# CS440/ECE448 Lecture 14: Bayesian Networks

Mark Hasegawa-Johnson
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#### Outline

- Review: Bayesian classifier
- The Los Angeles burglar alarm example
- Bayesian network: A better way to represent knowledge
- Inference using a Bayesian network
- Independence and Conditional independence

#### Review: Bayesian Classifier

- Class label Y = y, drawn from some set of labels
- Observation X = x, drawn from some set of features
- Bayesian classifier: choose the class label, y, that minimizes your probability of making a mistake:

$$f(x) = \underset{y}{\operatorname{argmax}} P(Y = y | X = x)$$

# Today: What if P(X,Y) is complicated, and the naïve Bayes assumption is unreasonable?

- Example: Y is a scalar, but  $X = [X_1, ..., X_{100}]^T$  is a vector
- Then, even if every variable is binary, P(Y=y|X=x) is a table with  $2^{101}$  numbers. Hard to learn from data; hard to use.
- The naïve Bayes assumption simplified the problem as

$$P(X_1, ..., X_{100}|Y) \approx \prod_{i=1}^{n} P(X_i|Y)$$

- ... but what if that assumption is unreasonable? Do we then have no alternative besides learning all  $2^{101}$  probabilities?
- Today: an alternative called a Bayesian network

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#### The Los Angeles burglar alarm example

- Suppose I have a house in LA. I'm in Champaign.
- My phone beeps in class: I have messages from both of my LA neighbors, John and Mary.
- Does getting messages from both John and Mary mean that my burglar alarm is going off?
- If my burglar alarm is going off, does that mean my house is being robbed, or is it just an earthquake?



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#### Variables

- B = T if my house is being burglarized, else  $B = \bot$
- $E=\top$  if there's an earthquake in LA right now, else  $E=\bot$
- A = T if my alarm is going off right now, else  $A = \bot$
- J = T if John is texting me, else  $J = \bot$
- M = T if Mary is texting me, else  $M = \bot$

#### Inference Problem

- Given that  $J={\sf T}$  and  $M={\sf T}$ , I want to know what is the probability that I'm being burglarized
- In other words, what is P(B = T | M = T, J = T)
- How on Earth would I estimate that probability? I don't know how to estimate that.

#### Available Knowledge

- LA has 1 million houses & 41 burglaries/day:  $Pr(B = T) = \frac{41}{1000000}$
- There are ~20 earthquakes/year:  $P(E = T) = \frac{20}{365}$
- My burglar alarm is pretty good:

|              | $B = \bot$ , $E = \bot$ | $B = \bot, E = \top$ | $B = T, E = \bot$ | B = T, E = T     |
|--------------|-------------------------|----------------------|-------------------|------------------|
| P(A = T B,E) | 1                       | 3                    | 99                | 99               |
|              | $\overline{100}$        | <u>-</u><br>5        | $\overline{100}$  | $\overline{100}$ |

- John would text if there was an alarm:  $P(J = T|A = T) = \frac{9}{10}$
- On days with no alarm, he often sends cat videos:  $P(J = T | A = \bot) = \frac{1}{2}$

#### Combining the Available Knowledge

Putting it all together, we have ... well, we have a big mess. And that's not including the variable M:

|                                      | $B = \bot$  | B = T  |
|--------------------------------------|---|--|
| $P(B, E = \bot, A = \bot, J = \bot)$ | $\left(\frac{999959}{1000000}\right) \left(\frac{345}{365}\right) \left(\frac{99}{100}\right) \left(\frac{1}{2}\right)$ | $\left(\frac{41}{1000000}\right) \left(\frac{345}{365}\right) \left(\frac{99}{100}\right) \left(\frac{1}{2}\right)$  |
| $P(B, E = \bot, A = \bot, J = \top)$ | $\left(\frac{999959}{1000000}\right) \left(\frac{345}{365}\right) \left(\frac{99}{100}\right) \left(\frac{1}{2}\right)$ | $\left(\frac{41}{1000000}\right) \left(\frac{345}{365}\right) \left(\frac{99}{100}\right) \left(\frac{1}{2}\right)$  |
| $P(B, E = \bot, A = \top, J = \bot)$ | $\left(\frac{999959}{1000000}\right)\left(\frac{345}{365}\right)\left(\frac{1}{100}\right)\left(\frac{1}{10}\right)$    | $\left(\frac{41}{1000000}\right) \left(\frac{345}{365}\right) \left(\frac{1}{100}\right) \left(\frac{1}{10}\right)$  |
| $P(B, E = \bot, A = \top, J = T)$    | $\left(\frac{999959}{1000000}\right)\left(\frac{345}{365}\right)\left(\frac{1}{100}\right)\left(\frac{9}{10}\right)$    | $\left(\frac{41}{1000000}\right) \left(\frac{345}{365}\right) \left(\frac{99}{100}\right) \left(\frac{9}{10}\right)$ |
| i i                                  | :   | <b>:</b>   |

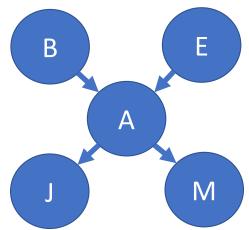
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Bayesian network: A better way to represent knowledge

A Bayesian network is a graph in which:

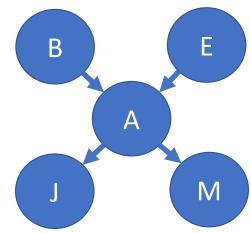
- Each variable is a node.
- An arrow between two nodes means that the child depends on the parent.
- If the child has no direct dependence on the parent, then there is no arrow.



