ECE 598HH: Advanced Wireless Networks and Sensing Systems

Lecture 12: Wireless Sensing Part 1
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WiVi: Tracking People Through Walls with WiFi

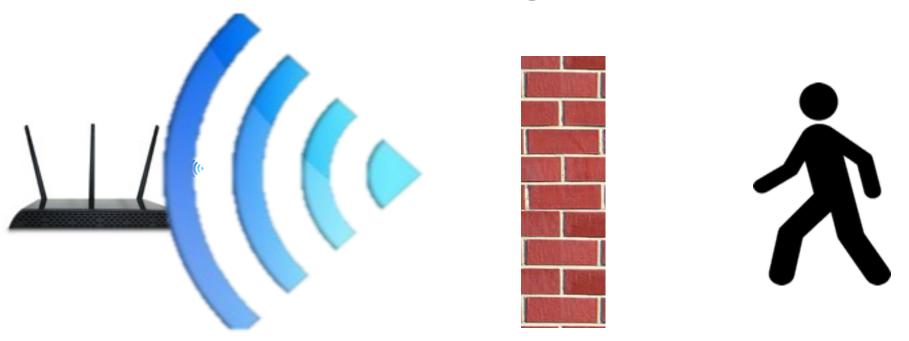
Key Idea







Challenges



Challenge #1: Wall reflection is 10,000x stronger than any reflections coming from behind the wall

Challenge #2: Tracking people from their reflections

How Can We Eliminate the Wall's Reflection?

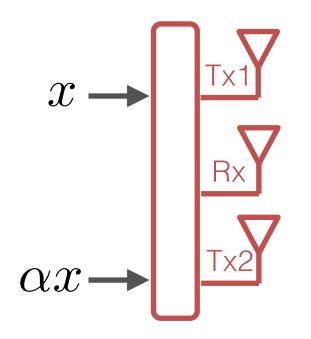
Idea: Transmit two waves that cancel each other when they reflect off static objects but not moving objects

Wall is static disappears

People tend detectable to move

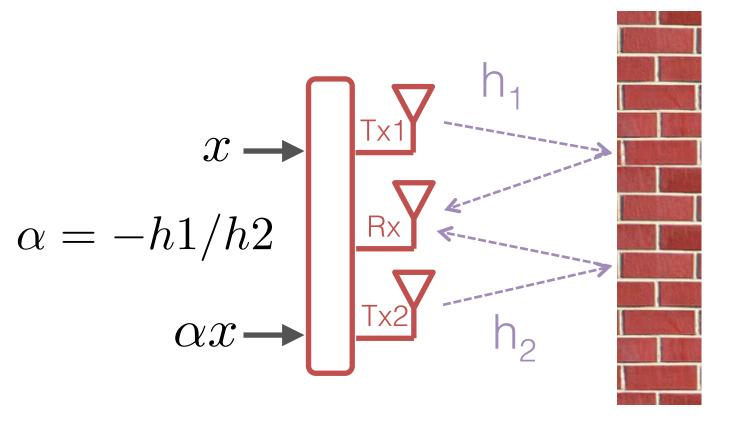
Eliminating the Wall's Reflection

Two transmit antennas and one receive antenna

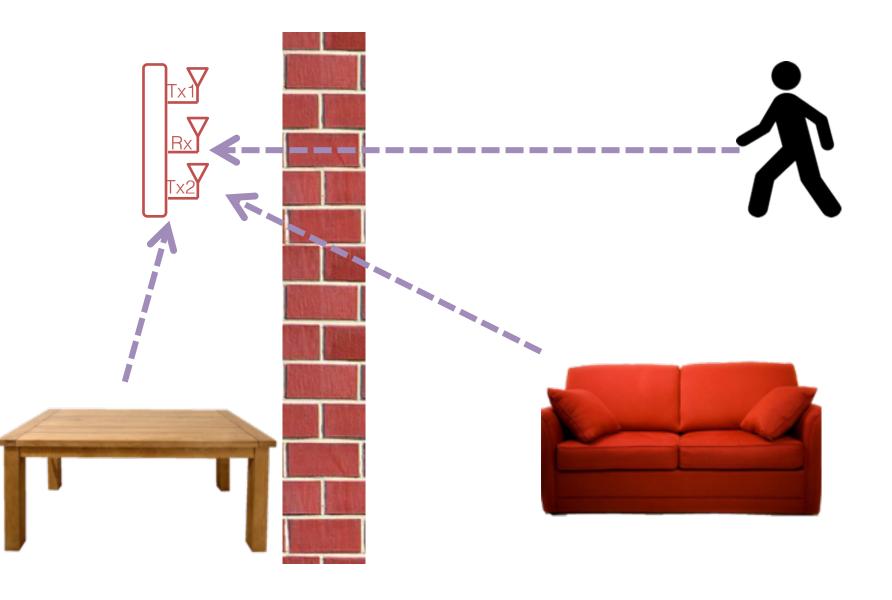


Eliminating the Wall's Reflection

Received signal: $y = h_1 x + h_2 \alpha x$



Eliminating All Static Reflections



Eliminating All Static Reflections

$$y = h_1 x + h_2 \alpha x$$

Reflections linearly combine over the wireless medium

$$y = \left(\sum_{i} h_{1i}\right) x + \left(\sum_{i} h_{2i}\right) \alpha x$$
 reflector i

Static objects (wall, furniture, etc.) have constant channels

$$y_i = h_{1i} x + h_{2i}(-h_{1i}/h_{2i})x$$
 $y_i = h_{1i} x + h_{2i}(-h_{1i}/h_{2i})x$

People move, therefore their channels change

$$y_i = h_{1i}^{'} x + h_{2i}^{'} (-h_{1i}/h_{2i}) x$$

Not Zero

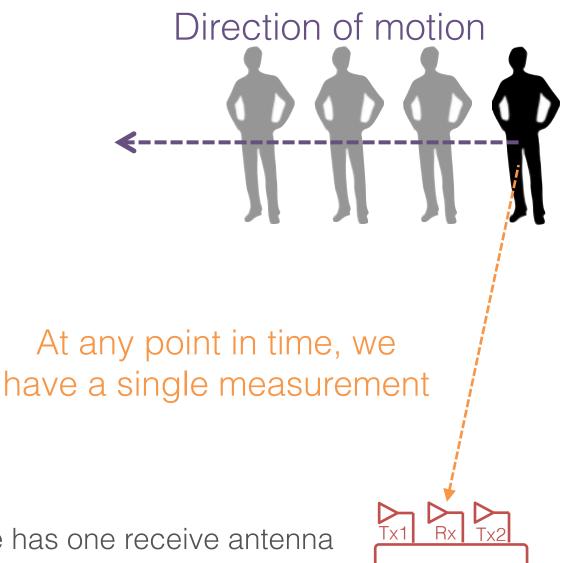
Eliminating All Static Reflections

- Noise leads to errors in estimating the channel
 - Limits ability to cancel static reflections and sense motion behind the wall
 - -Channel estimates ĥ≠h
- Refine channel estimates through an iterative nulling algorithm

How to extend to wideband WiFi channels?

