



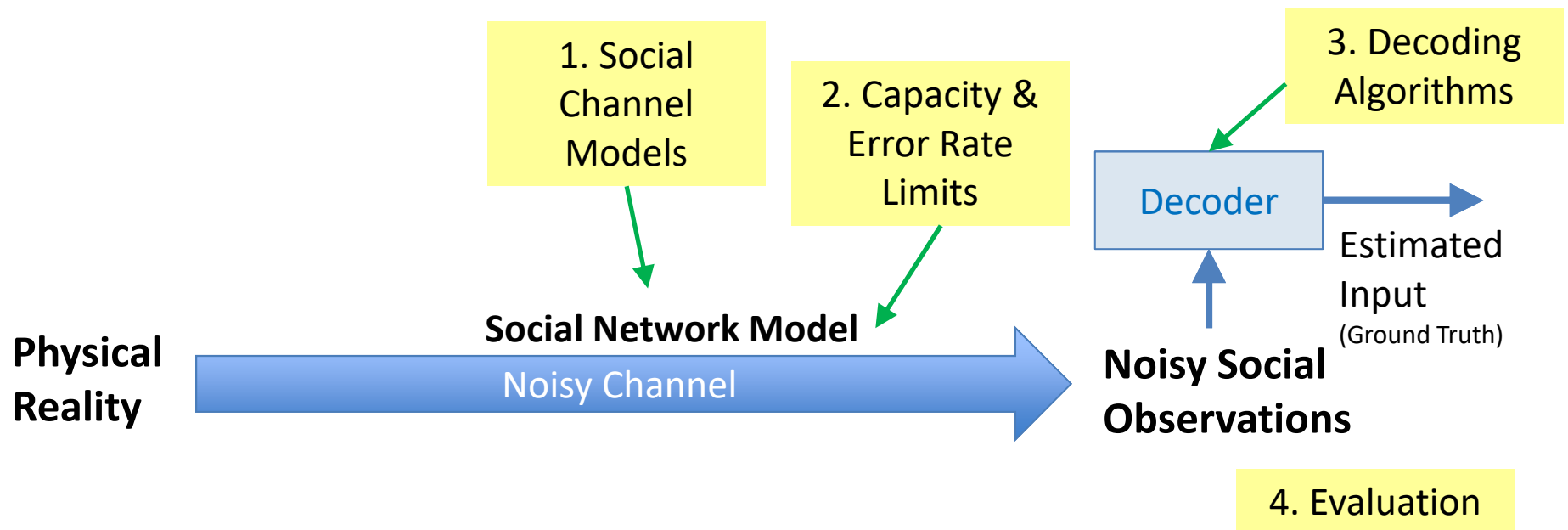
Veracity Analysis

Fact-finding Research Motivation and Approach



Goal: Develop a mathematical foundation for “*social sensing*” – the exploitation of noisy social network data to attain reliable situation awareness.

1. Construct *models of “social channels”*
2. Establish the *fundamental feasibility/accuracy limits* on truth recovery from noisy social network data
3. Construct social-influence-aware fact-finding *algorithms* that approach these limits

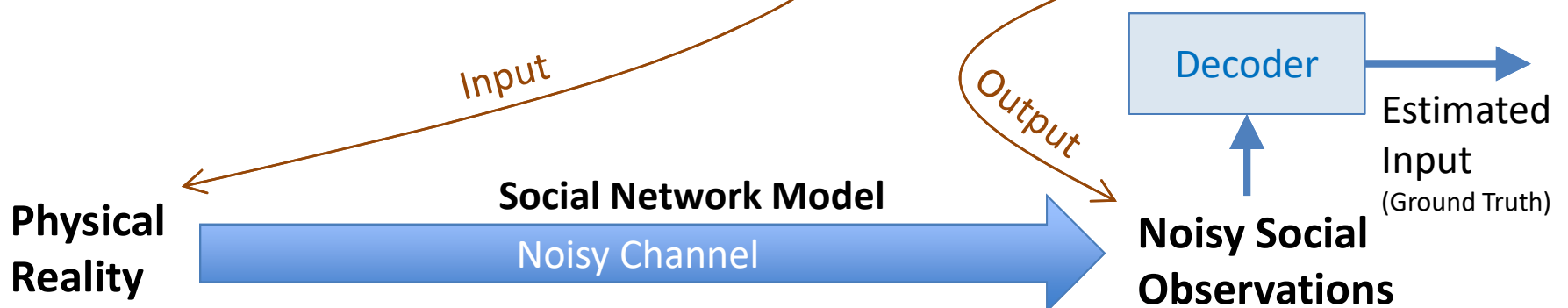
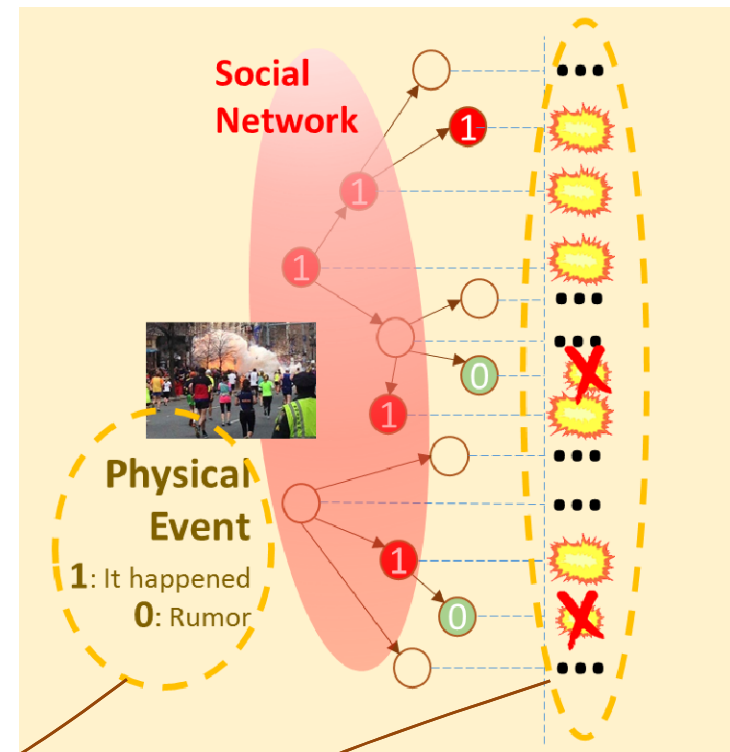


Motivation and Approach

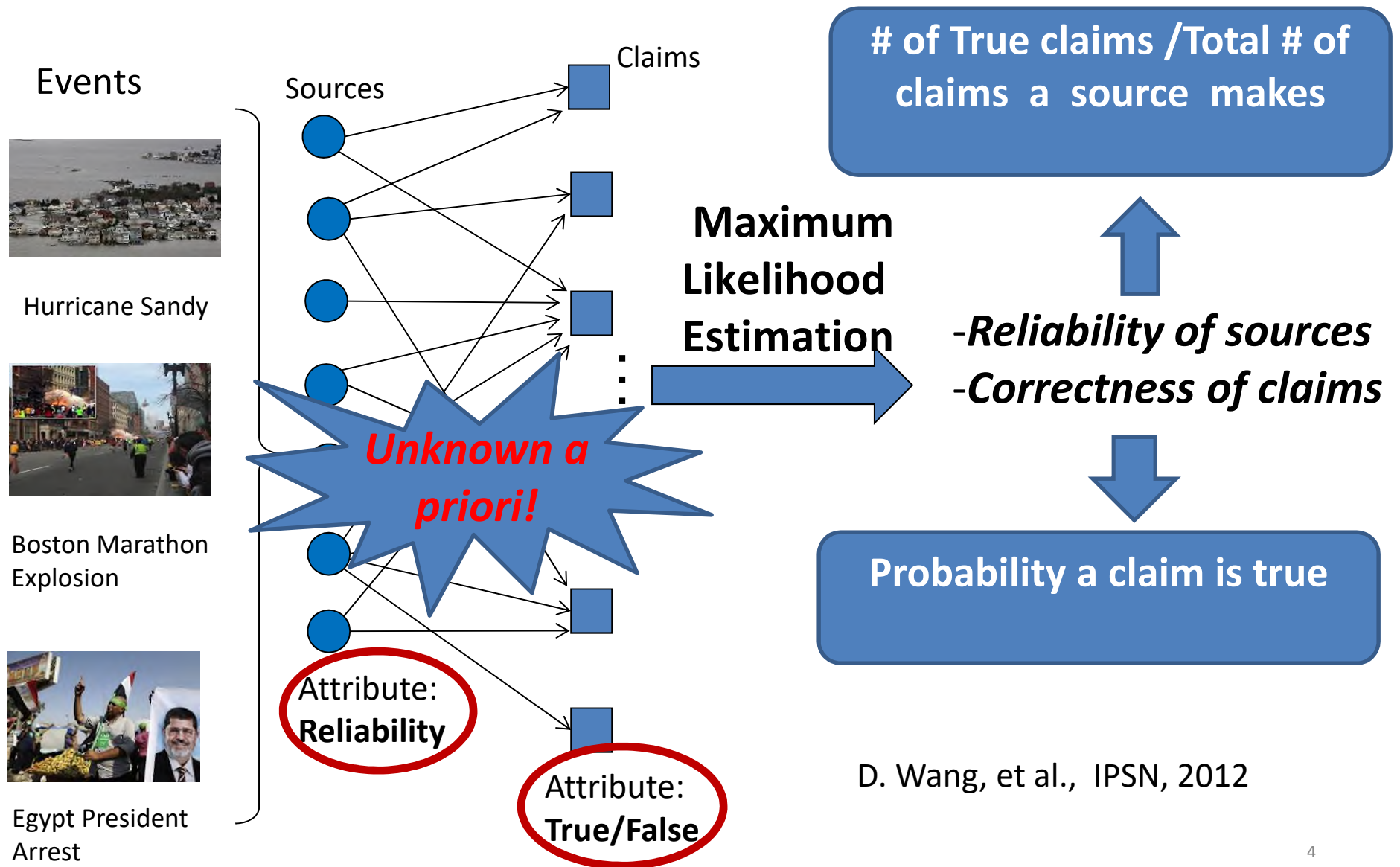


Approach: Model the social network as a noisy channel that transforms “ground truth” into noisy observations

- Use information-theoretic results to understand its fundamental performance limits.
- Use estimation theory to build optimal fact-finders (“channel decoders” that approach these limits)



