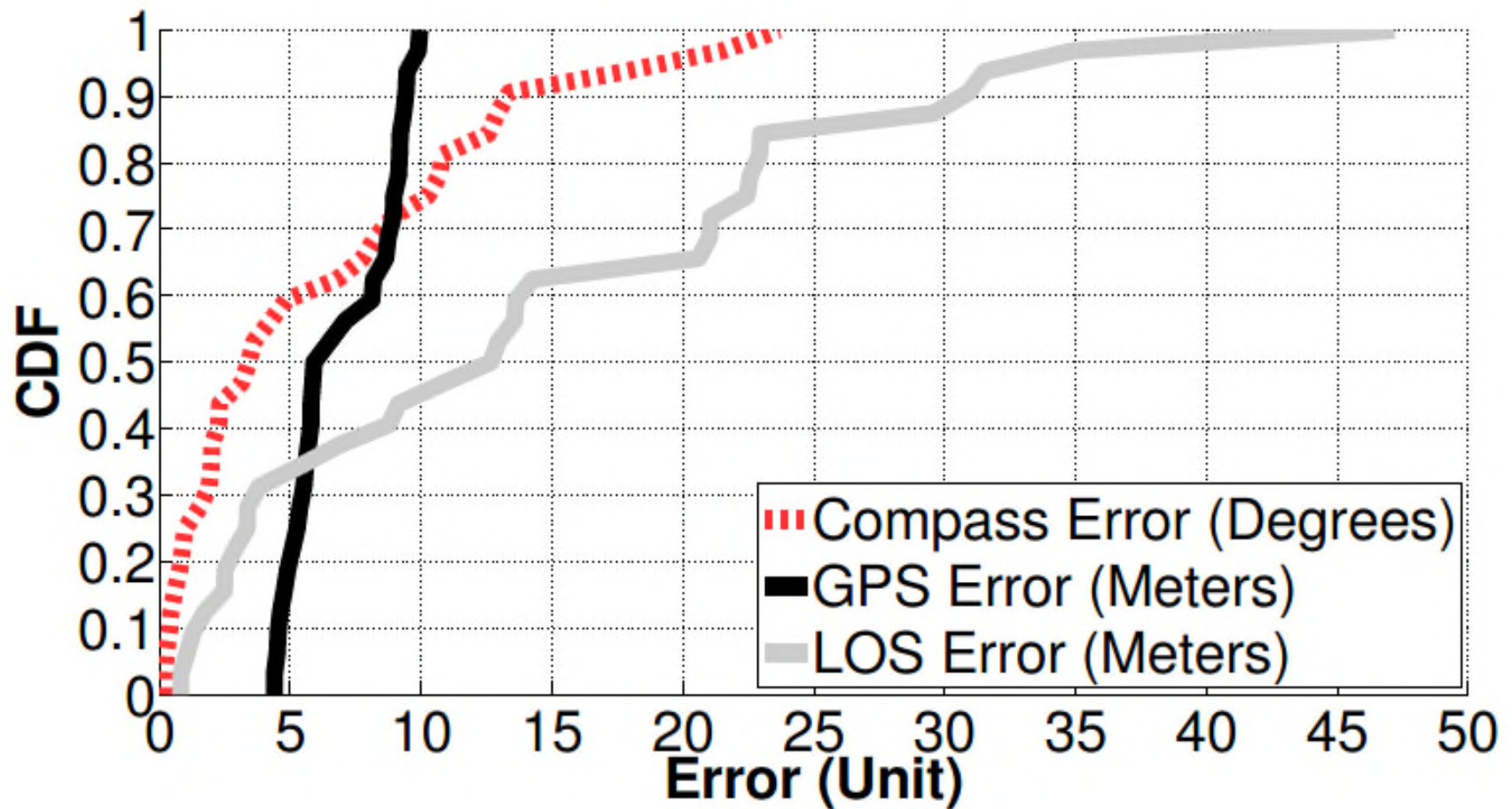


# Using the Camera: Augmented Reality

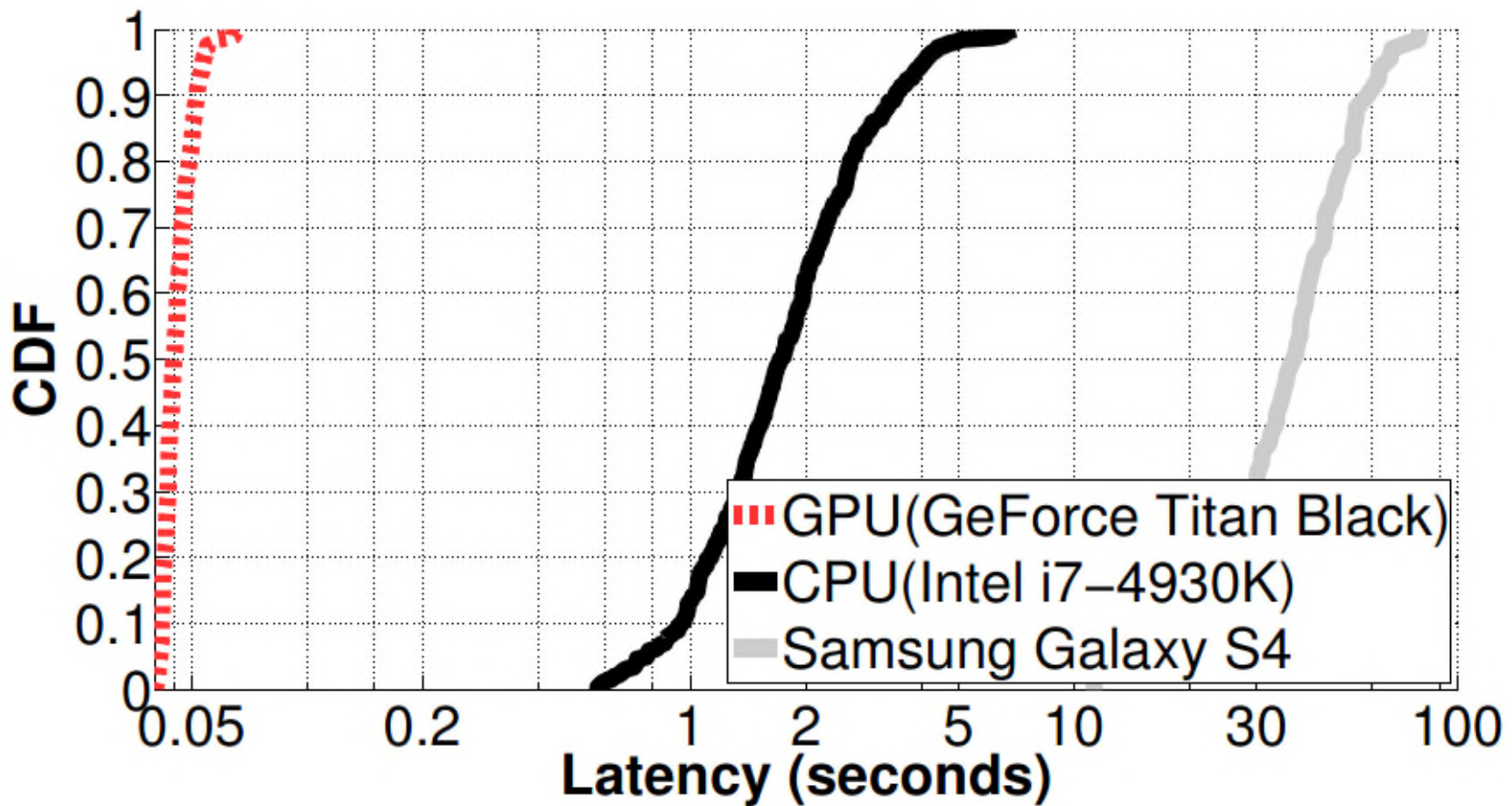
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- Vision:
  - Annotate everyday objects using mobile phones.
  - Allow others to retrieve annotations previously associated with objects