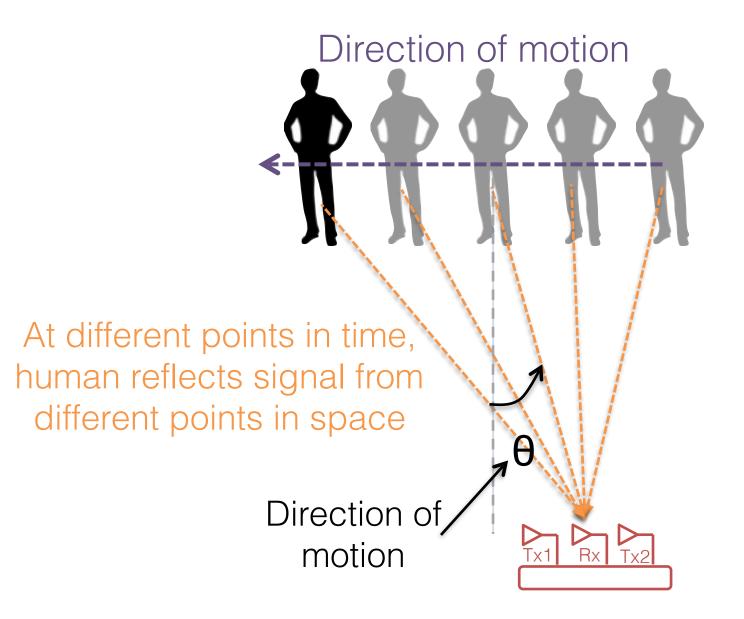
How Can We Track Using Reflections?

