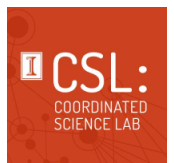


ECE 598HH: Advanced Wireless Networks and Sensing Systems

Lecture 13: Wireless Sensing Part 2 Haitham Hassanieh



Interest in Sensing the Human Body

Heart Rate



Breathing



Locations



Gestures



Heart Rate



Breathing



Locations

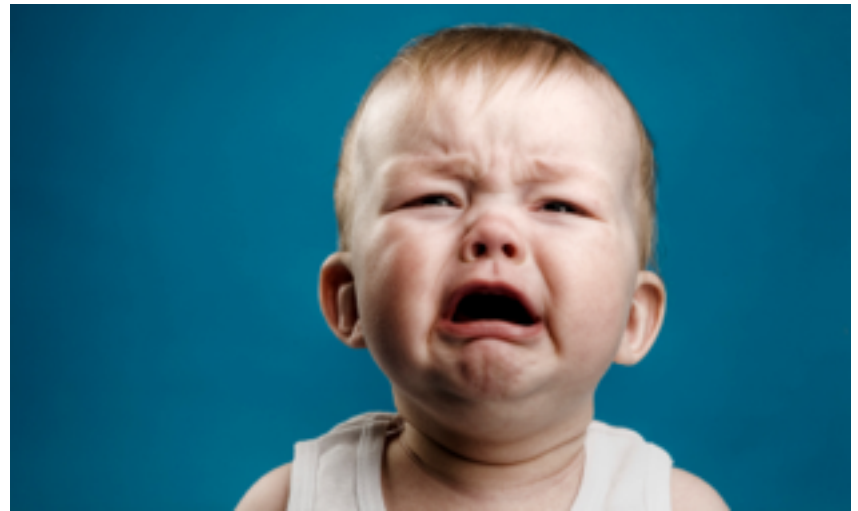


Gestures



On-body sensors can be cumbersome

Not suitable for elderly & babies



Heart Rate



Breathing



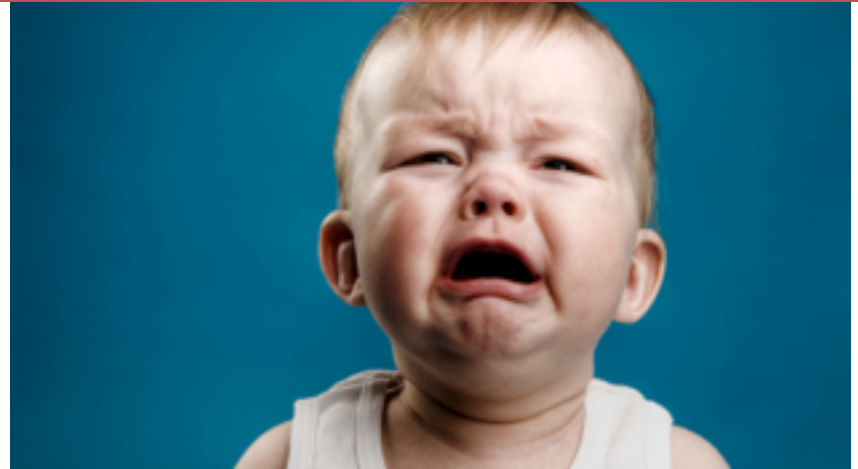
Locations

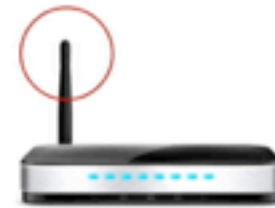
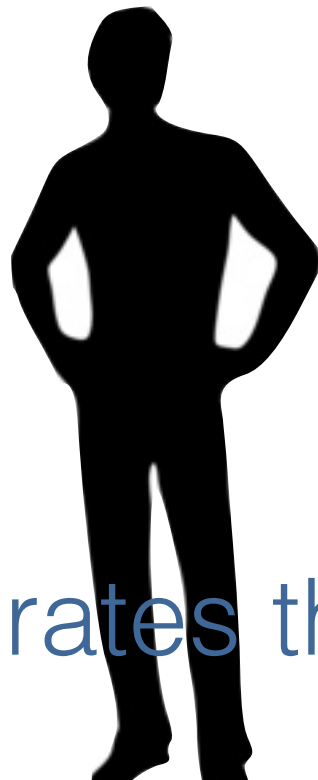


Gestures



Imagine enabling these applications without sensors on the human body





- Location
- Vital Signs
- Imaging

Operates through occlusions

Last Lecture

WiVi: Sensing humans through walls with WiFi

- MIMO Nulling
- Inverse SAR

WiTrack: Localizing humans through walls

- FMCW
- Dynamic Multipath
- Multi-Shift FMCW
- Successive Silhouette Cancellation
- Multi-Resolution Subtraction Window

This Lecture

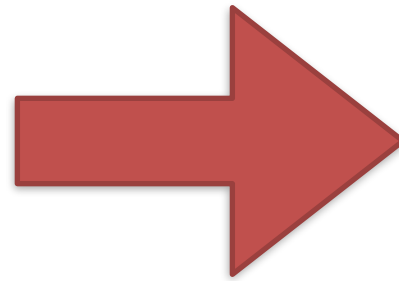
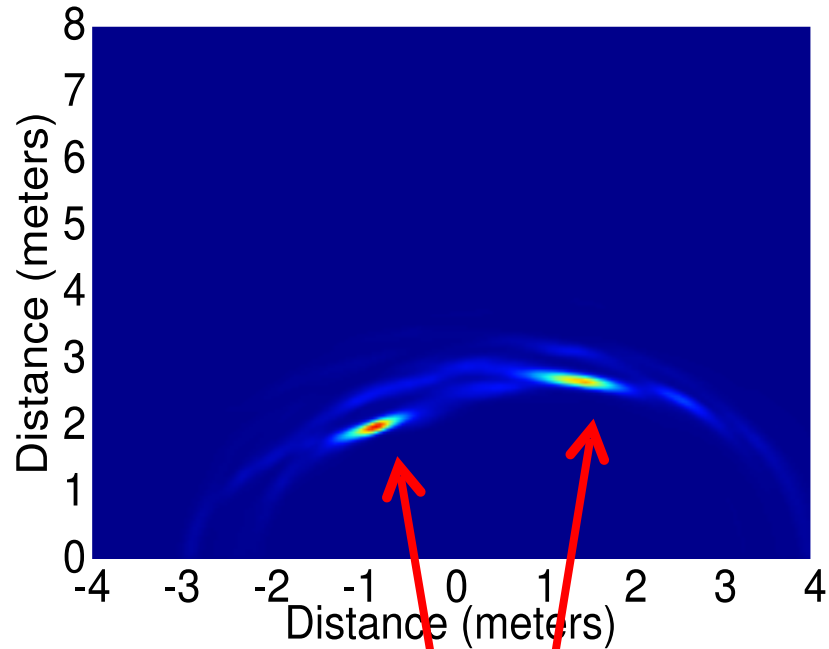
RF-Capture: Capturing human figure through walls

Vital Ratio: Extracting vital signs (Breathing rate and heart rate)

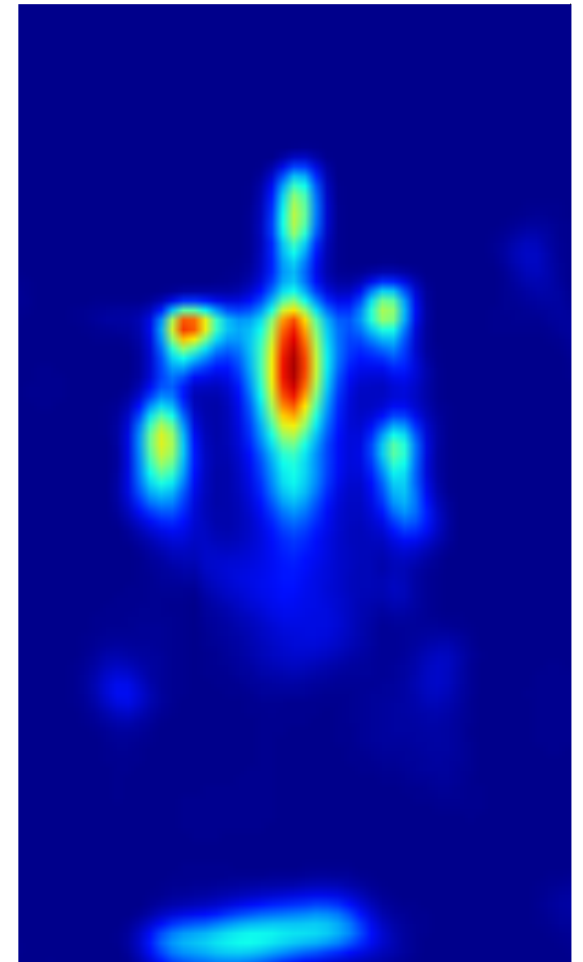
RF Imaging

Want a silhouette

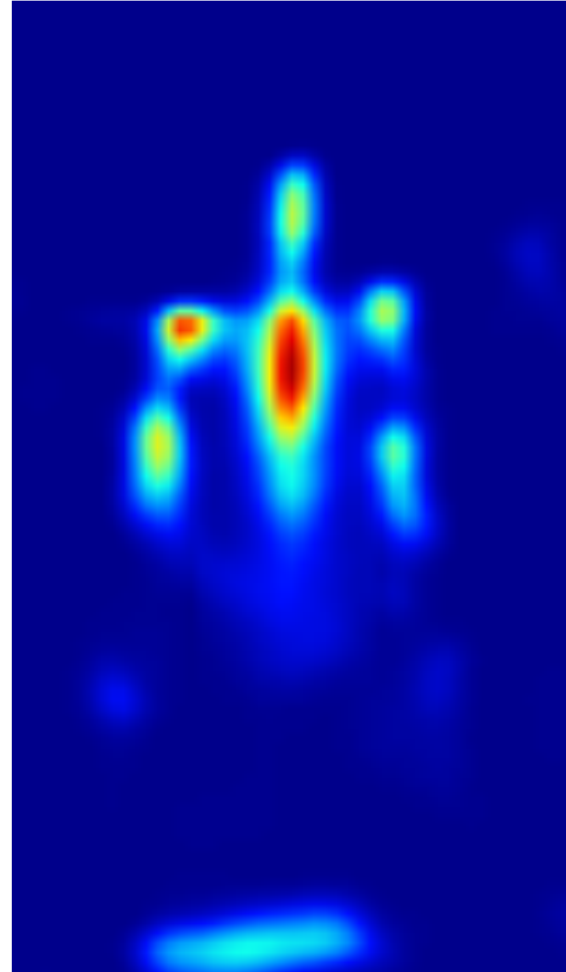
People are points



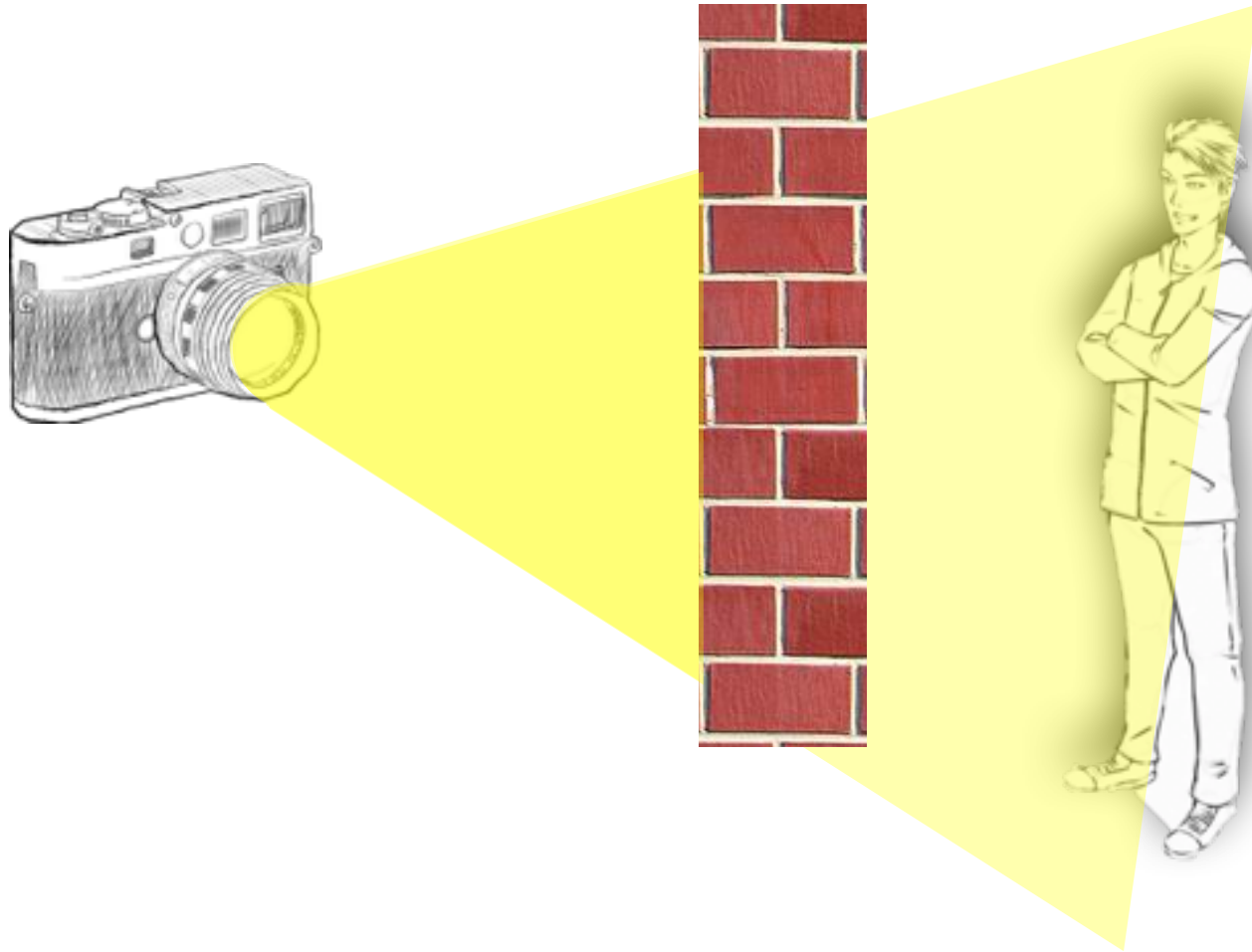
Localize the two users



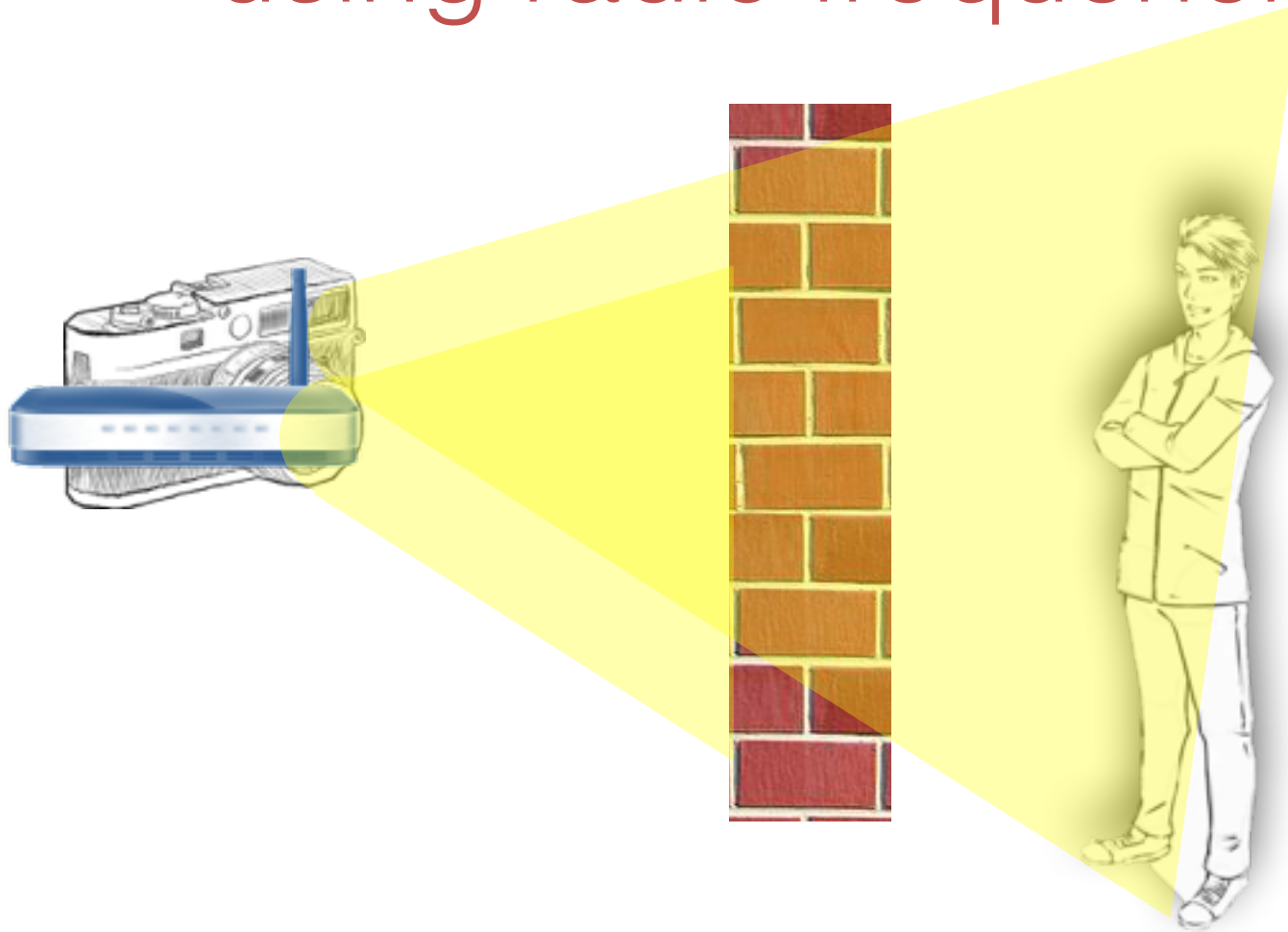
Capturing a Coarse Human Silhouette



Imaging through occlusions



Imaging through occlusions using radio frequencies



Traditional Imaging


Cannot image through occlusions like walls


Form 2D images using lenses

Get a reflection from all points: can image all the body

RF Imaging


 Walls are transparent and can image through them

 No lenses at these frequencies

 No reflections from most points: all reflections are specular


RF Imaging

 Walls are transparent and can image through them

 No lenses at these frequencies



Solution: A component that scans 3D space with RF and outputs reflection snapshots at every point in time

 No reflections from most points: all reflections are specular

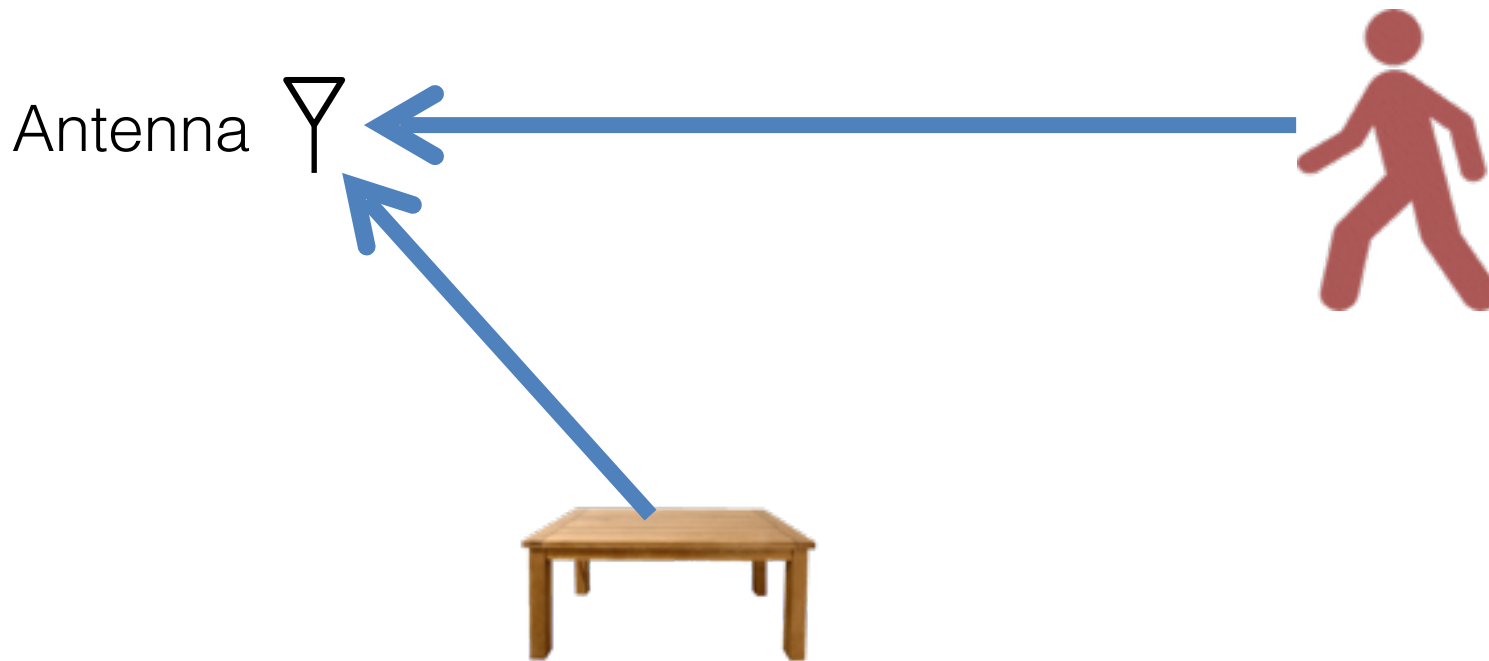


?

