

ECE 330 Exam #2, Fall 2012 Name: Solution
 90 Minutes

Section (Check One) MWF 10am _____ MWF 2pm _____

1. _____ / 25 2. _____ / 25

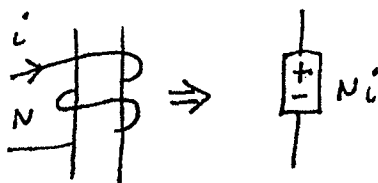
3. _____ / 25 4. _____ / 25 Total _____ / 100

Useful information

$$\sin(x) = \cos(x - 90^\circ) \quad \bar{V} = \overline{ZI} \quad \bar{S} = \overline{VI}^* \quad \mu_0 = 4\pi \cdot 10^{-7} \text{ H/m}$$

$$\int_C \mathbf{H} \cdot d\mathbf{l} = \int_S \mathbf{J} \cdot \mathbf{n} da \quad \int_C \mathbf{E} \cdot d\mathbf{l} = -\frac{\partial}{\partial t} \int_S \mathbf{B} \cdot \mathbf{n} da \quad \mathfrak{R} = \frac{l}{\mu A} \quad MMF = Ni = \phi \mathfrak{R}$$

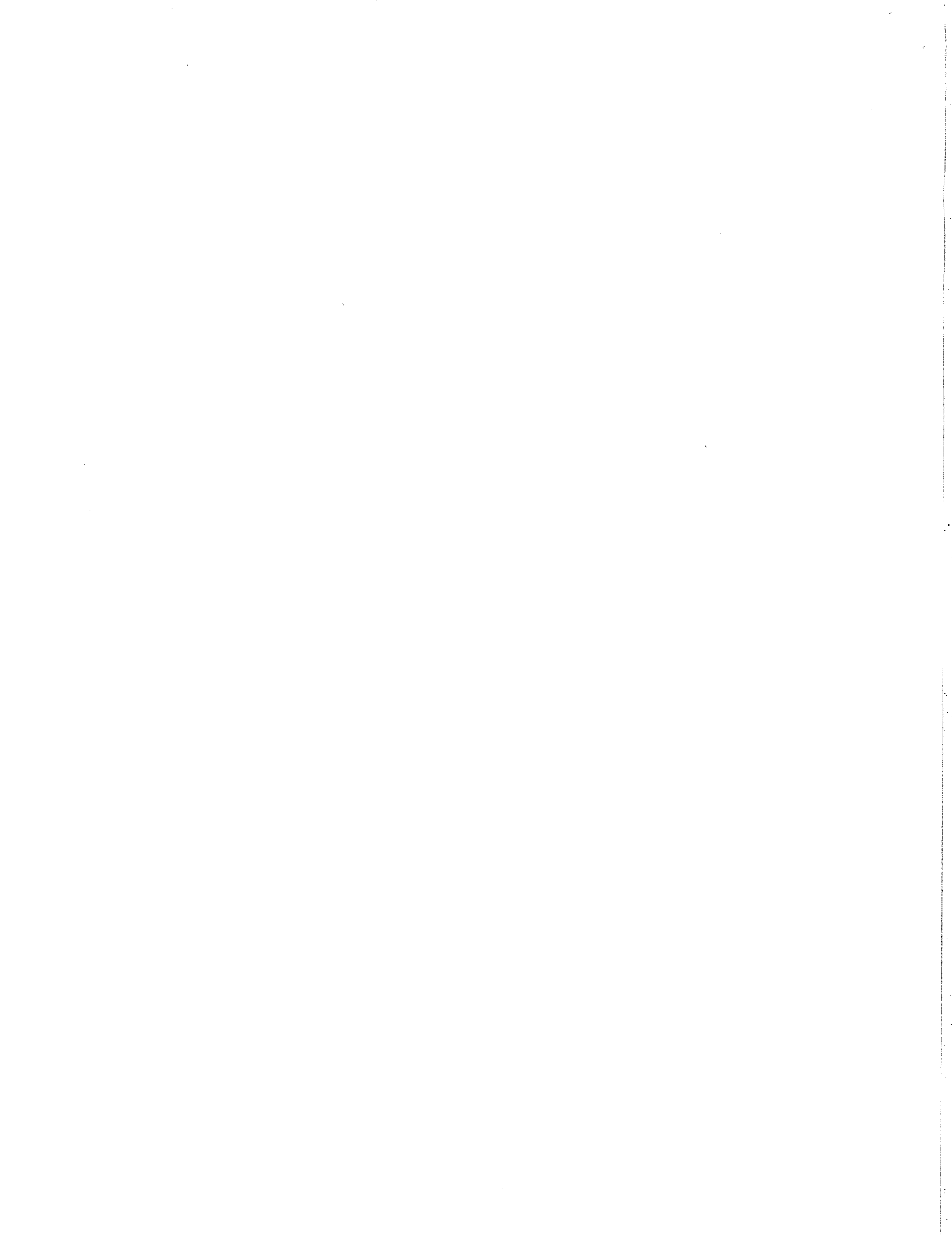
$$\mathfrak{R} = \frac{l}{\mu A} \quad B = \mu H \quad \phi = BA \quad \lambda = N\phi \quad \lambda = Li \text{ (if linear)}$$



