ECE 420 Lecture 4 Feb 11 2019

Signal Resampling

- General problem statement:
 - We have samples of a signal
 - These aren't the sample positions we want
 - Different sampling rate
 - Different sampling locations
 - Both of the above
- What algorithms can we use to synthesize the signal at the desired output locations?

Rate Changing Operators - Upsampler

- Performs zero insertion on the signal
 - Add K-1 zeros between each sample
- Always 'safe' as we do not lose any data



Rate Changing Operators - Upsampler

- "Compresses" spectrum by a factor of K
 - $Y(\omega) = X(\omega K)$
- Introduces aliased copies
- How can we eliminate aliased spectra?



Rate Changing Operators - Downsampler

- Reduce the number of samples in the signal
 - Keep first sample out of every batch of K samples
- Potentially unsafe as we are discarding samples

$$x \longrightarrow \fbox{} K \longrightarrow y$$



Rate Changing Operators - Downsampler

• "Expands" spectrum by a factor of K

$$Y(\omega) = \frac{1}{K} \sum_{k=0}^{K-1} X(\frac{\omega - 2\pi k}{K})$$

• Potential for aliasing to occur. Caution!



Rate Changing Operators - Downsampler

• How can we prevent aliased spectra?



Rate Changing - Fractional Rates

- Upsampling/downsampling operations defined for integer K
- How can you implement arbitrary fractional rates?
 - Cascade of Upsampler (rate M) followed by Downsampler (rate K)
 - Effective rate change of *M*/*K*
 - Why upsampling first?



Upsampling as Interpolation

- Another interpretation of upsampling with an LPF is an interpolation operation
- Interpolation kernel is the impulse response of the LPF
- Interpolated signal is this IR centered at each upsampled sample position and added together



Direct Interpolation

- Efficient filtering works for integer upsampling due to consistency of relative offset of desired sample locations to input sample locations
- For rational rate changes this is not the case
- We can still use the interpolation interpretation to directly resample the signal at arbitrary positions
- Can be costly due to large support of interpolation kernel



Alternate interpolation basis

- Generally speaking, recast the problem as a D-to-A-to-D
 - $x(t) = \sum x[k]\phi(t-k)$
- Therefore we can resample at an arbitrary position of x by evaluating x(t) at the desired non-integer t positions

•
$$y[n] = x(\tau_n) = \sum x[k]\phi(\tau_n - k)$$

- Assuming \(\phi(t)\) has small support, only a small number of samples in \(x[n]\) are required
- Linear interpolation (or 'tent function') is one such option





Spline Interpolation Basis

Splines are recursively defined

•
$$\beta_0(t) = \begin{cases} 1 & |t| \le \frac{1}{2} \\ 0 & |t| > \frac{1}{2} \end{cases}$$

•
$$\beta_n(t) = \beta_{n-1}(t) * \beta_0(t)$$

- β_0 is a box, β_1 is a tent, higher orders are progressively smoother, with more regularity
- Can provide good interpolation performance at reasonable computational cost
- Higher order splines no longer an interpolating function
 - Must perform a spline transform first



Interpolation Comparison



TD-PSOLA

- TD Time domain
 - Operating directly on the signal samples, no domain transformation
- PS Pitch Synchronous
 - Operations revolve around reference points (epoch markers or pitch-marks) corresponding to the input or desired pitch of the signal
- OLA Overlap-Add
 - The synthesized signal is produced by signals positioned about the pitch-marks, where those signals overlap and are added together to form the final output
- Prosody/Prosodic Patterns of stress and intonation in a language

Speech Synthesis Model

- Speech production initiated as a pulse train
- Vocal tract / mouth / tongue / etc. create a transfer function
- Spoken voice is a 'convolution' of these functions