Tracking Motion

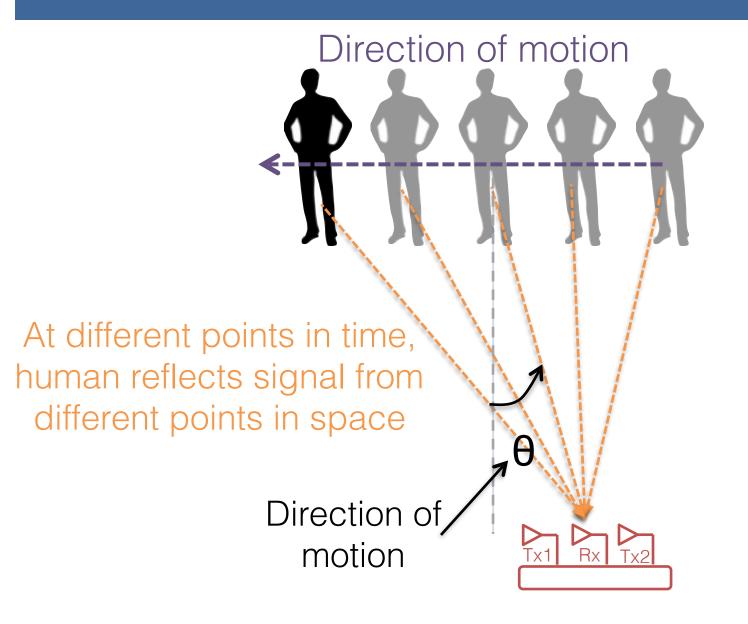


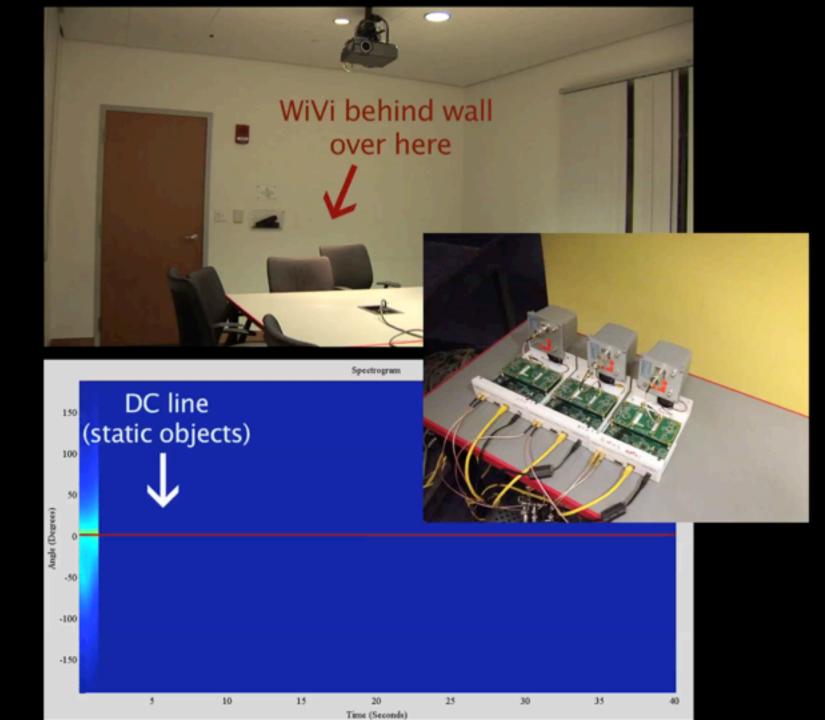
Device has one receive antenna

Tracking Motion



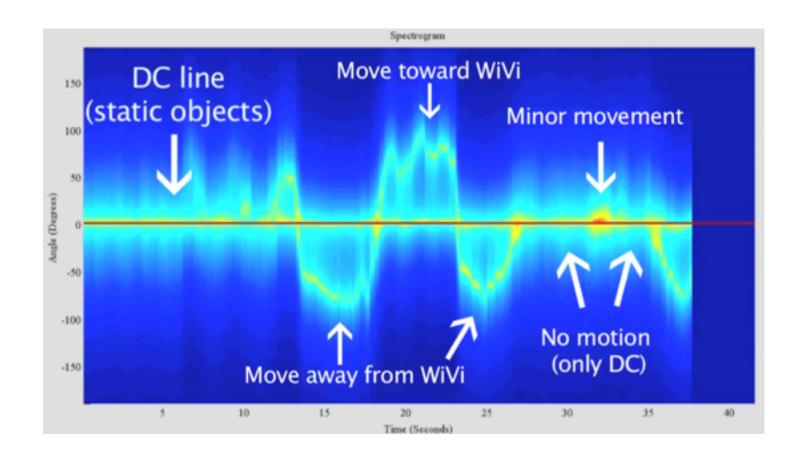
Human Motion Emulates an Antenna Array





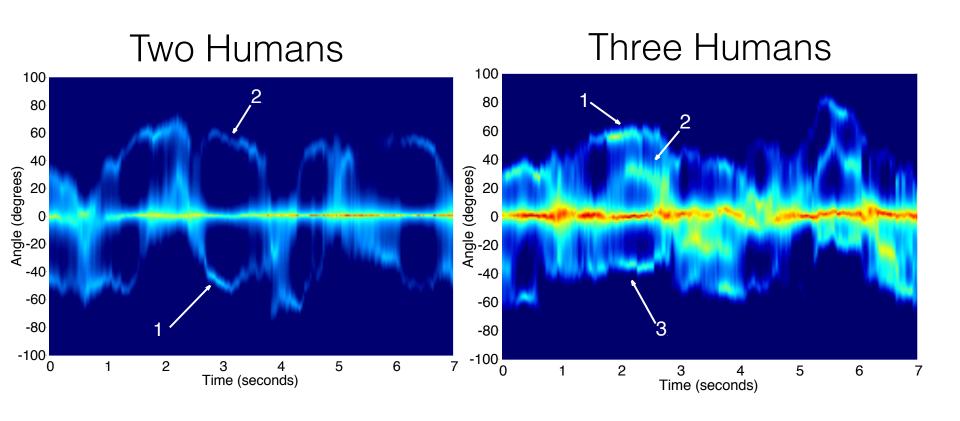
Tracking Multiple Humans

One moving person is indicated by a single curvy line



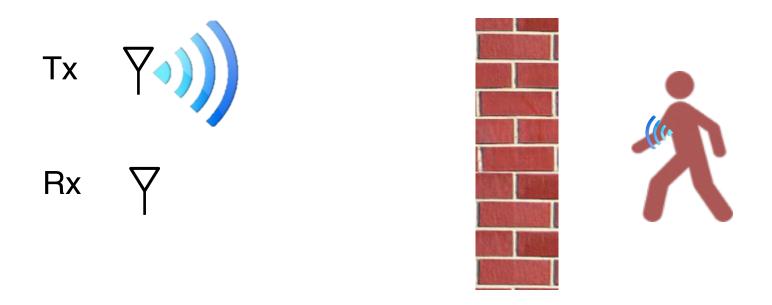
Tracking Multiple Humans

Number of distinct curves at the same time corresponds to the number of humans



WiTrack

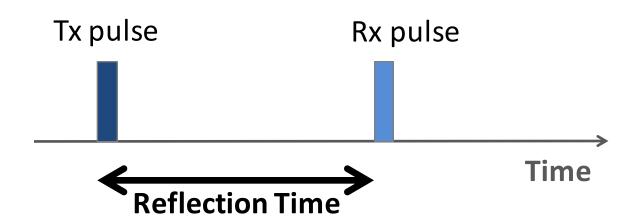
Measuring Distances



Distance = Reflection time x speed of light

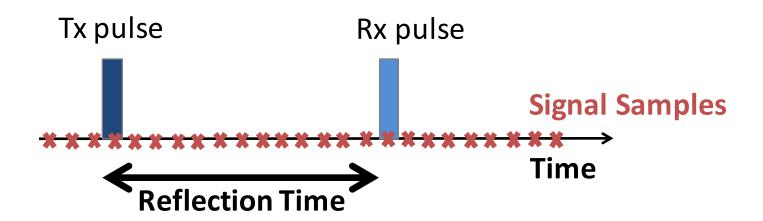
Measuring Reflection Time

 Option1: Transmit short pulse and listen for the echo.



Measuring Reflection Time

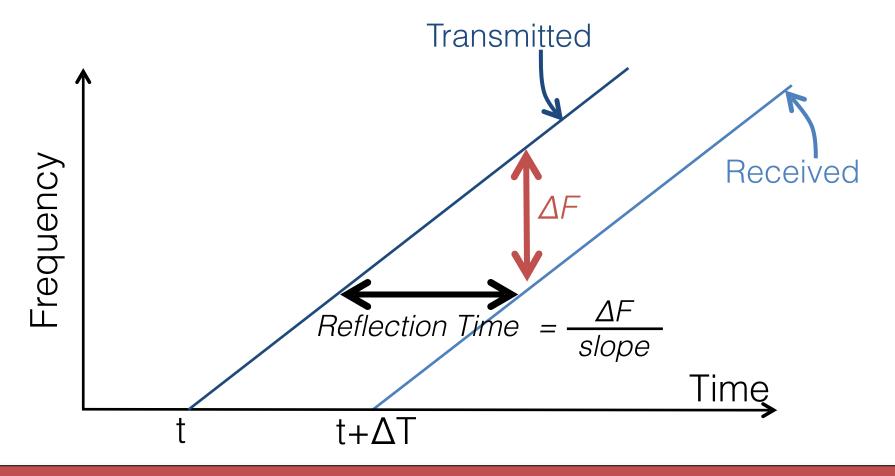
 Option1: Transmit short pulse and listen for the echo.



Need to sample at very high rate: UWB

Multi-GHz samplers are expensive and generate high noise: not suitable for this application

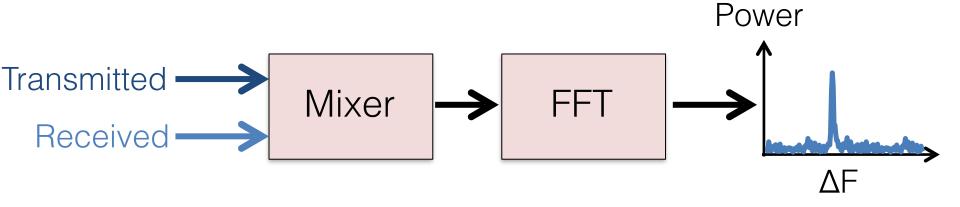
FMCW: Measure time by measuring frequency



How do we measure ΔF ?

Measuring ΔF

- Subtracting frequencies is easy (e.g., removing carrier in WiFi)
- Done using a mixer (low-power; cheap)



Signal whose frequency is ΔF

 $\Delta F \rightarrow Reflection Time \rightarrow Distance$

FMCW

slope

FMCW Transmitted Signal

Frequency is linear in time; hence phase is quadratic

$$x(t) = e^{j2\pi(\frac{k}{2}(t^2 + f_0 t))}$$

FMCW Received Signal:

$$y(t) = \sum_{i} A_{i} e^{j2\pi(\frac{k}{2}((t-\tau_{i})^{2} + f_{0}(t-\tau_{i})))}$$

Reflections linearly combine over the wireless medium

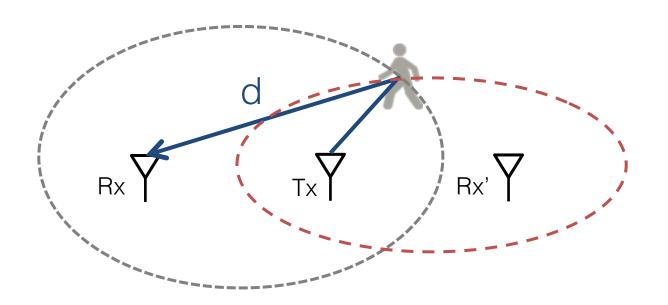
reflector i

hconversion:

$$y_b(t) = \sum_i A_i e^{j2\pi(k\tau_i t + f_0\tau_i)}$$
 frequency k τ_i

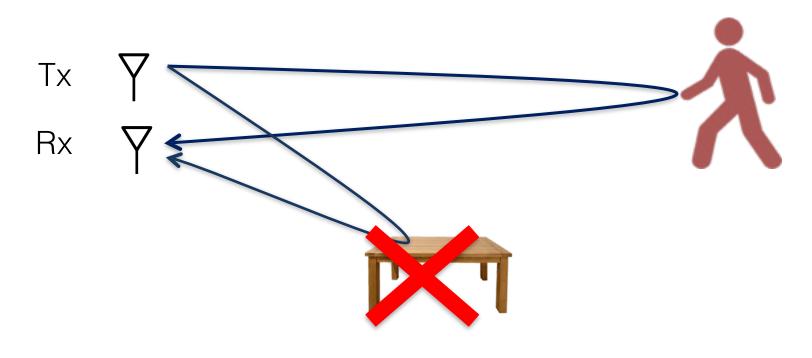
Mapping Distance to Location

Person can be anywhere on an ellipse whose foci are (Tx,Rx)



By adding another antenna and intersecting the ellipses, we can localize the person

Dealing with multi-path when there is one moving user

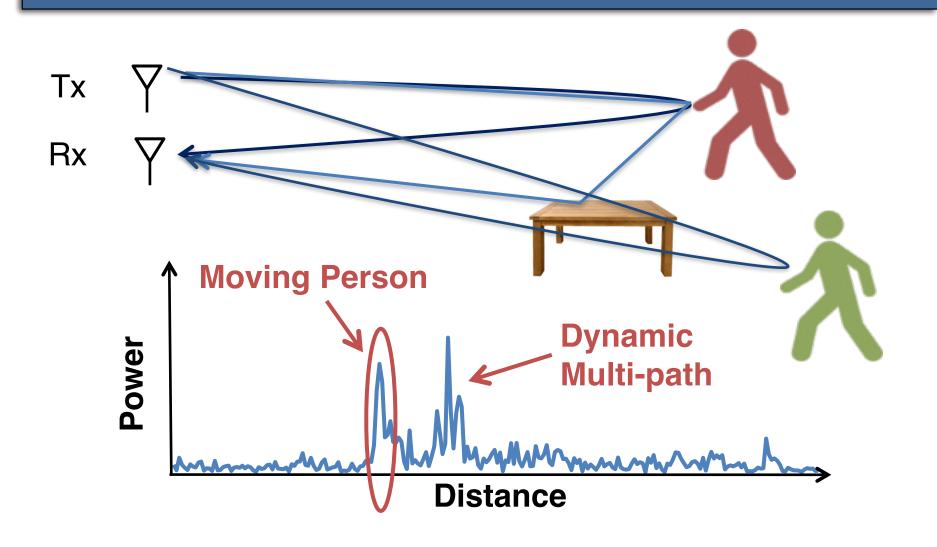


Direct furniture reflection:

eliminated by subtracting consecutive measurements

Needs User to Move

Fails for multiple people in the environment, and we need a more comprehensive solution