$$W_m = \int_0^\lambda i d\hat{\lambda} \quad W_m' = \int_0^i \lambda d\hat{i} \quad W_m + W_m' = \lambda i \quad f^e = \frac{\partial W_m'}{\partial x} = -\frac{\partial W_m}{\partial x} \quad x \rightarrow \theta$$

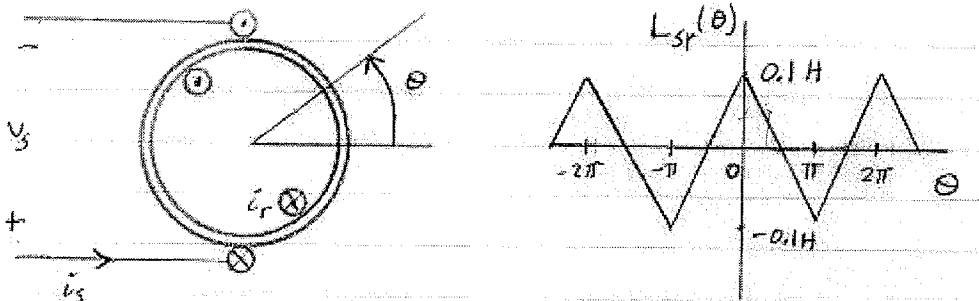
$$f^e \rightarrow T^e$$

$$EFE_{a \rightarrow b} = \int_a^b i d\lambda \quad EFM_{a \rightarrow b} = -\int_a^b f^e dx \quad EFE_{a \rightarrow b} + EFM_{a \rightarrow b} = W_{mb} - W_{ma} \quad \lambda = \frac{\partial W_m'}{\partial i} \quad i = \frac{\partial W_m}{\partial \lambda}$$

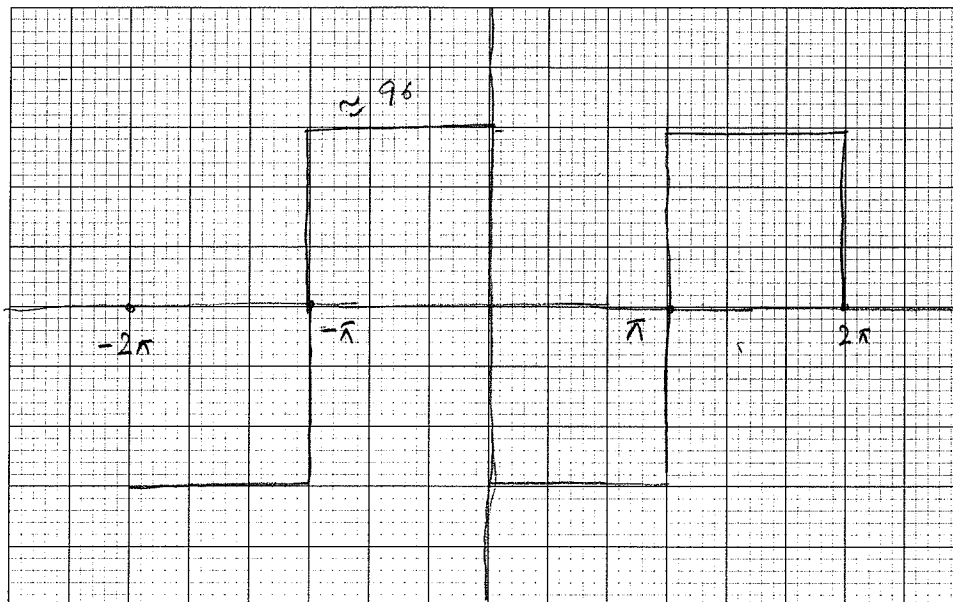


Problem 1. (25 points)