Maximum Likelihood Estimation



D. Wang, et al., IPSN, 2012

Uncertain Data Provenance



Events



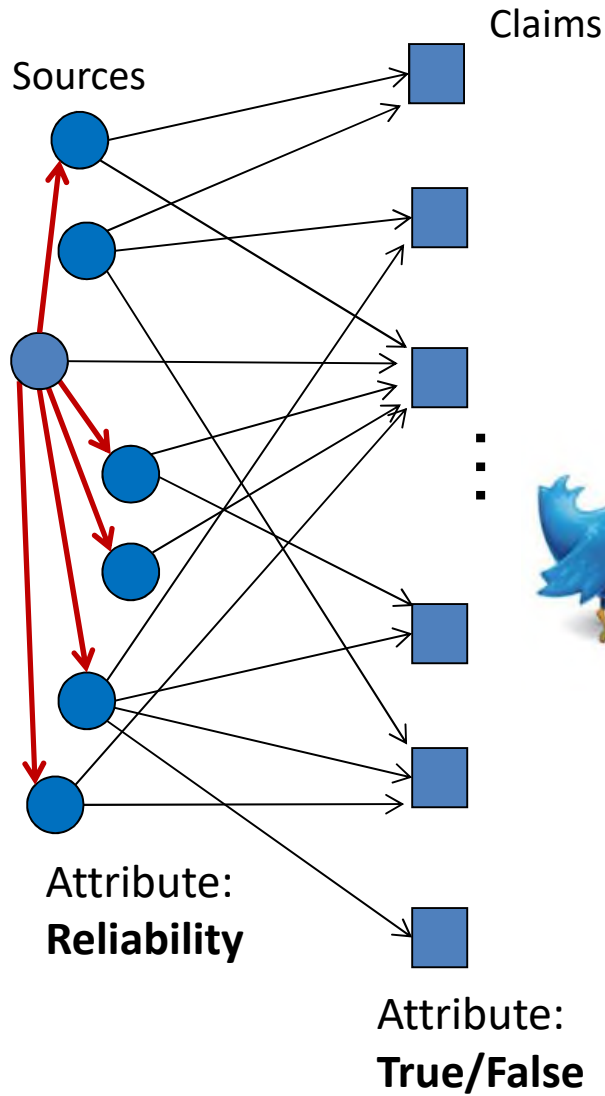
Hurricane Sandy



Boston Marathon
Explosion



Egypt President
Arrest



Sources are not independent!
Consider the social network and source forwarding behaviors



Formulate the Likelihood Function

Events



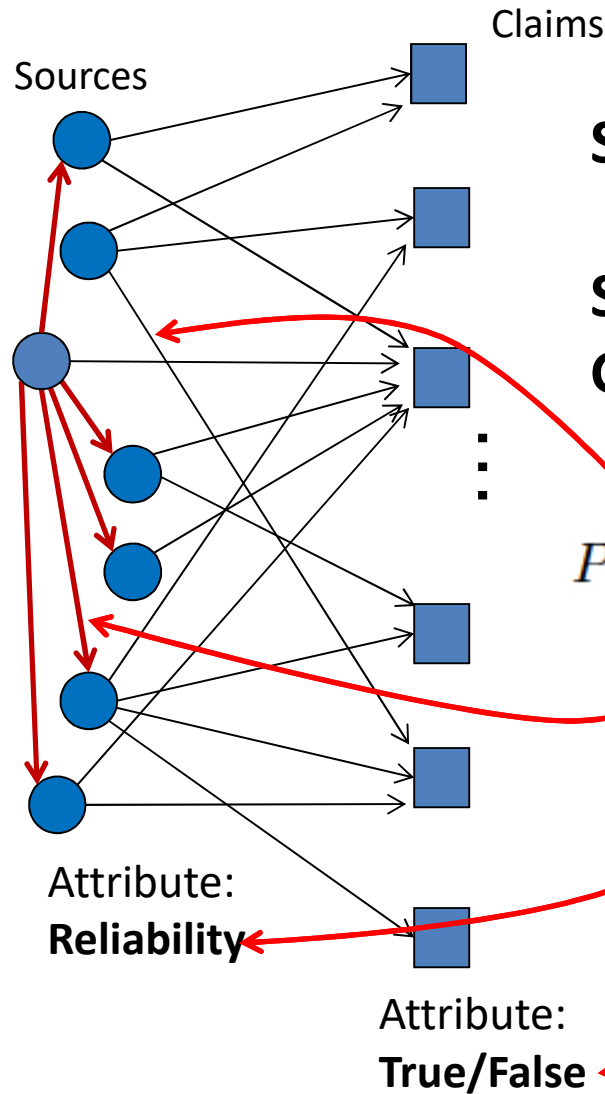
Hurricane Sandy



Boston Marathon
Explosion



Egypt President
Arrest

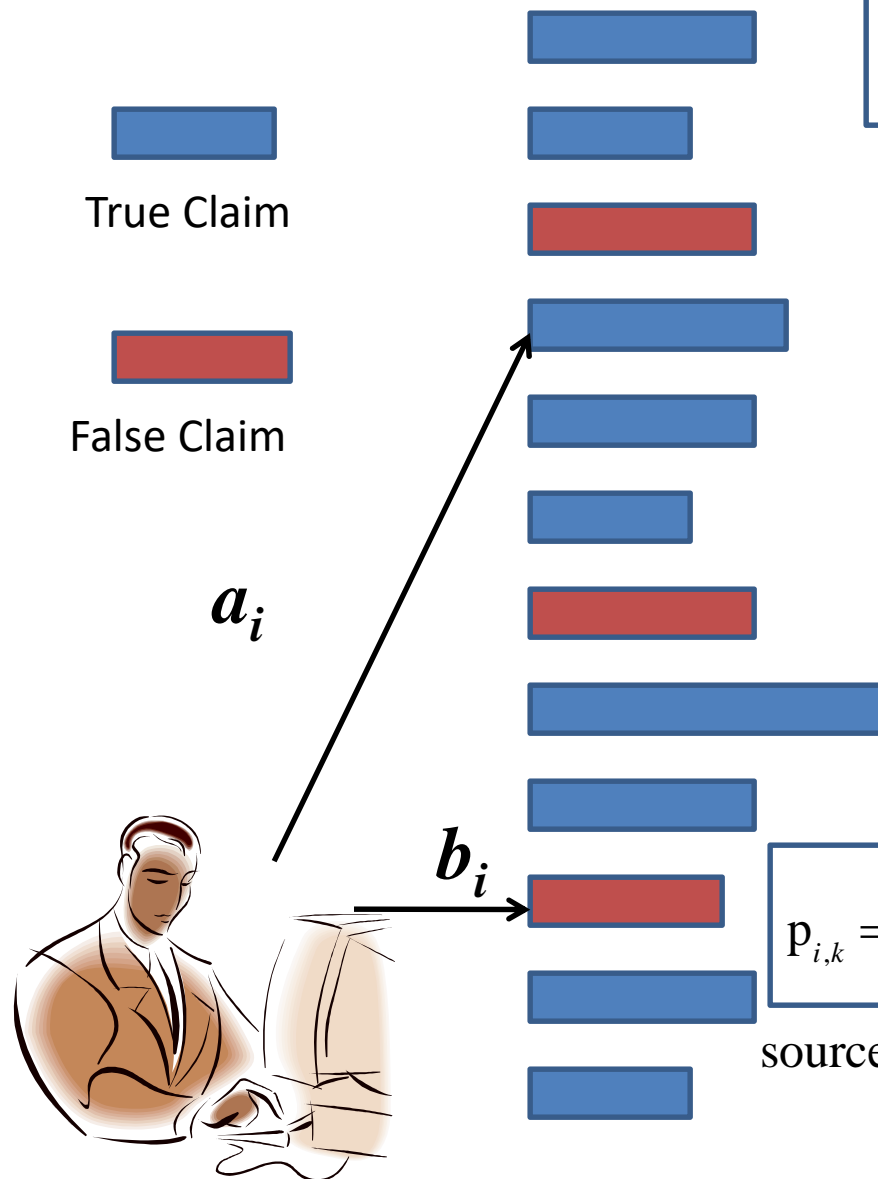


SC: Source Claim Graph

**SD: Social Dissemination
Graph**

$$P(SC|SD, \theta) = \sum_z P(SC, z|SD, \theta)$$

Basis Definition



$$a_i = P(S_i C_j | C_j = true)$$

Using Bayesian Theorem: $a_i = \frac{t_i \times s_i}{d}$

where d is the overall prior that a randomly chosen claim is true

$$b_i = P(S_i C_j | C_j = false)$$

Using Bayesian Theorem: $b_i = \frac{(1-t_i) \times s_i}{1-d}$

where d is the overall prior that a randomly chosen claim is true

$$p_{i,k} = \frac{\text{number of time } S_i \text{ and } S_k \text{ make the same claim}}{\text{number of claims made by } S_k}$$

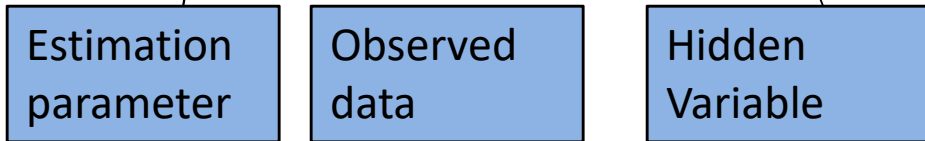
source S_k is the parent node of source S_i in social network

Expectation Maximization

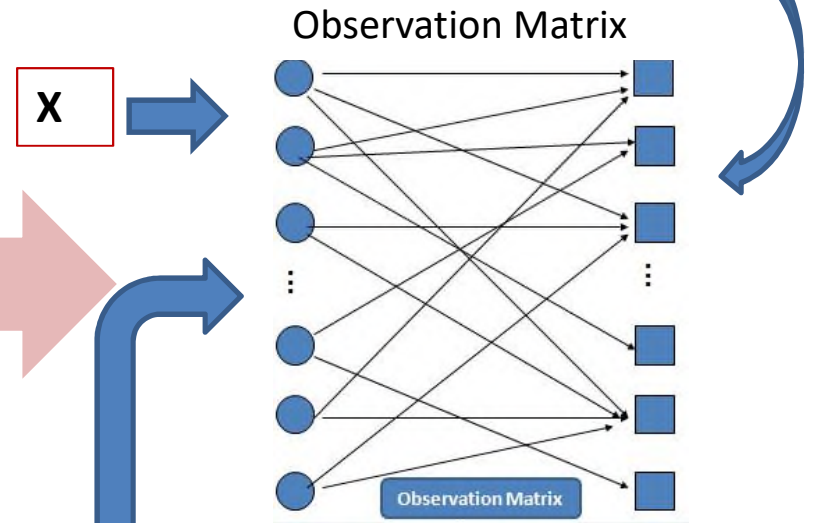


Expectation Maximization

$$L(\theta; X) = p(X|\theta) = \sum_Z p(X, Z|\theta)$$



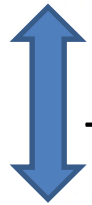
$Z = \{z_1, z_2, \dots, z_N\}$ where $z_j = 1$ when claim C_j is true and 0 otherwise