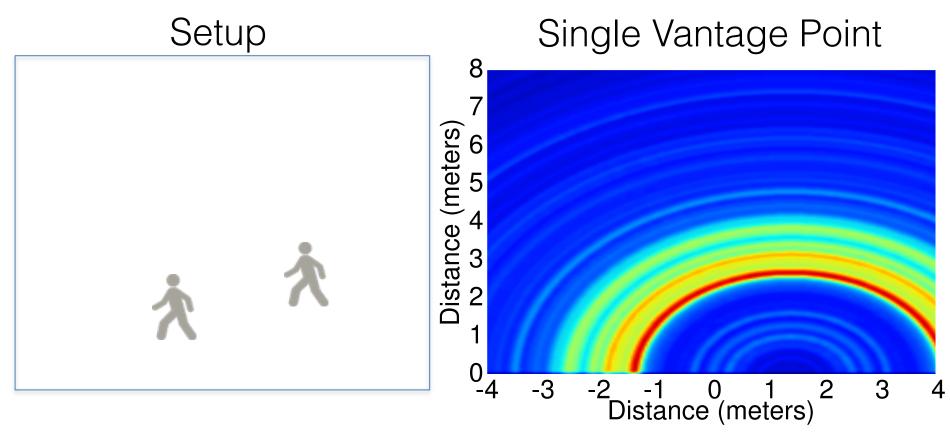


How can we deal with multi-path reflections when there are multiple persons in the environment?

Idea: Person is consistent across different vantage points while multi-path is different from different vantage points

Combining across Multiple Vantage Points

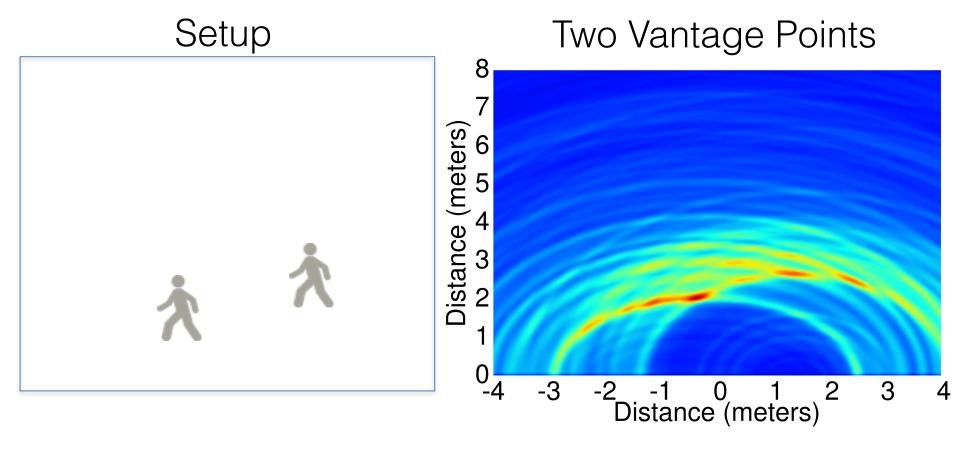
Experiment: Two users walking



Mathematically: each round-trip distance can be mapped to an ellipse whose foci are the transmitter and the receiver

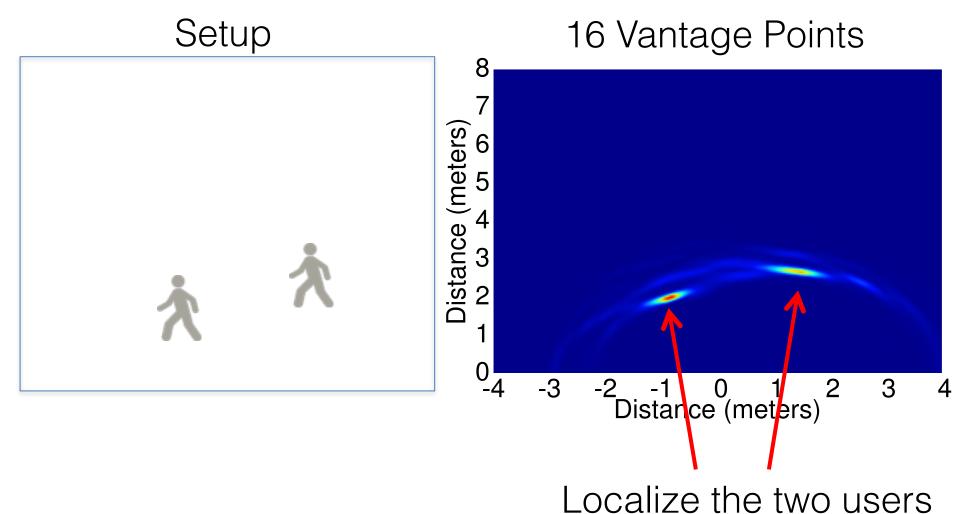
Combining across Multiple Vantage Points

Experiment: Two users walking



Combining across Multiple Vantage Points

Experiment: Two users walking



How can we obtain 16 vantage points?