# Sensor-based: Localization



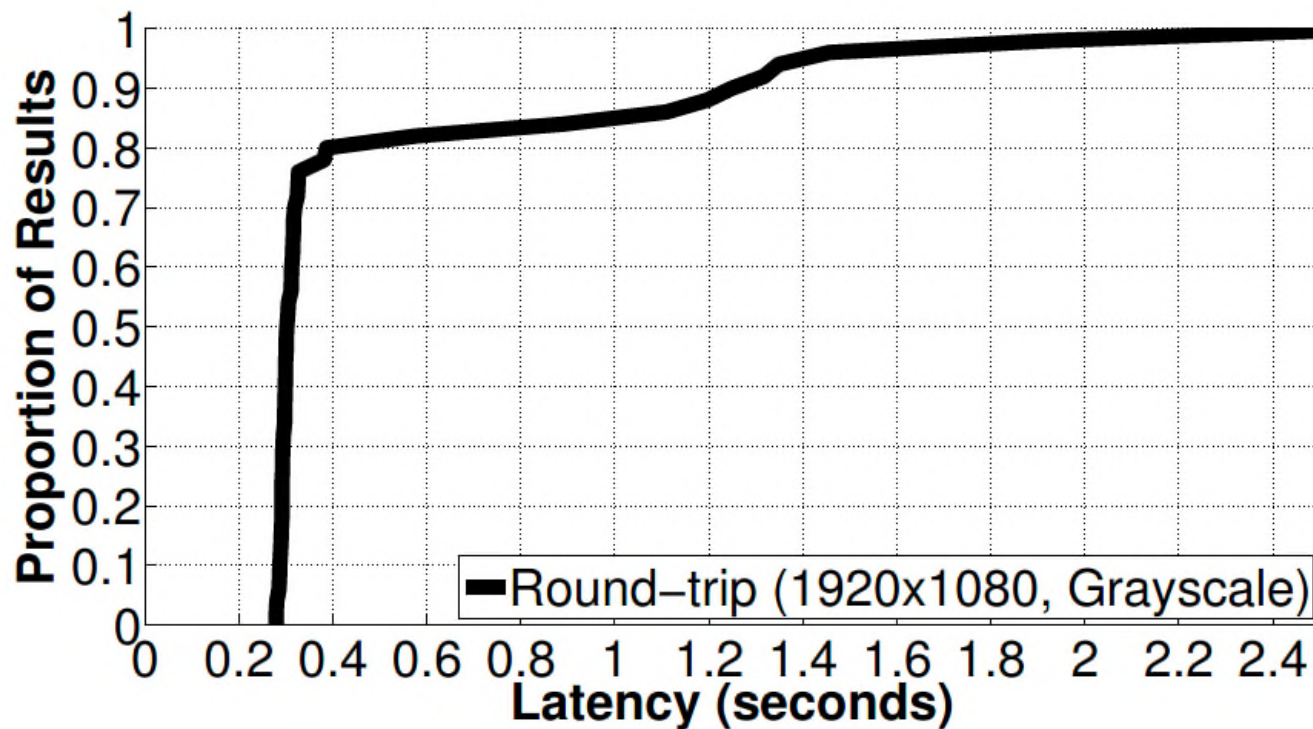
# Vision-based: Processing Latency





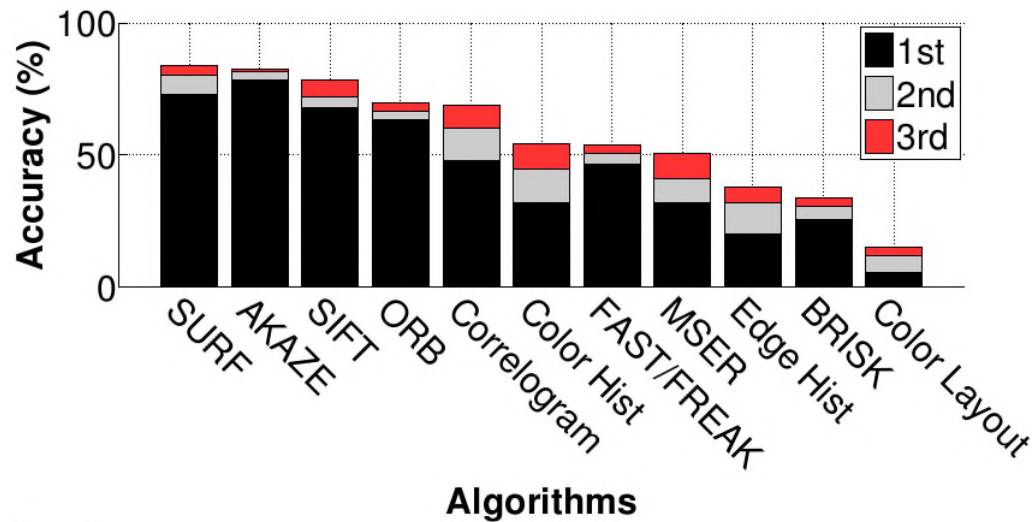
# Vision-based: Upload Latency

- Latency