Bayesian network: A better way to represent knowledge

For example, this graph shows my knowledge that:

- My alarm rings if there is a burglary or an earthquake.
- John is more likely to call if my alarm is going off.
- Mary is more likely to call if my alarm is going off.



Complete description of my knowledge about the burglar alarm

| P(B = T) | 41                   |
|----------|----------------------|
|          | $\overline{1000000}$ |

| P(E = T) | 20  |
|----------|-----|
|          | 365 |

| $E = \bot$ | B = T, $E = T$ |  |
|------------|----------------|--|
| _          | 0.0            |  |

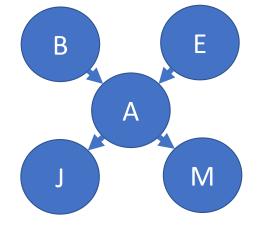
|               | $B = \bot$ , $E = \bot$ | $B = \bot$ , $E = \top$ | $B = T, E = \bot$ | B = T, E = T     |
|---------------|-------------------------|-------------------------|-------------------|------------------|
| P(A = T B, E) | 1                       | 3                       | 99                | 99               |
|               | $\overline{100}$        | <del>-</del> 5          | $\overline{100}$  | $\overline{100}$ |

|            | $A = \bot$               | A = T           |
|------------|--------------------------|-----------------|
| P(J = T A) | 1                        | 9               |
|            | $\frac{\overline{2}}{2}$ | $\overline{10}$ |

|            | $A = \bot$ | A = T |
|------------|------------|-------|
| P(M = T A) | 1          | 7     |
| , ,        | 8          | 8     |

#### Space complexity

- Without the Bayes network, space complexity is  $O(v^n)$ 
  - $v = \max \text{ cardinality of each variable}$
  - n = total # of variables
- With the Bayes network, space complexity is  $\mathcal{O}\{nv^p\}$ 
  - $p = \max \#$  parents any variable is allowed to have



#### Space complexity

- This is a Bayes network to help diagnose problems with your car's audio system.
- Naïve method: 41 binary variables, so the distribution is a table with  $2^{41} \approx 2 \times 10^{12}$  entries.
- Bayes network: each variable has at most four parents, so the whole distribution can be described by less than  $41\times2^4=656$  numbers.

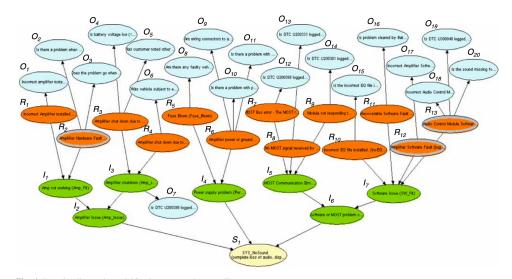


Fig. 6 Bayesian diagnostic model for the symptom "no sound"

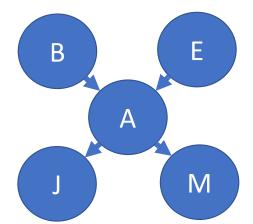
Huang, McMurran, Dhadyalla & Jones, "Probability-based vehicle fault diagnosis: Bayesian network method," 2008

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#### Inference

Both John and Mary texted me. Am I being burglarized?

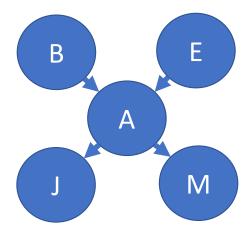


$$P(B = T|J = T, M = T) = \frac{P(B = T, J = T, M = T)}{P(B = T, J = T, M = T) + P(B = \bot, J = T, M = T)}$$

$$P(B = T, J = T, M = T) = \sum_{e=T}^{\perp} \sum_{a=T}^{\perp} P(B = T, E = e, A = a, J = T, M = T)$$

$$= \sum_{a=T}^{L} \sum_{a=T}^{L} P(B=T)P(E=e)P(A=a|B=T,E=e)P(J=T|A=a)P(M=T|A=a)$$

#### Time Complexity



- Using a Bayes network doesn't usually change the time complexity of a problem.
- If computing  $P(B = \top | J = \top, M = \top)$  required considering  $\mathcal{O}\{v^n\}$  possibilities without a Bayes network, it still requires considering  $\mathcal{O}\{v^n\}$  possibilities

#### Some unexpected conclusions

 Burglary is so unlikely that, even if both Mary and John call, it is still more probable that a burglary didn't happen

$$P(B = \top | J = \top, M = \top) < P(B = \bot | J = \top, M = \top)$$

The probability of an earthquake is higher!

$$P(B = T|J = T, M = T) < P(E = T|J = T, M = T)$$

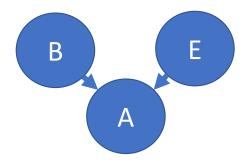
#### Quiz

Try the quiz!