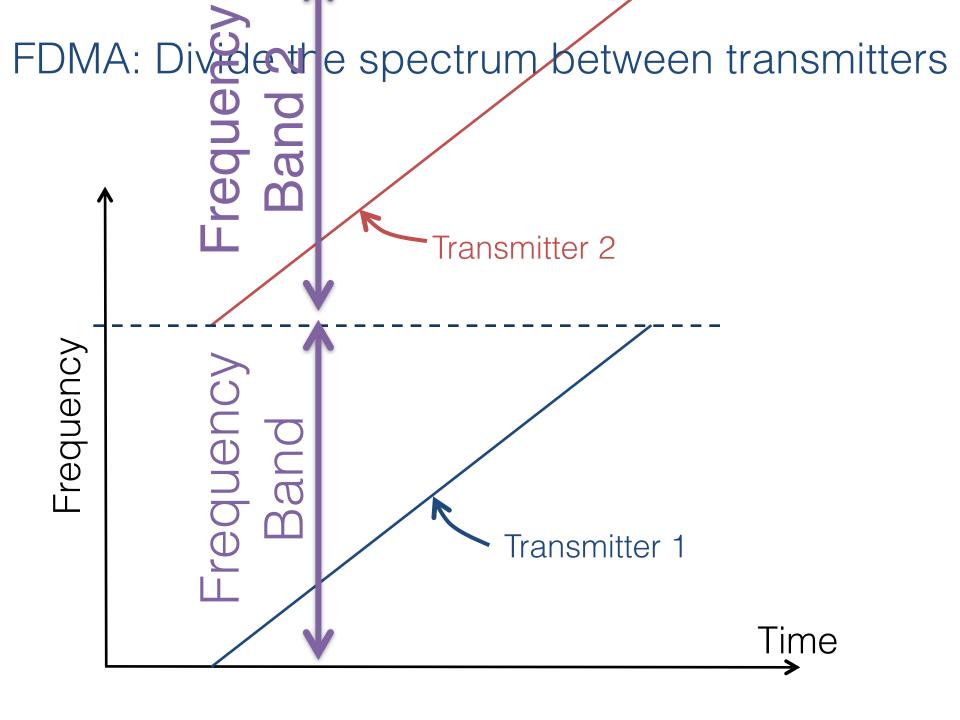
Achieving 16 vantage points

Naïve solution: 1 Transmitter and 16 Receivers

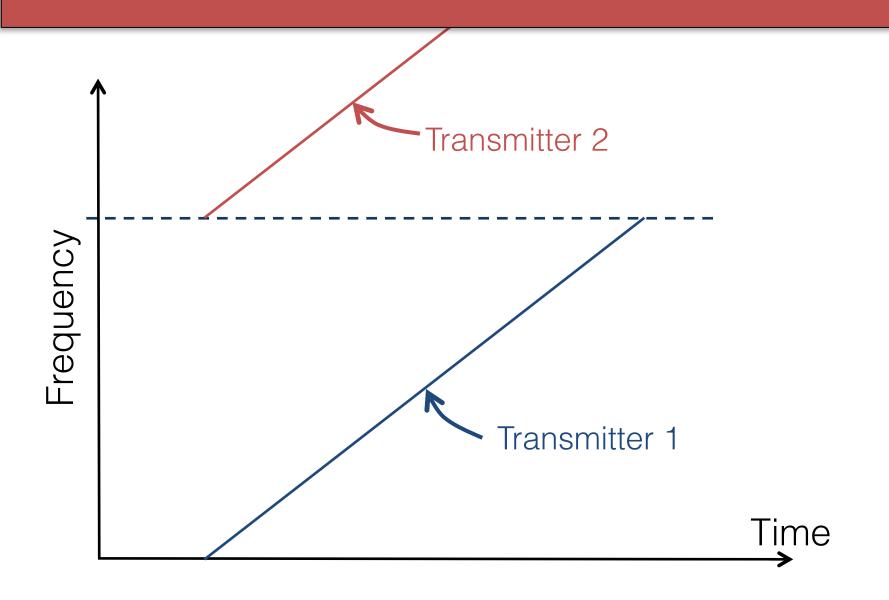
Ideally: 4 Transmitters and 4 Receivers

Problem: Different transmitters interfere with each other!

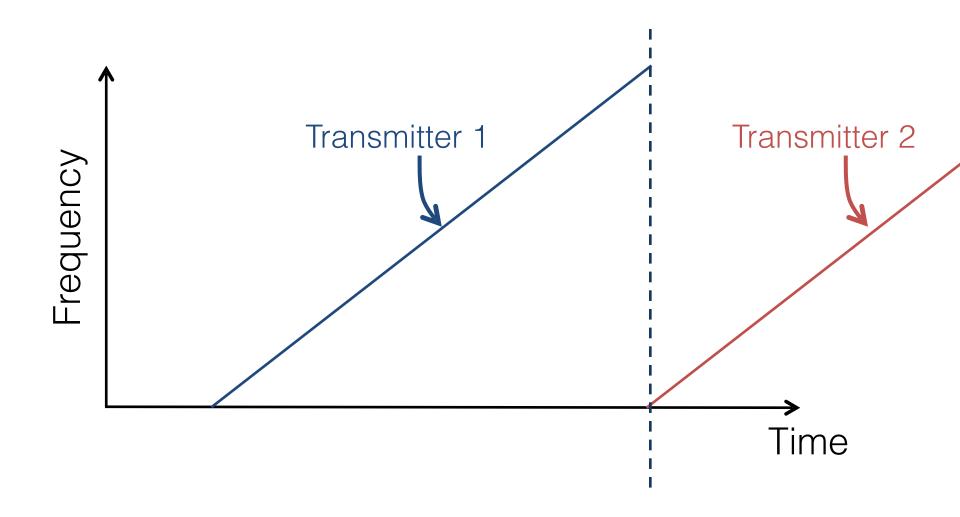
Let us look at standard mechanisms that are used to deal with interference



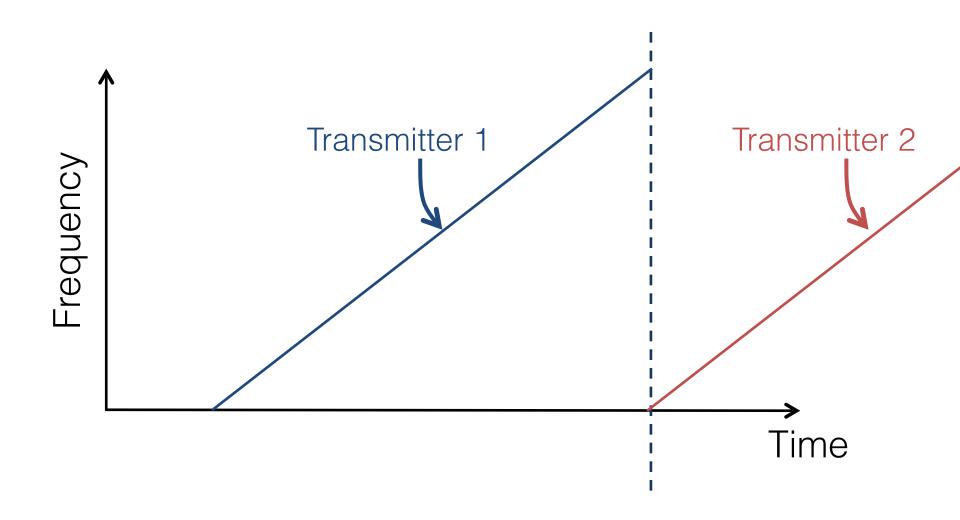
Would require N times the bandwidth!



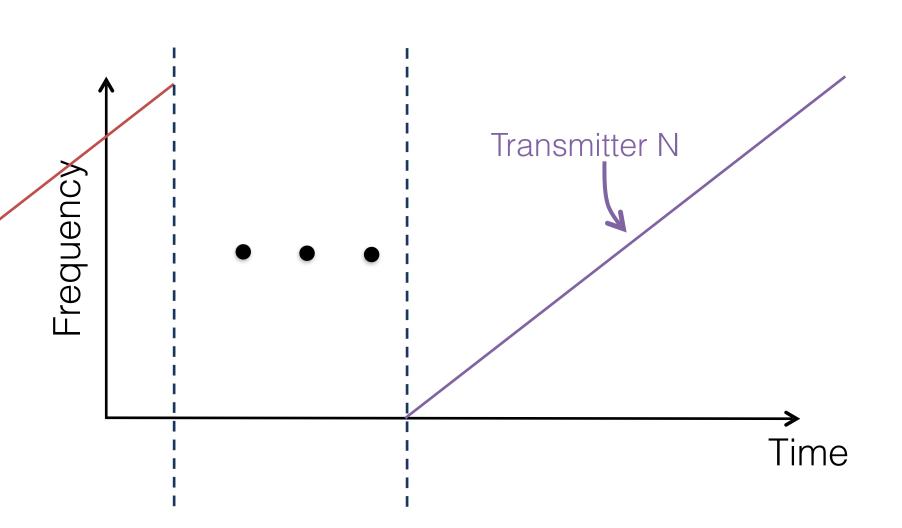
TDMA: Transmitters take turns transmitting