uploading a 1920\*1080 frame

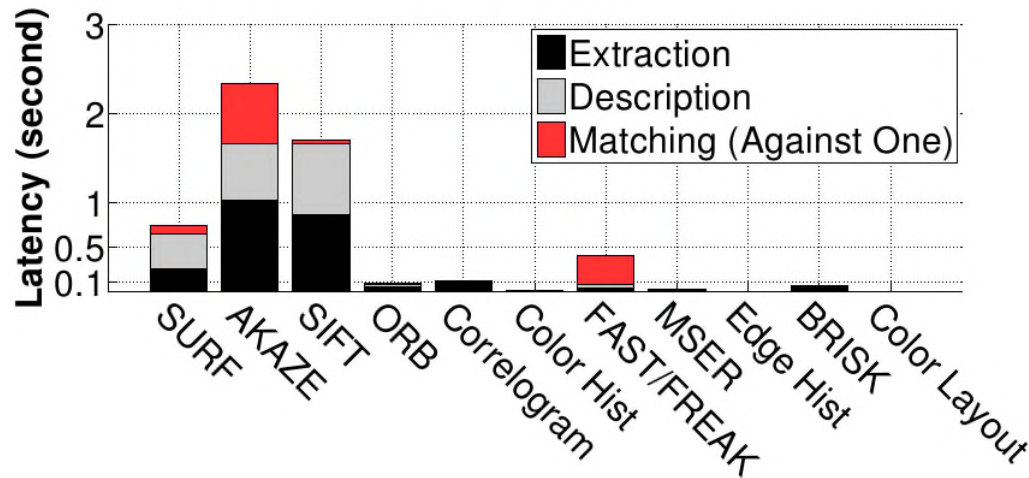


# Vision-based: Accuracy and Latency of Object Matching

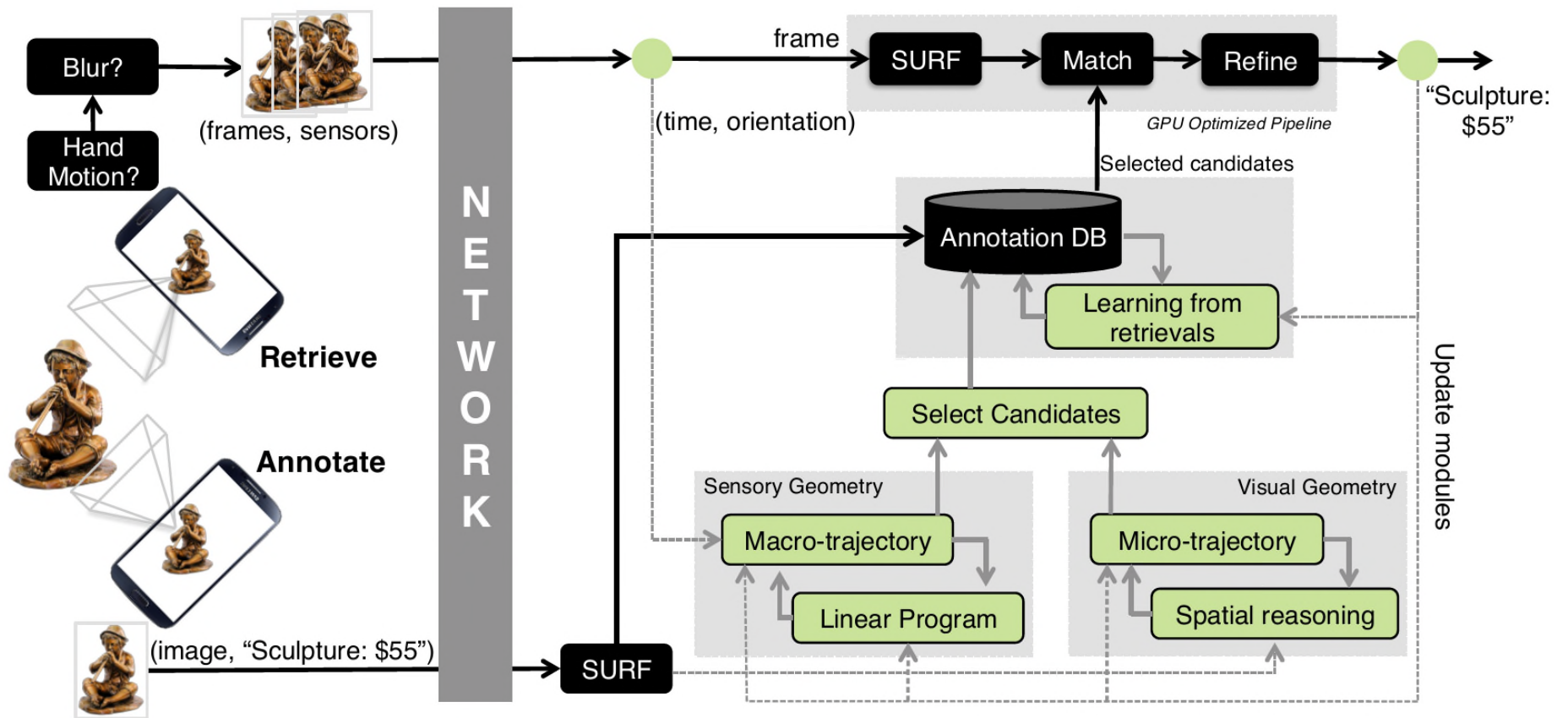
(Against 100 Objects)