Imaging with RF

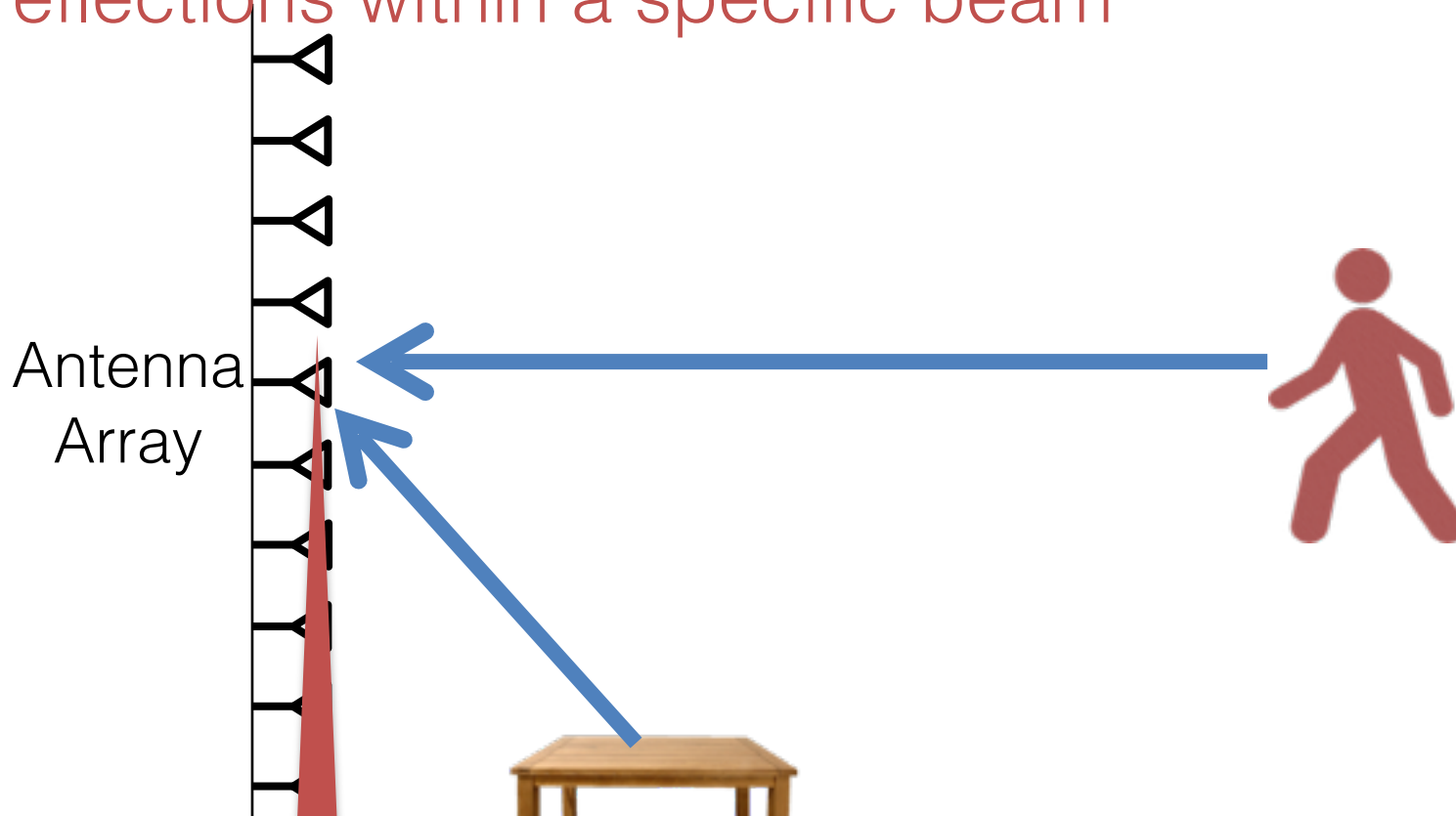
No lens at these frequencies

Antenna cannot distinguish bounces from different directions



Imaging with RF

Beamforming: Use multiple antennas to scan reflections within a specific beam



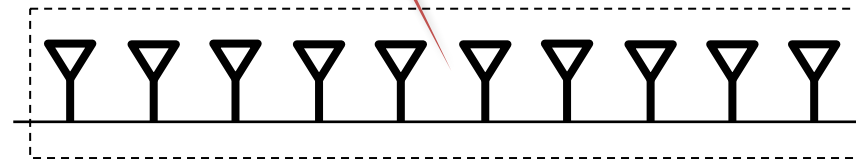
Extend to 3D with time-of-flight measurements by repeating this at every depth

Scanning every direction is slow

- Each angle/depth needs to be processed separately
- Most of the 3D scene is empty
- Solution: Coarse-to-fine scan that iteratively refines the resolution

Coarse-to-fine Scan

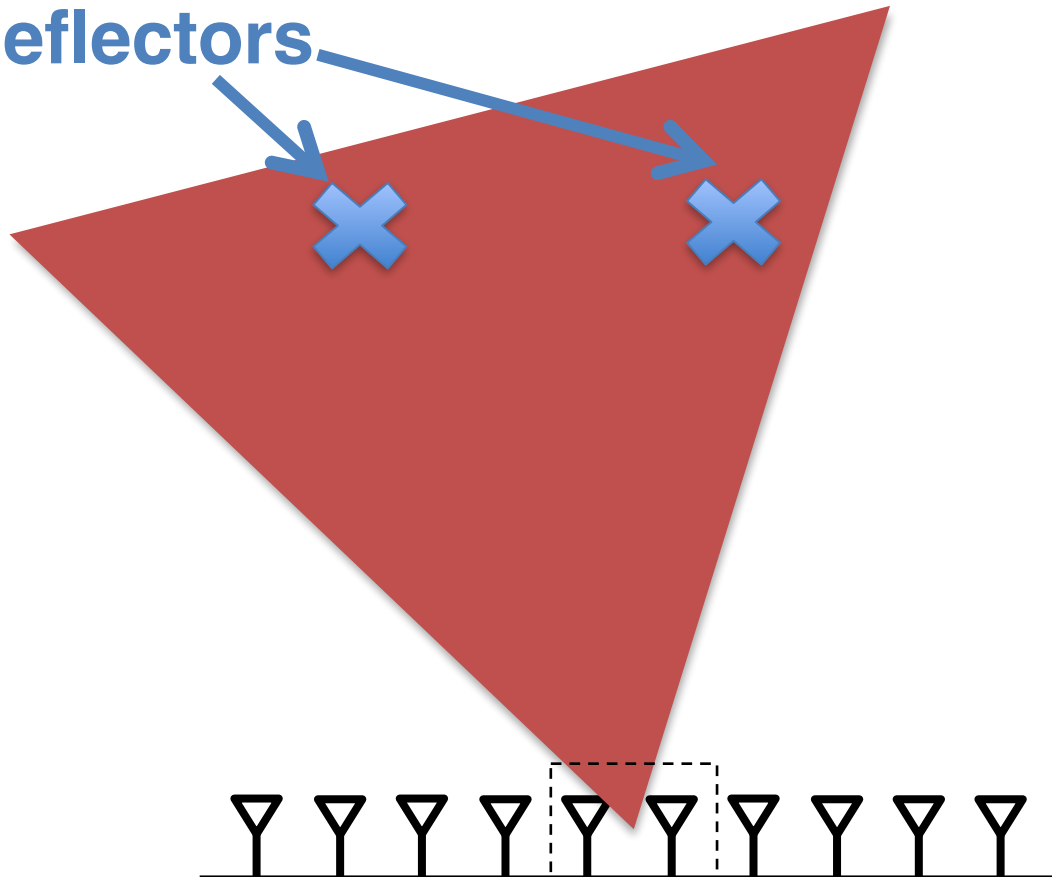
- Larger aperture (more antennas) means finer resolution



