ECE 420 Lecture 4 Feb 11 2019

Signal Resampling

- General problem statement:
	- We have samples of a signal
	- These aren't the sample positions we want
		- Different sampling rate
		- Different sampling locations
		- Both of the above
- What algorithms can we use to synthesize the signal at the desired output locations?

Rate Changing Operators - Upsampler

- Performs zero insertion on the signal
	- Add K-1 zeros between each sample
- Always 'safe' as we do not lose any data

Rate Changing Operators - Upsampler

- "Compresses" spectrum by a factor of K
	- $Y(\omega) = X(\omega K)$
- Introduces aliased copies
- How can we eliminate aliased spectra?

Rate Changing Operators - Downsampler

- Reduce the number of samples in the signal
	- Keep first sample out of every batch of K samples
- Potentially unsafe as we are discarding samples

$$
x \longrightarrow \boxed{\downarrow K} \longrightarrow y
$$

Rate Changing Operators - Downsampler

• "Expands" spectrum by a factor of K

$$
Y(\omega) = \frac{1}{K} \sum_{k=0}^{K-1} X(\frac{\omega - 2\pi k}{K})
$$

• Potential for aliasing to occur. Caution!

Rate Changing Operators - Downsampler

• How can we prevent aliased spectra?

Rate Changing – Fractional Rates

- Upsampling/downsampling operations defined for integer K
- How can you implement arbitrary fractional rates?
	- Cascade of Upsampler (rate M) followed by Downsampler (rate K)
	- Effective rate change of M/K
	- Why upsampling first?

Upsampling as Interpolation

- Another interpretation of upsampling with an LPF is an interpolation operation
- Interpolation kernel is the impulse response of the LPF
- Interpolated signal is this IR centered at each upsampled sample position and added together

Direct Interpolation

- Efficient filtering works for integer upsampling due to consistency of relative offset of desired sample locations to input sample locations
- For rational rate changes this is not the case
- We can still use the interpolation interpretation to directly resample the signal at arbitrary positions
- Can be costly due to large support of interpolation kernel

Alternate interpolation basis

- Generally speaking, recast the problem as a D-to-A-to-D
	- $x(t) = \sum x[k] \phi(t k)$
- Therefore we can resample at an arbitrary position of x by evaluating x(t) at the desired non-integer t positions

•
$$
y[n] = x(\tau_n) = \sum x[k]\phi(\tau_n - k)
$$

- Assuming $\phi(t)$ has small support, only a small number of samples in $x[n]$ are required
- Linear interpolation (or 'tent function') is one such option

Spline Interpolation Basis

Splines are recursively defined

•
$$
\beta_0(t) = \begin{cases} 1 & |t| \leq \frac{1}{2} \\ 0 & |t| > \frac{1}{2} \end{cases}
$$

•
$$
\beta_n(t) = \beta_{n-1}(t) * \beta_0(t)
$$

- β_0 is a box, β_1 is a tent, higher orders are progressively smoother, with more regularity
- Can provide good interpolation performance at reasonable computational cost
- Higher order splines no longer an interpolating function
	- Must perform a spline transform first

Interpolation Comparison

TD-PSOLA

- TD Time domain
	- Operating directly on the signal samples, no domain transformation
- PS Pitch Synchronous
	- Operations revolve around reference points (epoch markers or pitch-marks) corresponding to the input or desired pitch of the signal
- OLA Overlap-Add
	- The synthesized signal is produced by signals positioned about the pitch-marks, where those signals overlap and are added together to form the final output
- Prosody/Prosodic Patterns of stress and intonation in a language

Speech Synthesis Model

- Speech production initiated as a pulse train
- Vocal tract / mouth / tongue / etc. create a transfer function
- Spoken voice is a 'convolution' of these functions