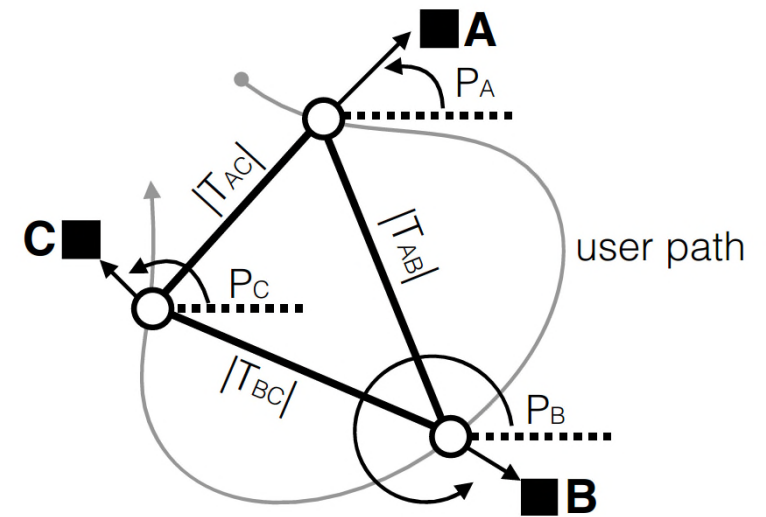
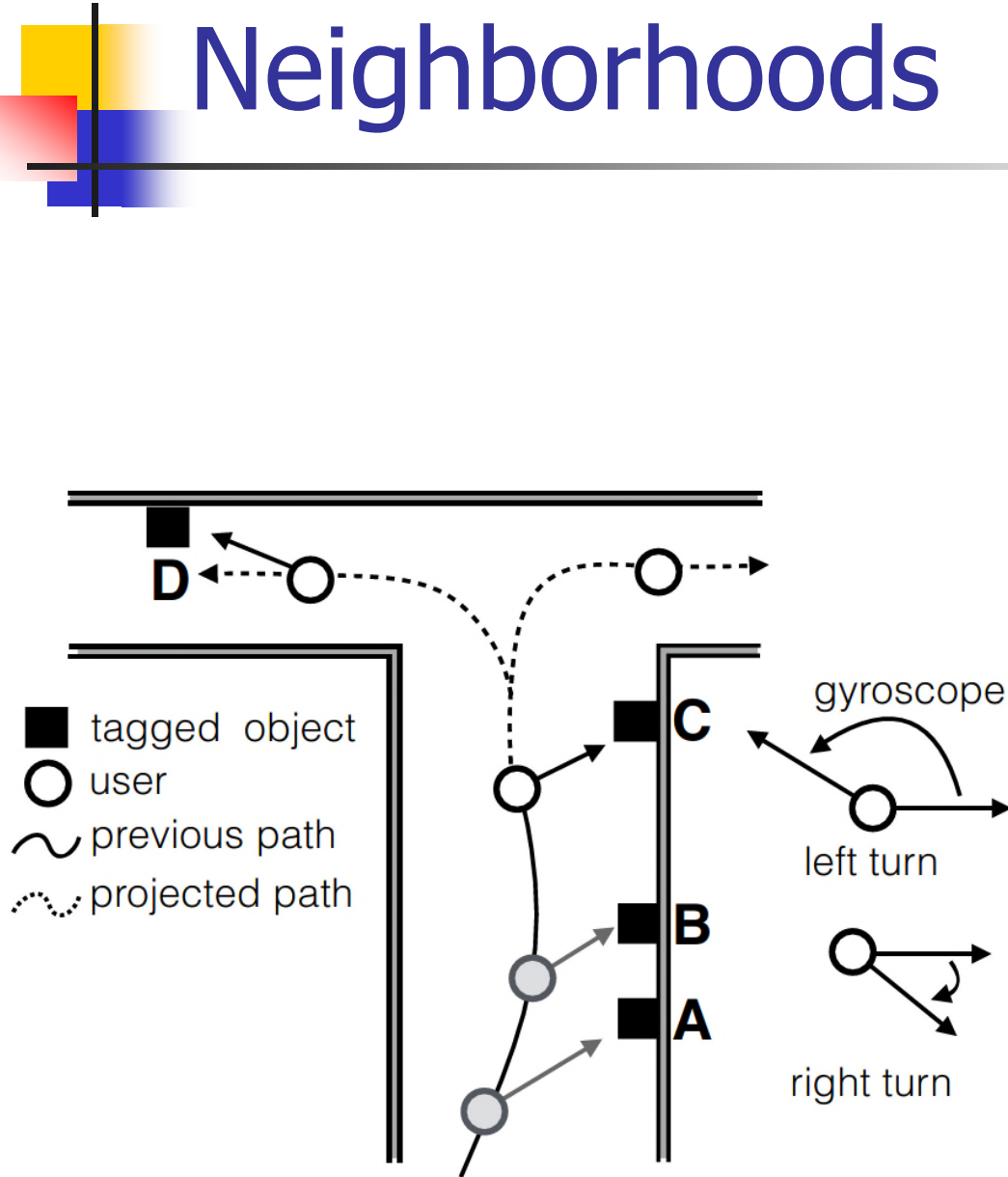
- Must minimize number of objects matched against