Used antennas

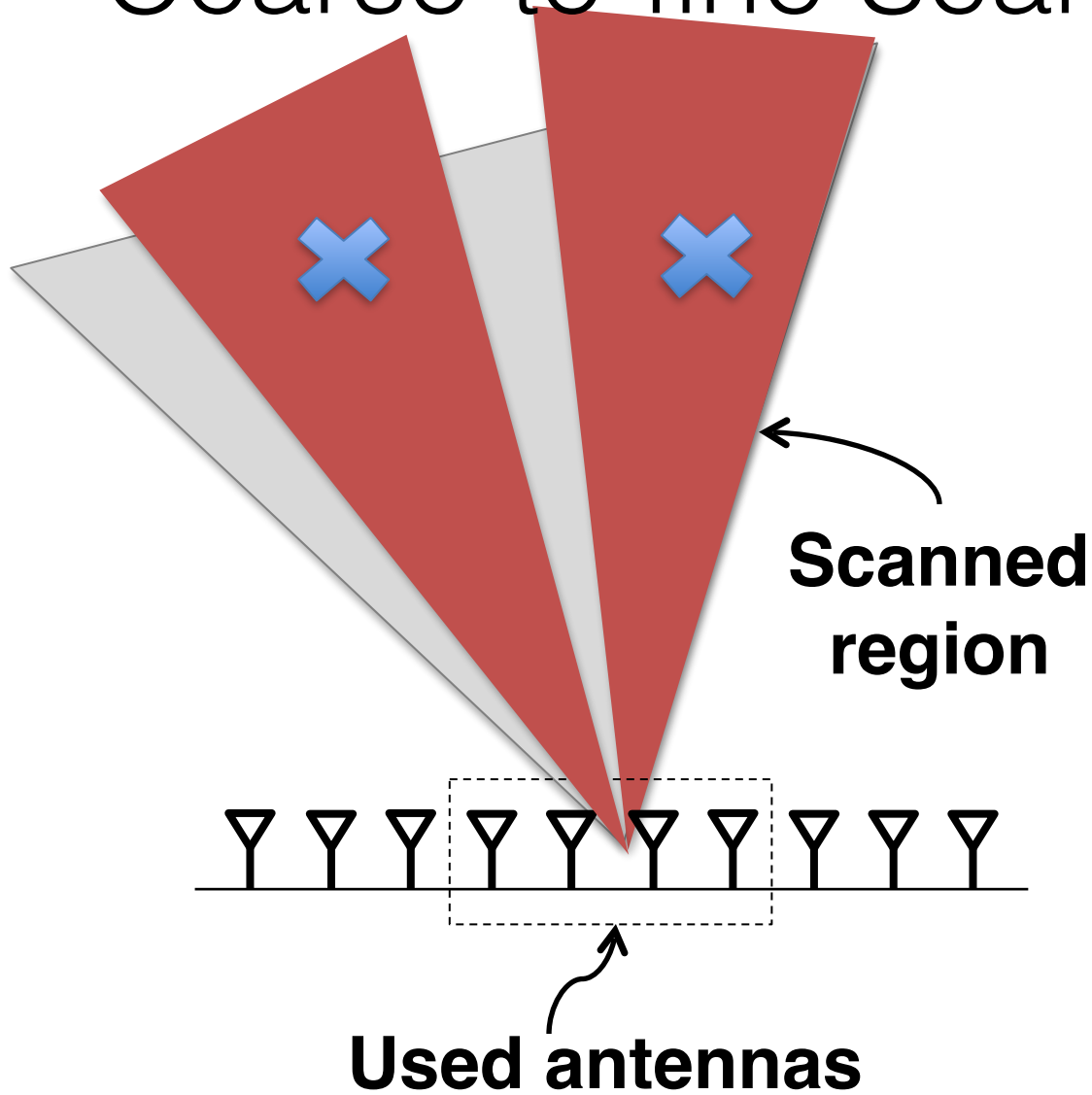
Coarse-to-fine Scan

Reflectors

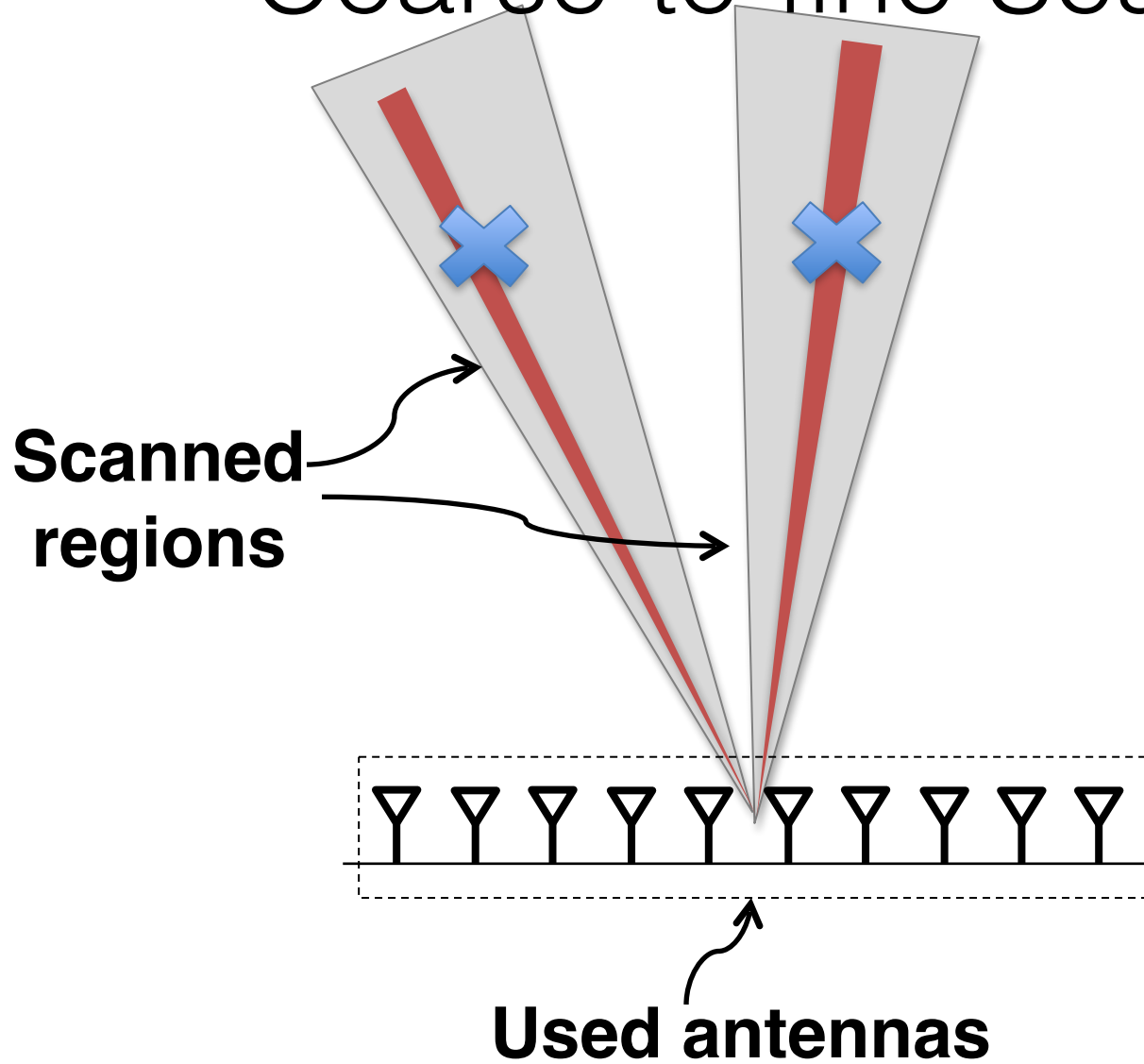


Used antennas

Coarse-to-fine Scan

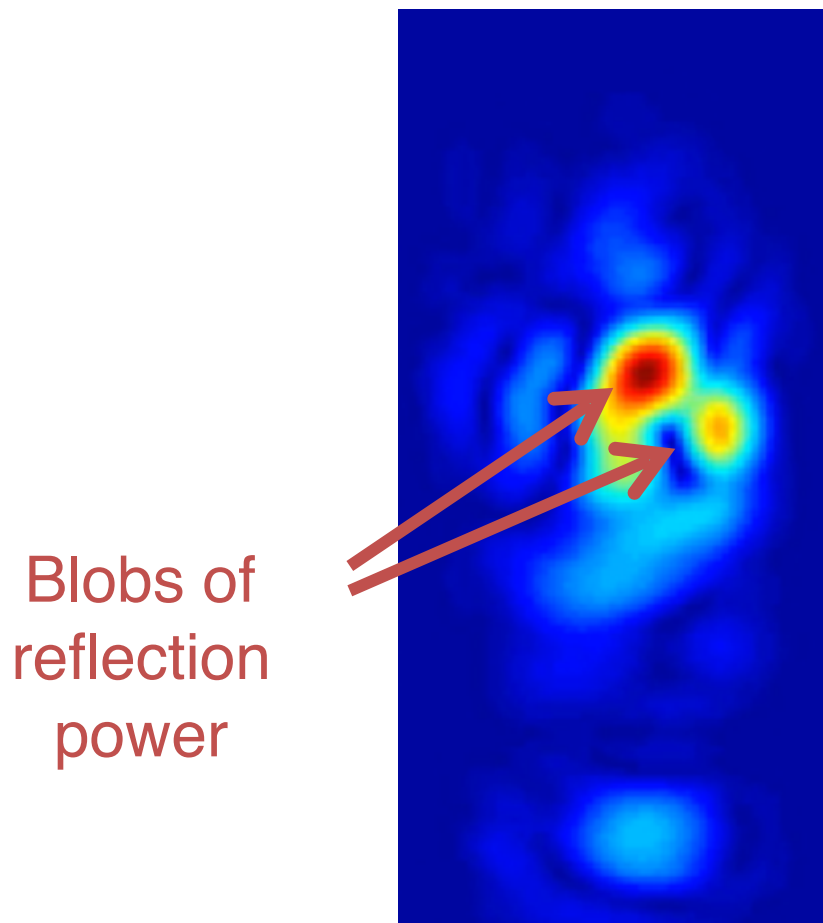


Coarse-to-fine Scan



Challenge: We only obtain blobs in space

Output of 3D RF Scan

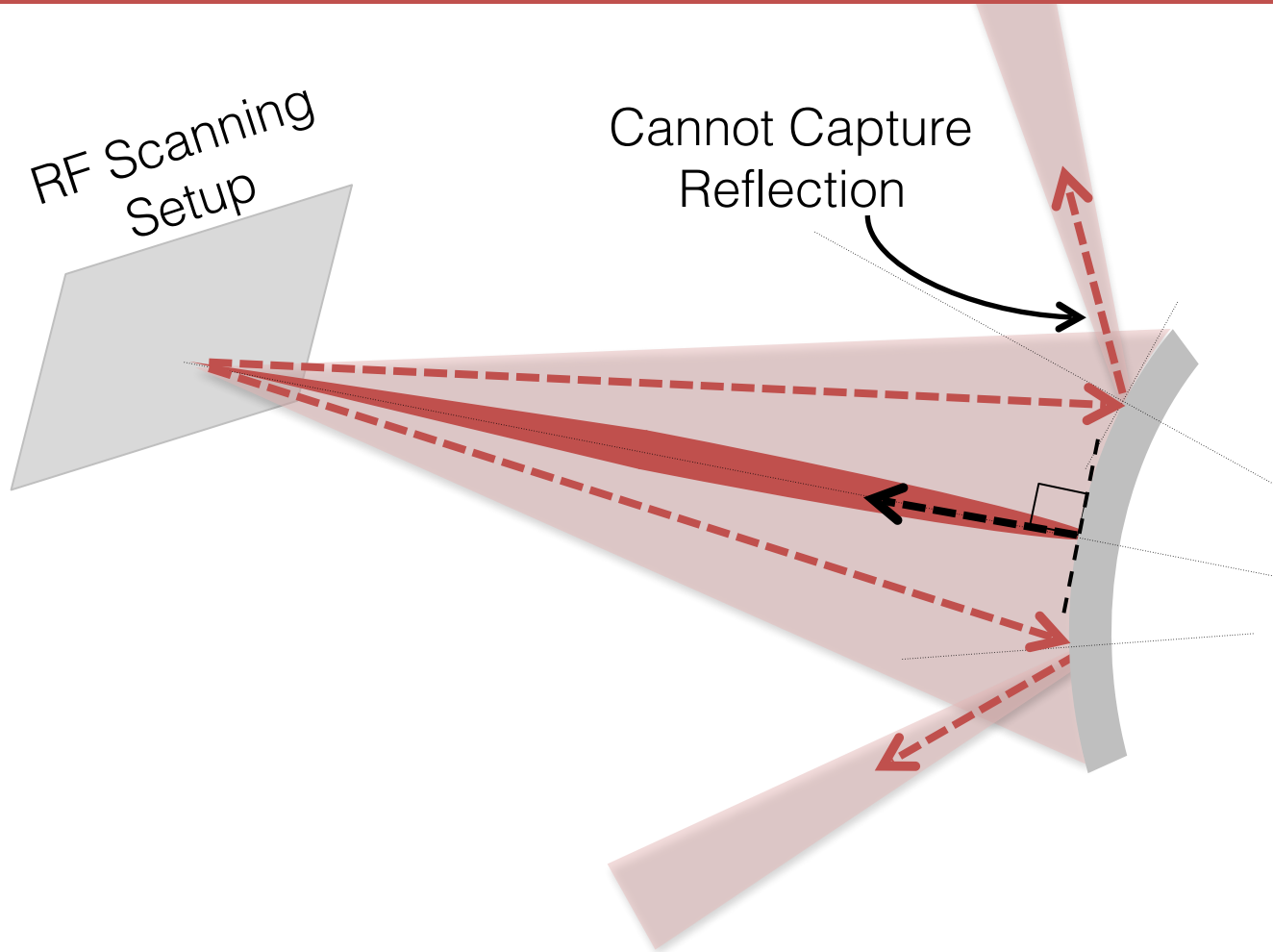


Challenge: Don't get reflections from most points in RF

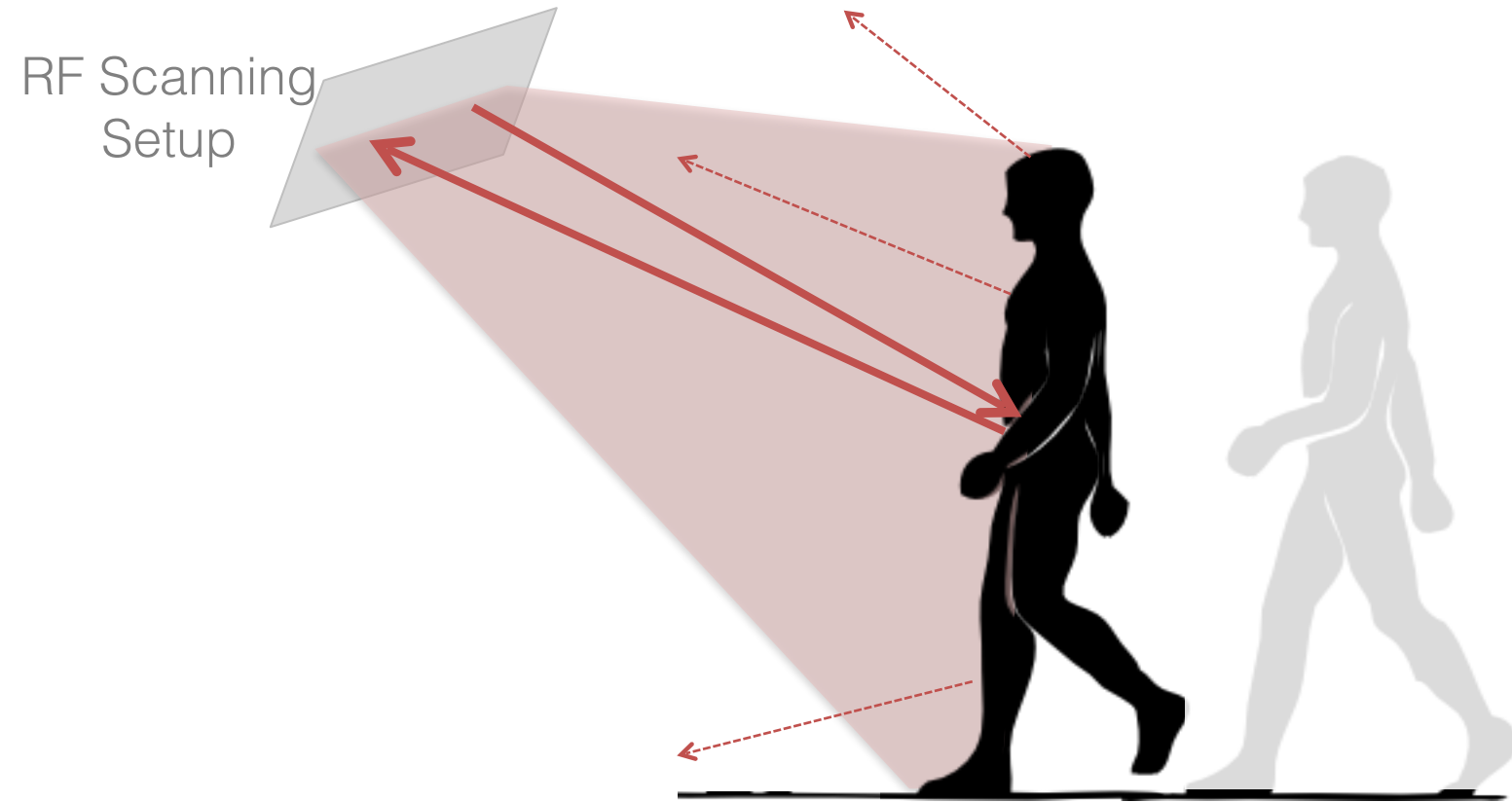
At frequencies that traverse walls, human body parts are specular (**pure mirror**)



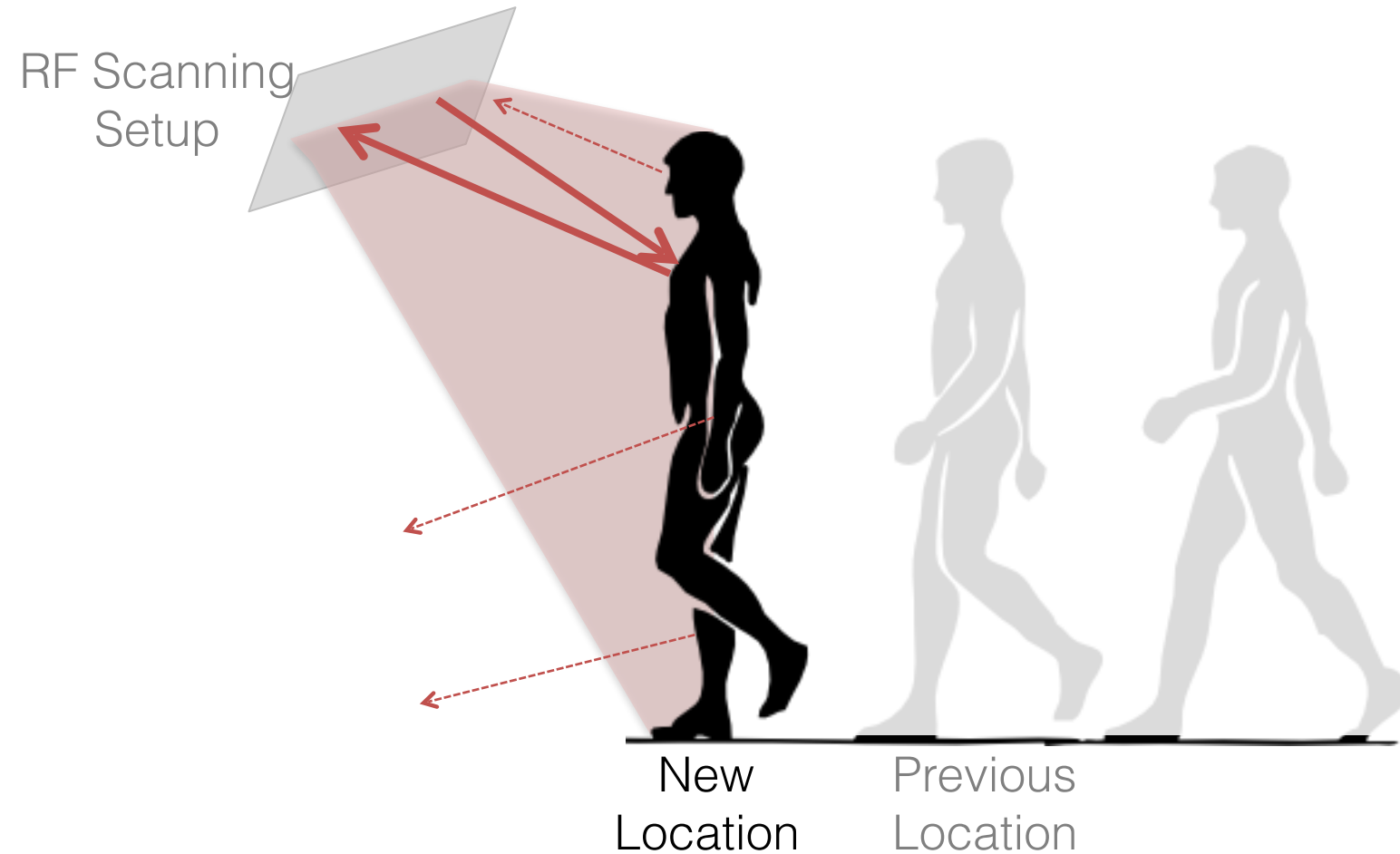
At every point in time, we get reflections from only a subset of body parts.



Solution Idea: Exploit Human Motion and Aggregate over Time



Solution Idea: Exploit Human Motion and Aggregate over Time



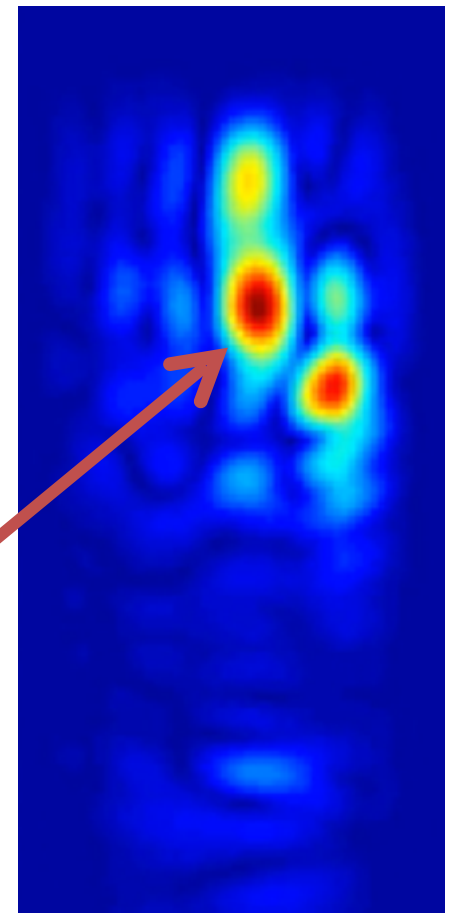
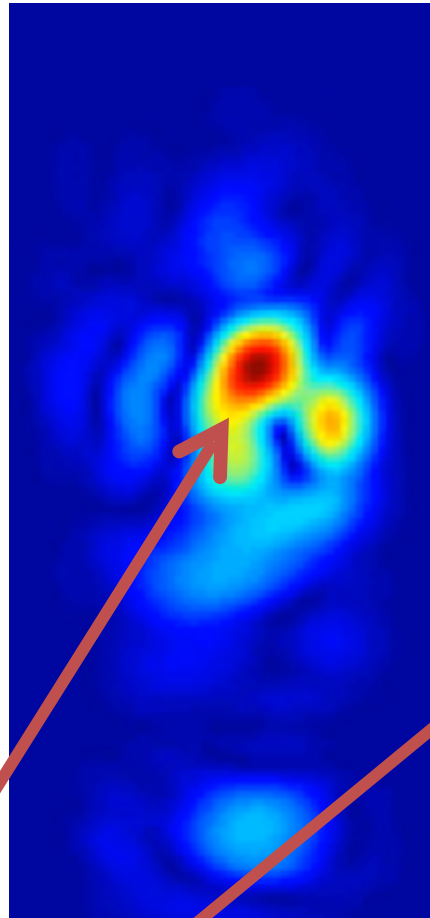
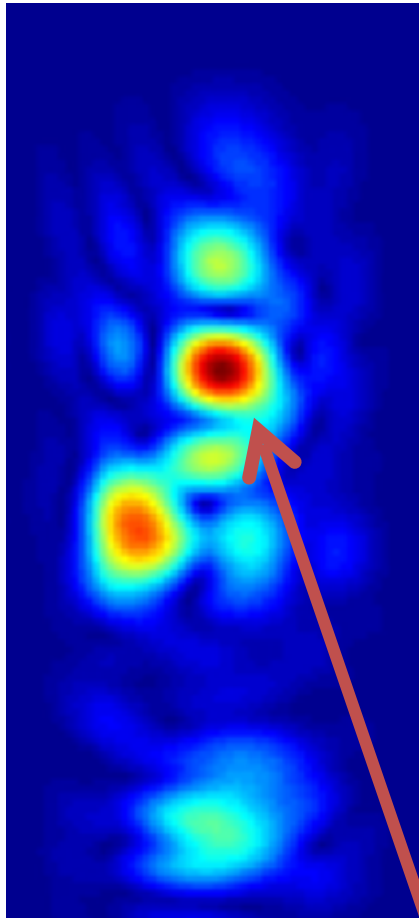
Combine the various snapshots

Human Walks toward Sensor

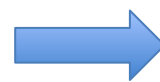
3m

2.5m

2m



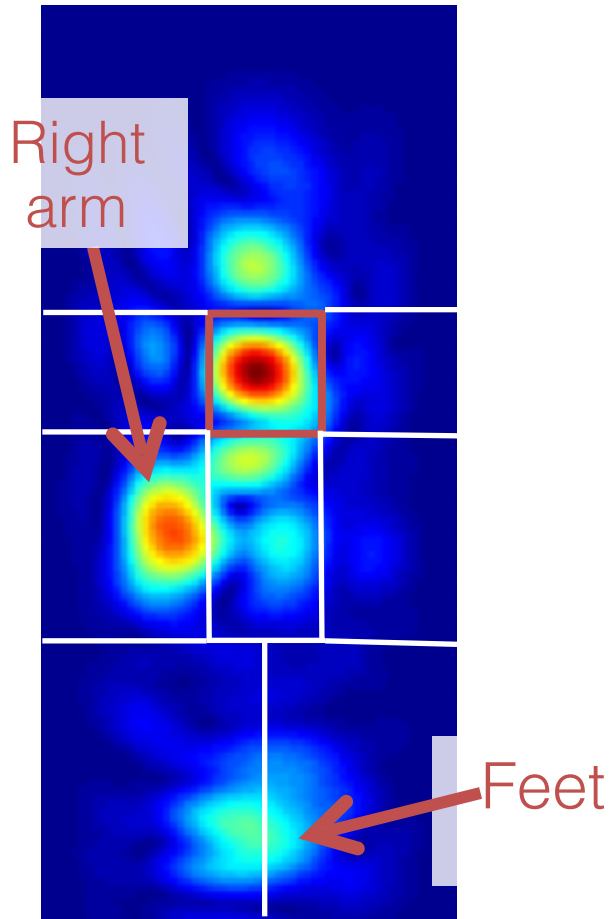
Chest (Largest
Convex Reflector)



