

# Lecture 11: Frequency Response

ECE 401: Signal and Image Analysis

University of Illinois

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- 1 LTI Review
- 2 Frequency Response
- 3 Frequency Response of an Averager

# Outline

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# LTI Review

Is this system linear? Is it time-invariant? Can you prove your answers?

$$y[n] = x[n] + x[n + 5]$$

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# Frequency Response Example

Consider the system

$$y[n] = x[n - 1] + x[n] + x[n + 1]$$

Suppose the input is a cosine at some frequency  $\omega$ ,  
 $x[n] = \cos(\omega n)$ . Then the output is

$$y[n] = \cos(\omega(n - 1)) + \cos(\omega n) + \cos(\omega(n + 1))$$

Using the phasor method, we can write this as

$$\begin{aligned} y[n] &= \Re \{ e^{j\omega n} e^{-j\omega} + e^{j\omega n} + e^{j\omega n} e^{j\omega} \} \\ &= \Re \{ (e^{-j\omega} + 1 + e^{j\omega}) e^{j\omega n} \} \\ &= \Re \{ (1 + 2 \cos(\omega)) e^{j\omega n} \} = (1 + 2 \cos \omega) \cos(\omega n) \end{aligned}$$

So the output is a cosine at **exactly the same frequency**, but scaled by the frequency-dependent scaling factor

$$H(\omega) = 1 + 2 \cos \omega$$

# Frequency Response Derivation

Consider the LTI system

$$y[n] = x[n] * h[n] = \sum_{m=-\infty}^{\infty} h[m]x[n-m]$$

Suppose the input is  $x[n] = e^{j\omega n}$ . Then the output is

$$\begin{aligned} y[n] &= \sum_{m=-\infty}^{\infty} h[m]e^{j\omega(n-m)} = e^{j\omega n} \sum_{m=-\infty}^{\infty} h[m]e^{-j\omega m} \\ &= e^{j\omega n} H(\omega) \end{aligned}$$

So the output is a complex exponential at **exactly the same frequency**, but scaled by the complex-valued, frequency-dependent constant

$$H(\omega) = \sum_{m=-\infty}^{\infty} h[m]e^{-j\omega m}$$

# Frequency Response Definition

## Frequency Response Definition

$$H(\omega) = \sum_{m=-\infty}^{\infty} h[m]e^{-j\omega m}$$

## $x[n]$ = Complex Exponential

$$x[n] = e^{j\omega n} \rightarrow y[n] = H(\omega)x[n]$$



# Frequency Response: Sinusoidal Inputs

$x[n] = \text{Cosine}$

$$x[n] = \cos(\omega n) \rightarrow y[n] = |H(\omega)| \cos(\omega n + \angle H(\omega))$$

$x[n] = \text{Sine}$

$$x[n] = \sin(\omega n) \rightarrow y[n] = |H(\omega)| \sin(\omega n + \angle H(\omega))$$

where  $|H(\omega)|$  and  $\angle H(\omega)$  are just the magnitude and phase of  $H(\omega)$ , i.e.,

$$H(\omega) = |H(\omega)| e^{j\angle H(\omega)}$$

# Example: Averager = The Simplest Lowpass Filter

$$h[n] = \delta[n] + \delta[n - 1]$$

$$H(\omega) = \sum_{m=-\infty}^{\infty} h[m]e^{-j\omega m} = 1 + e^{-j\omega}$$

$$= e^{-j\omega/2}(e^{j\omega/2} + e^{-j\omega/2}) = 2e^{-j\omega/2} \cos(\omega/2)$$

So

$$|H(\omega)| = 2 \cos(\omega/2), \quad \angle H(\omega) = -\omega/2$$

Notice that  $H(0) = 1$ , while  $H(\pi) = 0$ , so this is a **lowpass filter**.

Thus if  $x[n] = \cos(\omega n)$  then

$$y[n] = \left(2 \cos\left(\frac{\omega}{2}\right)\right) \cos\left(\omega\left(n - \frac{1}{2}\right)\right) = \begin{cases} 2 \cos(\omega(n - 1/2)) & \omega = 0 \\ 0 & \omega = \pi \end{cases}$$

# Example: Euler Differencer = The Simplest Highpass Filter

$$h[n] = \delta[n] - \delta[n - 1]$$

$$H(\omega) = \sum_{m=-\infty}^{\infty} h[m]e^{-j\omega m} = 1 - e^{-j\omega}$$

$$= e^{-j\omega/2}(e^{j\omega/2} - e^{-j\omega/2}) = 2je^{-j\omega/2} \sin(\omega/2)$$

So

$$|H(\omega)| = 2 \sin(\omega/2), \quad \angle H(\omega) = \frac{\pi - \omega}{2}$$

Notice that  $H(0) = 0$ , while  $H(\pi) = 1$ , so this is a **highpass filter**.