# OverLay System



# Main Idea: Geometric Neighborhoods



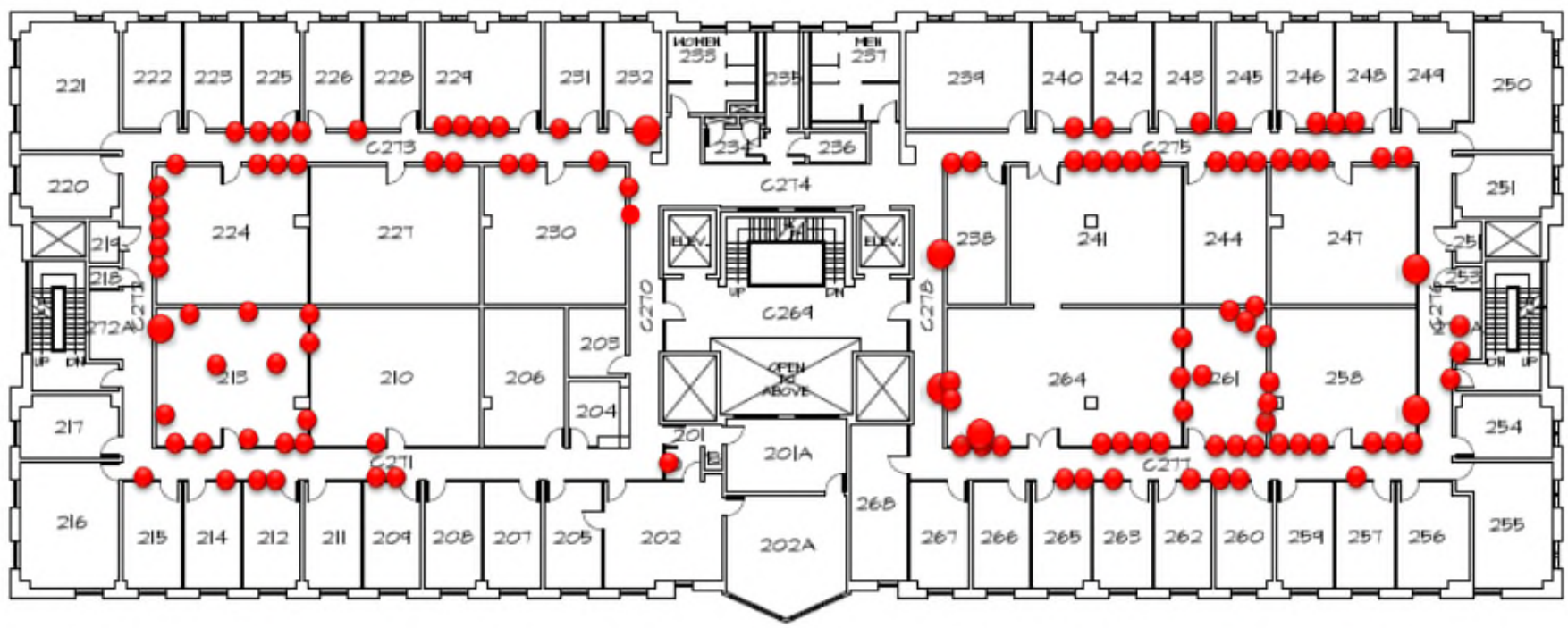


# Question: How many images to keep of each object?

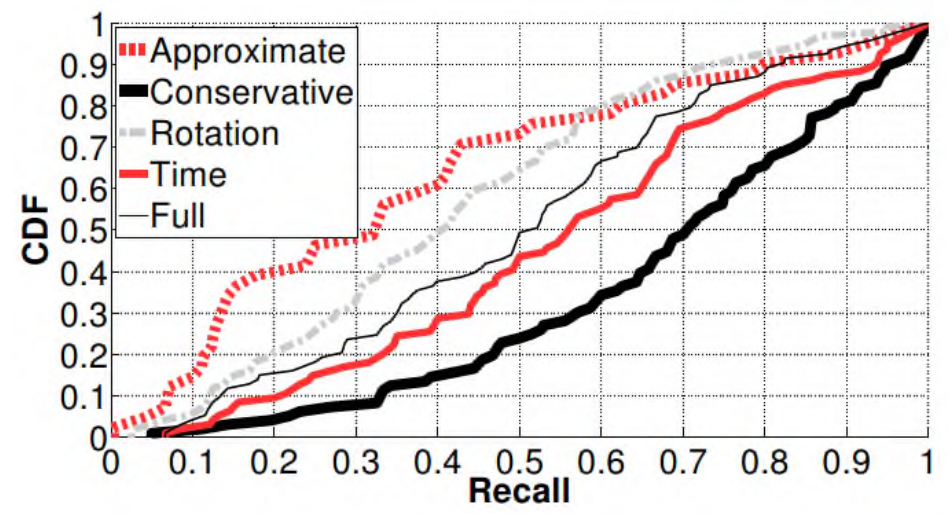
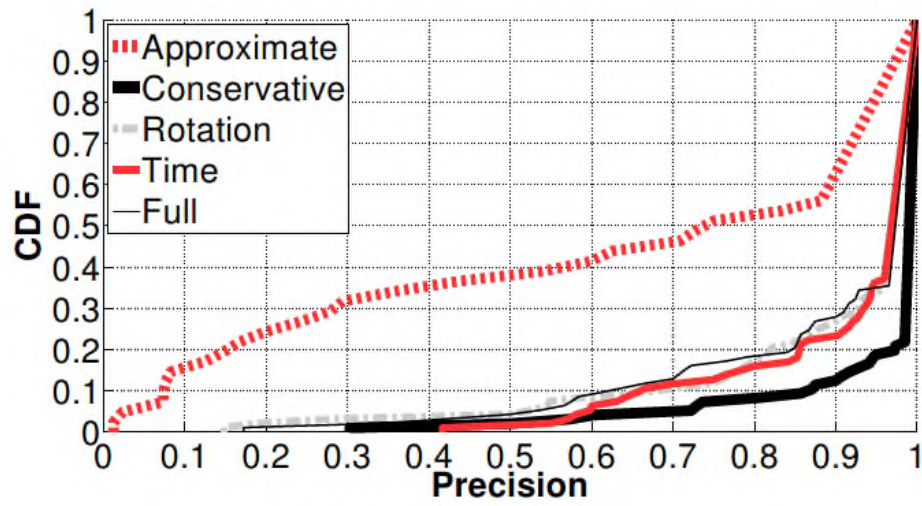
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- Too few → accuracy problems
- Too many → latency problems
- What is the best way to reduce number of views without reducing accuracy?

