ECE 330 POWER CIRCUITS AND ELECTROMECHANICS

LECTURE 8 TRANSFORMERS (2)

Acknowledgment-These handouts and lecture notes given in class are based on material from Prof. Peter Sauer's ECE 330 lecture notes. Some slides are taken from Ali Bazi's presentations

Disclaimer- These handouts only provide highlights and should not be used to replace the course textbook.

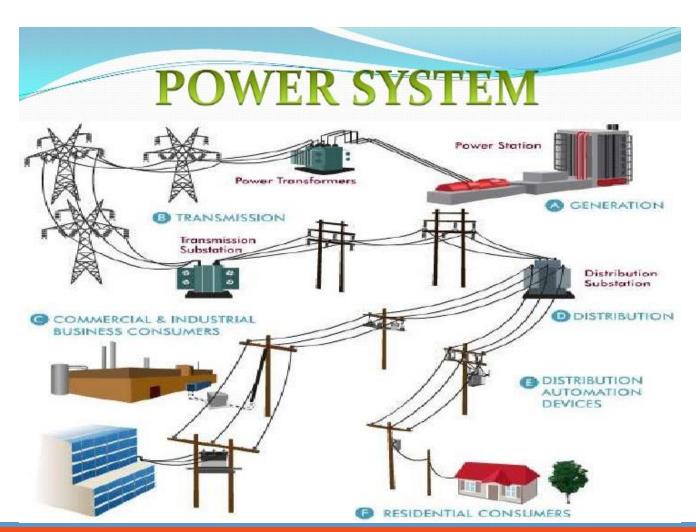


The power transformer is an essential component of the power system. It steps up the voltage at the generating point, transmits it over long distances, and

then steps it down at the sub-transmission and distribution levels for use by both commercial units and individual homes.



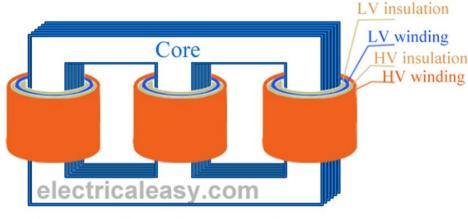
Source: torbosquid.com



A physical transformer consists of two windings mounted on a core, generally of a ferromagnetic material of high permeability.



Source: electronichub.org



Core type three phase transformer

Source: electricaleasy.com

- The construction of the core is such as to keep the leakage flux to a minimum.
- The winding to which power is supplied is called the "primary" winding, and the other one is called the "secondary" winding.
- In the case of power transformers, the terms high-voltage (HV) and low-voltage (LV) windings are also used, depending on the voltage levels.

We assume it to be an ideal transformer. This implies:

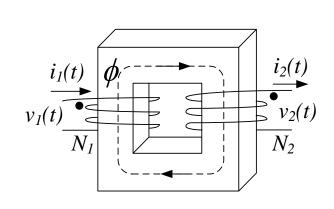
- No leakage flux.
- Winding resistances are neglected.
- Core has infinite permeability. Hence, reluctance of the core is zero and negligible current is required to set up the magnetic field.
- Magnetic core is lossless

- Power transformers are usually excited with sinusoidal voltages and currents.
- It is interesting to find the maximum flux, flux density, and current that a transformer can handle.

$$v_{1}(t) = V_{m1} \cos(\omega t) = N_{1} \frac{d\phi}{dt}$$

$$\Rightarrow \phi(t) = \frac{1}{N_{1}} \int V_{m1} \cos(\omega t) dt = \frac{V_{m1}}{\omega N_{1}} \sin(\omega t)$$

$$\Rightarrow \phi_{\text{max}} = \frac{V_{m1}}{\omega N_{1}} = \frac{V_{m1}}{2\pi f N_{1}}$$



• Also, $V_{m1} = 2\pi f \ N_1 \phi_{\text{max}}$ $\Rightarrow V_{1ms} = V_1 = \frac{V_{m1}}{\sqrt{2}} = \sqrt{2}\pi f \ N_1 \phi_{\text{max}} = 4.44f \ N_1 \phi_{\text{max}}$