A single-phase generator consists of a coil on the stator and a coil on the rotor with a mutual inductance variation with θ as shown in the figure below. The rotor is being driven at a constant speed of 377 radians per second and the rotor coil has a constant dc current $i_r = 4$ A.



(a) Plot the open circuit voltage (the case with $i_s = 0$) as a function of θ (label all points and do not use sinusoidal approximations)



$$\begin{aligned}
 V &= \frac{d\lambda}{dt} \\
 &= \frac{d(Li)}{dt} \\
 &= \frac{d(L_{sr}(\theta) \times 4)}{dt}
 \end{aligned}$$

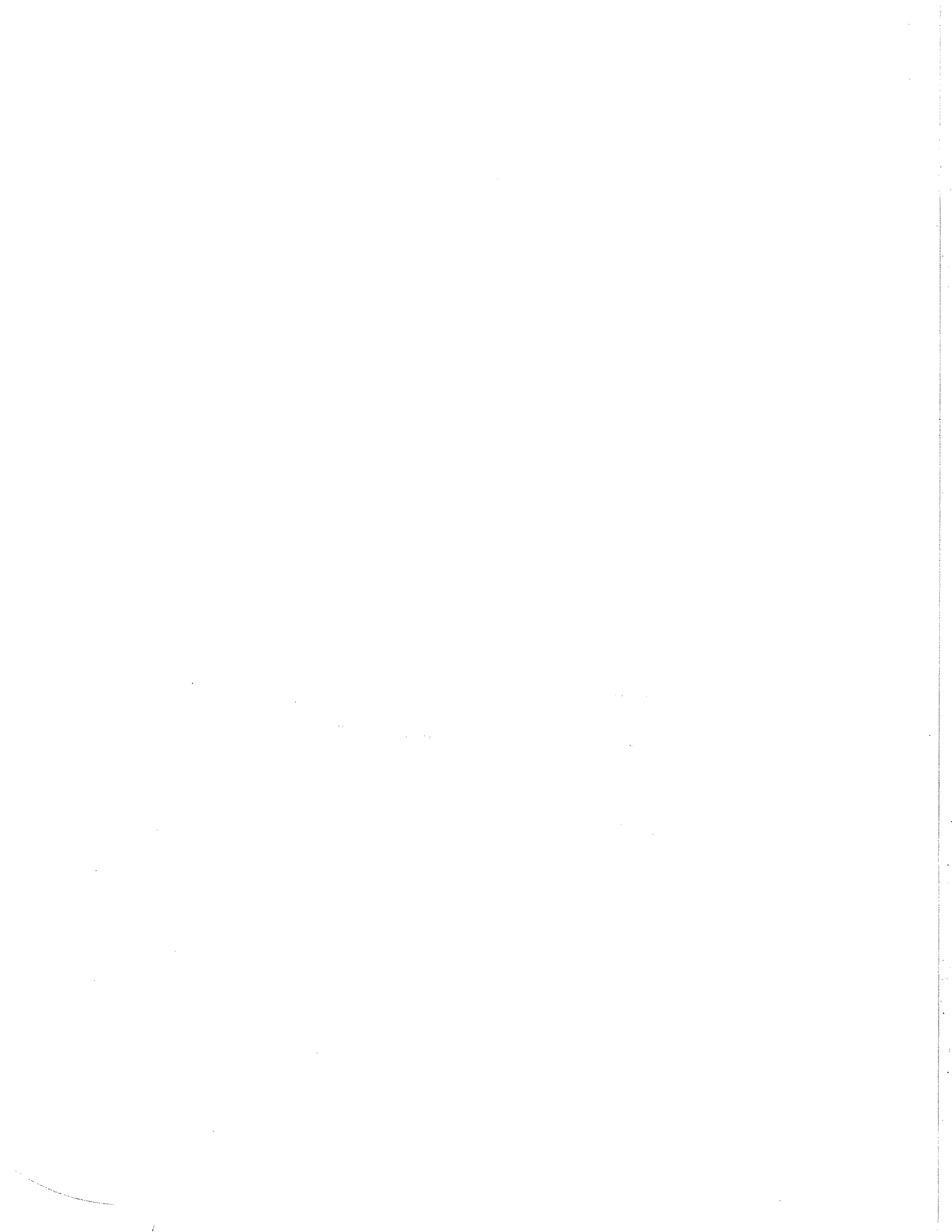
Note: $L_{sr}(\theta) = 0.1 - \frac{0.2\theta}{\pi}$
 $0 < \theta < \pi$
 $L_{sr}(\theta) = 0.1 + \frac{0.2\theta}{\pi}$