# Evaluation

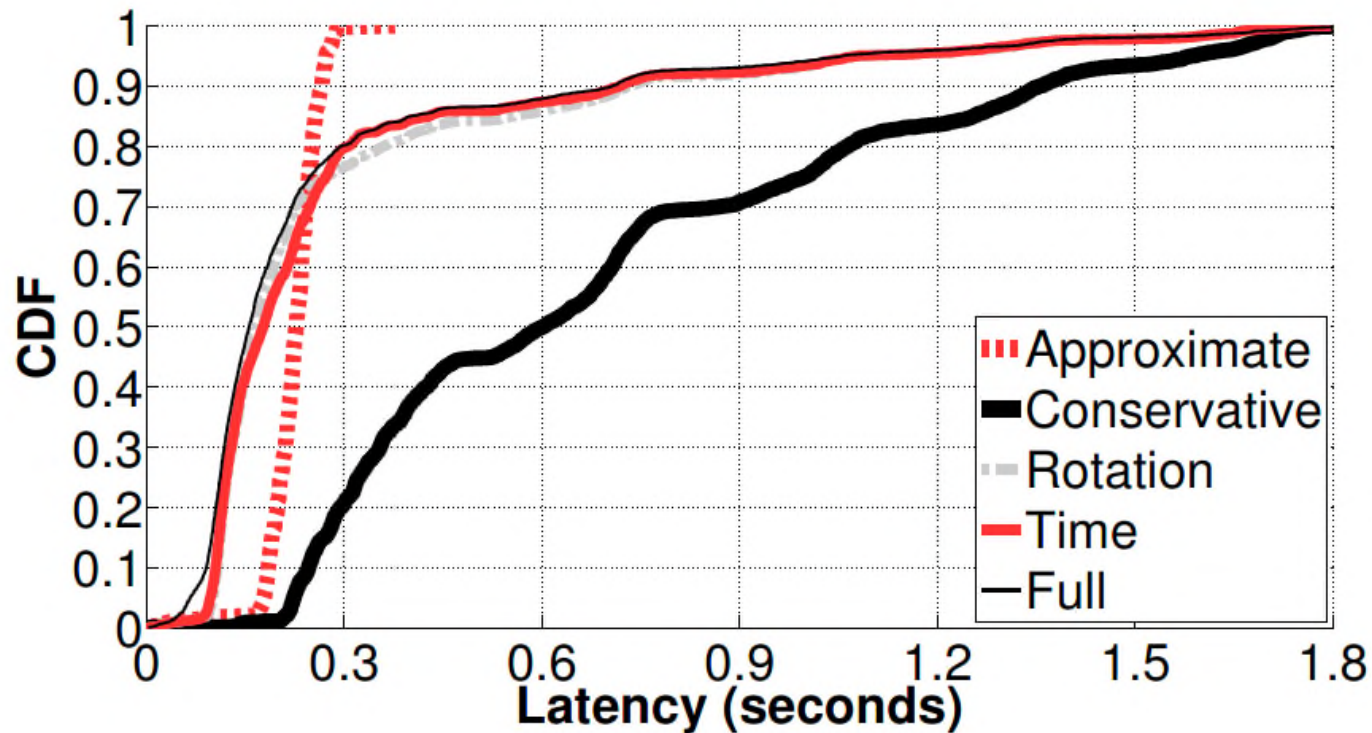


# Evaluation



# Evaluation

- Optimizations reduce the amount of matching that needs to happen





# Ultra Power Eye-Gaze Tracking

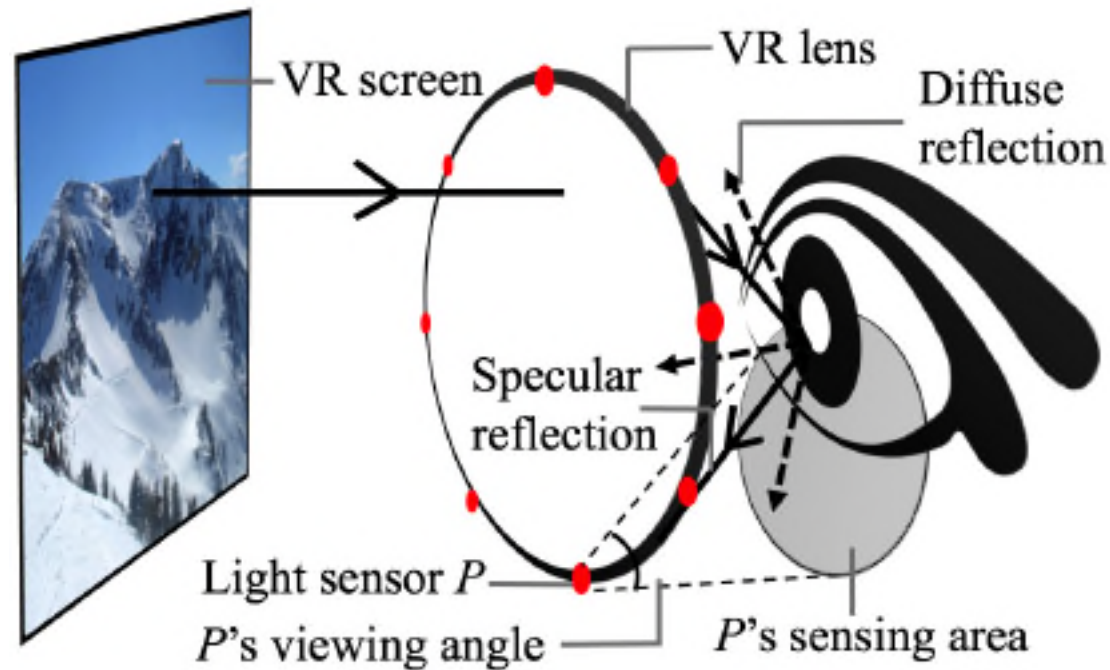


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- What was the main idea in reducing power of eye-gaze trackers?
  - Do (what) instead of (what)?
- What main challenges did the authors list in implementing the above low-power gaze-tracking idea?
  - How did they argue that this was a difficult problem?