- Expectation Step (E-step)



$$Q(\theta|\theta^{(t)}) = E_{Z|X, \theta^{(t)}}[\log L(\theta; X, Z)]$$



- Maximization Step (M-step)

$$\theta^{(t+1)} = \underset{\theta}{\operatorname{argmax}} Q(\theta|\theta^{(t)})$$

$$\theta = (a_1, a_2, \dots, a_M; b_1, b_2, \dots, b_M; d)$$

Find MLE of estimation parameter and values of hidden variables



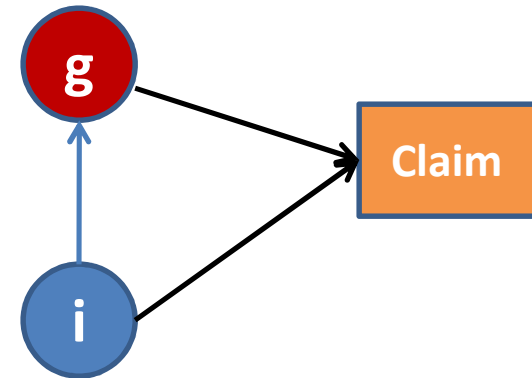
Likelihood Function Incorporating Source Dependency

$$P(SC, z | SD, \theta) = \prod_{j=1}^N P(z_j) \times \left\{ \prod_{g \in M_j} P(S_g C_j | \theta, z_j) \prod_{i \in c_g} P(S_i C_j | S_g C_j) \right\}$$

$$P(z_j) = \begin{cases} d & z_j = 1 \\ (1 - d) & z_j = 0 \end{cases}$$

$$P(S_g C_j | \theta, z_j) = \begin{cases} a_g & z_j = 1, S_g C_j = 1 \\ (1 - a_g) & z_j = 1, S_g C_j = 0 \\ b_g & z_j = 0, S_g C_j = 1 \\ (1 - b_g) & z_j = 0, S_g C_j = 0 \end{cases}$$

$$P(S_i C_j | S_g C_j) = \begin{cases} p_{ig} & S_g C_j = 1, S_i C_j = 1 \\ 1 - p_{ig} & S_g C_j = 1, S_i C_j = 0 \end{cases}$$



Dependent Sources



E-Step

$$\begin{aligned}
 Q(\theta|\theta^{(n)}) = \sum_{j=1}^N & \left\{ Z(n, j) \times \left[\left\{ \sum_{g \in M_j} \left(\log P(S_g C_j | \theta, z_j) \right. \right. \right. \right. \\
 & \left. \left. \left. + \sum_{i \in c_g} \log P(S_i C_j | S_g C_j) \right) \right\} + \log d \right] \\
 & + (1 - Z(n, j)) \times \left[\left\{ \sum_{g \in M_j} \left(\log P(S_g C_j | \theta, z_j) \right. \right. \right. \\
 & \left. \left. \left. + \sum_{i \in c_g} \log P(S_i C_j | S_g C_j) \right) \right\} + \log(1 - d) \right] \right\} \quad (10)
 \end{aligned}$$



M-Step

$$a_g^{(n+1)} = a_g^* = \frac{\sum_{j \in S J_g} Z(n, j)}{\sum_{j=1}^N Z(n, j)}$$

$$a_i^{(n+1)} = a_i^* = \frac{\sum_{j \in \bar{S} J_g \cap S J_i} Z(n, j)}{\sum_{j \in \bar{S} J_g} Z(n, j)}$$

for $i \in c_g$

$$b_g^{(n+1)} = b_g^* = \frac{\sum_{j \in S J_g} (1 - Z(n, j))}{\sum_{j=1}^N (1 - Z(n, j))}$$

$$b_i^{(n+1)} = b_i^* = \frac{\sum_{j \in \bar{S} J_g \cap S J_i} (1 - Z(n, j))}{\sum_{j \in \bar{S} J_g} (1 - Z(n, j))}$$

for $i \in c_g$

$$d^{(n+1)} = d^* = \frac{\sum_{j=1}^N Z(n, j)}{N}$$

Simple Illustrative Examples



True Claim



SD Links

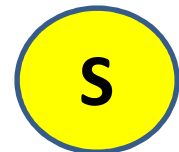


SC Links

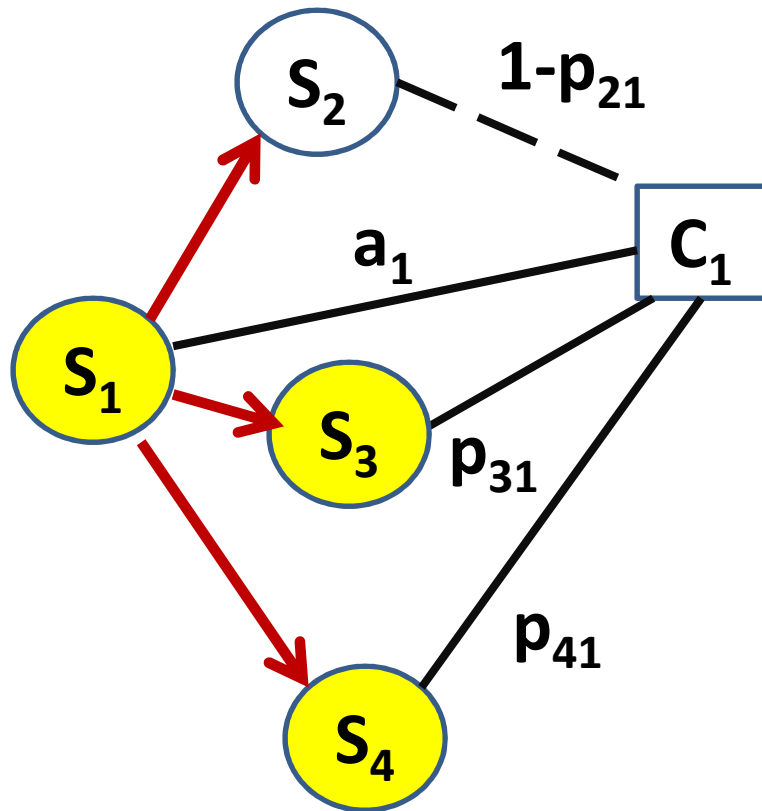


SD Links
that are
ignored

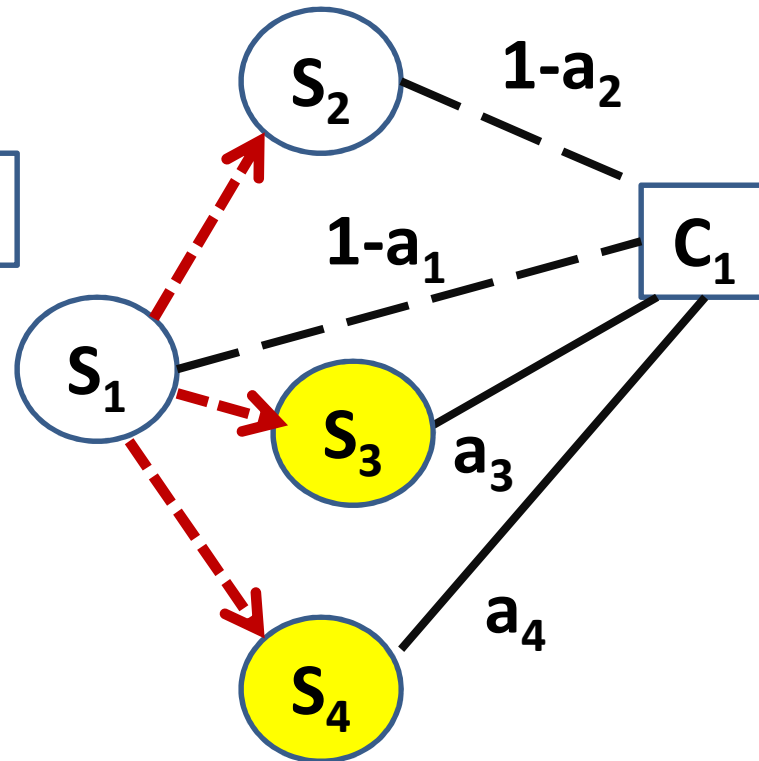
Missing SC
Links



Source that
made claim



Example 1



Example 2

The Apollo Fact-finder

<http://apollo.cs.illinois.edu/>



Apollo

Toward Fact-finding for human centric sensing

Overview

People
Publications
Demos
Datasets

Apollo is a new sensor information processing tool for uncovering likely facts in noisy social (human-centric) sensing data.

Social sensing, where users proactively document and share their observations, has received significant attention in recent years as a paradigm for crowd-sourcing observation tasks. However, it poses interesting challenges in assessing confidence in the information received.

By borrowing clustering and ranking tools from data mining literature, we show how to group data into sets (or claims), corroborating specific events or observations, then iteratively assess both claim and source credibility, ultimately leading to a ranking of described claims by their likelihood of occurrence. Apollo belongs to a category of tools called fact-finders. It is the first fact-finder designed and implemented specifically for social sensing.