(b) What is the torque of electrical origin when $i_s = 8$ A and $\theta = 30^\circ$?

$$\begin{aligned}
 \Rightarrow V &= -0.2\omega \times 4 \quad 0 < \theta < \pi \\
 2 &= \frac{0.2\omega \times 4}{\pi} \quad -\pi < \theta < 0
 \end{aligned}$$

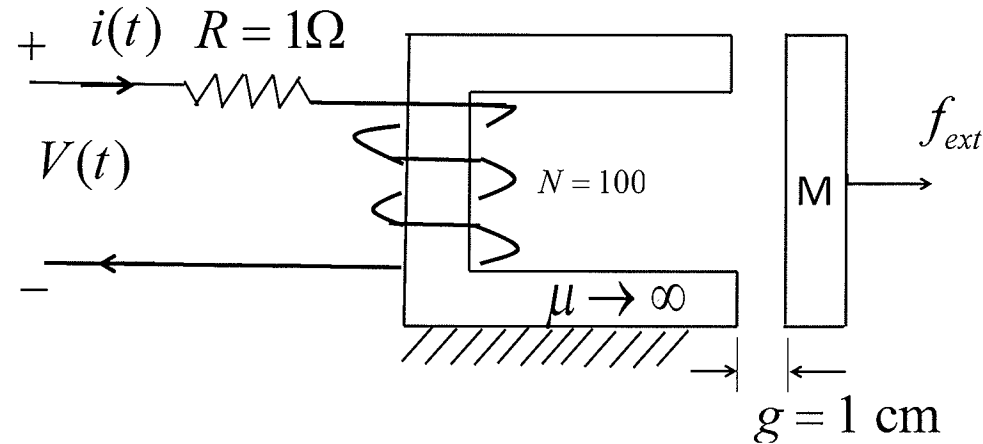
$$(3) \quad W_m' = \frac{1}{2} L_{ss} i_s^2 + \frac{L_{sr}(\theta)}{\pi} i_s i_r + \frac{1}{2} L_{rr} i_r^2$$

$$\begin{aligned}
 \Rightarrow T^e &= \frac{\partial W_m'}{\partial \theta} = i_s i_r \cdot \left(\frac{0.2}{\pi}\right) \Rightarrow T^e = -8 \times 4 \times \frac{0.2}{\pi} \\
 (2) \quad T^e &= -\frac{64}{\pi} \Rightarrow \boxed{T^e = 2.038 \text{ N-m}}
 \end{aligned}$$



Problem 2. (25 points.)

Consider the electromechanical system shown in the figure below. Let the air-gap length between the fixed and the moving parts be $g = 1 \text{ cm}$. The cross sectional area of the fixed and the moving part is $A = 100 \text{ cm}^2$.



- 10 a) Compute the external force f_{ext} required to maintain the air-gap length between the fixed and moving part at $g = 1 \text{ cm}$ when a voltage of $V(t) = 12 \text{ VDC}$ is applied.
- 10 b) If the external force is removed and the mass M is allowed to move, compute the energy from the mechanical system (EFM) when mass M moves and closes the air gap.
- 5 c) When the air-gap length is reduced to nearly zero, what happens to the flux in the core?