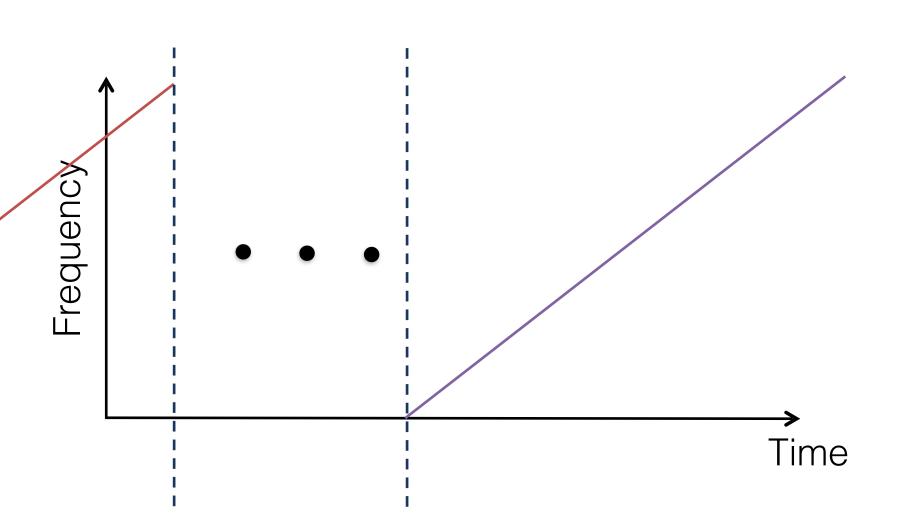
Would require N more time to localize



Ideally: Transmit in the same time and in the same frequency band without interfering



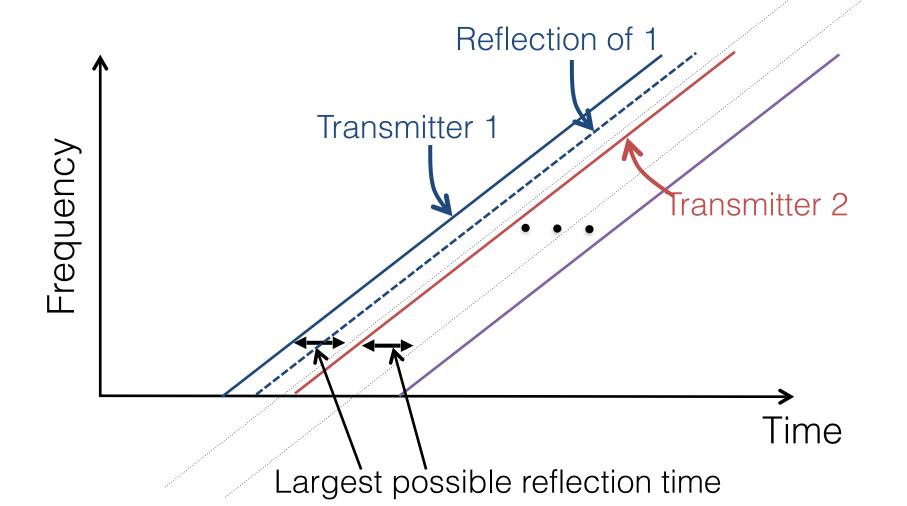
Ideally: Transmit in the same time and in the same frequency band without interfering



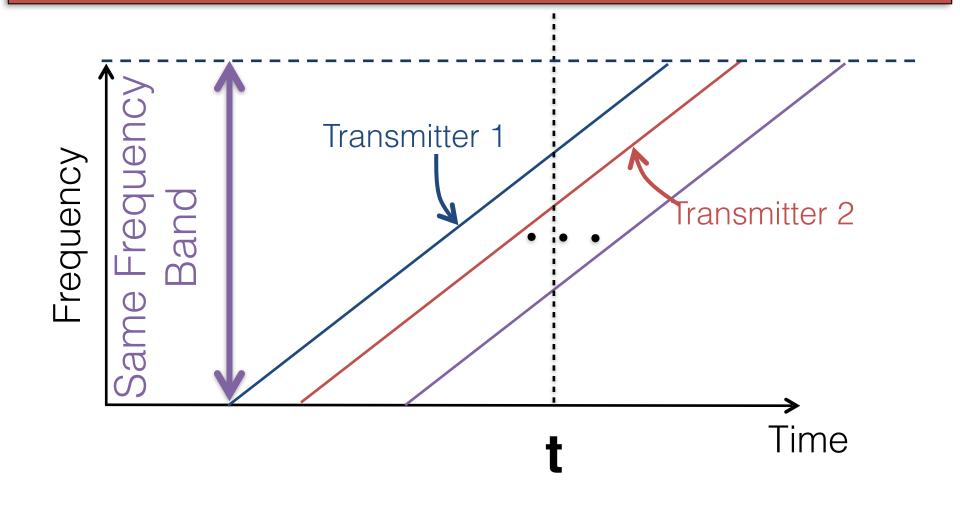
Multi-shift FMCW: a new mechanism to divide resources between transmitters so that they don't suffer from interference

Objective: Transmit and Get Reflection

Largest reflection time indoors: 100ns



Multi-shift FMCW enables multiple transmissions at the **same time** and in the **same frequency band** without interference

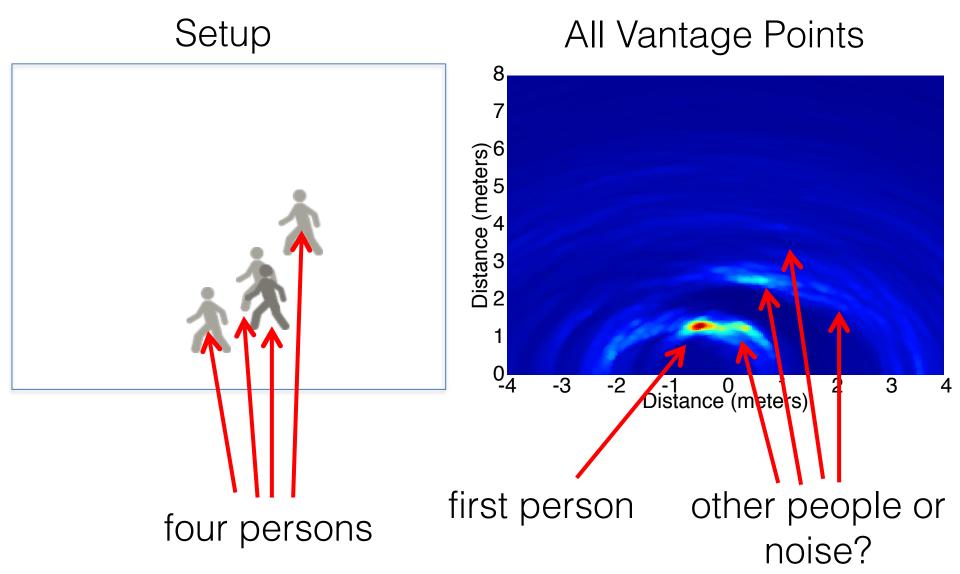


Multi-Person Localization

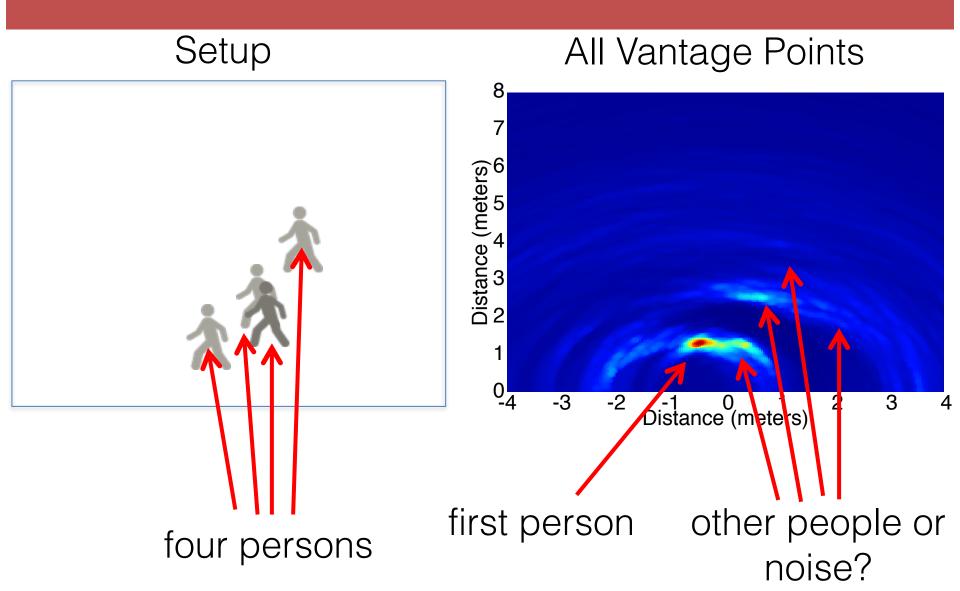
 Multi-shift FMCW enables a large number of vantage points for accurate localization of multiple subjects