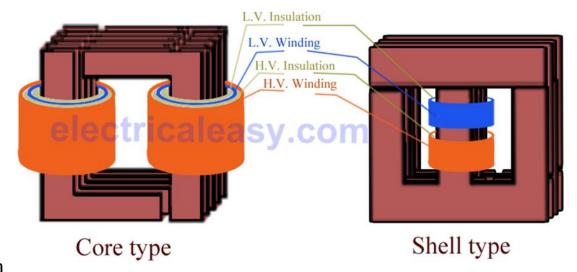
• Example: Coil 1 has 100 turns, operating at 60 Hz and $V_{rms} = 230$ V. The core area is 50 cm² and the core length is 25 cm. Find the maximum flux and flux density.

$$\phi_{\text{max}} = 8.64 \times 10^{-3} \ Wb$$

$$B_{\text{max}} = \frac{\phi_{\text{max}}}{A} = 1.728 \text{ Wb/m}^2$$

• Given that H = 600 A.turns/m at B_{max} , find the maximum current.

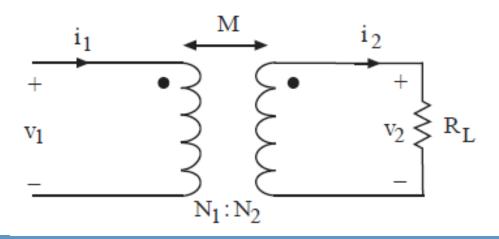
$$i_{\text{max}} = \frac{H \,\ell}{N} = 1.5 \ A$$



Source: electricaleasy.com

Consider the two-winding transformer. Let v_2 be the voltage across R_L . Let the resistances of the primary and secondary windings be R_1 and R_2 , respectively. Viewing the two windings as coupled coils, the

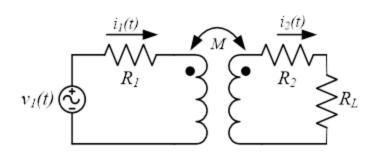
differential equations are written as





Source: machineequipmentonline.com

• Non-ideal:



VALENT CIRCUIT MODEL
$$\begin{cases} v_1 = R_1 i_1 + L_1 \frac{di_1}{dt} - M \frac{di_2}{dt} \\ 0 = R_2 i_2 + L_2 \frac{di_2}{dt} - M \frac{di_1}{dt} + i_2 R_L \\ v_2 = i_2 R_L \end{cases}$$
act $M di_1/dt$ to the first equation and

• Add and subtract *M di*₁/dt to the first equation and *M di*/*dt* to the second equation:

$$\begin{cases} v_{1} = R_{1}i_{1} + (L_{1} - M)\frac{di_{1}}{dt} + M\frac{di_{1}}{dt} - M\frac{di_{2}}{dt} \\ 0 = R_{2}i_{2} + (L_{2} - M)\frac{di_{2}}{dt} + M\frac{di_{2}}{dt} - M\frac{di_{1}}{dt} + i_{2}R_{L} \\ v_{2} = i_{2}R_{L} \end{cases}$$

$$\begin{cases} v_{1} = R_{1}i_{1} + (L_{1} - M)\frac{di_{1}}{dt} + M\frac{d}{dt}(i_{1} - i_{2}) \\ 0 = R_{2}i_{2} + (L_{2} - M)\frac{di_{2}}{dt} + M\frac{d}{dt}(i_{2} - i_{1}) + i_{2}R_{L} \\ v_{2} = i_{2}R_{L} \end{cases} \xrightarrow{R_{1}} \xrightarrow{L_{1} - M} \xrightarrow{R_{2}} \xrightarrow{L_{2} - M} \xrightarrow{i_{2}} \\ v_{1} \xrightarrow{L_{1} - M} \xrightarrow{i_{1}} v_{2} \xrightarrow{R_{L}} \end{cases}$$

What if $(L_1 - M)$ or $(L_2 - M) < 0$? There is something wrong.