This is a collaborative work of





EM is Integrated with Apollo

A Real World Application



Create new task

Keyword 1 or
 Keyword 2 or
 Keyword 3 or from

Latitude Longitude Radius (miles)

Keywords/Location

Crawl with Search API

Current tasks

Task ID	Created Time (Central Time)	Running time (Seconds)	Collected Data (Bytes)	Q
1319495970	Mon Oct 24 17:39:30 2011	14402967	2768896	50

Data Collection Frontend

Datasets/Analysis

Datasets:

egypt-4-6

Analysis:

New Analysis:

Fact-finder/EM-SOCIAL

No Re-tweet

ID	Type	Params	Status	Actions
Voting-with retweet-1365286071	Voting	{"include_retweet":true}	active	Delete Show
EM_CRB-with retweet-1365286067	EM_CRB	{"include_retweet":true}	active	Delete Show
EM_SOCIAL-with retweet-1365233335	EM_SOCIAL	{"include_retweet":true}	active	Delete Show
Voting-with retweet-1365291553	Voting	{"include_retweet":true}	active	Delete Show

Analysis Viewer

Information Analysis Frontend

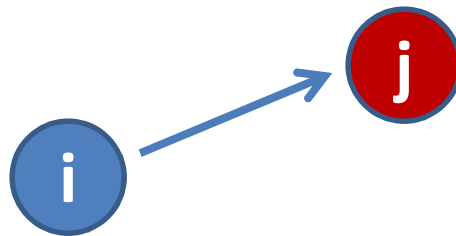


Trace	Hurricane Sandy	Hurricane Irene	Egypt Unrest
Time duration	14 days (Nov.2-15, 2012)	8 days (Aug.26-Sept.2, 2011)	18 days (Feb.2-Feb.19,2011)
Locations	16 cities in East Coasts	New York	Cairo, Egypt
# of users tweeted	7,583	207,562	13,836
# of tweets	12,931	387,827	93,208
# of users crawled in social network	704,941	2,510,316	5,285,160
# of follower-followee links	37,597	3,902,713	10,490,098



Estimate Latent Social Dissemination (SD) Network

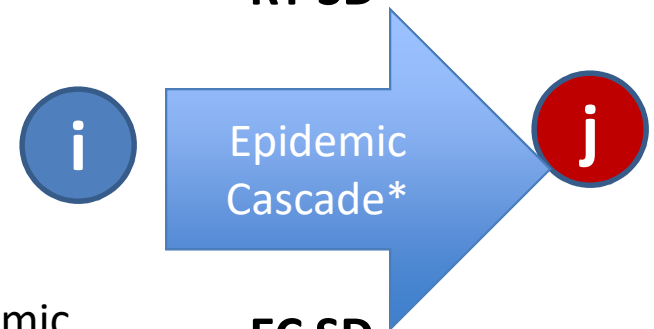
Estimate Latent
Social
Dissemination
Network



FF SD



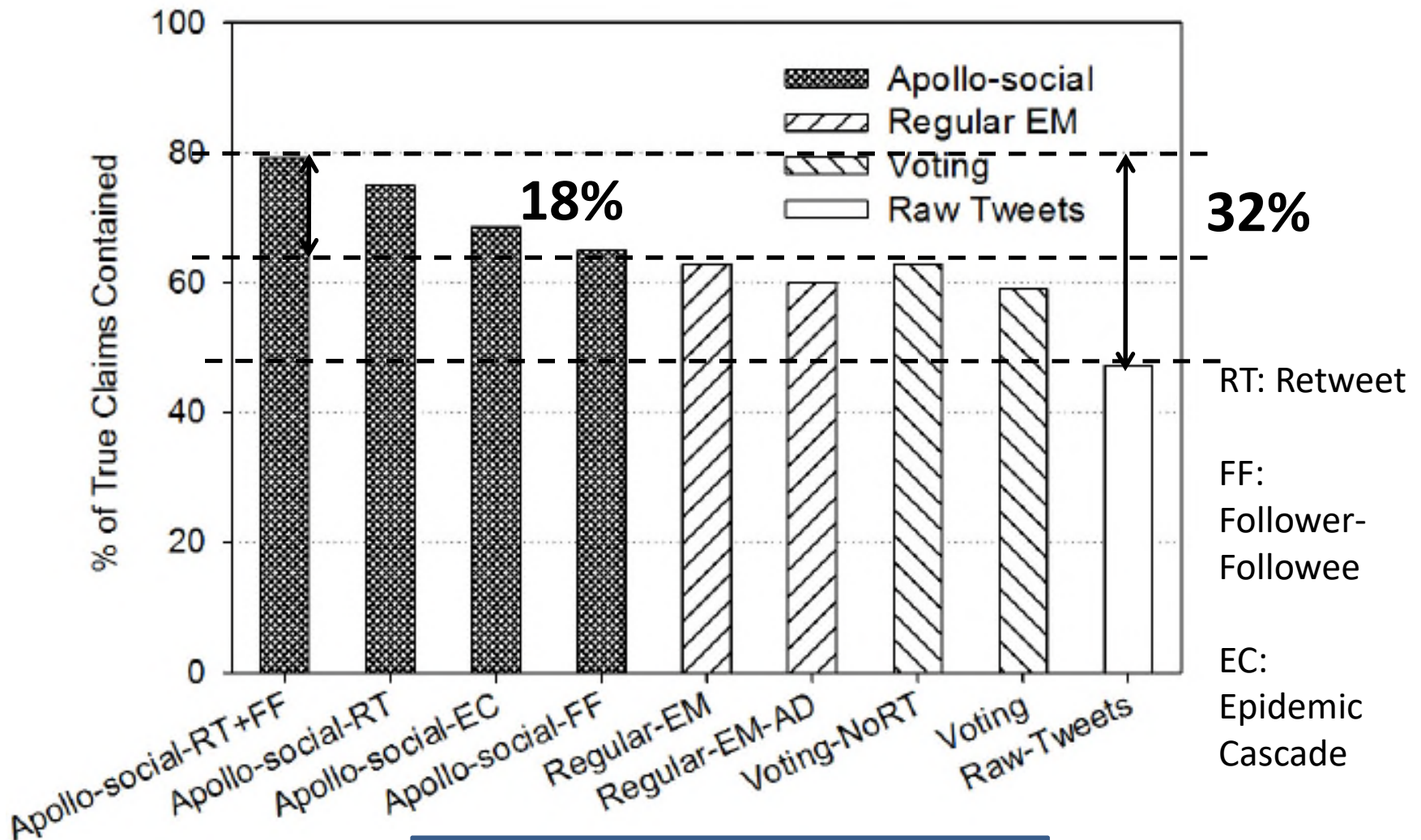
RT SD



EC SD

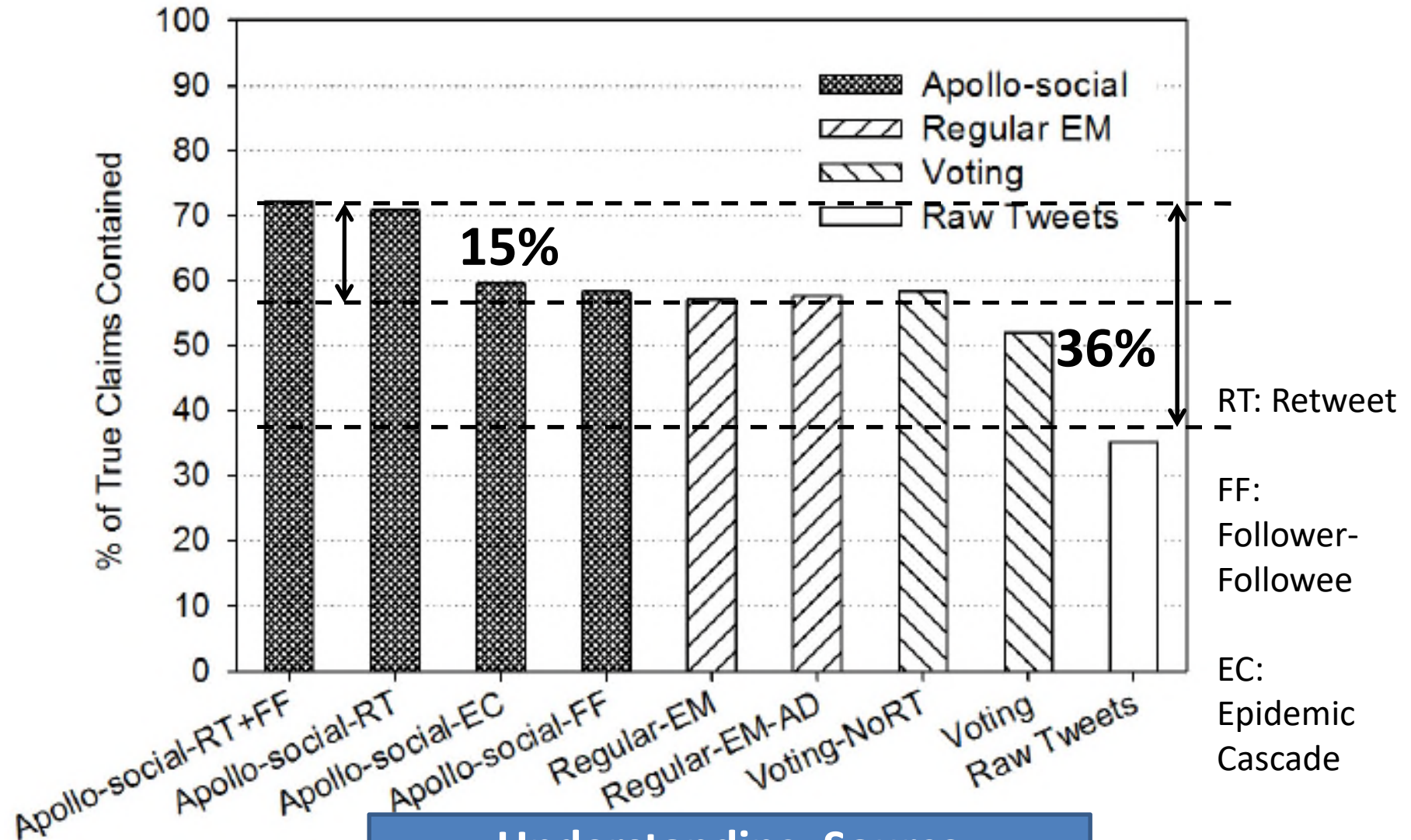
* P. Netrapalli and S. Sanghavi. Learning the graph of epidemic cascades. SIGMETRICS '12, pages 211–222, New York, NY, USA, 2012. ACM.