Multi-User Localization

Experiment: Four persons walking



Near-Far Problem: Nearby persons have more power than distance reflectors and can mask them



Successive Silhouette Cancellation: a new algorithm that localizes multiple persons in the scene by addressing the near-far problem

Successive Silhouette Cancellation:
a new algorithm that localizes multiple
persons in the scene by addressing the
near-far problem

inspired by

Successive Interference Cancellation iteratively decode interfering transmissions by addressing the near-far problem

Successive Interference Cancellation

Recover 0's and 1's

Decode 0's and 1's

Subtract

Reconstruct modulation & coding

Deterministic

Successive Silhouette Cancellation

Recover human reflections

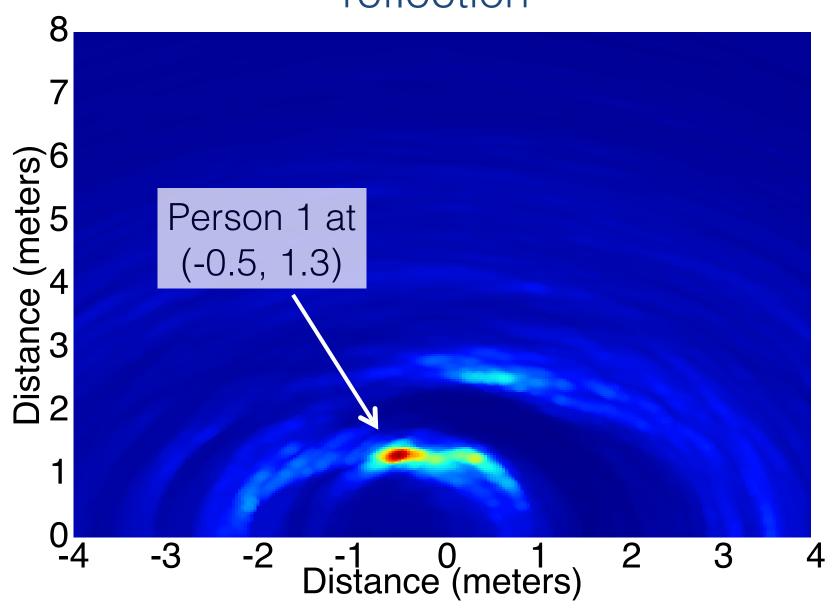
Decode human location

Subtract

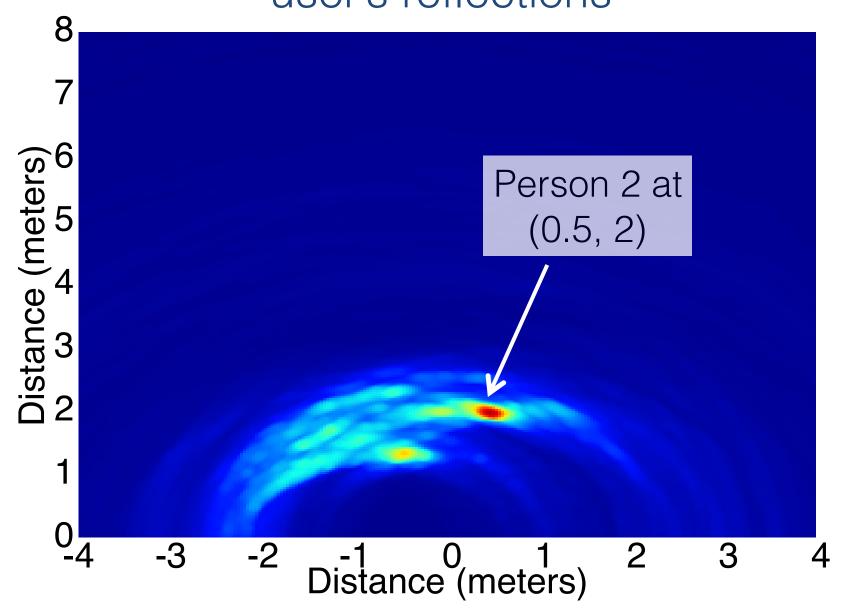
Model human and reconstruct reflection patterns

Stochastic

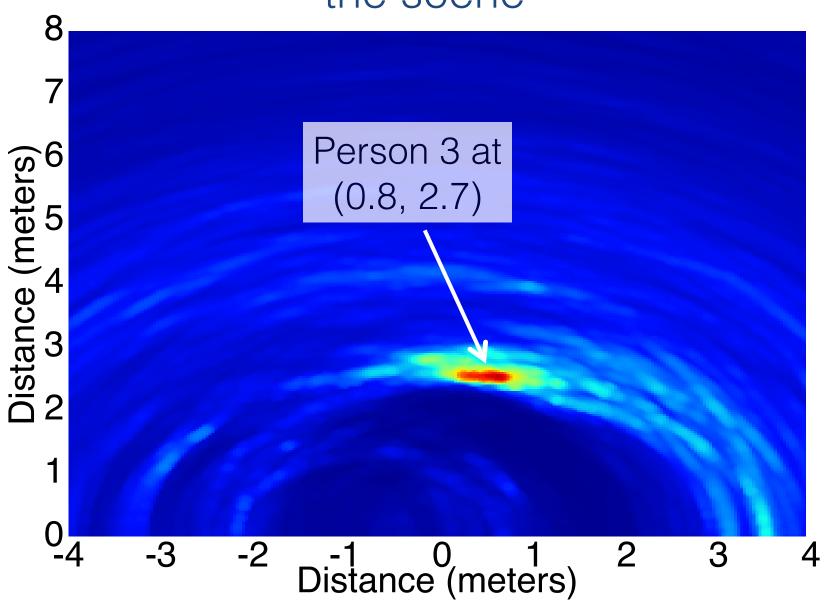
First localize the user with the strongest reflection