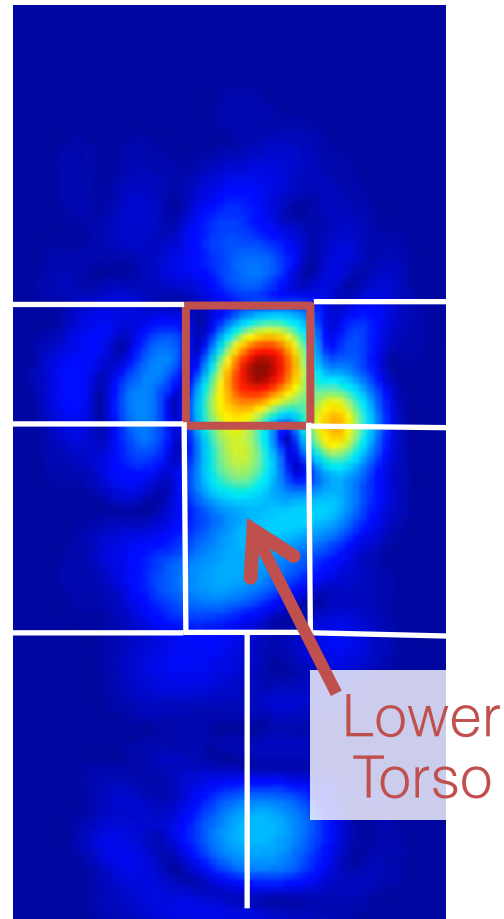
Use it as a pivot: for motion
compensation and segmentation

Human Walks toward Sensor

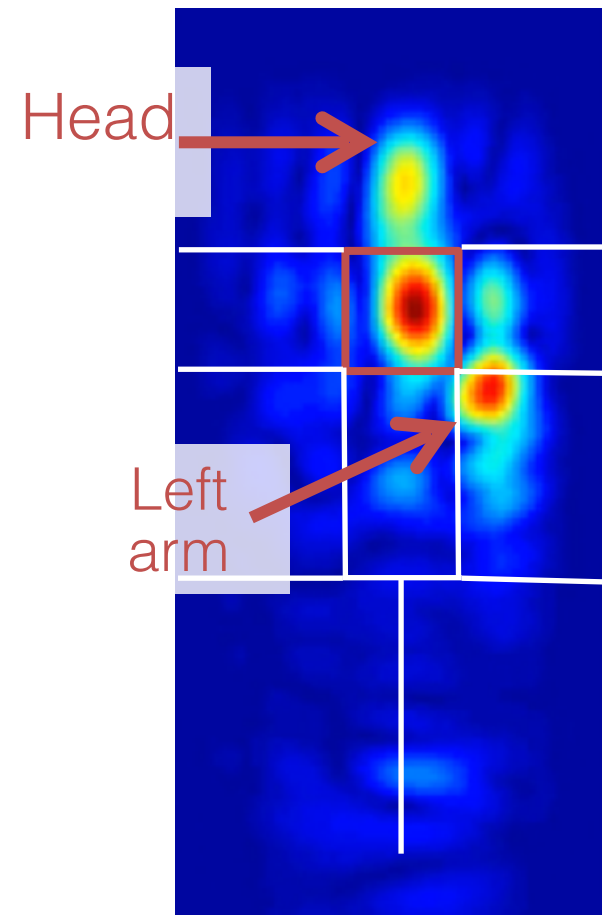
3m



2.5m



2m



Combine the various snapshots

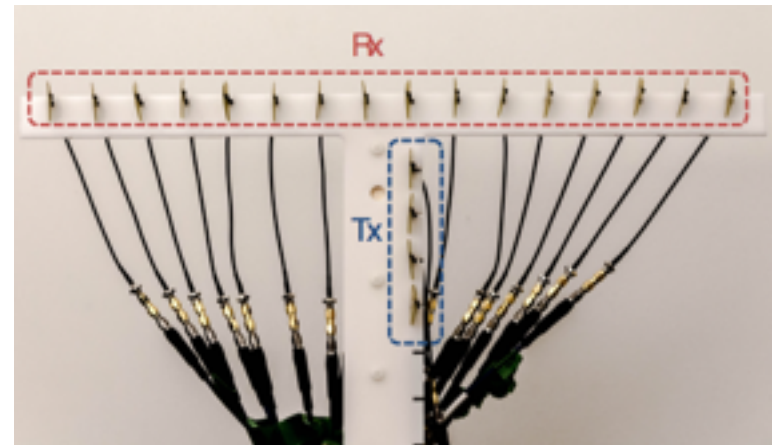
Human Walks toward Sensor



Implementation

- Hardware

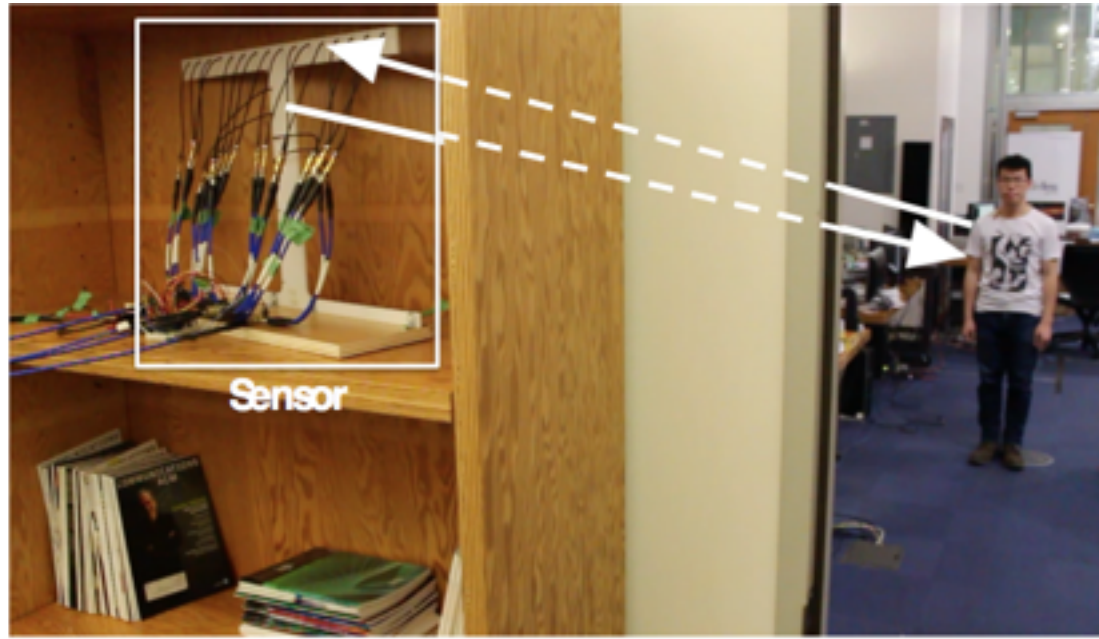
- 2D Antenna Array
- Built RF circuit
 - 1/1,000 power of WiFi
 - USB connection to PC



- Software

- Coarse-to-fine algorithm implemented in GPU to generate reflection snapshots in real-time

Evaluation

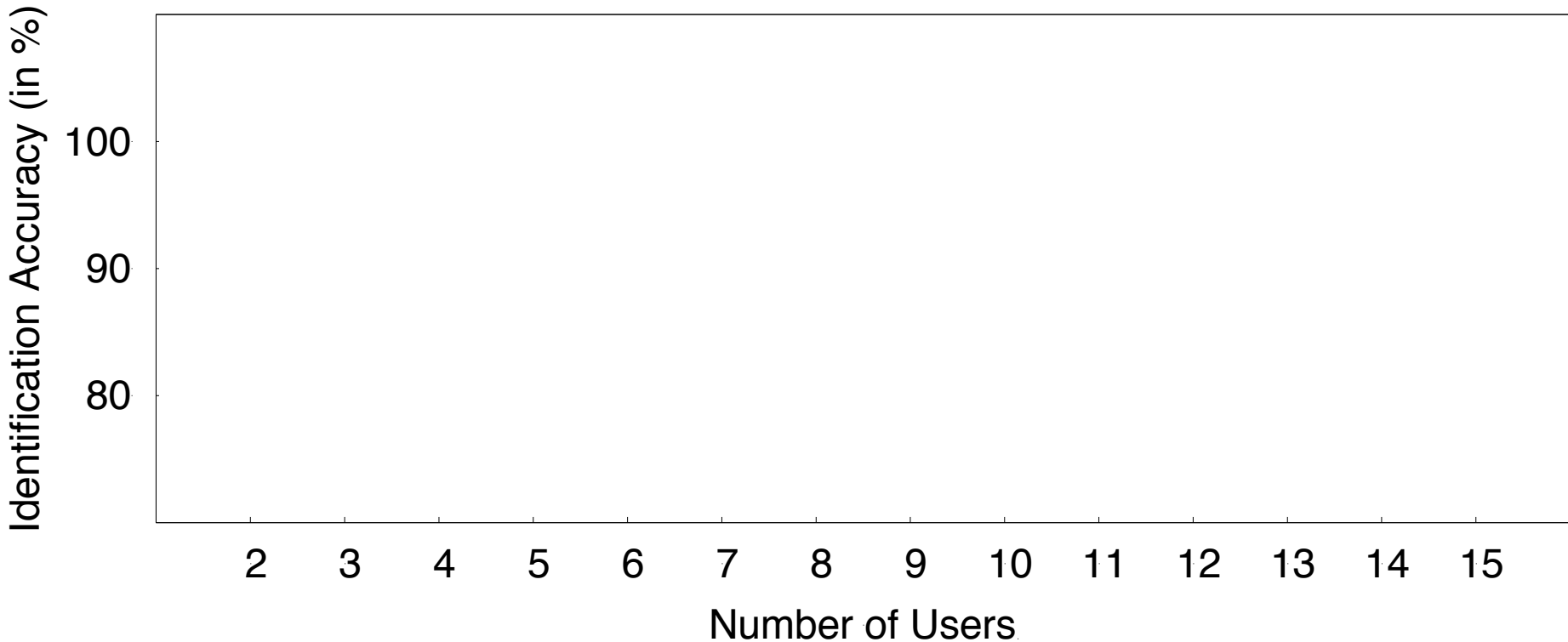


- RF-Capture sensor placed behind the wall
- 15 participants
- Use Kinect as baseline when needed

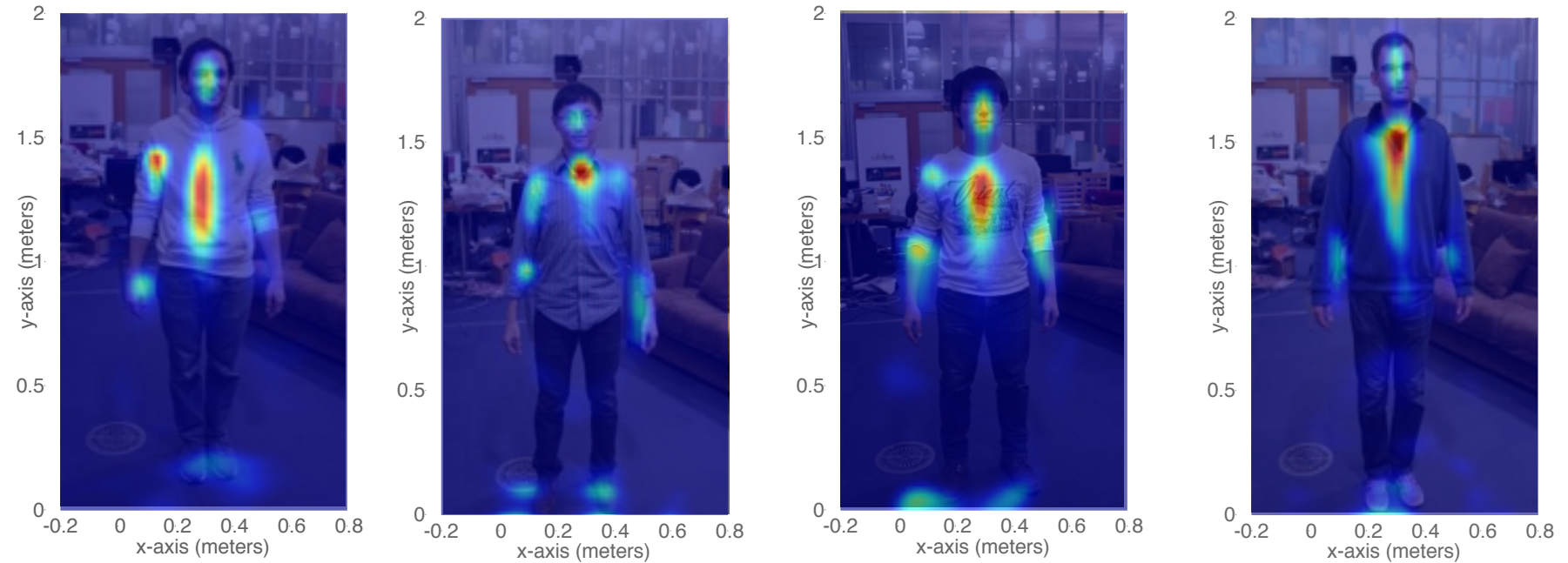
Distinguishing Among Subjects

Experiment: Subjects walk to device behind wall

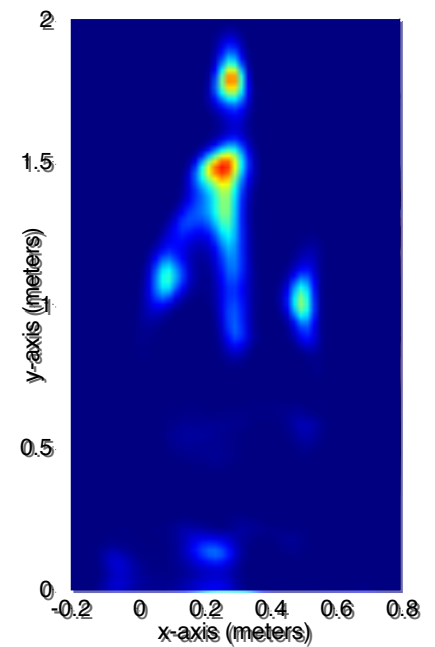
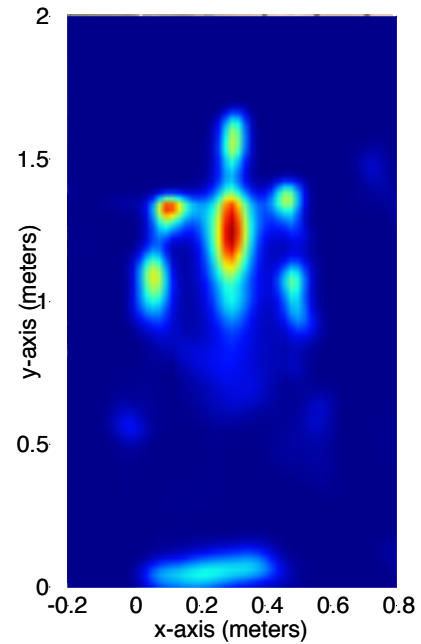
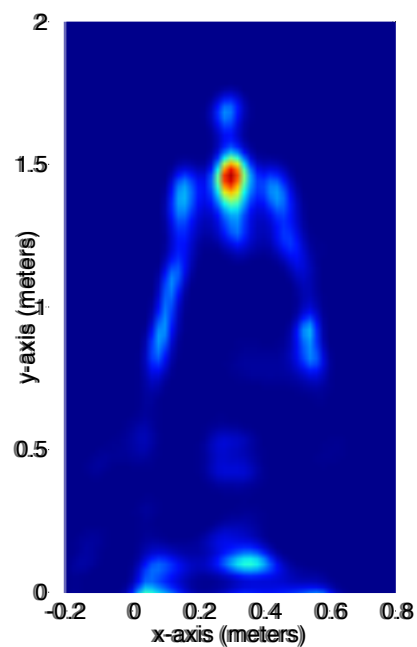
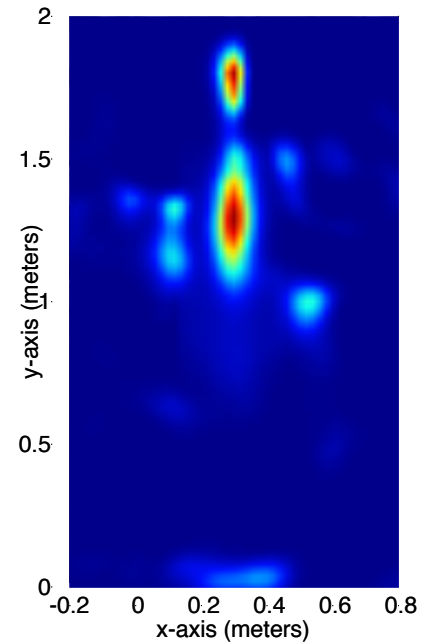
Training: PCA+SVM on captured figures



Sample Captured Figures through Walls



Through-wall classification accuracy of 90% among 13 users

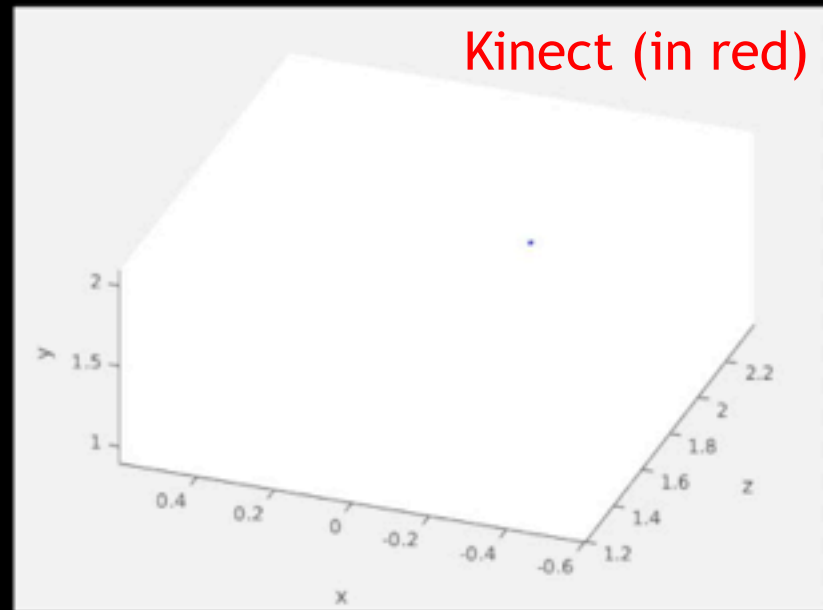


Writing in the air

Device



Our Tracking Result

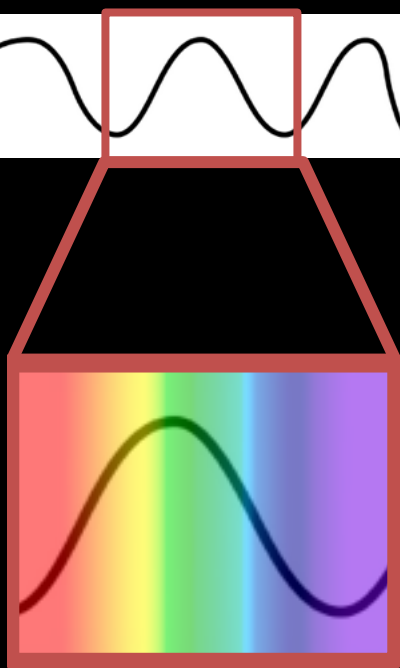
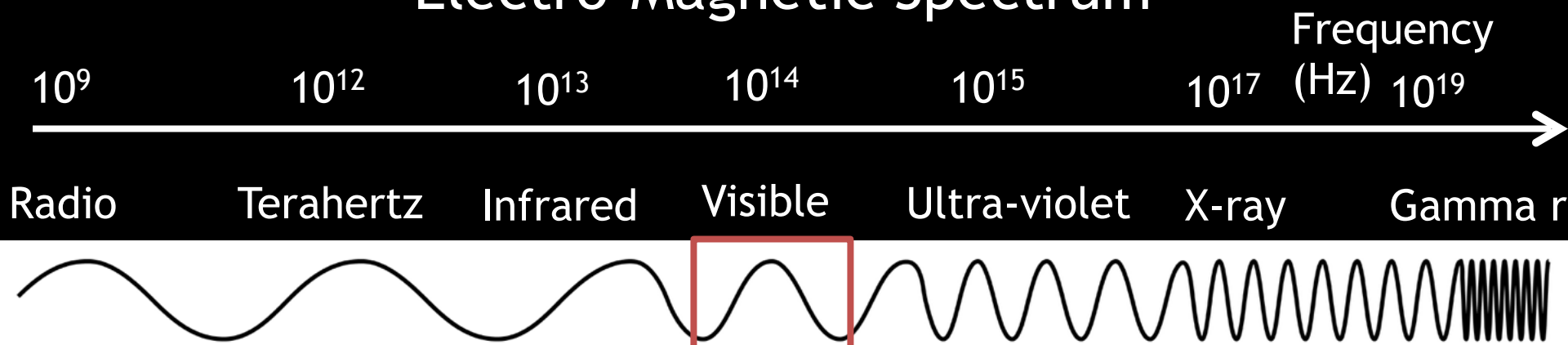