a)

$$Ni = 2Rg\phi$$

$$\Rightarrow \phi = \frac{Ni}{2Rg} = \frac{\mu_0 AN^2 i}{2g}$$

$$\Rightarrow \lambda(i, g) = N\phi = \frac{\mu_0 AN^2 i}{2g}$$

$$\Rightarrow W_m'(i, g) = \int_0^i \frac{\mu_0 AN^2 \hat{i}}{2g} d\hat{i}$$

$$= \frac{\mu_0 AN^2 i^2}{4g}$$

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$$\Rightarrow f^e(i, g) = - \frac{\mu_0 AN^2 i^2}{4g^2}$$

for $i = 12 \text{ A}$, $g = 1 \text{ cm}$

$$f^e(i, g) = -45.23 \text{ N}$$

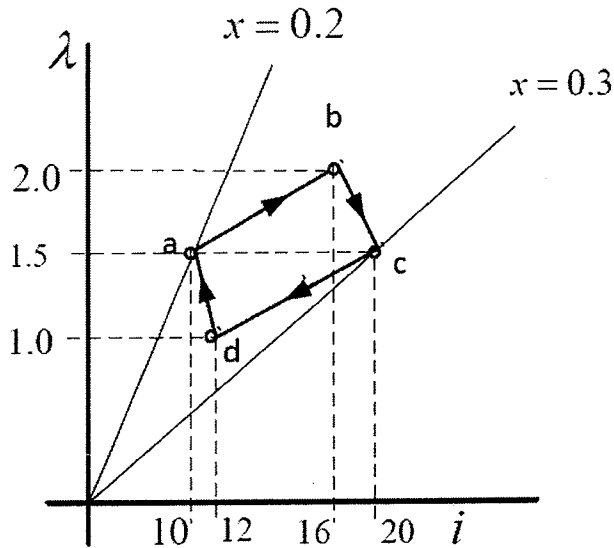
$$\Rightarrow \boxed{f_{ext} = 45.23 \text{ N}}$$

$$\begin{aligned}
 \text{b) } E_{FM}|_{a \rightarrow b} &= - \int_{g_a}^{g_b} f_e dg \\
 &= - \int_{+0.01}^{0.00001} \frac{-\mu_0 AN^2 i^2}{4g^2} dg \\
 &= \frac{\mu_0 AN^2 i^2}{4} \cdot \left. \frac{-1}{g} \right|_{0.01}^{0.00001} \\
 &= -451.9 \text{ J}
 \end{aligned}$$

c) As the gap is reduced nearly to zero, the assumption of $\mu \rightarrow \infty$ (iron) no longer holds.

Problem 3. (25 points.)

An electromechanical device is operated over the cycle abcd shown in the figure below. The system is known to be electrically linear, i.e., $\lambda = L(x)i$.



- Calculate the energy stored in the coupling field (W_m) at points 'a' and 'd'.
- Calculate EFE_{cycle} in Joules.
- Calculate EFM_{cycle} in Joules.
- Is the machine operating as a motor or a generator?

(Note : You must clearly show the steps for parts a) - c) and state the reason for your answer in part d))

a) $w_{ma} = \frac{1}{2} \times 10 \times 1.5 = 7.5 \text{ J}$ $w_{md} = \frac{1}{2} \times 12 \times 1.0 = 6 \text{ J}$