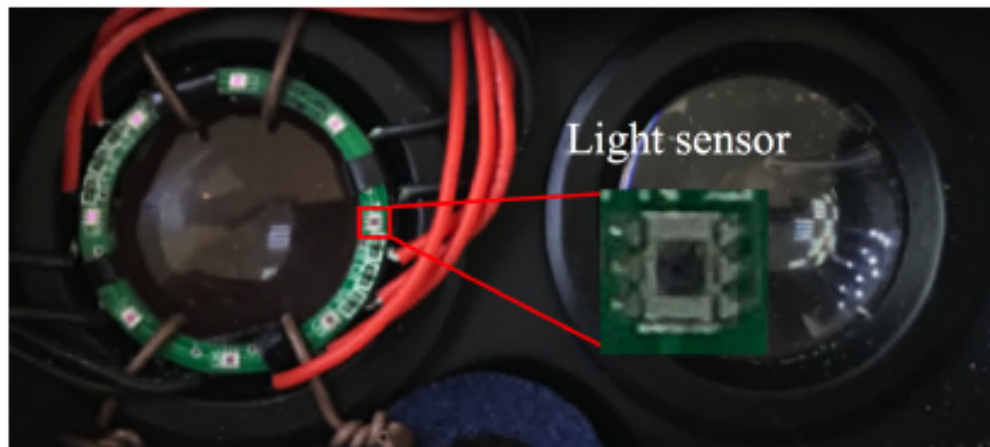
# Ultra Power Eye-Gaze Tracking

- Photo-diodes measure reflected light

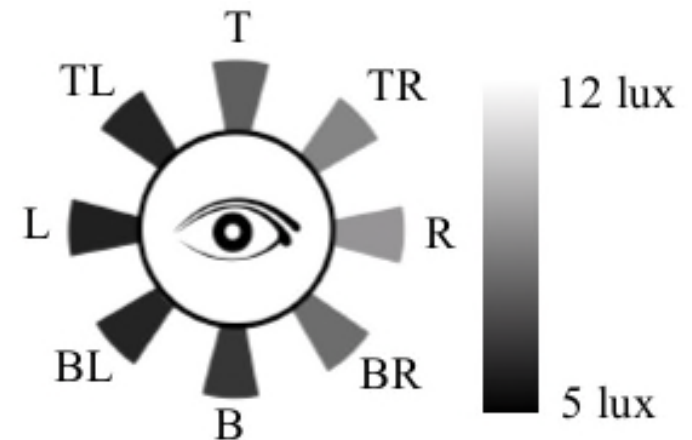


# Ultra Power Eye-Gaze Tracking

- Reflected light is non-uniform and depends on scene



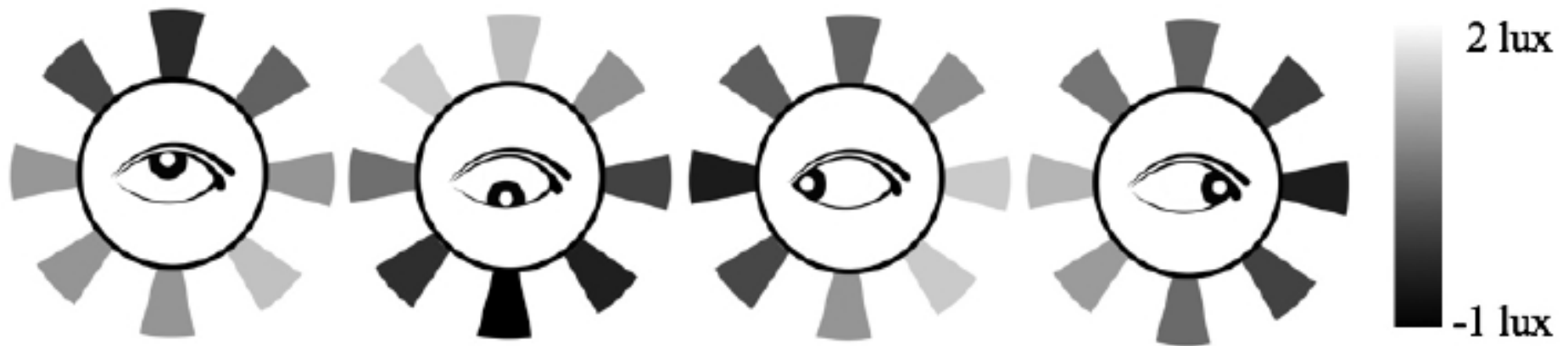
(a) A ring-shaped PCB on a VR lens



(b) Reflected light w/ center pupil

# Ultra Power Eye-Gaze Tracking

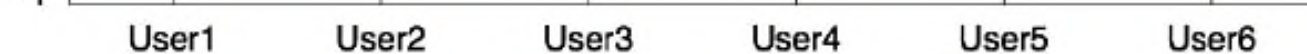
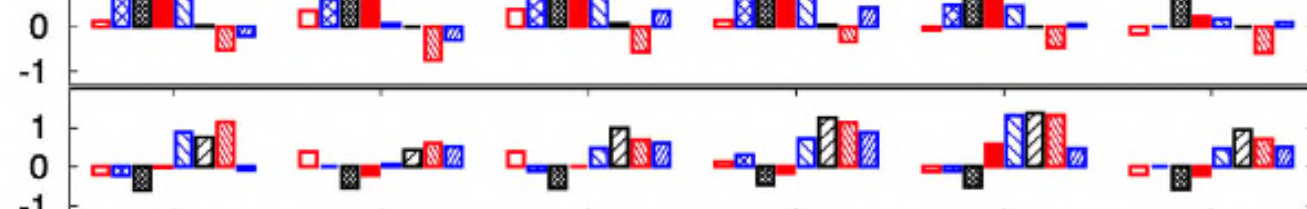
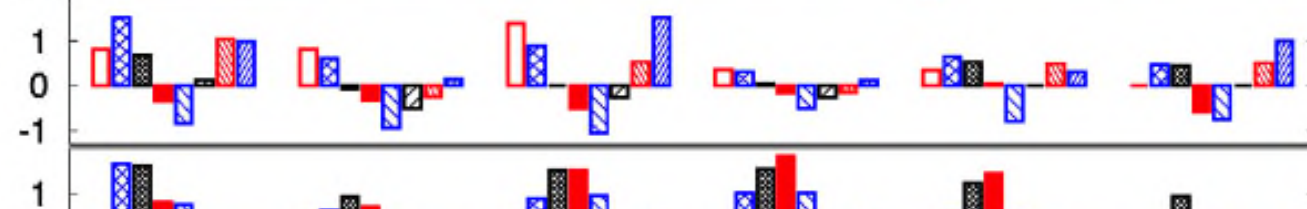
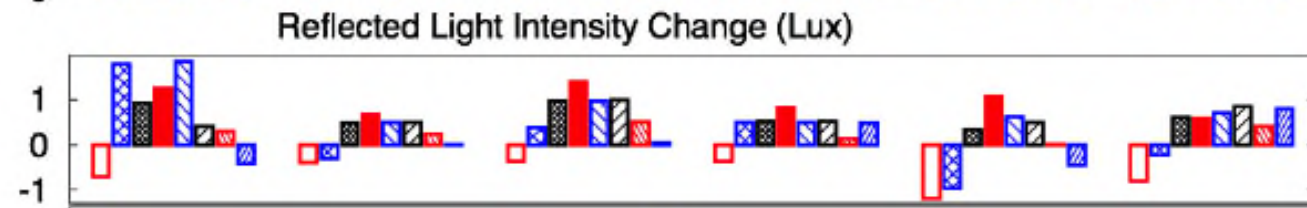
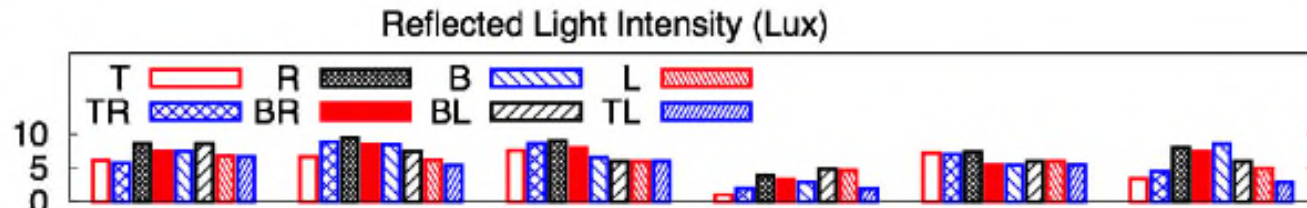
- Reflected light also depends on pupil position (why?)