Median Accuracy is 2cm

Access to a new type of visual information by RF

Access to a new type of visual information by RF

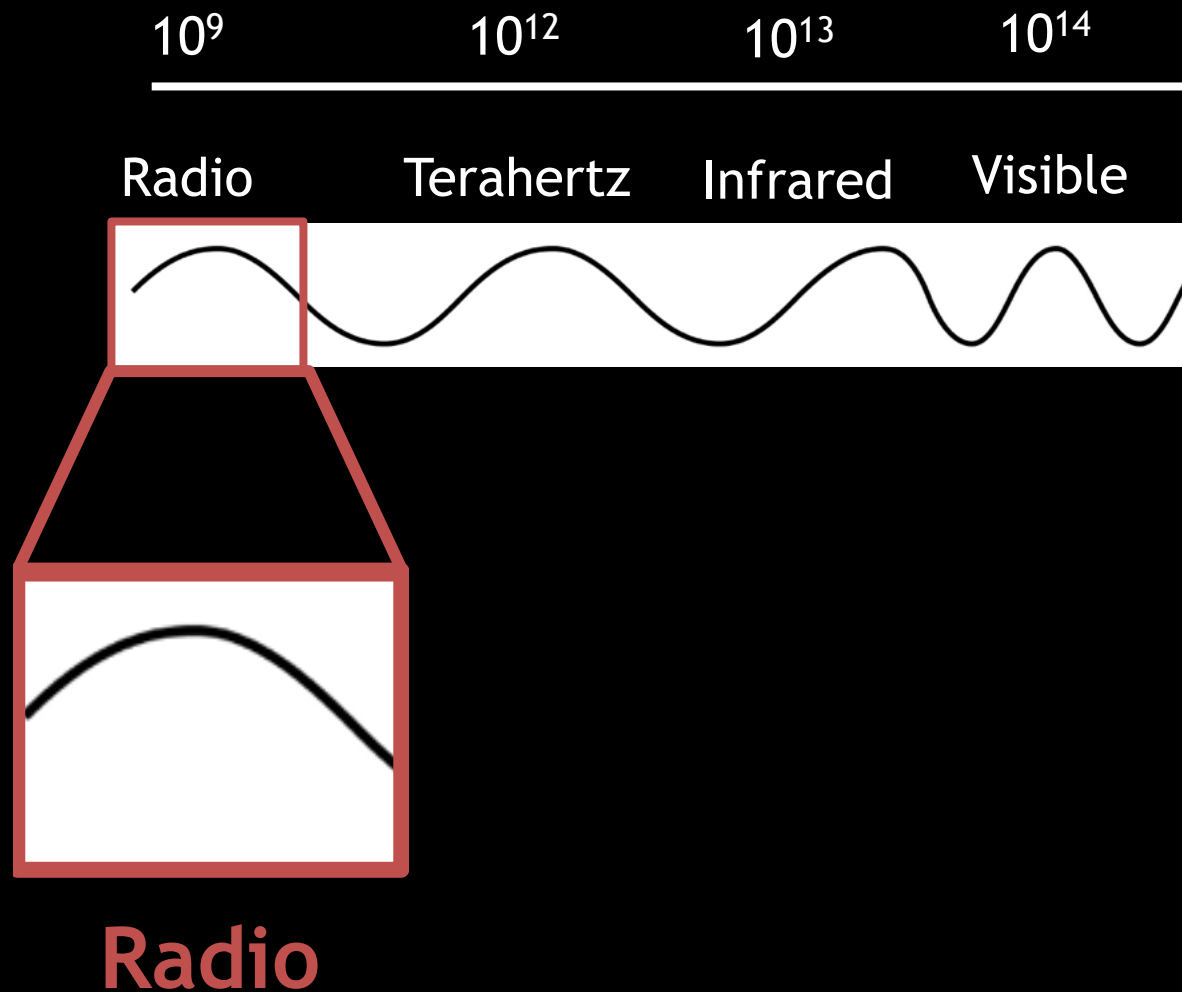
Electro-Magnetic Spectrum



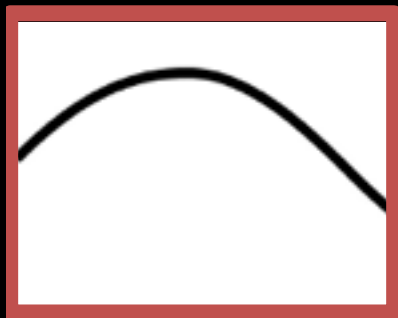
Visible

Access to a new type of visual information by RF

Electro-Magnetic Spectrum

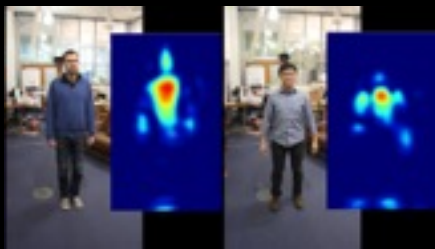


Access to a new type of visual information by RF



Radio

Applications



Challenges

- Achieving Sufficient Resolution
- Dealing with Specularity

Limitations

Limited Spatial & Temporal Resolution

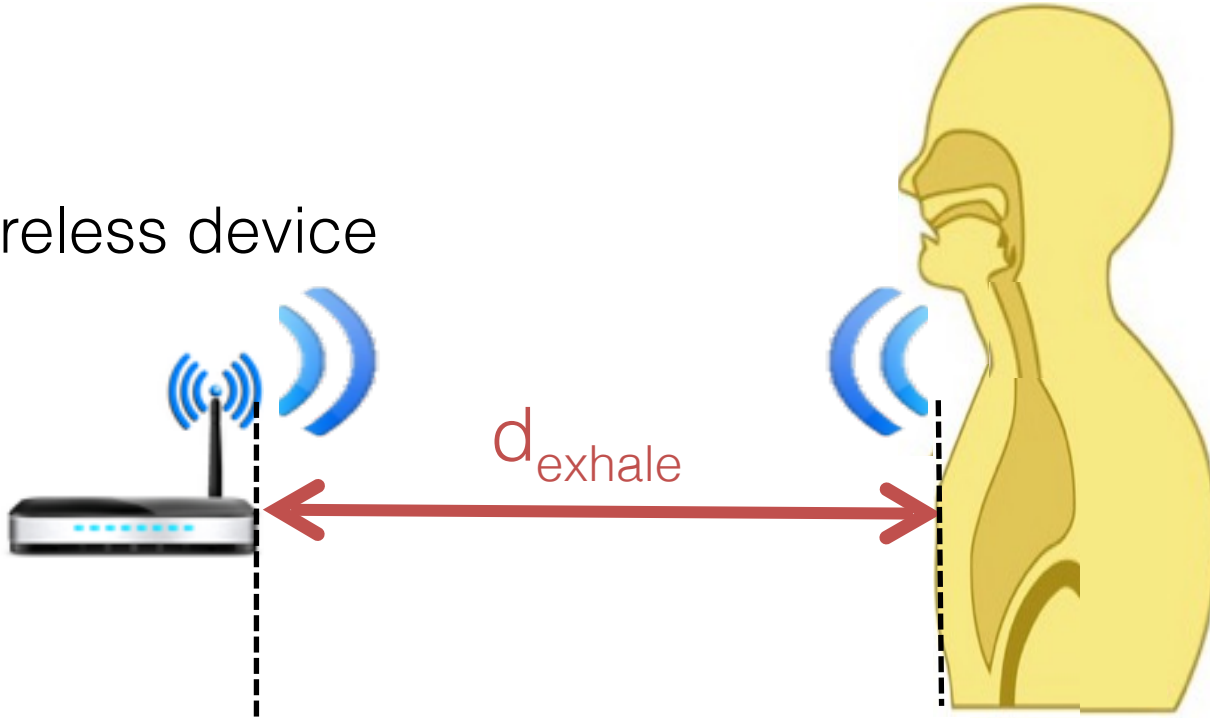
Device

Our Tracking Result

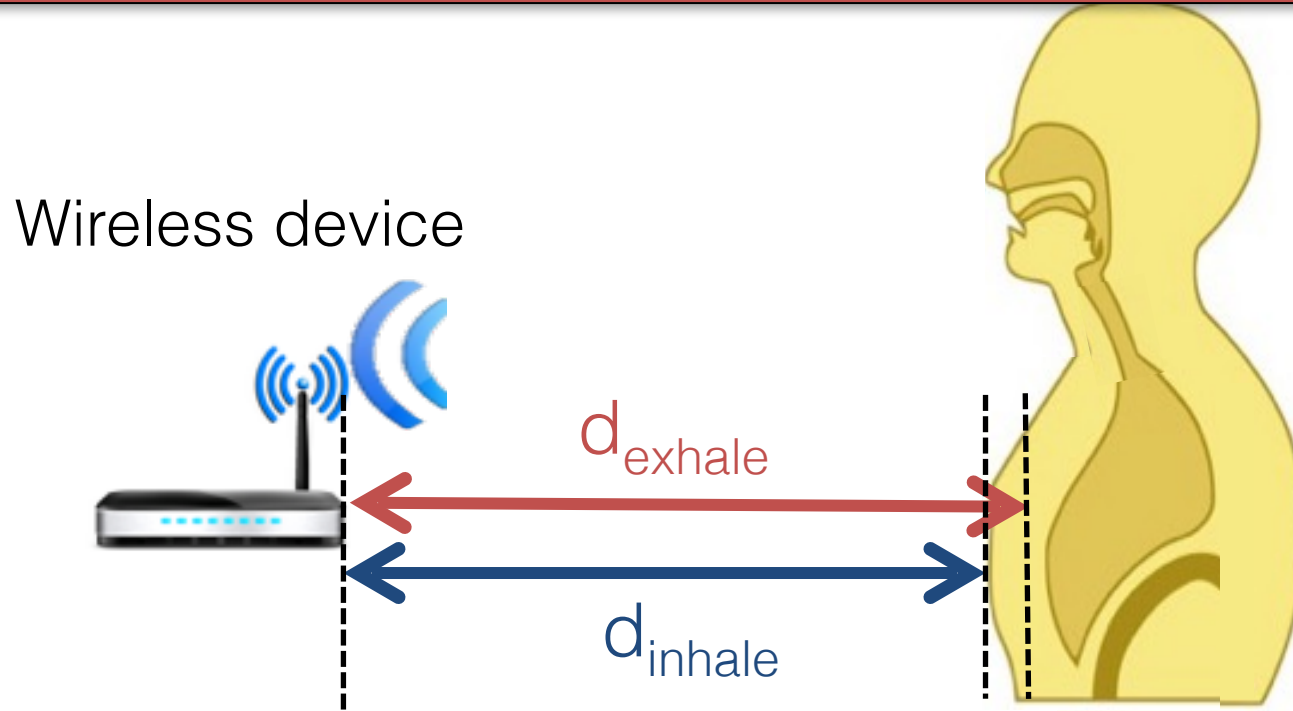


Vital Radio: Use wireless reflections off the human body to monitor breathing and heart rate

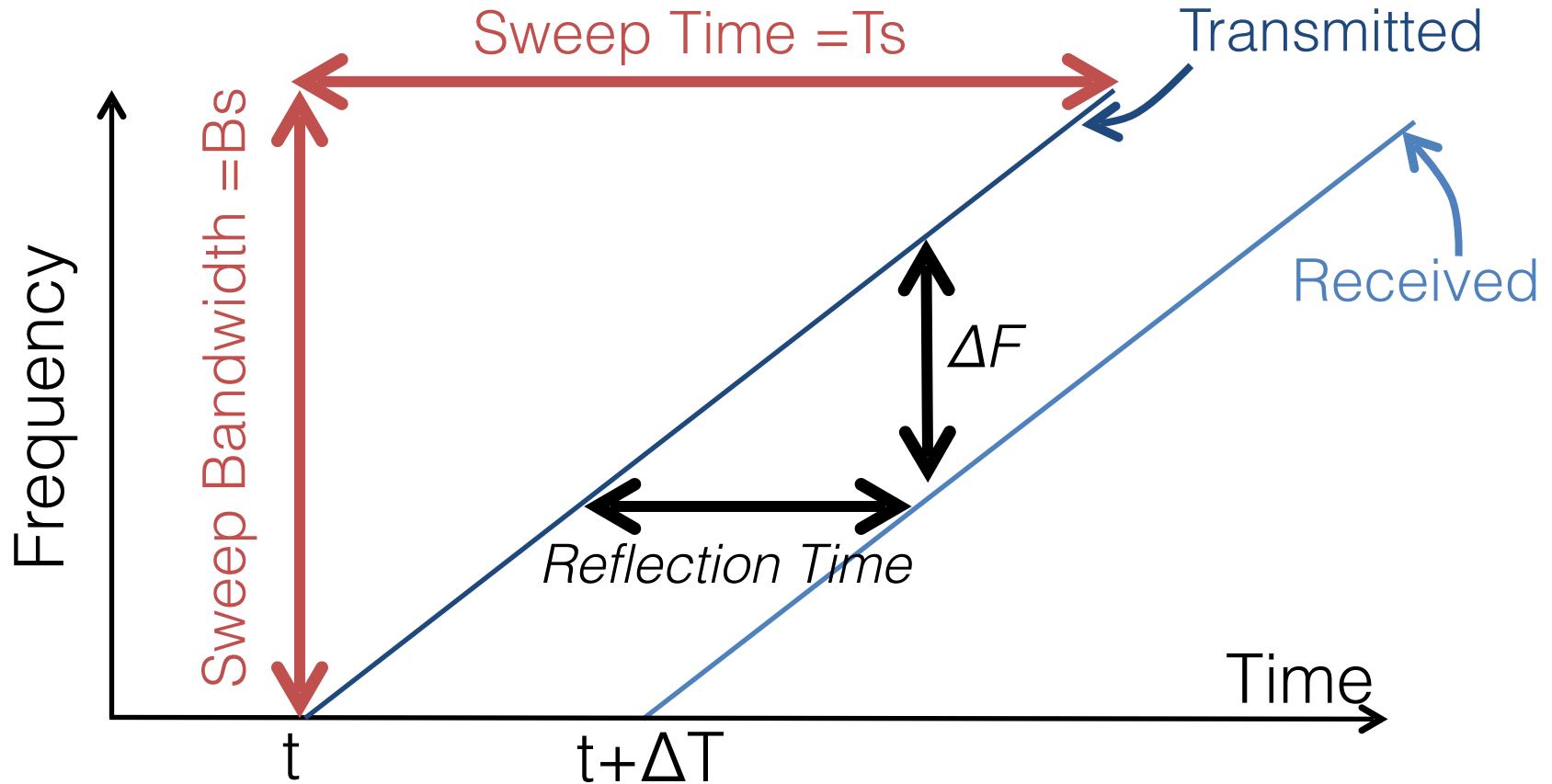
Wireless device



Problem: Localization accuracy is only 12cm and cannot capture vital signs



FMCW: Measure time by measuring frequency



$$\text{Slope} = k = B_s/T_s$$

$$\text{Reflection Time} = \Delta F/k$$

FMCW

- FMCW Transmitted Signal:

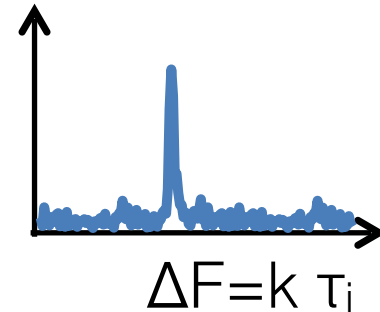
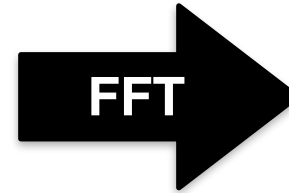
$$x(t) = e^{j2\pi(\frac{k}{2}(t^2 + f_0 t))}$$

- FMCW Received Signal:

$$y(t) = \sum_i A_i e^{j2\pi(\frac{k}{2}((t-\tau_i)^2 + f_0(t-\tau_i)))}$$

- FMCW after downconversion:

$$y_b(t) = \sum_i A_i e^{j2\pi(k\tau_i t + f_0\tau_i)}$$



- Sampling Rate = R

$$\Delta F < R \longrightarrow \tau_{\max} = R/k = R \times T_s / B_s \longrightarrow d_{\max} = c \times R \times T_s / 2B_s$$

FMCW

- FMCW Transmitted Signal:

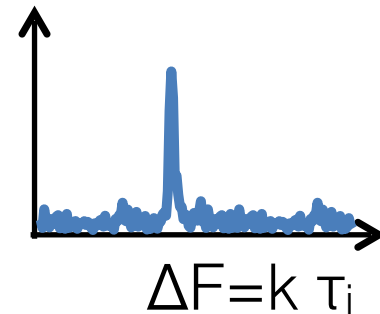
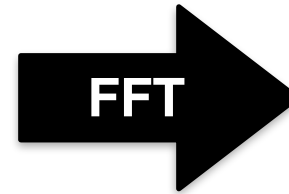
$$x(t) = e^{j2\pi(\frac{k}{2}(t^2 + f_0 t))}$$

- FMCW Received Signal:

$$y(t) = \sum_i A_i e^{j2\pi(\frac{k}{2}((t-\tau_i)^2 + f_0(t-\tau_i)))}$$

- FMCW after downconversion:

$$y_b(t) = \sum_i A_i e^{j2\pi(k\tau_i t + f_0\tau_i)}$$



- Sampling Rate = R

$$\Delta F < R \longrightarrow \tau_{\max} = R/k = R \times T_s / B_s \longrightarrow d_{\max} = c \times R \times T_s / 2 B_s$$