Pitch-synchronous Manipulation

- Let production model be y[n] = x[n] * h[n]
- Spacing of the pulses/delta functions defines pitch of the signal
- Main idea behind pitch synchronous processing is to
 - Identify delta locations of x[n] and filter h[n]
 - Manipulate the delta locations to alter the signal to have the desired characteristics
 - Resynthesize the modified signal by reapplying h[n]
- For example, if we want to change the pitch to a new value \hat{P}
 - $\hat{x}[n] = \sum \delta[n \hat{P}k]$
 - $\hat{y}[n] = \hat{x}[n] * h[n] = \sum h[n \hat{P}k]$

Types of Pitch-Synchronous Modifications

- Pitch-scale modifications
 - Modify the pitch of the signal to a desired target pitch
 - Focus of the lab
- Time-scale modifications
 - Modify the time extent of the signal without changing the pitch
- Pitch- and time- scale modifications
 - Can be done as a cascade of operations or jointly
 - Jointly allows us to skip reprocessing of the signal and manipulate the delta positions in one step

Challenges

- Varying pitch over time
 - Even variation with a 'constant' pitch region
- Variations in speech waveform over time
 - Uniform *h*[*n*] assumption does not hold
- Preventing distortions in the synthesized signal
- Block processing of the audio frames

Epoch Definition

- We want to extract the delta positions
- While mostly regular, they do not follow an exact spacing
- Also *h*[*n*] varies with time
- Attempt to pick a consistent point within each h[n]
 - Denote this the epoch or pitch-mark
 - Strategy: search for the maximum value within each estimated pitch interval



Epoch Mapping

- Establish relationship between input and output epoch points
- Input epochs: from pitch / waveform analysis
- Output epochs: regularly spaced positions at target pitch / time duration
- Algorithm: For each output epoch location, find the nearest input epoch location





Signal Synthesis

- To accommodate variations in h[n], estimate over two adjacent periods
- Window h[n] to taper transitions
- Position at output epoch points
- Combine all outputs together to form synthesized signal



Block Processing Challenges

- Data is broken up into blocks/frames of data for processing due to practical reasons
 - Memory
 - Responsiveness
- Depending on the algorithm, there may be dependencies among blocks of data
- How can we address this problem?
 - Buffering!
- Be aware of impact on
 - Memory Footprint
 - Latency

Overlap-Add

- Consider a filtering operation application
- Application of the filter to a frame of data will result in an output wider than the input frame
- Buffer this output in a larger 'working' output buffer and aggregate block outputs
- Send off an output block once all contributions are complete



Overlap-Save

- As opposed to buffering outputs we can instead buffer inputs
- 'Work backwards' from a given output block to determine what input data is required to produce it
- Buffer all input data that falls outside of block boundaries



PSOLA Block Processing

- Two main issues that arise from framing the data
 - Depending on epochs selected, windowed interval may stretch across multiple input frames
 - After repositioning on output epoch location, windowed response may stretch across multiple output frames



PSOLA Block Processing

- Approach: Keep buffer of input blocks and output blocks ٠
 - Denoted 'past', 'present', and 'future'
- Determine contributions for ۲ output epoch points in the 'Present'
- Allow impulse response to spill over into 'Past' and 'Future'
- After all 'Present' points processed • 'Past' will be complete, ready to emit



Shift down Present to Past and Future to Present ۲



Pitch Synthesis Algorithm Summary



PSOLA Variations

- Linear Prediction PSOLA
 - Effectively tries to model h[n] and decompose speech to find excitation signal x[n]
 - Manipulate x[n] as desired and then reapply filter to synthesize speech
- Fourier-Domain PSOLA
 - Perform STFT on pitch periods
 - Estimate spectral envelope of speech and divide out
 - Modify pitch harmonics
 - Reapply spectral envelope and inverse STFT

This week

- Lab 4: Pitch Analyzer Quiz/Demo
- Lab 5: Pitch Synthesizer
 - Linked video recommended!
- Be thinking about Assigned Project Labs / Groups
 - Proposal due March 1