Evaluation on Sandy Trace



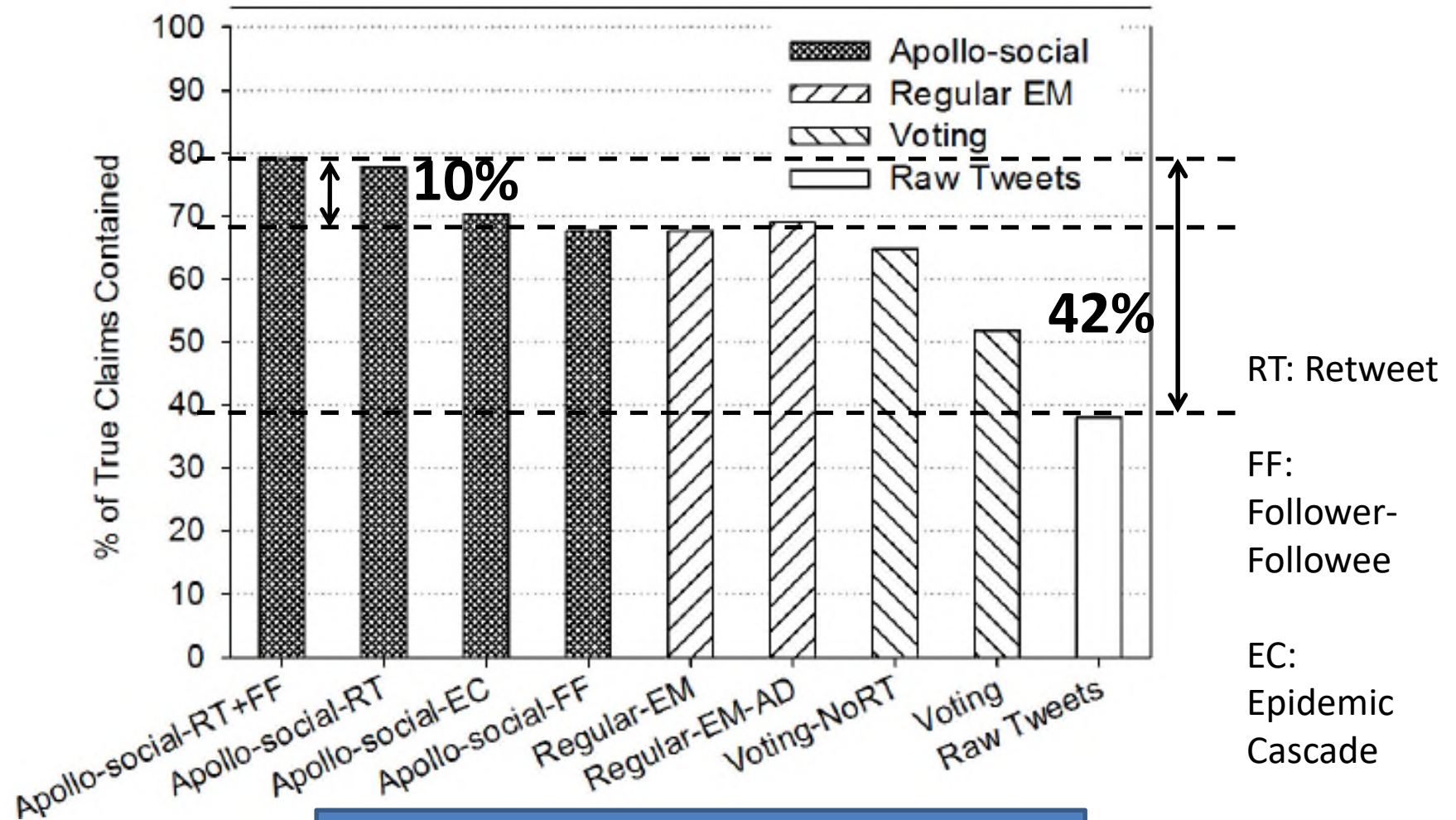
Understanding Source Dependency Helps !

Evaluation on Irene Trace



Understanding Source Dependency Helps !

Evaluation on Egypt Trace



Understanding Source Dependency Helps !

Ground Truth Events Found by Social EM vs Regular EM



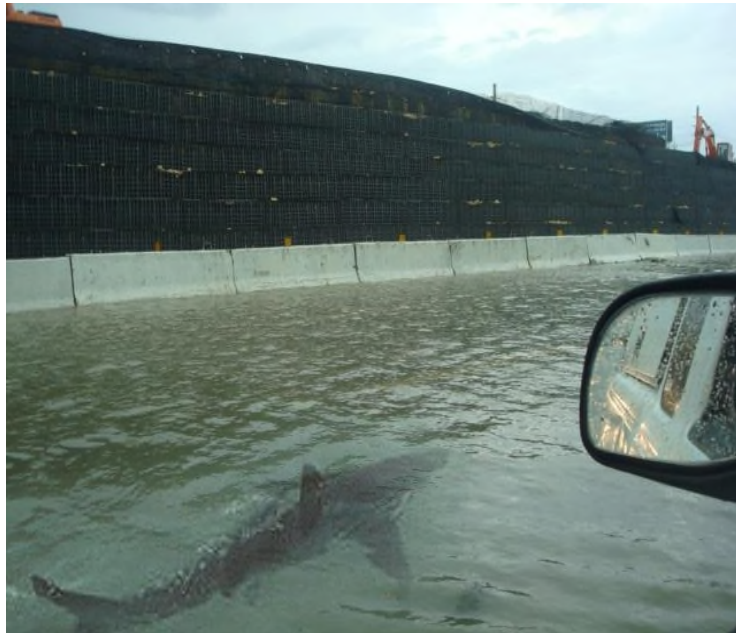
#	Media	Tweet found by Apollo-social	Tweet found by Regular EM
1	Rockland County Executive C. Scott Vanderhoef is announcing a Local Emergency Order restricting the amount of fuel that an individual can purchase at a gas station.	Rockland County Orders Restrictions on Gas Sales - Nyack-Piermont, NY Patch http://t.co/cDSrqa2	MISSING
2	New York City Mayor Michael Bloomberg has announced that the city will impose an indefinite program of gas rationing after fuel shortages led to long lines and frustration at the pump in the wake of superstorm Sandy.	Gas rationing plan set for New York City: The move follows a similar announcement last week in New Jersey to eas... http://t.co/nkmF7U9I	RT @nytimes: Breaking News: Mayor Bloomberg Imposes Odd-Even Gas Rationing Starting Friday, as Does Long Island http://t.co/eax7KMVi
3	New Jersey authorities filed civil suits Friday accusing seven gas stations and one hotel of price gouging in the wake of Hurricane Sandy.	RT @MarketJane: NJ plans price gouging suits against 8 businesses. They include gas stations and a lodging provider.	MISSING
4	The rationing system: restricting gas sales to cars with even-numbered license plates on even days, and odd-numbered on odd days will be discontinued at 6 a.m. Tuesday, Gov. Chris Christie announced on Monday.	# masdirin City Room: Gas Rationing in New Jersey to End Tuesday # news	RT @nytimes: City Room: Gas Rationing in New Jersey to End Tuesday http://t.co/pYIVOmPo
5	New Yorkers can expect gas rationing for at least five more days: Bloomberg.	Mayor Bloomberg: Gas rationing in NYC will continue for at least 5 more days. @eyewitnessnyc #SandyABC7	Bloomberg: Gas Rationing To Stay In Place At Least Through The Weekend http://t.co/mmqqjYRx

TABLE III. GROUND TRUTH EVENTS AND RELATED CLAIMS FOUND BY APOLLO-SOCIAL VS REGULAR EM IN SANDY

One Interesting Example



Shark in the street!



Suppressed by Social EM

The Washington Post

Posted at 08:53 AM ET, 08/26/2011

Hurricane Irene: 'Photo' of shark swimming in street is fake

By Sarah Anne Hughes



Holy moly! A (fake) picture of a shark swimming on a Puerto Rico street! (Reddit)

http://www.washingtonpost.com/blogs/blogpost/post/hurricane-irene-photo-of-shark-swimming-in-street-is-fake/2011/08/26/gIQABHAvfJ_blog.html



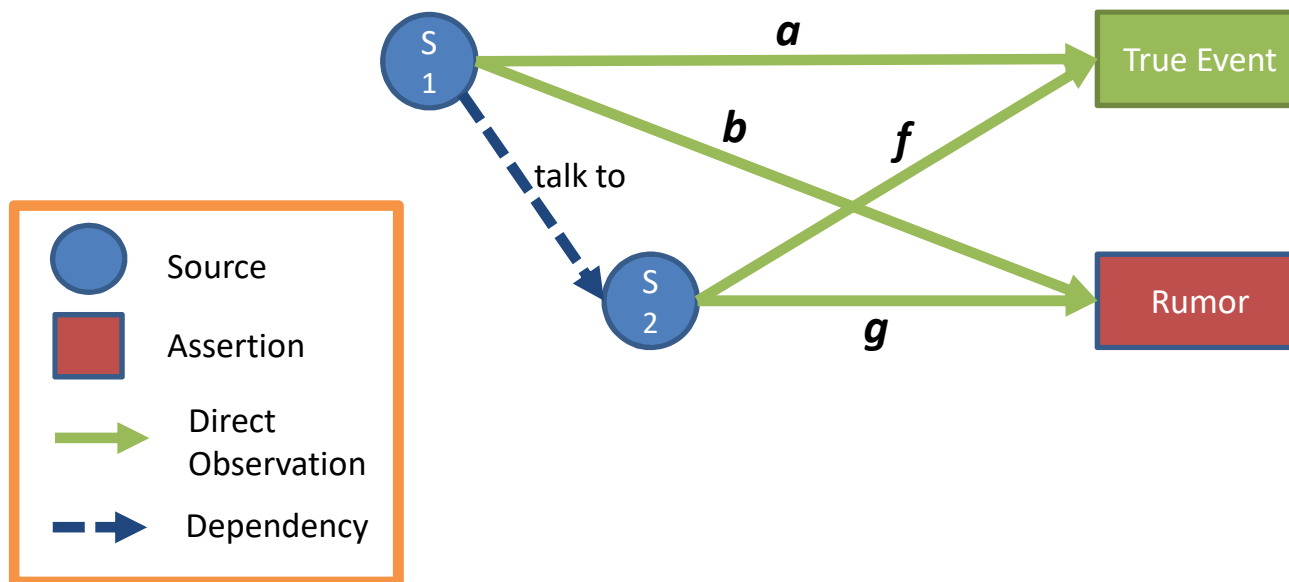
Social Sensing: Source Dependencies



- Failure of physical sensor: independent
- Failure of social sensing sensor: dependent
 - People talk and influence each other
 - Correlated errors
- We need to formulate source dependency correctly!



Estimator Parameters



Expectation-Maximization Solution



E Step

$$Q(\theta|\theta^{(t)}) = \sum_{j=1}^m P(C_j | S C_j; \theta^{(t)}) \sum_{C_j \in \{0,1\}} \ln(P(C_j; \theta))$$

$$\left(\sum_{i=1}^n \ln(P(S_i C_j | C_j; \theta, D_{ij})) \right)$$

M Step

$$a_i^{(t+1)} = \frac{\sum_{C_j \in S_i C_1^{D_0}} P(C_j = 1 | S_i C_j; \theta^{(t)})}{\sum_{C_j \in S_i C_1^{D_0} \cup S_i C_0^{D_0}} P(C_j = 1 | S_i C_j; \theta^{(t)})}$$