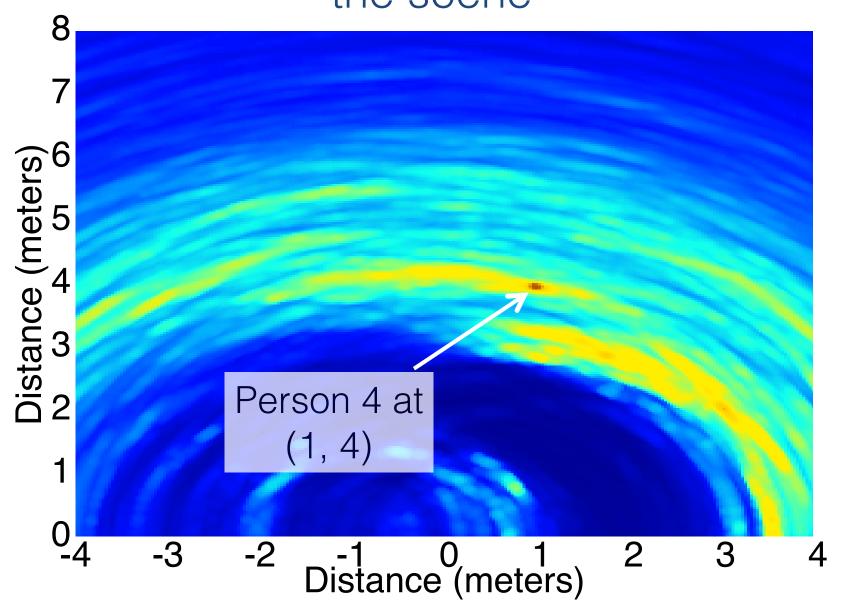
After reconstructing and cancelling the first user's reflections



Iteratively localize the remaining users in the scene

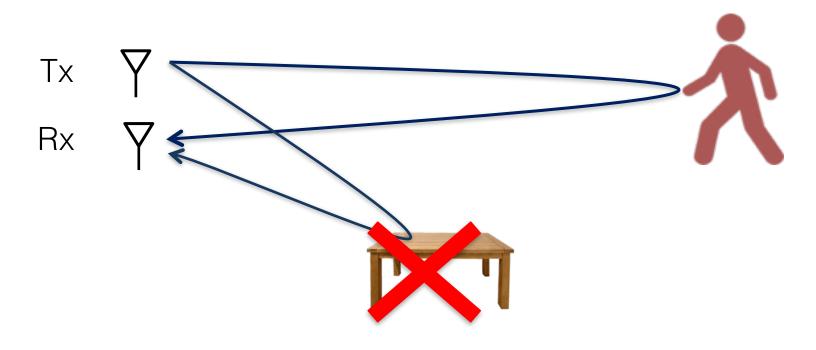


Iteratively localize the remaining users in the scene





Dealing with multi-path when there is one moving user

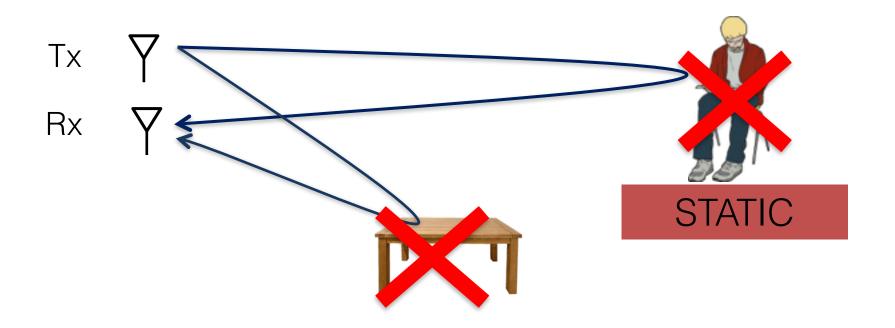


1. Direct furniture reflection:

eliminated by subtracting consecutive measurements

Needs User to Move

Dealing with multi-path when there is one moving user



1. Direct furniture reflection:

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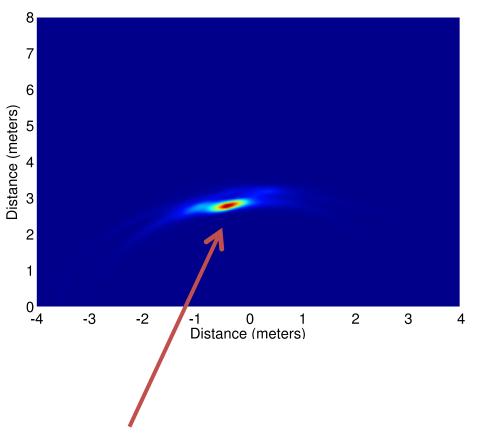
Exploit breathing motion for localize static users

- Breathing and walking happen at different time scales
 - A user that is pacing moves at 1m/s
 - -When you breathe, chest moves by few mm/s

 Cannot use the same subtraction window to eliminate multi-path

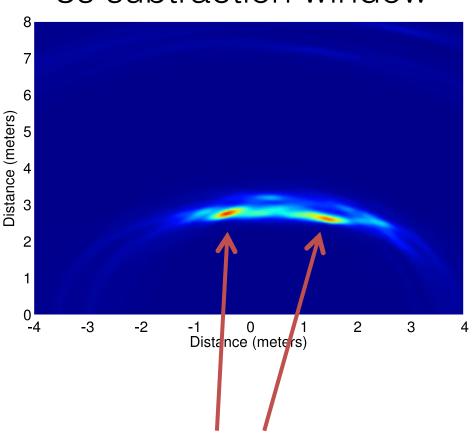
User Walking at 1m/s





Localize the person

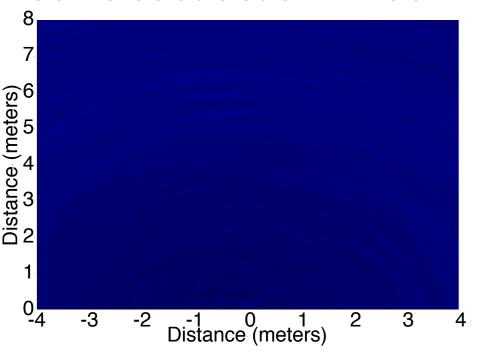
3s subtraction window



Person appears in two locations

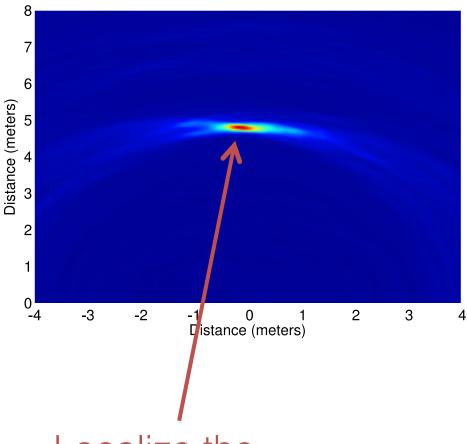
User Sitting Still (Breathing)

30ms subtraction window



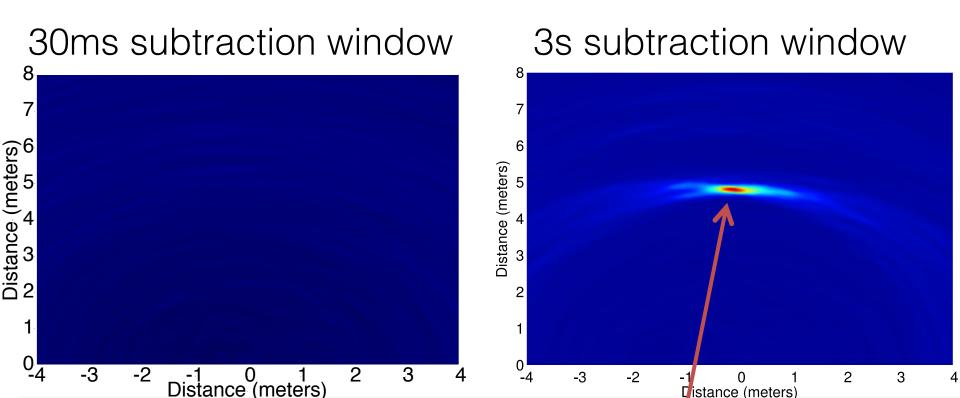
Cannot localize

3s subtraction window



Localize the person

User Sitting Still (Breathing)



Use multi-resolution subtraction window to eliminate multi-path while being able to localize both static and moving users