- Sampling Window = T_s

$$dF > 1/T_s \longrightarrow \tau_{\min} = 1/(k \times T_s) = 1/B_s \longrightarrow d_{\min} = c/2B_s$$

FMCW

- FMCW Transmitted Signal:

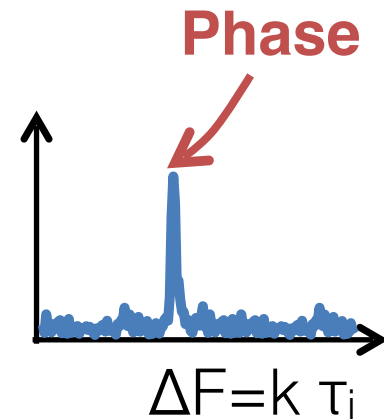
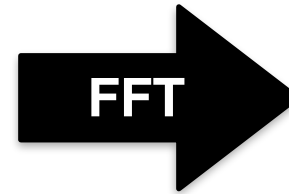
$$x(t) = e^{j2\pi(\frac{k}{2}(t^2 + f_0 t))}$$

- FMCW Received Signal:

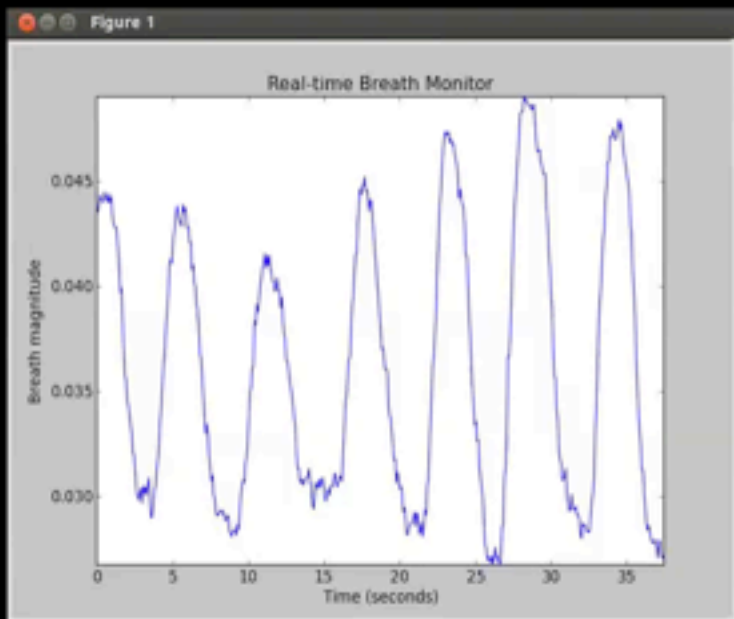
$$y(t) = \sum_i A_i e^{j2\pi(\frac{k}{2}((t-\tau_i)^2 + f_0(t-\tau_i)))}$$

- FMCW after downconversion:

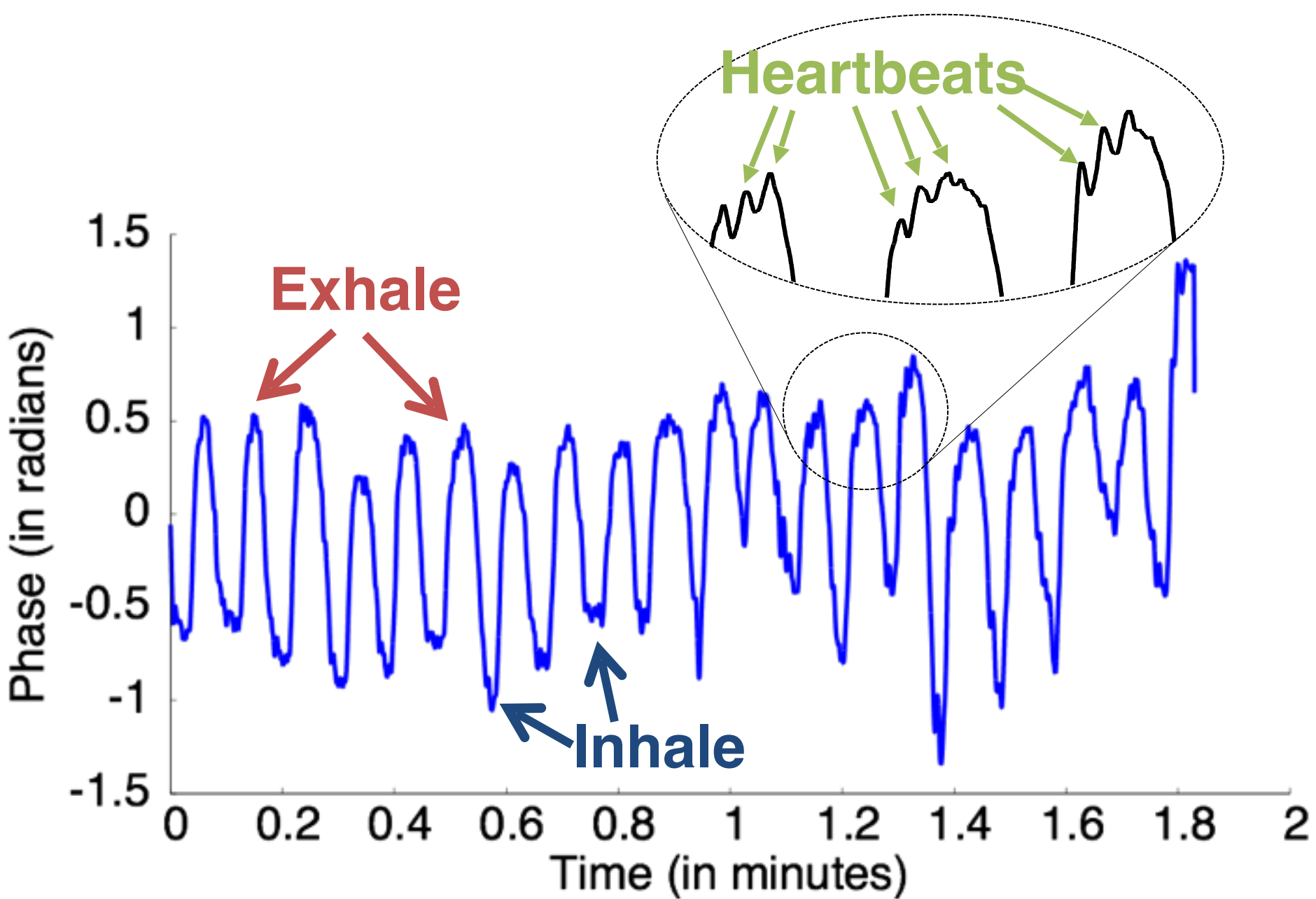
$$y_b(t) = \sum_i A_i e^{j2\pi(k\tau_i t + f_0\tau_i)}$$



- Phase of peak = $f_0\tau_i$
 - Phase wraps around 2π
 - Use peak position $\Delta F = k \tau_i$ for coarse estimate of τ_i
 - Use peak phase $f_0\tau_i$ for fine estimate of τ_i

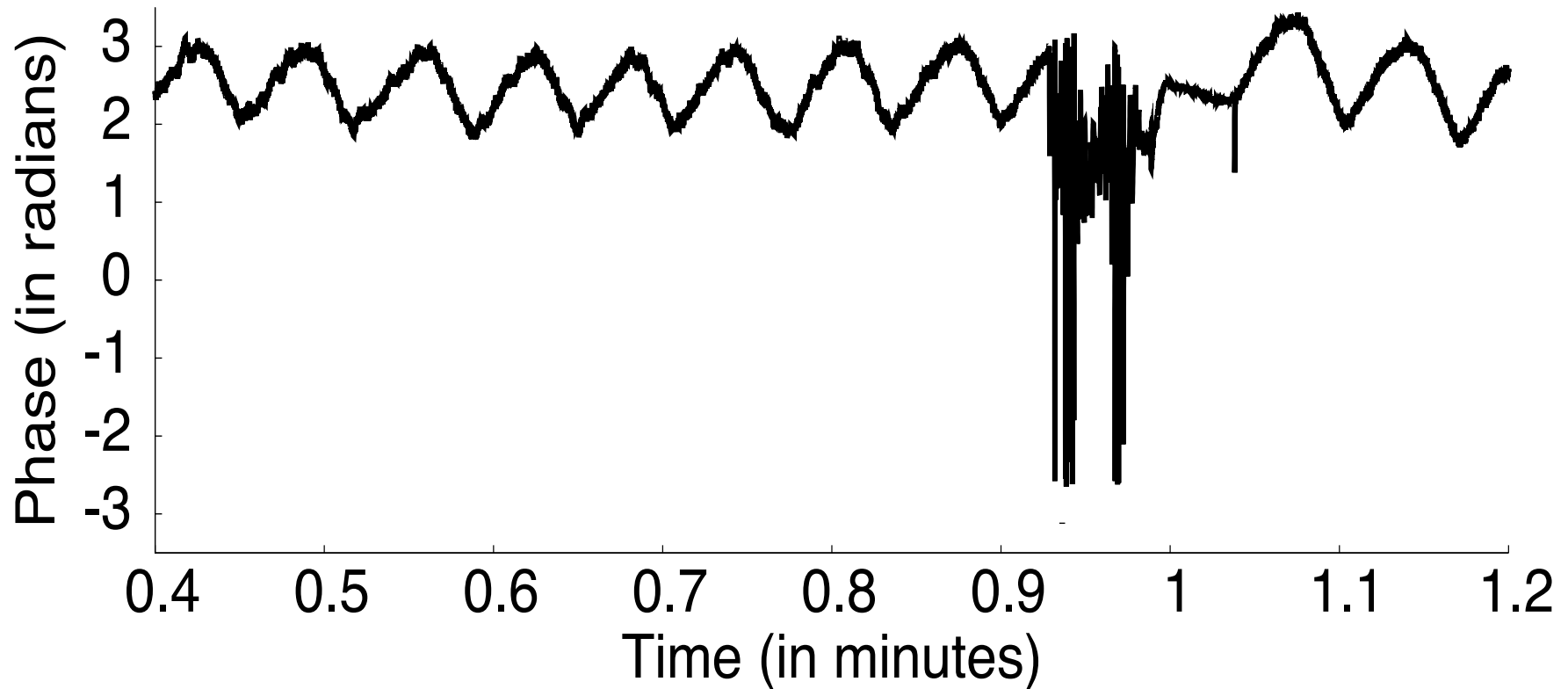


Let's zoom in on these signals

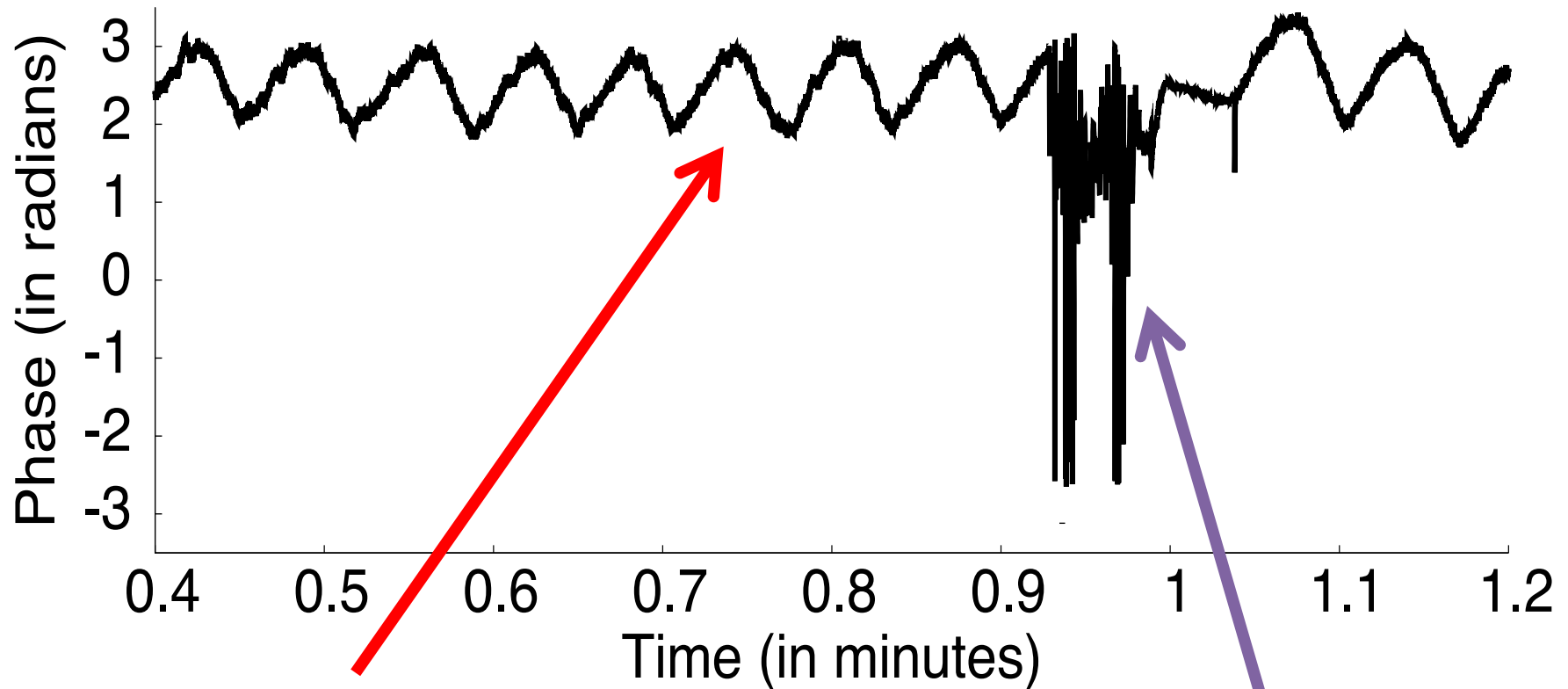


What happens when a person moves
his limb?

What happens when a person moves his limb?



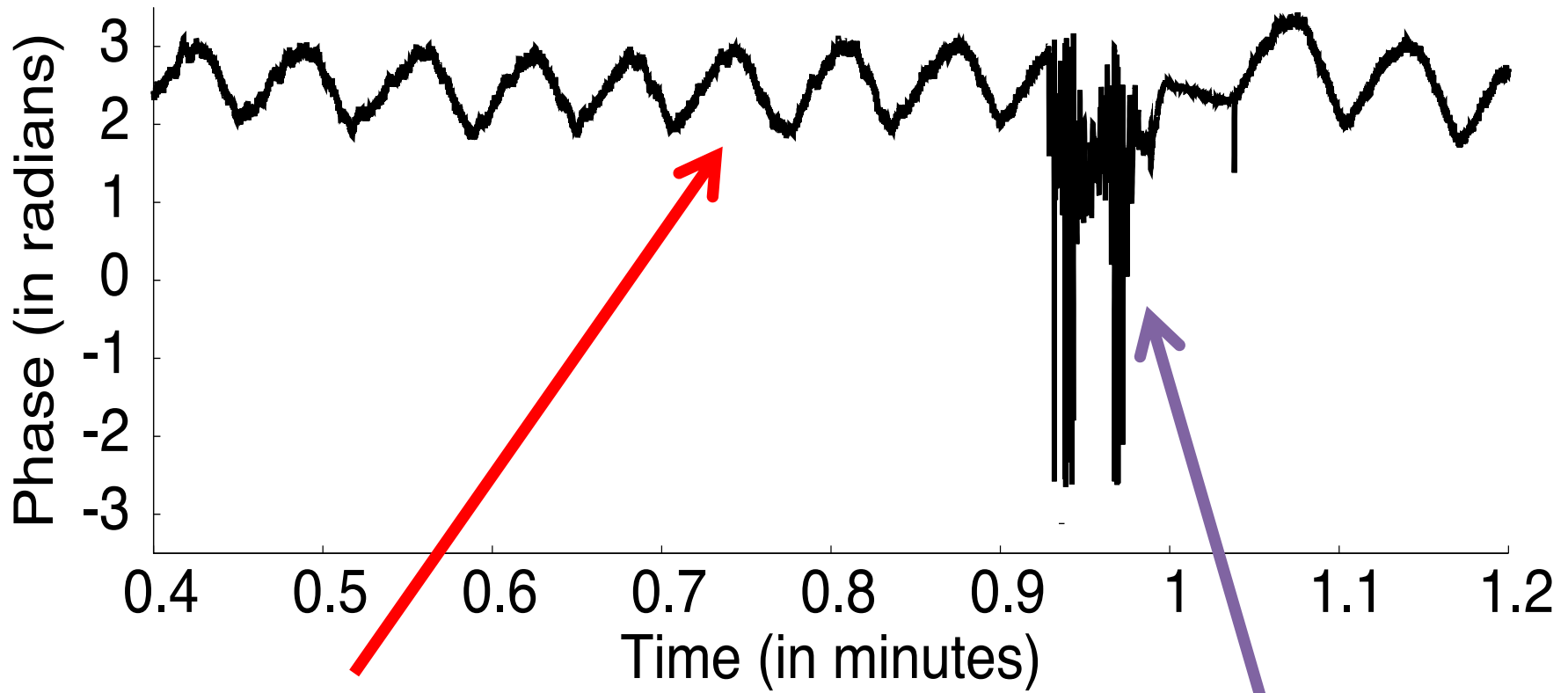
What happens when a person moves his limb?