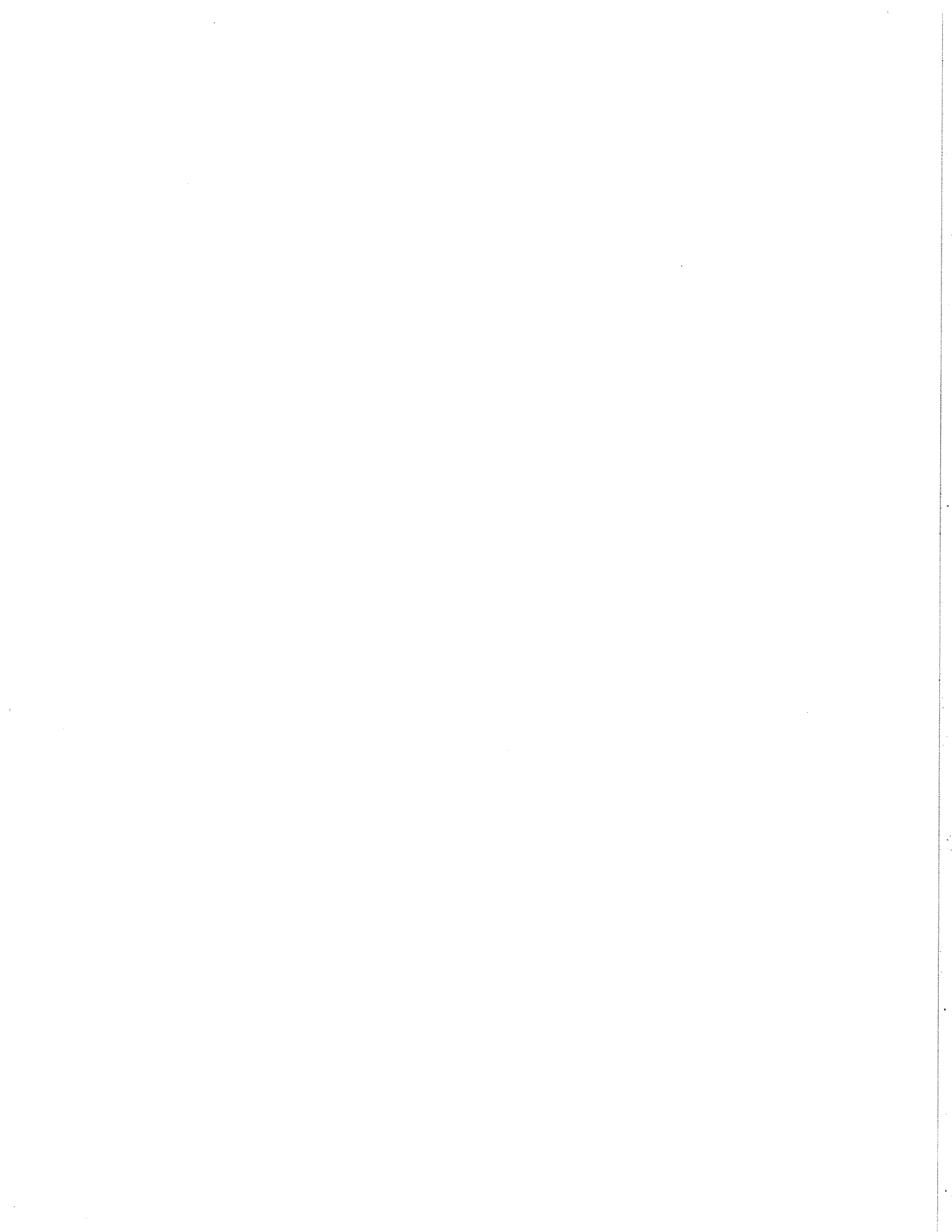
b) $EFE_{cycle} = \int_a^b \lambda di - \int_b^c \lambda di - \int_c^d \lambda di + \int_d^a \lambda di$