# Ultra Power Eye-Gaze Tracking

- Reflected light also depends on user

Pupil Position



User1

User2

User3

User4

User5

User6



# General Idea

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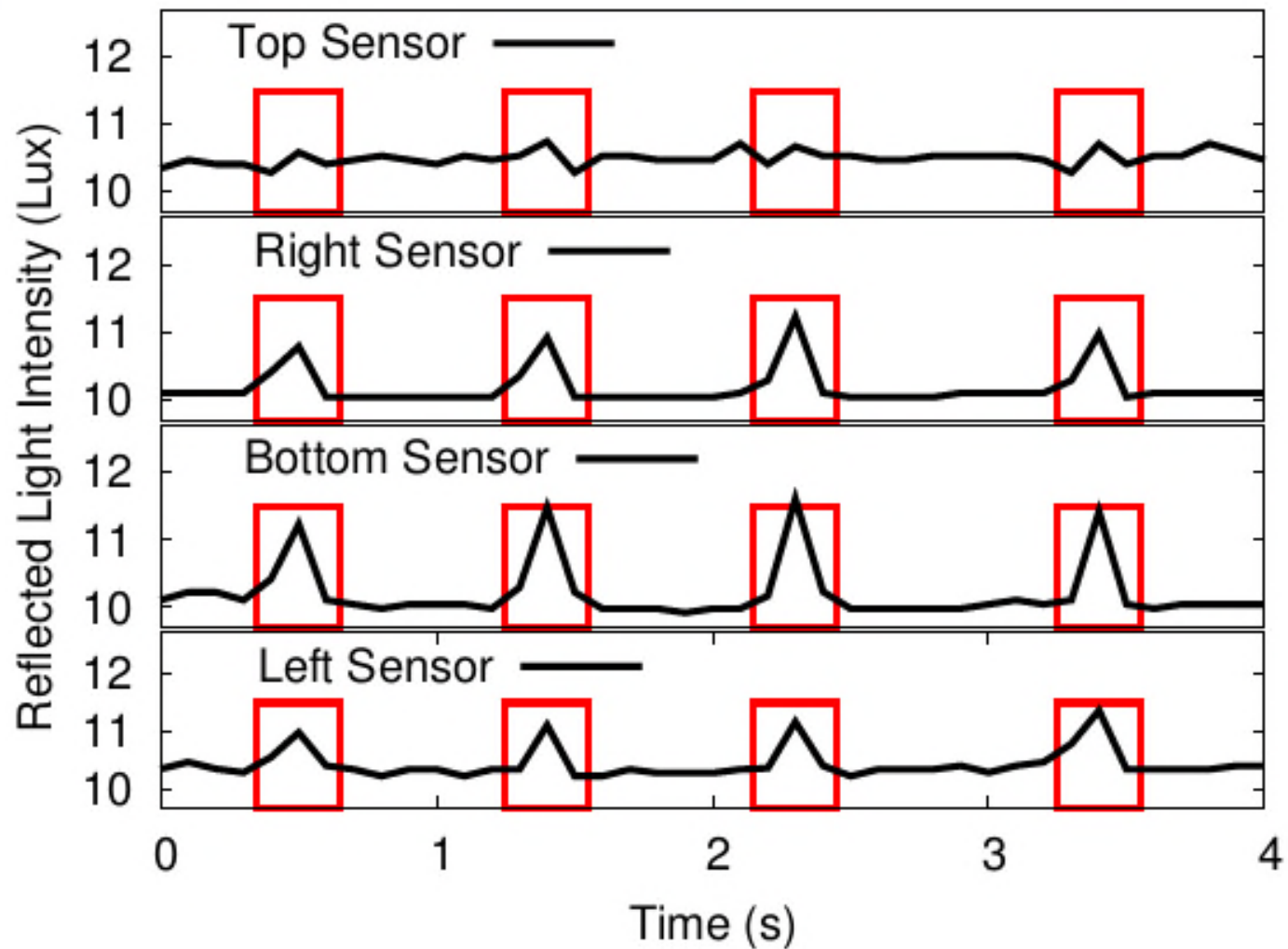
- Understand correlations between front and back facing sensors for different eye positions and use it to train a boosted decision tree classifier to estimate eye position vector

# Examples

- Correlations with eye staring straight ahead (pupil in the middle)

		Front sensor (facing display)							
		T	TR	R	BR	B	BL	L	TL
Back sensor (facing eye)	T	0.48	0.75	0.87	0.87	0.96	0.81	0.59	0.54
	TR	0.69	0.55	0.76	0.76	0.79	0.91	0.88	0.78
	R	0.66	0.64	0.55	0.67	0.79	0.83	0.93	0.89
	BR	0.86	0.79	0.62	0.51	0.64	0.74	0.76	0.84
	B	0.97	0.83	0.68	0.55	0.50	0.51	0.78	0.79
	BL	0.84	0.90	0.89	0.86	0.85	0.61	0.60	0.58
	L	0.80	0.91	0.92	0.78	0.65	0.49	0.52	0.58
	TL	0.66	0.88	0.89	0.91	0.86	0.78	0.52	0.47

# Blink Detection





# Evaluation: Tracking Error

- Smaller error when training and testing with the same user