Breathing
Periodic

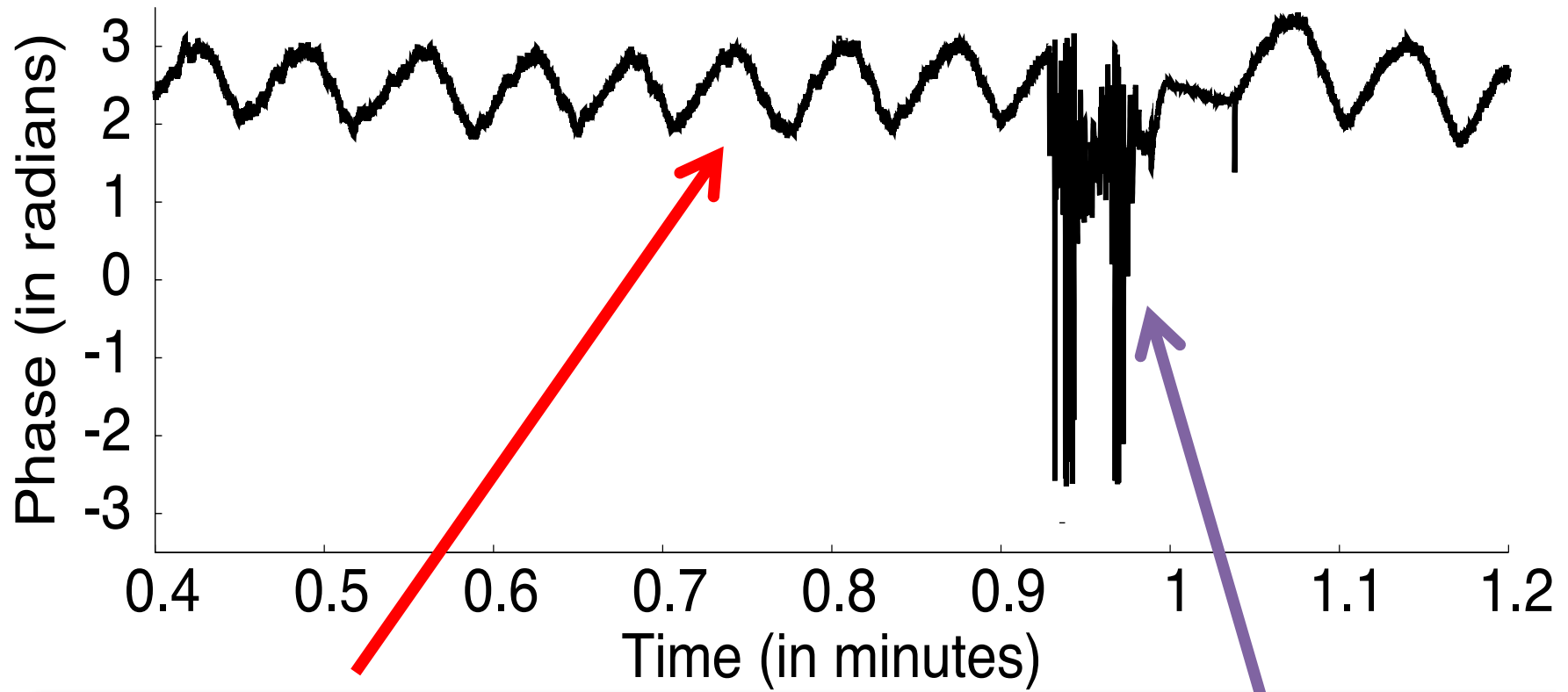
Limb Motion
Not periodic

What happens when a person moves his limb?



Use periodicity test to eliminate variations that are not due to breathing/heartbeats

What happens when a person moves his limb?

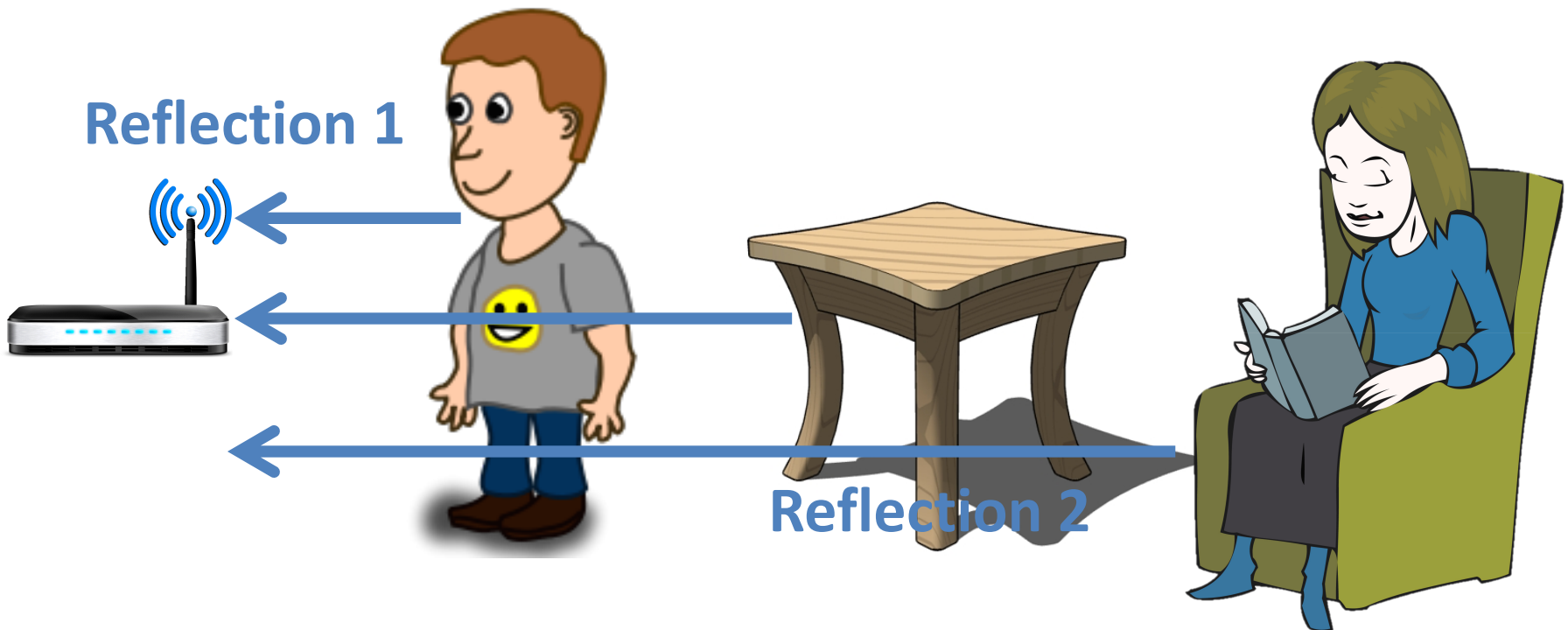


Band-pass filter the cleaned signals to extract breathing and heart rate

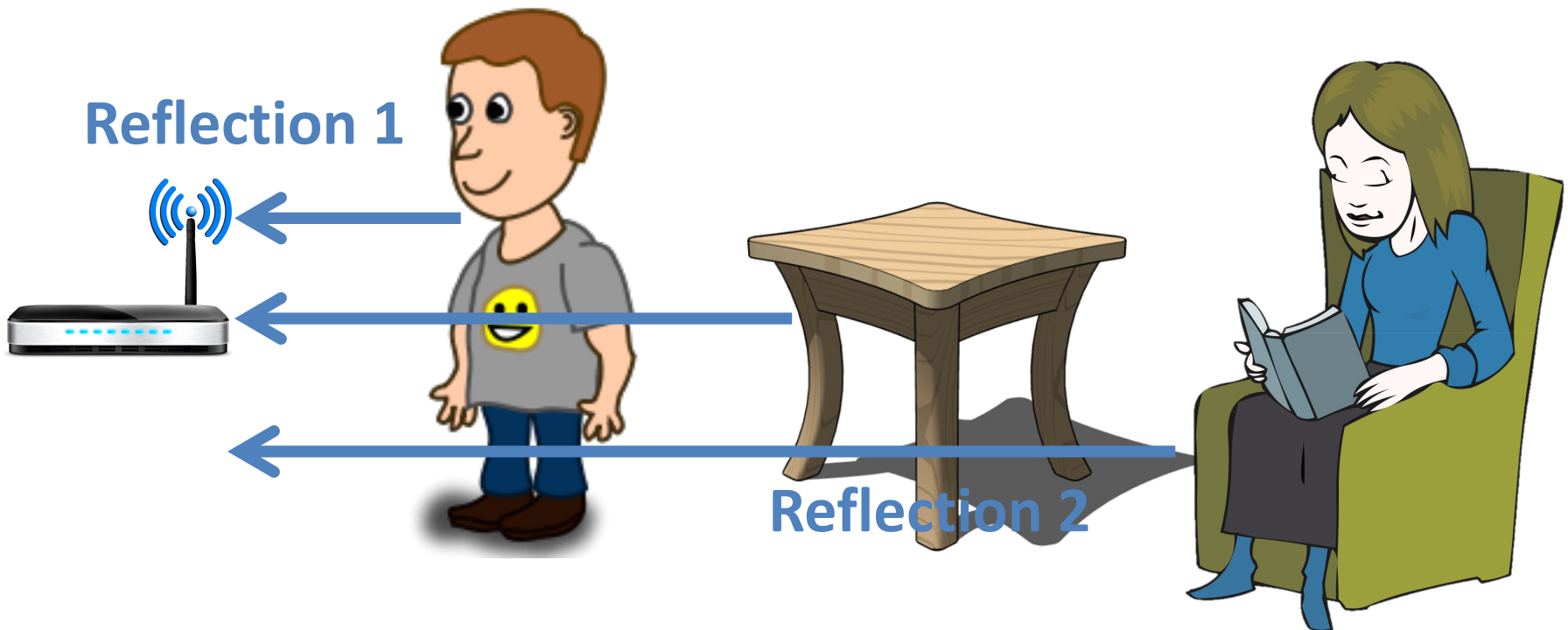
What happens with multiple users in the environment?

Reflections from different objects **collide**

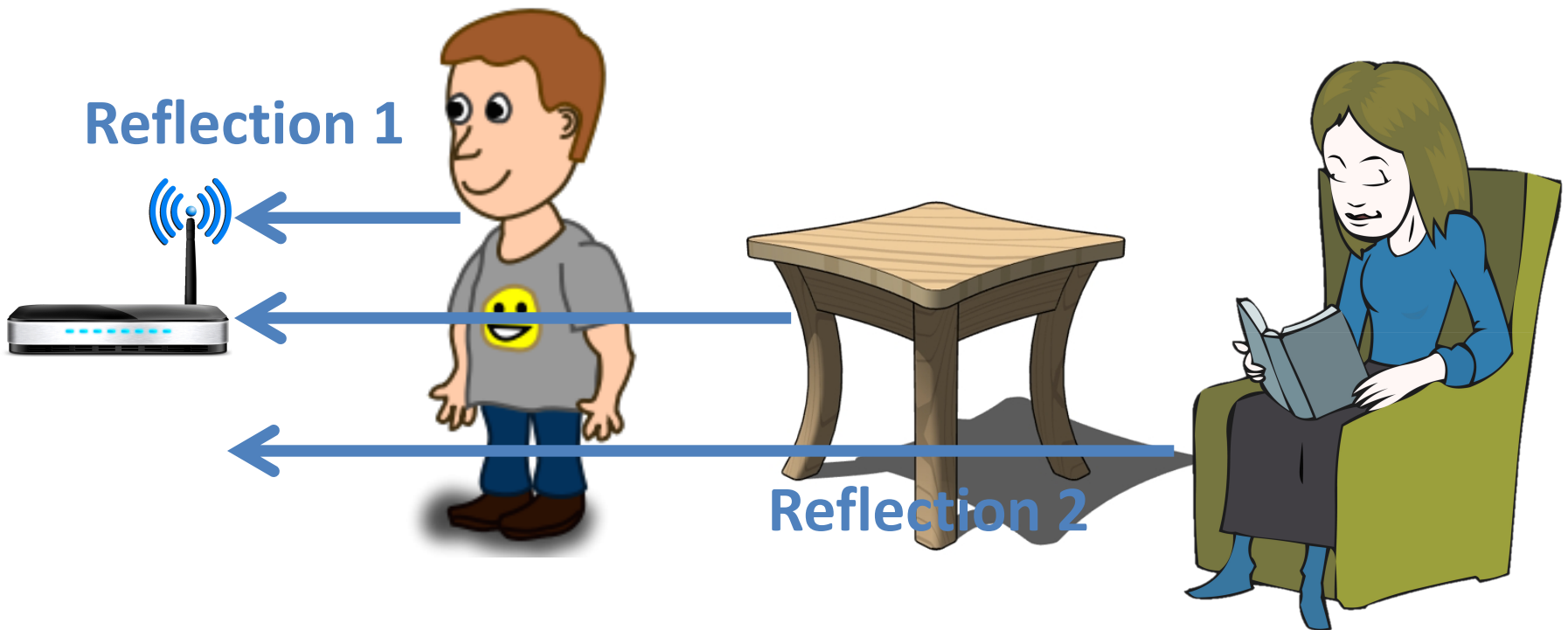
Problem: Phase becomes meaningless!



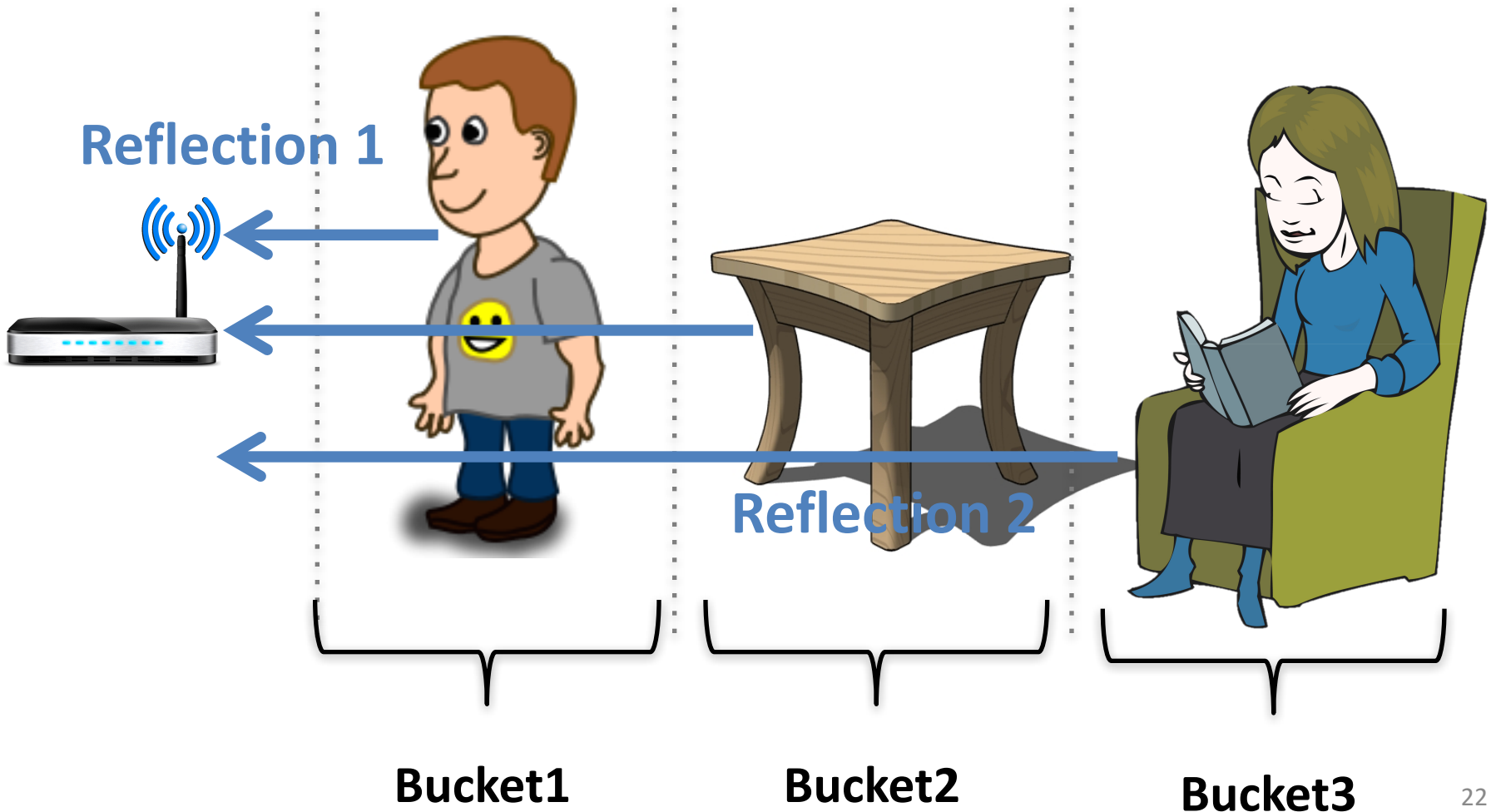
Idea: **Wireless localization** can be used to locate various devices



Solution: Use **wireless localization as a filter** to isolate reflections from different positions



Solution: Use **wireless localization as a filter** to isolate reflections from different positions



Putting It Together

Step 1: Transmit a wireless signal and capture its reflections

Step 2: Isolate reflections from different objects based on their positions

Step 3: Zoom in on each object's reflection to obtain phase variations due to vital signs

Through-wall breath monitoring of multiple users

It captures chest motion using wireless signal reflections



Device is
behind
the wall

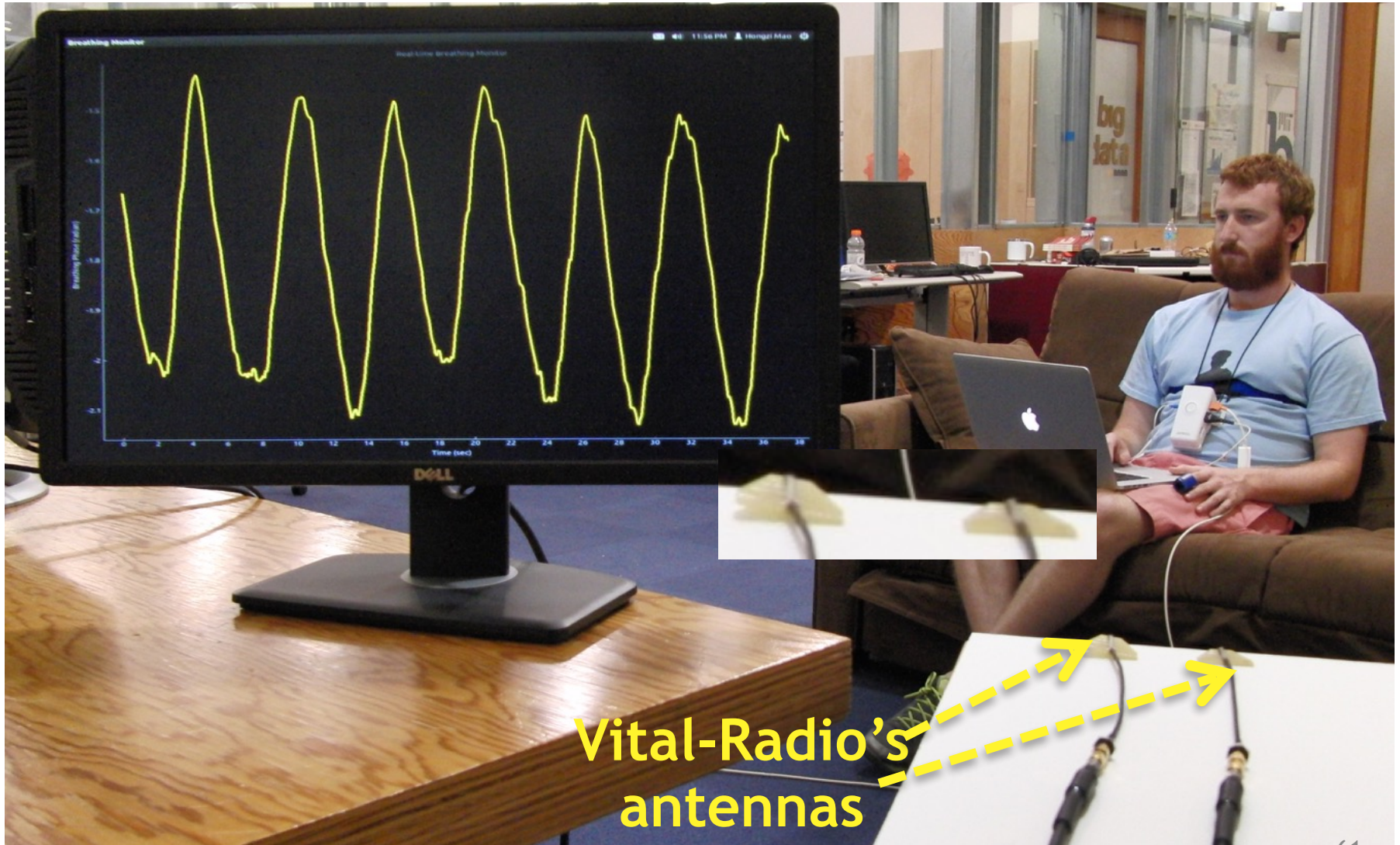
Vital-Radio Implementation

- Wireless positioning device to transmits and receives wireless signals
 - 10,000x lower power than cellphones
 - 1 transmit & 1 receive antenna