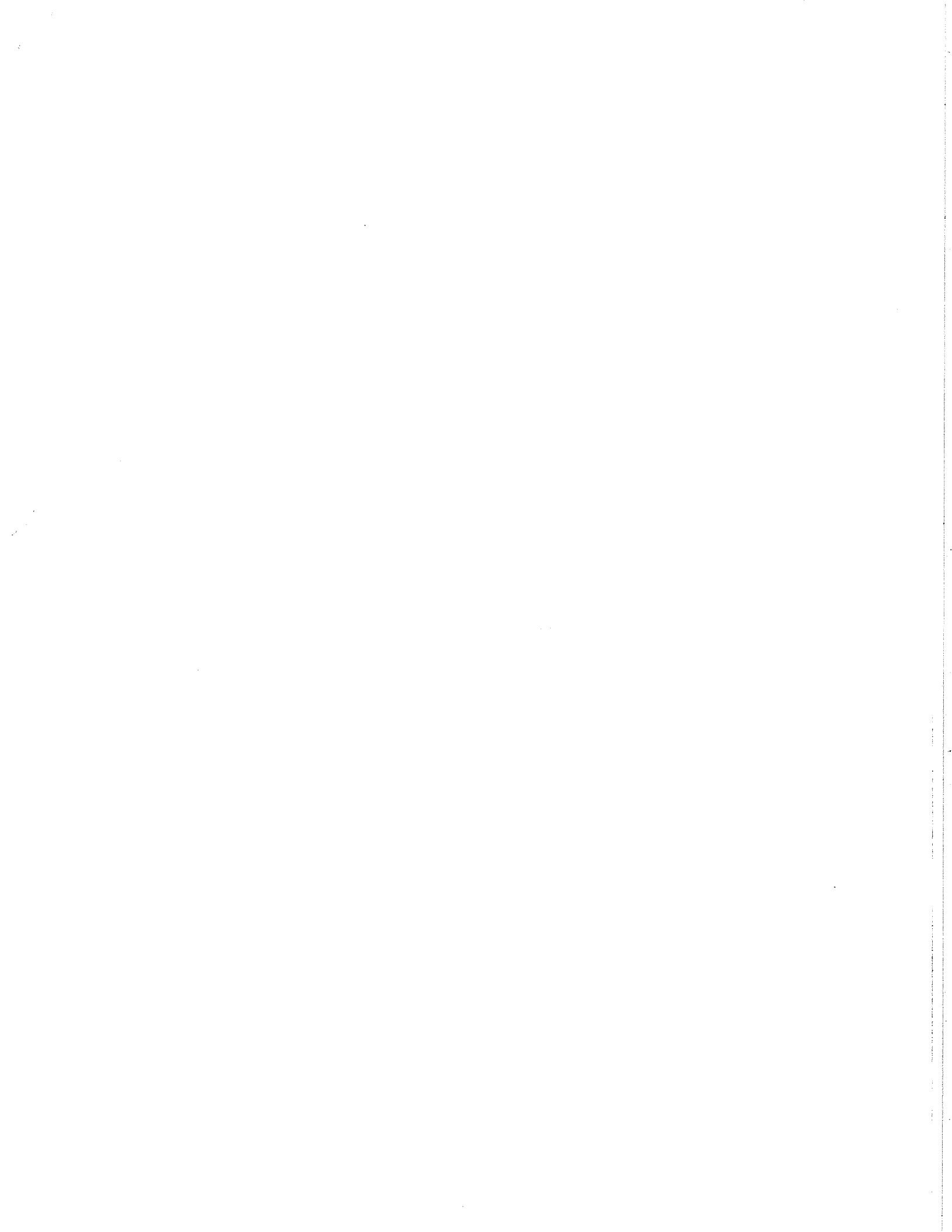
$= 6.5 - 9 - 8 + 5.5 = -5 \text{ J}$

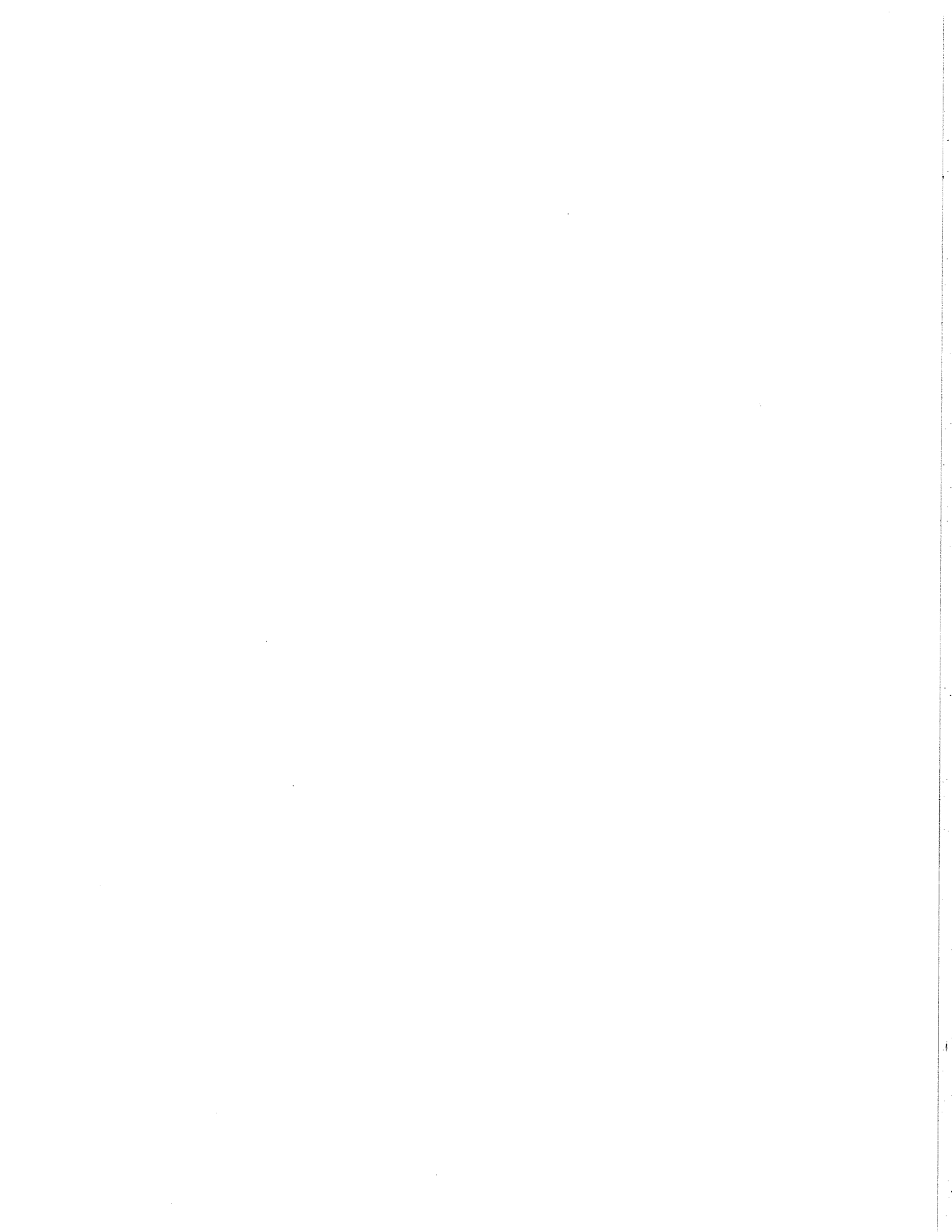
c) $EFM_{cycle} = -EPE_{cycle} = 5 \text{ J}$

d) $Efm > 0$ so generator

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Problem 4. (25 points.)

An electro-mechanical device has the following nonlinear dynamic model:

$$0.04 \frac{d^2 \delta}{dt^2} = 2 - 3 \sin \delta$$

- Write this model in standard state-space form.
- Find all of the equilibrium points in the interval with δ between -180 degrees and $+180$ degrees.
- Speculate on which of these equilibrium points might be stable (indicate why)
- Demonstrate that you might be right by using Euler's method on the nonlinear model with time step $\Delta t = 0.1$ s to compute the values of the two state variables at $t = 0.1$ s and $t = 0.2$ s if the initial conditions are $\delta(0) =$ the equilibrium angle you think is stable plus 1 degree and $d\delta/dt$ (at $t = 0$) = 0