Pitch-synchronous Manipulation

- Let production model be $y[n] = x[n] * h[n]$
- Spacing of the pulses/delta functions defines pitch of the signal
- Main idea behind pitch synchronous processing is to
	- Identify delta locations of $x[n]$ and filter $h[n]$
	- Manipulate the delta locations to alter the signal to have the desired characteristics
	- Resynthesize the modified signal by reapplying $h[n]$
- For example, if we want to change the pitch to a new value \hat{P}
	- $\hat{x}[n] = \sum \delta[n \hat{P}k]$
	- $\hat{y}[n] = \hat{x}[n] * h[n] = \sum h[n \hat{P}k]$

Types of Pitch-Synchronous Modifications

- Pitch-scale modifications
	- Modify the pitch of the signal to a desired target pitch
	- Focus of the lab
- Time-scale modifications
	- Modify the time extent of the signal without changing the pitch
- Pitch- and time- scale modifications
	- Can be done as a cascade of operations or jointly
	- Jointly allows us to skip reprocessing of the signal and manipulate the delta positions in one step

Challenges

- Varying pitch over time
	- Even variation with a 'constant' pitch region
- Variations in speech waveform over time
	- Uniform $h[n]$ assumption does not hold
- Preventing distortions in the synthesized signal
- Block processing of the audio frames

Epoch Definition

- We want to extract the delta positions
- While mostly regular, they do not follow an exact spacing
- Also $h[n]$ varies with time
- Attempt to pick a consistent point within each $h[n]$
	- Denote this the epoch or pitch-mark
	- Strategy: search for the maximum value within each estimated pitch interval

Epoch Mapping

- Establish relationship between input and output epoch points
- Input epochs: from pitch / waveform analysis
- Output epochs: regularly spaced positions at target pitch / time duration
- Algorithm: For each output epoch location, find the nearest input epoch location

Signal Synthesis

- To accommodate variations in $h[n]$, estimate over two adjacent periods
- Window $h[n]$ to taper transitions
- Position at output epoch points
- Combine all outputs together to form synthesized signal

Block Processing Challenges

- Data is broken up into blocks/frames of data for processing due to practical reasons
	- **Memory**
	- **Responsiveness**
- Depending on the algorithm, there may be dependencies among blocks of data
- How can we address this problem?
	- Buffering!
- Be aware of impact on
	- **Memory Footprint**
	- Latency

Overlap-Add

- Consider a filtering operation application
- Application of the filter to a frame of data will result in an output wider than the input frame
- Buffer this output in a larger 'working' output buffer and aggregate block outputs
- Send off an output block once all contributions are complete

Overlap-Save

- As opposed to buffering outputs we can instead buffer inputs
- 'Work backwards' from a given output block to determine what input data is required to produce it
- Buffer all input data that falls outside of block boundaries

PSOLA Block Processing

- Two main issues that arise from framing the data
	- Depending on epochs selected, windowed interval may stretch across multiple input frames
	- After repositioning on output epoch location, windowed response may stretch across multiple output frames

PSOLA Block Processing

- Approach: Keep buffer of input blocks and output blocks
	- Denoted 'past', 'present', and 'future'
- Determine contributions for output epoch points in the 'Present'
- Allow impulse response to spill over into 'Past' and 'Future'
- After all 'Present' points processed 'Past' will be complete, ready to emit

• Shift down Present to Past and Future to Present

Pitch Synthesis Algorithm Summary

PSOLA Variations

- Linear Prediction PSOLA
	- Effectively tries to model $h[n]$ and decompose speech to find excitation signal $x[n]$
	- Manipulate $x[n]$ as desired and then reapply filter to synthesize speech
- Fourier-Domain PSOLA
	- Perform STFT on pitch periods
	- Estimate spectral envelope of speech and divide out
	- Modify pitch harmonics
	- Reapply spectral envelope and inverse STFT

This week

- Lab 4: Pitch Analyzer Quiz/Demo
- Lab 5: Pitch Synthesizer
	- Linked video recommended!
- Be thinking about Assigned Project Labs / Groups
	- Proposal due March 1