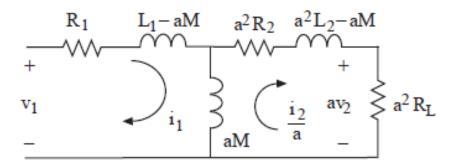
• We need to refer all impedances from side 2 to side 1:

$$i_2' = \frac{i_2}{a} =$$
, $Z_2' = a^2 Z_2$, $M' = a M$ (since M either sees i_1 or i_2).

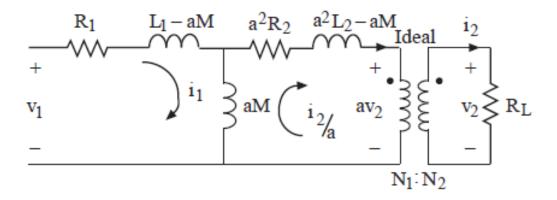
$$\begin{cases} v_1 = R_1 i_1 + L_1 \frac{di_1}{dt} - aM \frac{d}{dt} \left(\frac{i_2}{a} \right) \\ 0 = a^2 R_2 \left(\frac{i_2}{a} \right) + a^2 L_2 \frac{d \left(\frac{i_2}{a} \right)}{dt} - aM \frac{di_1}{dt} + \left(\frac{i_2}{a} \right) a^2 R_L \end{cases}$$

$$av_2 = \left(\frac{i_2}{a} \right) a^2 R_L$$

• The equivalent circuit becomes:



• If we wish to preserve R_L , the circuit becomes:



Losses:

Hysteresis losses due to the nonlinear multi-valued nature of the ϕ -i relationship of the actual core.

Hysteresis loss
$$P_h = K_h f B_m^n W$$

• B_m the maximum flux density, and n (often assumed to be 1.6) and are constants depending on the material of the core

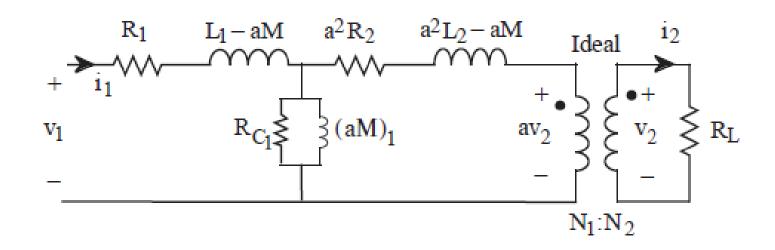
• Eddy current losses occurring in the laminations, resulting in an -type loss.

Eddy current loss
$$P_e = K_e f^2 B_m^2$$
 W

- K_e is a constant that depends on the resistivity of the material of the laminations
- The sum of these two losses represents the constant losses for the transformer and depends only on the value of B_m

• B_m depends on the applied voltage V_m

Losses are represented by means of a resistance R_c in parallel with the magnetizing inductance aM.



• What does $(L_1 - aM)$ mean? (and similarly the secondary term)?

$$\begin{split} L_1 i_1 &= N_1 \phi_{11}, \quad M i_1 = N_2 \phi_{21} \\ L_1 - a M &= \frac{N_1 \phi_{11}}{i_1} - \frac{a N_2 \phi_{21}}{i_1} = \frac{N_1}{i_1} \left(\phi_{11} - \phi_{21} \right) = \frac{N_1}{i_1} \phi_{l1} \end{split}$$

• Therefore, $(L_1 - aM)$ is a leakage term.

• $\omega(L_1 - aM) = X_{\ell_1}$ Leakage reactance of winding 1

$$\omega(aM) = X_{m_1}$$
 magnetizing reactance referred to winding 1

$$\omega(L_2 - M/a) = X_{\ell_2}$$
 Leakage reactance of winding 2

$$\omega(a^2 L_2 - aM) = a^2 X_{\ell_2}$$
 Leakage reactance of winding 2

referred to side 1