$$\begin{aligned} \text{a)} \quad x_1 &= \delta & \dot{x}_1 &= x_2 \\ x_2 &= \frac{d\delta}{dt} & \dot{x}_2 &= 25x_2 - 25 \times 3 \sin x_1 \end{aligned}$$

$$\begin{aligned} \text{b)} \quad 0 &= x_{2e} & x_{2e} &= 0 \\ 0 &= 50 - 75 \sin x_{1e} & x_{1e} &= 41.8^\circ \text{ or } 138.2^\circ \end{aligned}$$

c) 41.81 is stable because if it moves a little to the right, the $\sin x_1$ gets bigger which will make \dot{x}_2 negative which will make x_2 negative, pulling it back. Reverse if it is 138.2°

$$\begin{aligned} \text{d)} \quad x_1(0.1) &= (41.81^\circ + 1^\circ) \frac{\pi}{180} + 0.1(0) = 42.81^\circ \frac{\pi}{180} \text{ radians} \\ x_2(0.1) &= 0 + (50 - 75 \sin 42.81^\circ) \times 0.1 = -0.968 \times 0.1 = -0.097 \frac{\text{rad}}{\text{sec}} \end{aligned}$$

$$x_1(0.2) = 42.81^\circ \frac{\pi}{180} + 0.1(-0.097) = 42.25^\circ \frac{\pi}{180} \text{ radians}$$

$$x_2(0.2) = -0.097 + 0.1(-.970) = -0.194 \text{ rad/sec}$$

yes, moving back