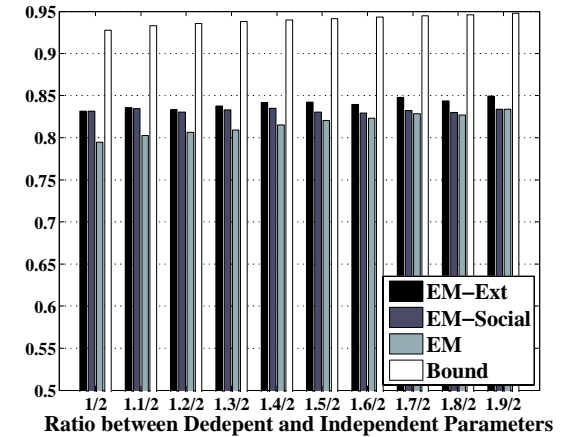
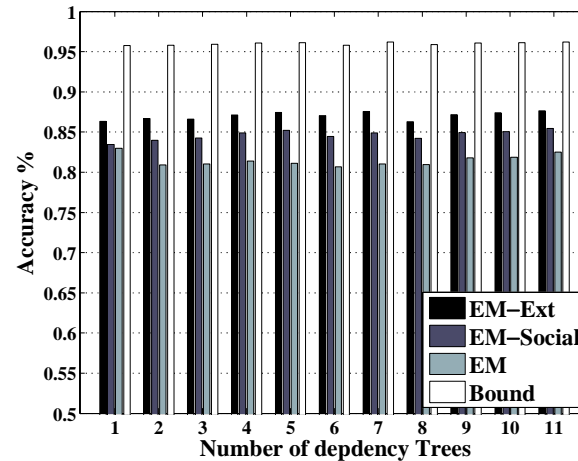
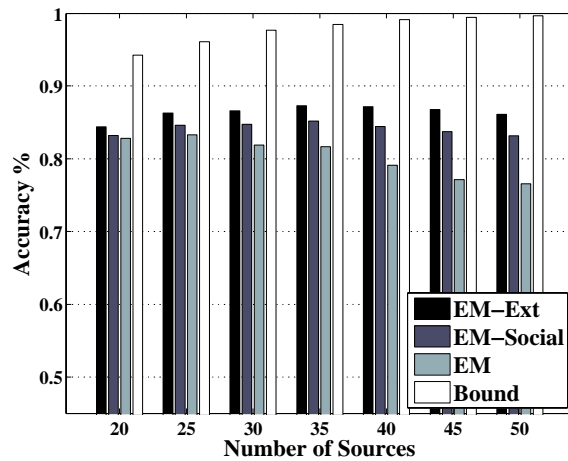
$$f_i^{(t+1)} = \frac{\sum_{C_j \in S_i C_1^{D_1}} P(C_j = 1 | S_i C_j; \theta^{(t)})}{\sum_{C_j \in S_i C_1^{D_1} \cup S_i C_0^{D_1}} P(C_j = 1 | S_i C_j; \theta^{(t)})}$$

$$b_i^{(t+1)} = \frac{\sum_{C_j \in S_i C_1^{D_0}} P(C_j = 0 | S_i C_j; \theta^{(t)})}{\sum_{C_j \in S_i C_1^{D_0} \cup S_i C_0^{D_0}} P(C_j = 0 | S_i C_j; \theta^{(t)})}$$

$$g_i^{(t+1)} = \frac{\sum_{C_j \in S_i C_1^{D_1}} P(C_j = 0 | S_i C_j; \theta^{(t)})}{\sum_{C_j \in S_i C_1^{D_1} \cup S_i C_0^{D_1}} P(C_j = 0 | S_i C_j; \theta^{(t)})}$$

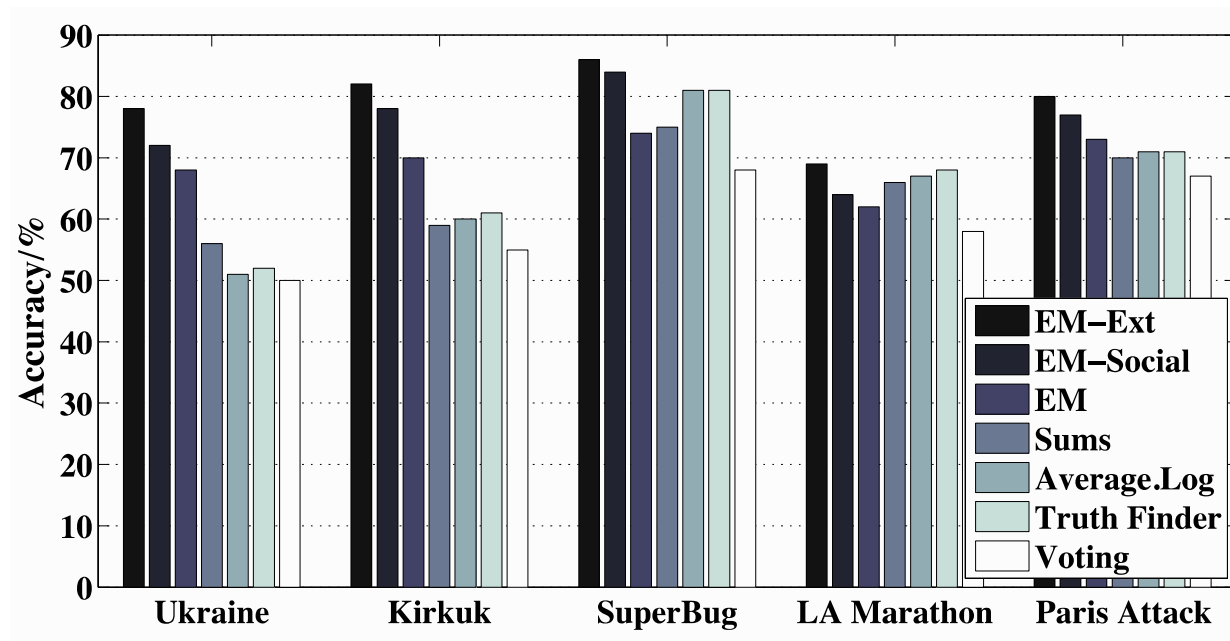
$$z^{(t+1)} = \frac{\sum_{j=1}^m P(C_j = 0 | S_i C_j; \theta^{(t)})}{m}$$

Simulation of Dependency-Aware Estimator



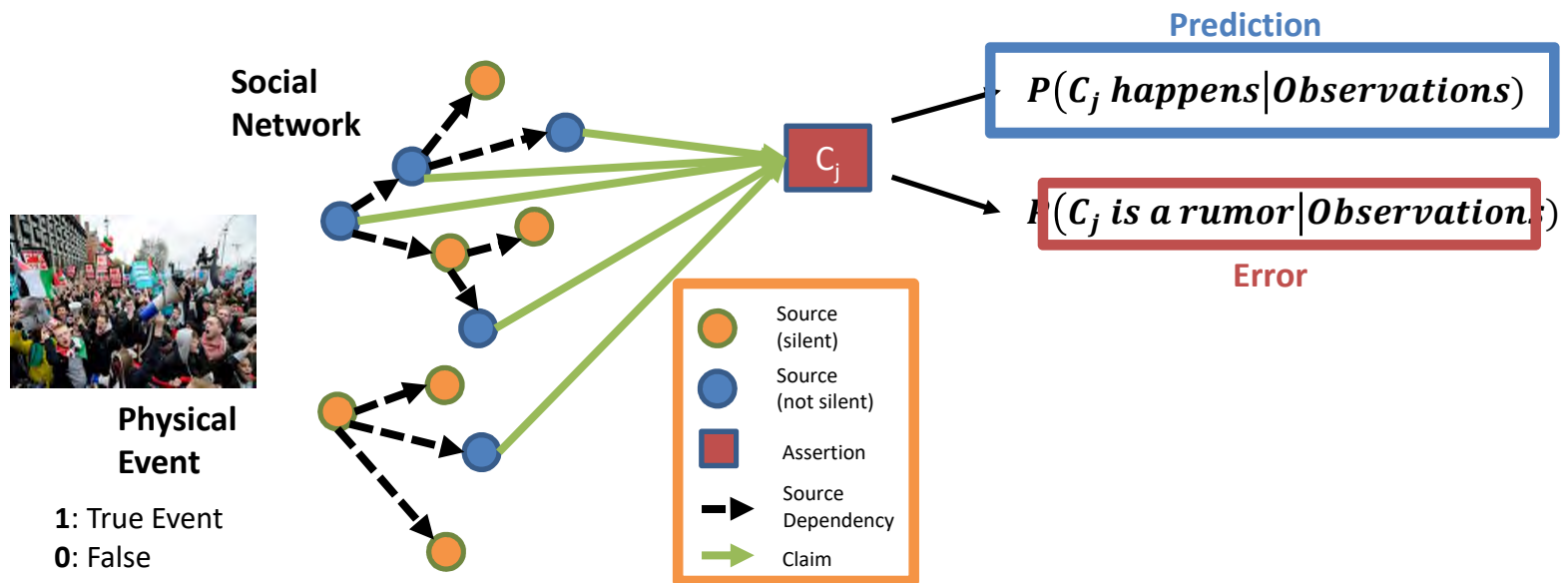


Empirical Evaluation





Optimal Estimator





Error Bounds

- Alleged event: “France bombs Iraq”

Pravda	Jazeera	Ahram	Falsehood Probability	Truth Probability
Silent	Silent	Silent	99%	1%
Silent	Silent	Report	80%	20%
Silent	Report	Silent	90%	10%
Silent	Report	Report	40%	60%
Report	Silent	Silent	95%	5%
Report	Silent	Report	60%	40%
Report	Report	Silent	70%	30%
Report	Report	Report	5%	95%



Error Bounds

- Alleged event: “France bombs Iraq”

The odds	Pravda	Jazeera	Ahram	Falsehood Probability	Truth Probability
4%	Silent	Silent	Silent	99%	1%
10%	Silent	Silent	Report	80%	20%
10%	Silent	Report	Silent	90%	10%
20%	Silent	Report	Report	40%	60%
20%	Report	Silent	Silent	95%	5%
13%	Report	Silent	Report	60%	40%
13%	Report	Report	Silent	70%	30%
10%	Report	Report	Report	5%	95%



Error Bounds

- Alleged event: “France bombs Iraq”

The odds	Pravda	Jazeera	Ahram	Falsehood Probability	Truth Probability
4%	Silent	Silent	Silent	99%	1%
10%	Silent	Silent	Report	80%	20%
10%	Silent	Report	Silent	90%	10%
20%	Silent	Report	Report	40%	60%
20%	Report	Silent	Silent	95%	5%
13%	Report	Silent	Report	60%	40%
13%	Report	Report	Silent	70%	30%
10%	Report	Report	Report	5%	95%

Odds of omission = 4%



Error Bounds

- Alleged event: “France bombs Iraq”

The odds	Pravda	Jazeera	Ahram	Falsehood Probability	Truth Probability
4%	Silent	Silent	Silent	99%	1%
10%	Silent	Silent	Report	80%	20%
10%	Silent	Report	Silent	90%	10%
20%	Silent	Report	Report	40%	60%
20%	Report	Silent	Silent	95%	5%
13%	Report	Silent	Report	60%	40%
13%	Report	Report	Silent	70%	30%
10%	Report	Report	Report	5%	95%

Odds of omission = 4%

Odds of error = $0.1 * 0.2 + \dots$



Error Bounds

- Alleged event: “France bombs Iraq”