#### Outline

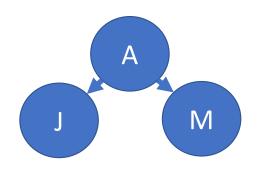
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#### Independence: No shared ancestors



- The variables B and E are independent
- Days with earthquakes and days w/o earthquakes have the same number of burglaries: P(B = T | E = T) = P(B = T | E = T) = P(B = T).

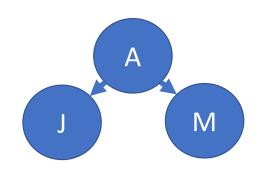
#### Shared ancestor = Not independent



- The variables J and M are not independent!
- If you know that John texted, that tells you that there was probably an alarm.
   Knowing that there was an alarm tells you that Mary will probably text you too:

$$P(M = T|J = T) \neq P(M = T|J = \bot)$$

## Conditional Independence if the Connection is Cut

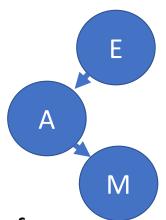


- The variables J and M are conditionally independent of one another given knowledge of A
- If you know that there was an alarm, then knowing that John texted gives no extra knowledge about whether Mary will text:

$$P(M = \top | J = \top, A = \top) = P(M = \top | J = \bot, A = \top) = P(M = \top | A = \top)$$

Our knowledge of A "cuts the connection" between J and M

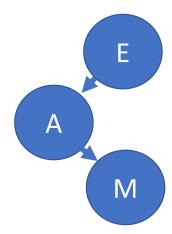
#### Shared ancestor = Not independent



- The "shared ancestor" rule also applies when the shared ancestor of one variable is the descendant of the other
- For example, the variables E and M are not independent! M's ancestor, A, is the descendant of E.
- If you know that Mary texted, that tells you that there was probably an alarm. Knowing that there was an alarm tells you that there is a >50% probability that there was an earthquake:

$$P(E = T|M = T) \neq P(E = T|M = \bot)$$

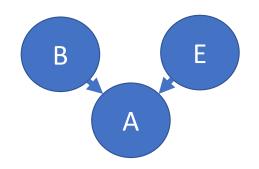
### Conditional Independence if the Connection is Cut



- The variables E and M are conditionally independent of one another given knowledge of A
- If you know that there was an alarm, then knowing that Mary texted gives no extra knowledge about the existence of an earthquake:

$$P(E = T | M = T, A = T) = P(E = T | M = \bot, A = T) = P(E = T | A = T)$$

# Independent variables may not be conditionally independent!



- The variables B and E are not conditionally independent of one another given knowledge of A
- If your alarm is ringing, then you probably have an earthquake <u>OR</u> a burglary.
   If there is an earthquake, then the conditional probability of a burglary goes down:

$$P(B = T | E = T, A = T) \neq P(B = T | E = \bot, A = T)$$

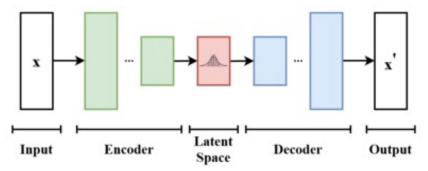
 This is called the "explaining away" effect. The earthquake "explains away" the alarm, so you become less worried about a burglary.

# Knowing about Independence and Conditional Independence can improve time complexity

 Improve time complexity by specifying the value of a shared ancestor: cuts the network into conditionally independent halves

• Example: Variational Autoencoder. Given the latent variable, the encoder and decoder are conditionally independent, can be solved with less time

complexity



https://commons.wikimedia.org/wiki/File:VAE\_Basic.png

#### Summary

- Bayesian network: A better way to represent knowledge
  - Reduces space complexity from  $\mathcal{O}\{v^n\}$  to  $\mathcal{O}\{nv^p\}$  -- huge if  $n\gg p$
  - Does not automatically reduce time complexity.
- Key ideas: Independence and Conditional independence

|                              |     | Shared Ancestor (of at least one)?                  |  |  |
|------------------------------|-----|---|--|--|
|                              |     | No  | Yes  |  |
| Shared Descendant (of both)? | No  | Independent   | Dependent unless shared ancestor value is known                                  |  |
| ,                            | Yes | Independent unless shared descendant value is known | Dependent unless shared ancestor value known AND shared descendant value unknown |  |