Thus if  $x[n] = \cos(\omega n)$  then

$$y[n] = \left(2 \sin\left(\frac{\omega}{2}\right)\right) \cos\left(\omega\left(n - \frac{1}{2}\right) + \frac{\pi}{2}\right) = \begin{cases} 0 & \omega = 0 \\ 2 \sin(\omega(n - 1/2)) & \omega = \pi \end{cases}$$

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# Frequency Response of an Averager, in General

$$h[n] = u[n] - u[n - N] \quad \text{for some integer } N$$

$$H(\omega) = \sum_{m=-\infty}^{\infty} h[m]e^{-j\omega m} = \sum_{m=0}^{N-1} e^{-j\omega m}$$

In order to solve this one, we need to use Zeno's paradox, which can be stated as follows. For any fraction  $a$  such that  $|a| < 1$ ,

$$\sum_{m=0}^{\infty} a^m = \frac{1}{1-a}$$

(In the fable created by the ancient Greek philosopher Zeno of Elea, the fraction is  $a = \frac{1}{2}$ ).

$$\begin{aligned}
 H(\omega) &= \sum_{m=0}^{\infty} e^{-j\omega m} - \sum_{m=N}^{\infty} e^{-j\omega m} \\
 &= \sum_{m=0}^{\infty} e^{-j\omega m} - e^{-j\omega N} \sum_{m=0}^{\infty} e^{-j\omega m}
 \end{aligned}$$

using Zeno's paradox, we convert this to

$$\begin{aligned}
 &= \frac{1}{1 - e^{-j\omega}} - \frac{e^{-j\omega N}}{1 - e^{-j\omega}} \\
 &= \frac{1 - e^{-j\omega N}}{1 - e^{-j\omega}} = \left( \frac{e^{-j\omega N/2}}{e^{-j\omega/2}} \right) \left( \frac{e^{j\omega N/2} - e^{-j\omega N/2}}{e^{j\omega/2} - e^{-j\omega/2}} \right) \\
 &= e^{-j\omega \frac{(N-1)}{2}} \frac{\sin(\omega N/2)}{\sin(\omega/2)}
 \end{aligned}$$

# Frequency Response of an Averager

So the frequency response of this averager:

$$h[n] = u[n] - u[n - N] \quad \text{for some integer } N$$

is

$$H(\omega) = A(\omega)e^{-j\theta(\omega)}$$

where

$$A(\omega) = \left( \frac{\sin(\omega N/2)}{\sin(\omega/2)} \right) \quad \theta(\omega) = -\omega(N - 1)/2$$

# Frequency Response of an Averager

The **signed-amplitude response** of an averager has the following important characteristics

$$A(\omega) = \left( \frac{\sin(\omega N/2)}{\sin(\omega/2)} \right)$$

We call that the **signed-amplitude response** because it can be either positive or negative; we only require that it should be real. So it's not exactly the same thing as the magnitude of the complex number.

$$A(\omega) = \begin{cases} N & \omega = 0 \\ 0 & \omega = 2\pi\ell/N, \text{ any integer } \ell \neq 0 \end{cases}$$

In particular,  $H(\pi) = 0$ , so this is a lowpass filter. We could say that the  $N$ -point averager is much more lowpass than the 2-point averager; its **cutoff frequency** is  $\omega = 2\pi/N$ .



# Linear Phase

The **phase response** of an averager has the following important characteristic:

$$\theta(\omega) = -\omega(N - 1)/2$$

Notice that this phase is a **linear** function of  $\omega$  (we say the filter has **generalized linear phase**). In general, a linear phase filter is one whose phase response looks like

$$\theta(\omega) = -\omega d$$

for any constant  $d$ . The constant  $d$  is called the **filter delay**, because

$$x[n] = \cos(\omega n) \rightarrow y[n] = A(\omega) \cos(\omega(n - d))$$

So the filter acts as though it **delays** the input, by a delay of  $d$  samples.