The odds	Pravda	Jazeera	Ahram	Falsehood Probability	Truth Probability
4%	Silent	Silent	Silent	99%	1%
10%	Silent	Silent	Report	80%	20%
10%	Silent	Report	Silent	90%	10%
20%	Silent	Report	Report	40%	60%
20%	Report	Silent	Silent	95%	5%
13%	Report	Silent	Report	60%	40%
13%	Report	Report	Silent	70%	30%
10%	Report	Report	Report	5%	95%

Odds of omission = 4%

Odds of error = $0.1 * 0.2 + 0.1 * 0.1 + \dots$



Error Bounds

- Alleged event: “France bombs Iraq”

The odds	Pravda	Jazeera	Ahram	Falsehood Probability	Truth Probability
4%	Silent	Silent	Silent	99%	1%
10%	Silent	Silent	Report	80%	20%
10%	Silent	Report	Silent	90%	10%
20%	Silent	Report	Report	40%	60%
20%	Report	Silent	Silent	95%	5%
13%	Report	Silent	Report	60%	40%
13%	Report	Report	Silent	70%	30%
10%	Report	Report	Report	5%	95%

Odds of omission = 4%

Odds of error = $0.1 * 0.2 + 0.1 * 0.1 + 0.2 * 0.4 + \dots$



Error Bounds

- Alleged event: “France bombs Iraq”

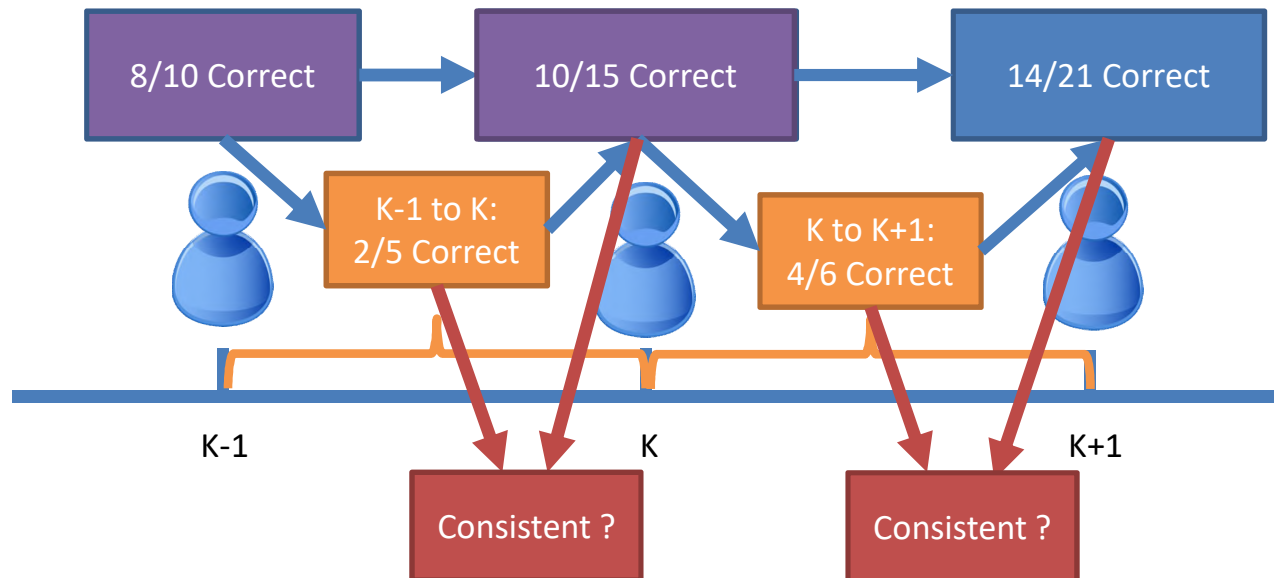
The odds	Pravda	Jazeera	Ahram	Falsehood Probability	Truth Probability
4%	Silent	Silent	Silent	99%	1%
10%	Silent	Silent	Report	80%	20%
10%	Silent	Report	Silent	90%	10%
20%	Silent	Report	Report	40%	60%
20%	Report	Silent	Silent	95%	5%
13%	Report	Silent	Report	60%	40%
13%	Report	Report	Silent	70%	30%
10%	Report	Report	Report	5%	95%

Odds of omission = 4%

Odds of error = $0.1 * 0.2 + 0.1 * 0.1 + 0.2 * 0.4 + 0.2 * 0.05 + 0.4 * 0.13 + 0.3 * 0.13 + 0.05 * 0.1$
 = 23.6%