- Signal is analyzed in software to extract vital signs

Vital-Radio Implementation



Vital-Radio's
antennas

Vital-Radio Evaluation

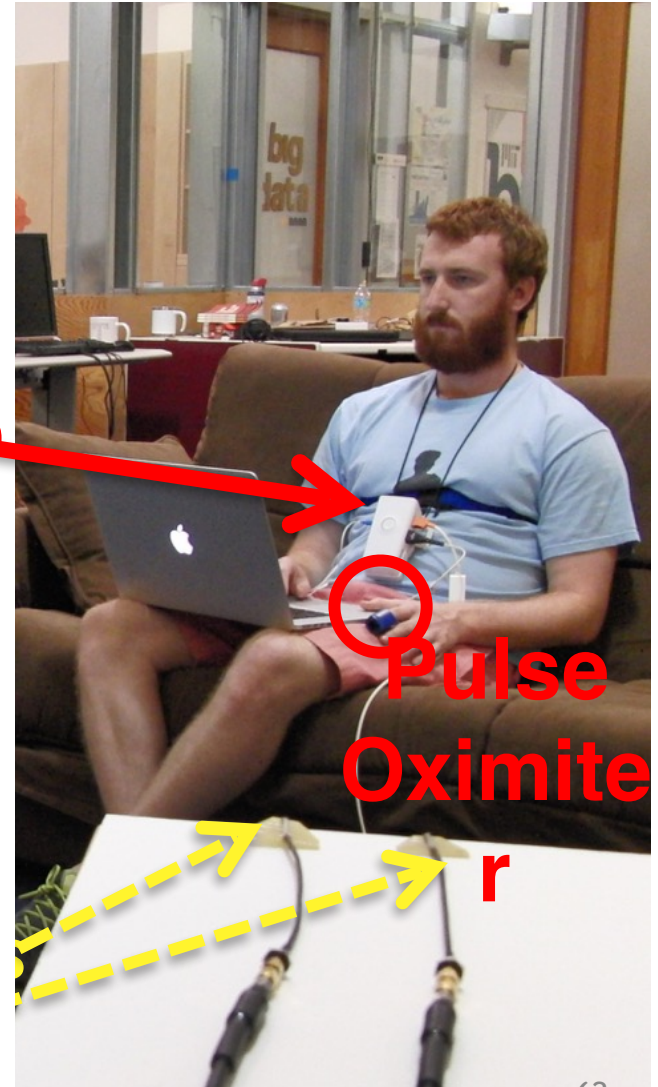
Baseline:

- FDA-approved breathing and heart rate monitor

Chest Strap

Experiments:

- 200 experiments
- 14 participants
- 1 million measurements



Accuracy vs. Orientation

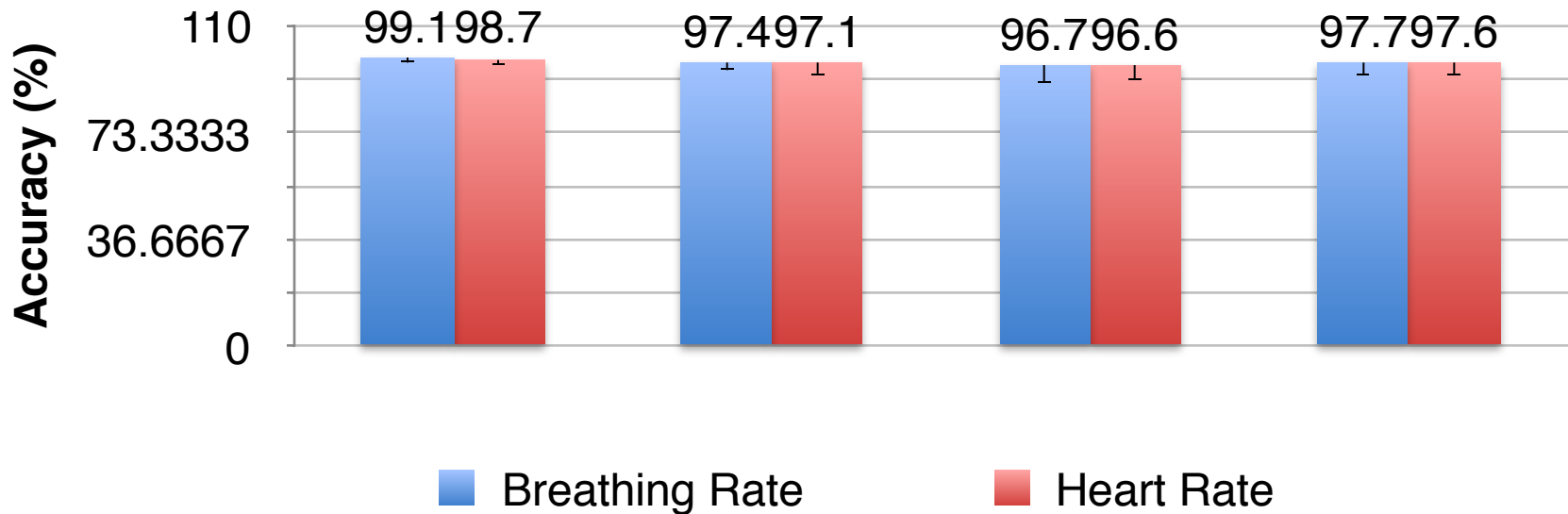
User is 4m from device, with different orientations

Forward

Right

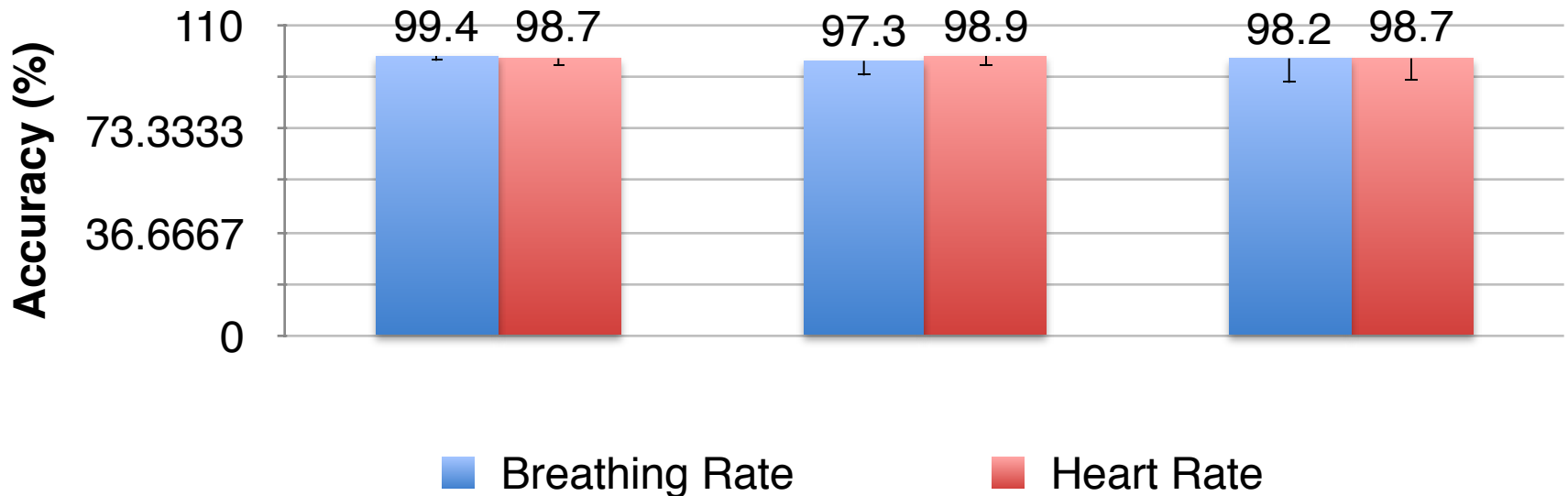
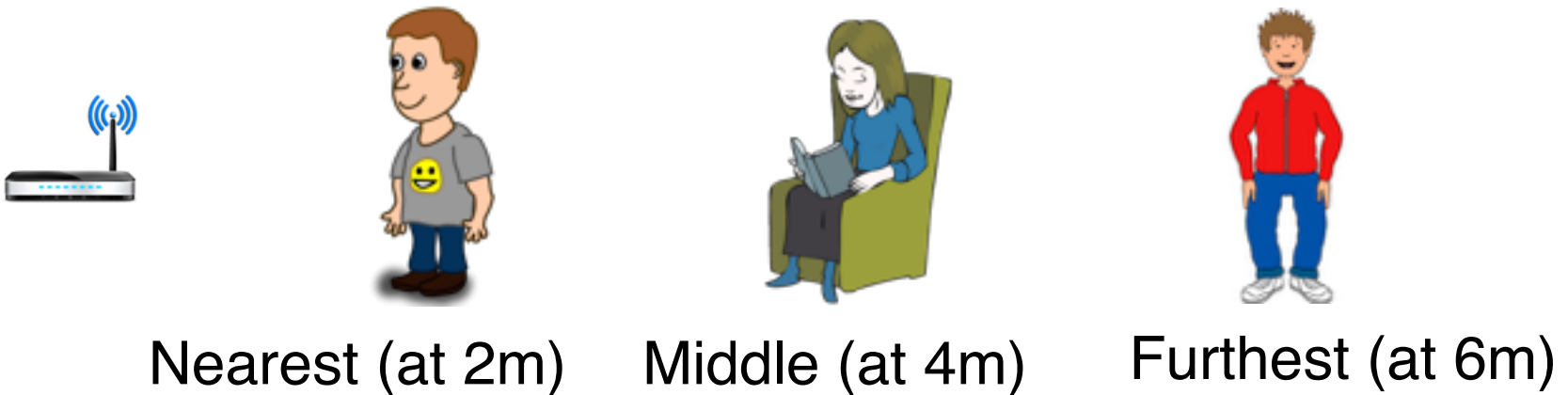
Backward

Left



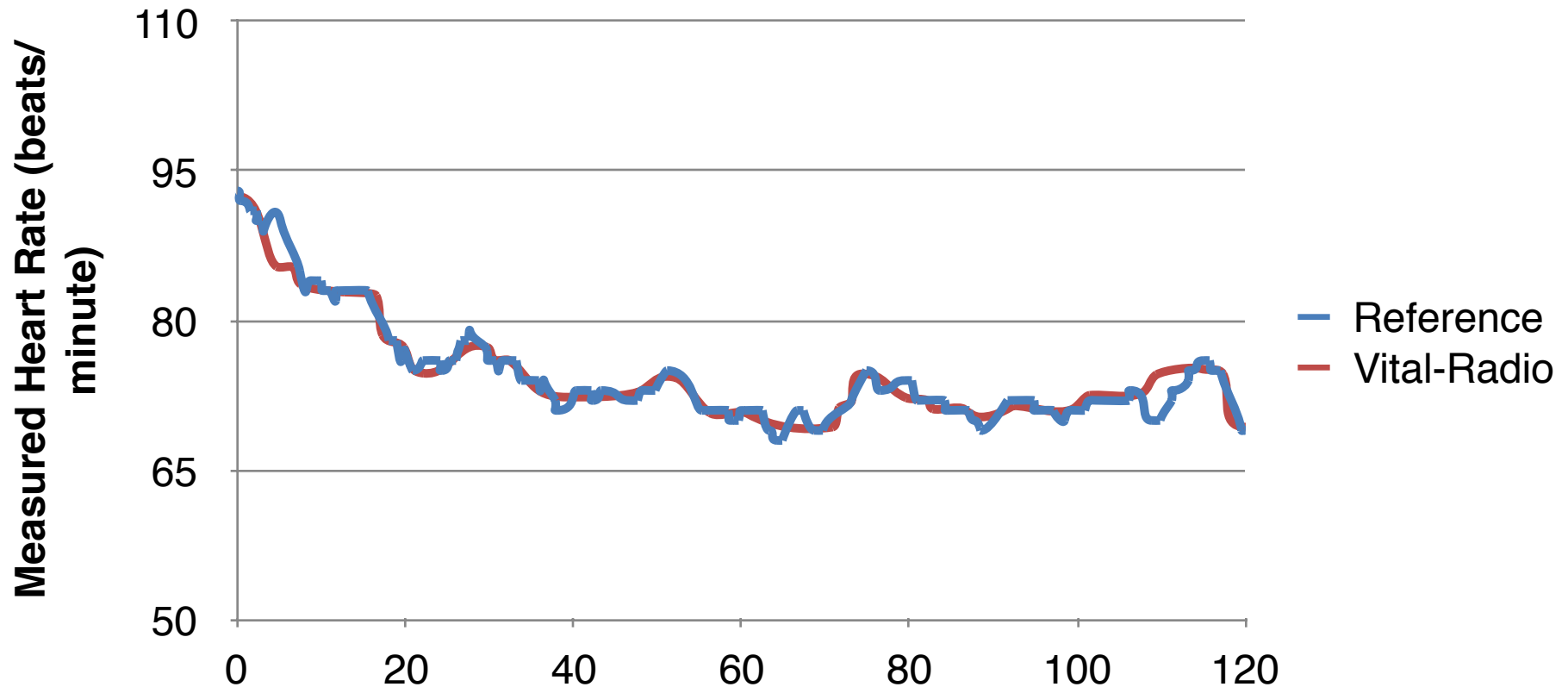
Accuracy for Multi-User Scenario

Multiple users sit at different distances



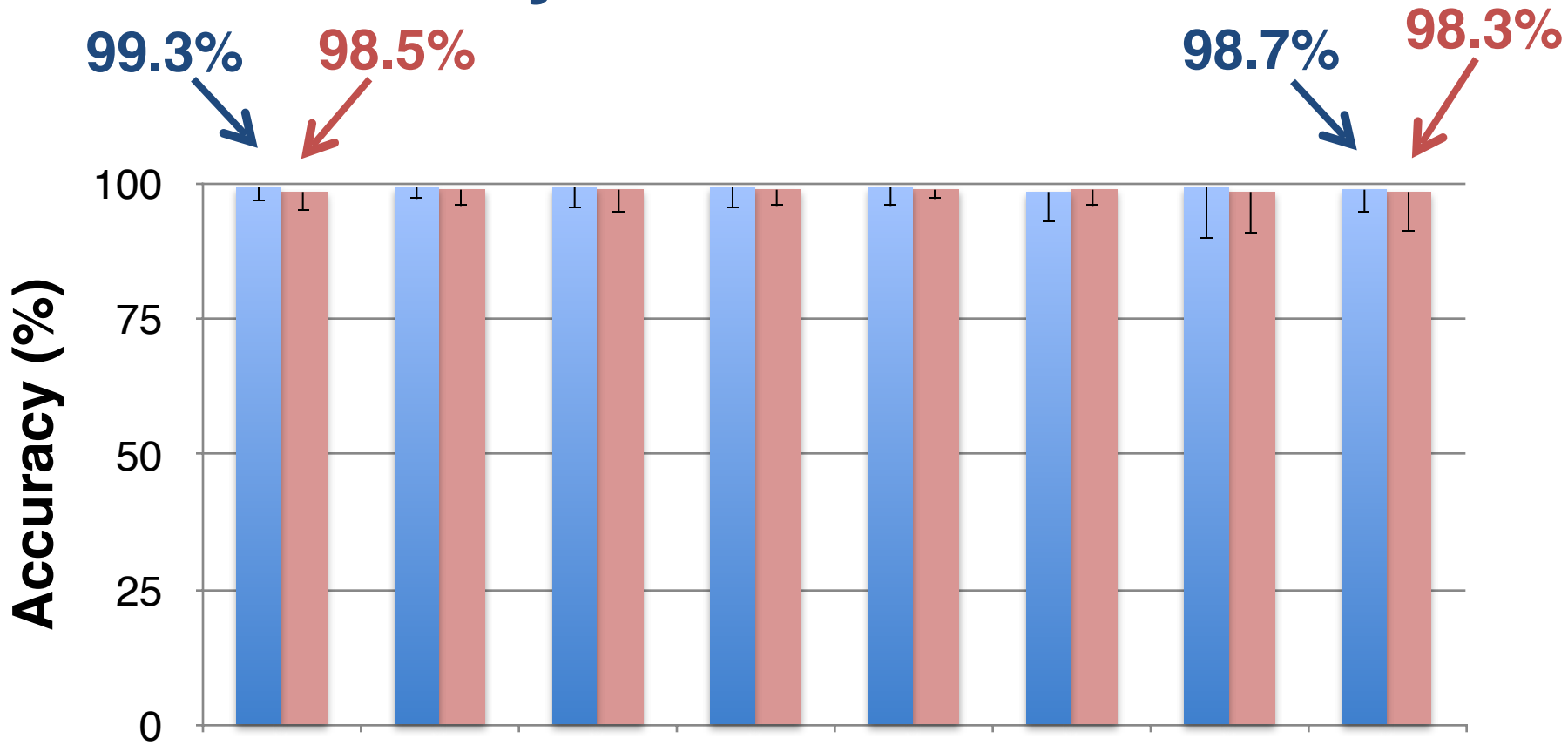
Accuracy for Tracking Heart Rate

Measure user's heart rate after exercising



Vital-Radio accurately tracks changes in vital signs

Accuracy versus Distance



Breathing and Heart Rate Accuracy is ~99% in comparison to FDA-approved baseline

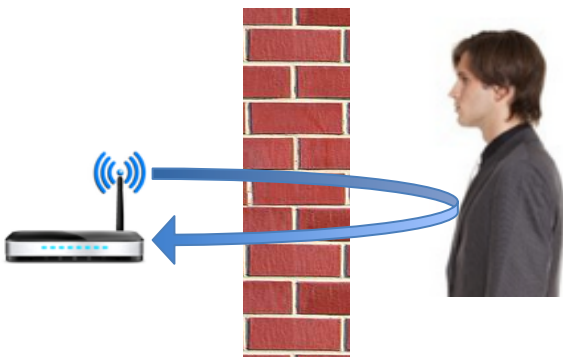
Accuracy for various cases

- User sits at 4m from device



- Highest when facing (99%), lowest for back (96%)

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- Through-Wall: User sits behind the wall (at 4m)



- Breathing: **99.2%**
- Heart Rate: **90.1%**

Accuracy for various cases

- **Multi-User:** Users sit at different distances



Nearest: **99.1%**

Middle: **98.1%**

Furthest: **98.4%**

- **Daily Activities:**



Smartphone: **99.2%**



Laptop: **99%**

Vital-Radio Limitations

- Minimum separation between users: 1-2m
- Monitoring range: 8m
- Collects measurements when users are quasi-static

Baby Monitoring