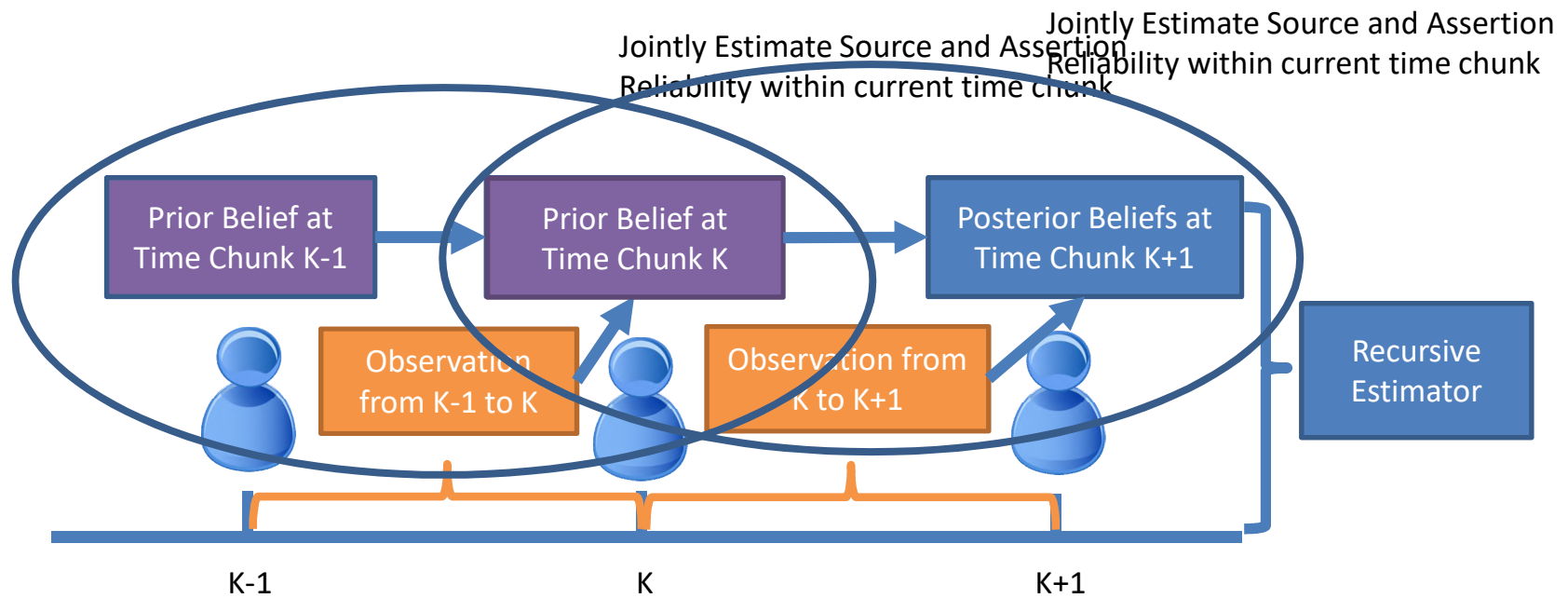


Example



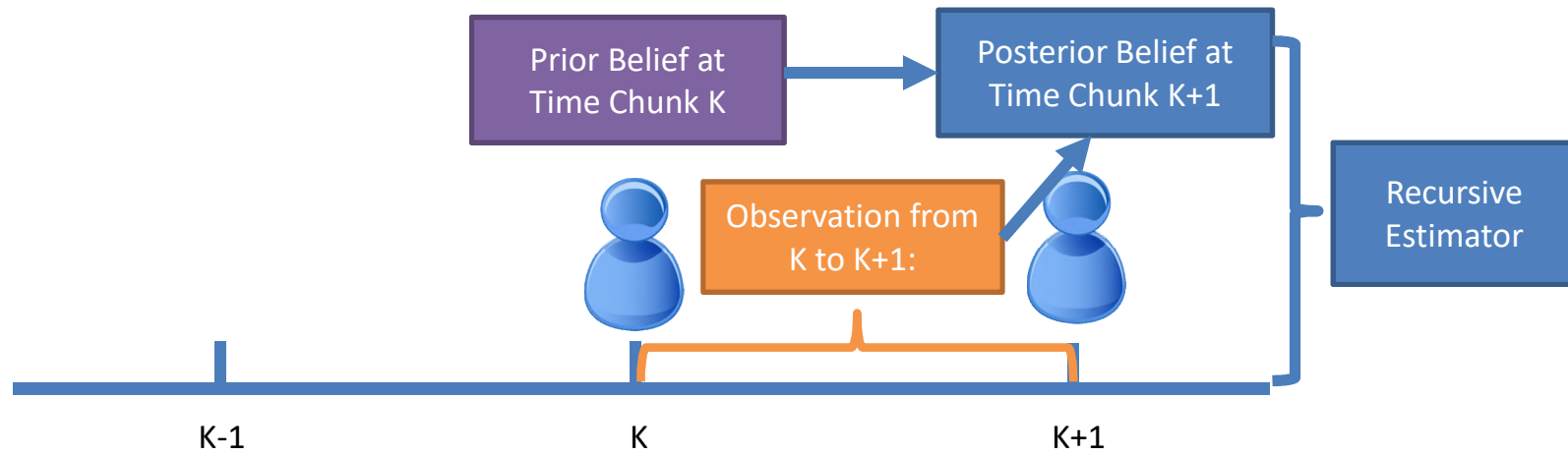


Overview





Recursive Estimator

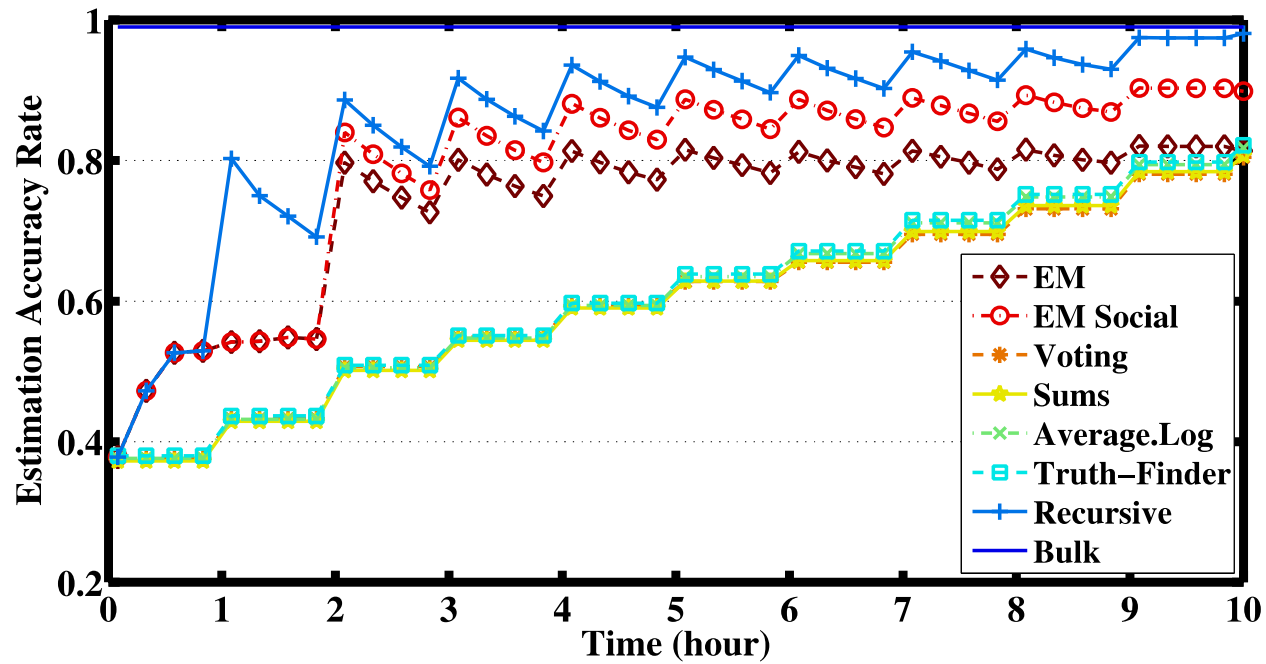




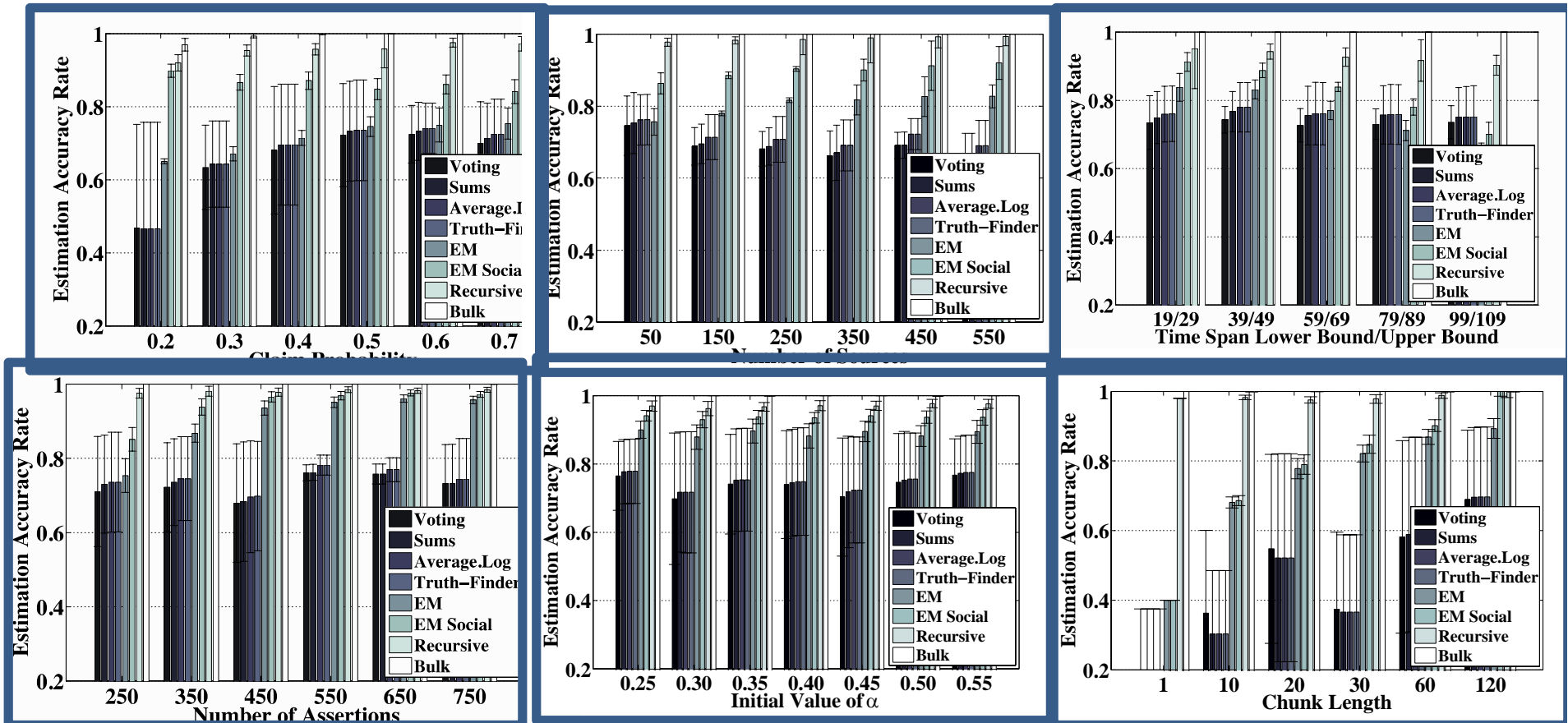
Recursive Estimator

- Recursively update the belief of reliability distribution:
 - Compute mean reliability (Compute 1st Moment)
 - source reliability parameters, θ_i
 - probability of correctness, $P(t(C) = 1 | S C_k, D, \theta)$
 - Computing the error variance (Compute 2nd Moment)
 - error variance of source reliability parameters, θ_i
 - Computing the posterior belief (Update Distribution with Moment Matching)
 - updated belief in source reliability

Synthetic Data: estimation accuracy of 10-hour trace

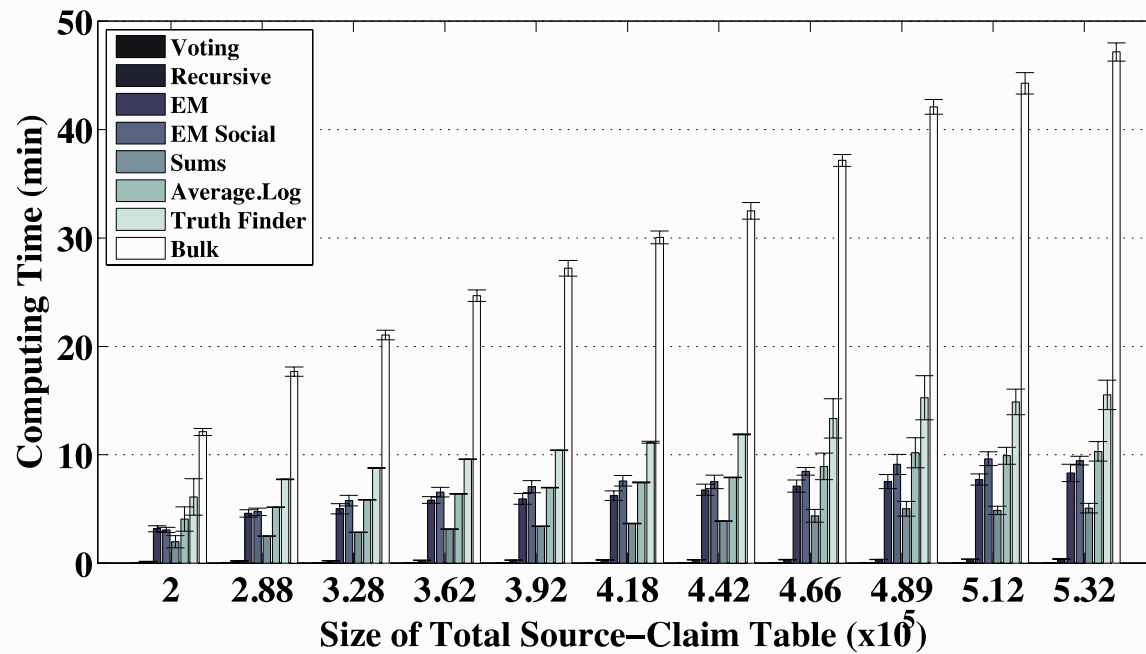


Synthetic Data: effect of changing Simulation parameters

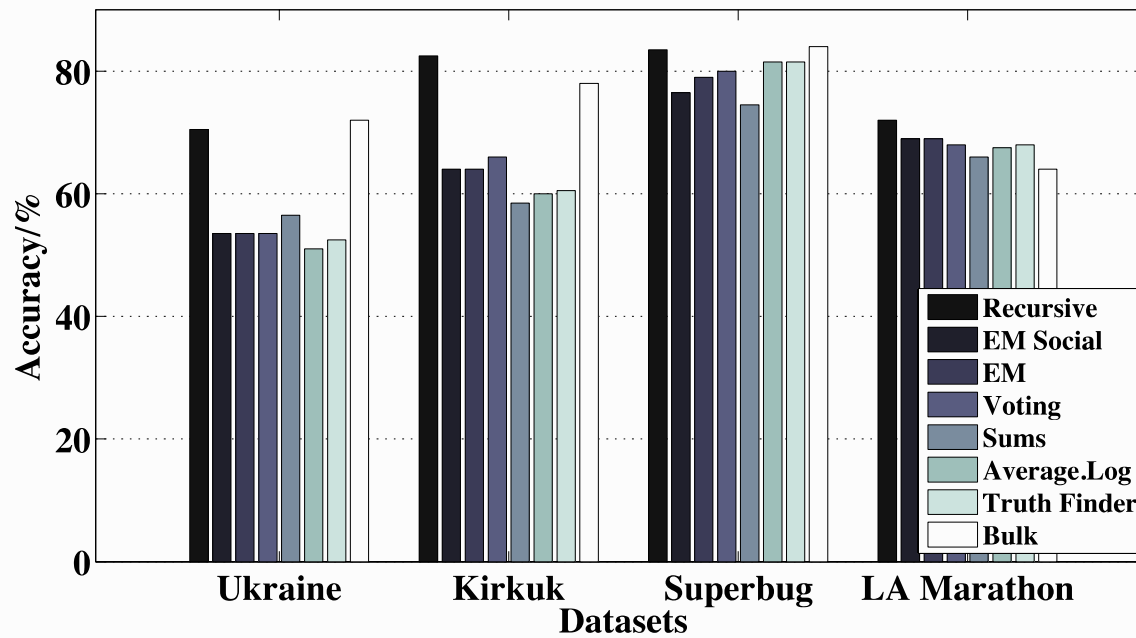




Synthetic Data: computation time



Empirical Evaluation: Empirical Accuracy Results





Empirical Evaluation: empirical execution time

