

# ECE 598HH: Advanced Wireless Networks and Sensing Systems

## Lecture 9: MIMO Part 2

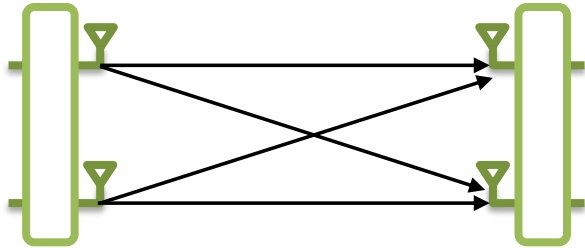
### Haitham Hassanieh



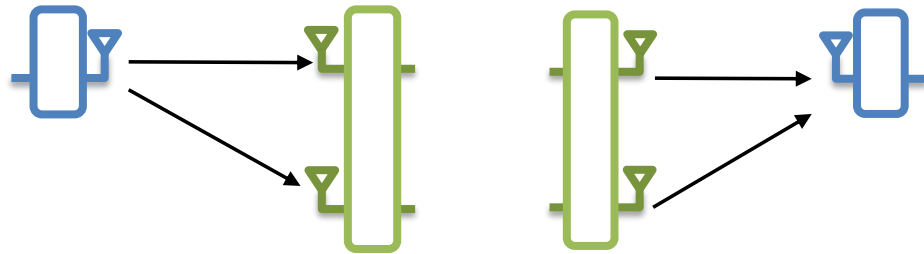
\*Some of the slides in this lecture are courtesy of on Kate Lin, Hariharan Rahul, & Omid Abari

# Last Lecture

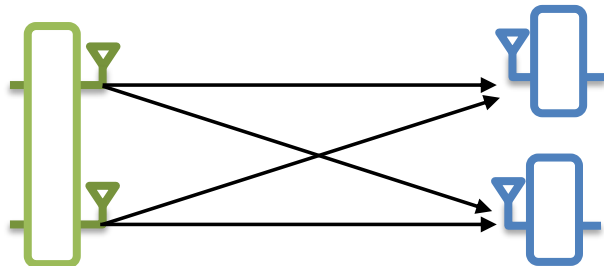
## MIMO Multiplexing Gain



## MIMO TX/RX Diversity Gain

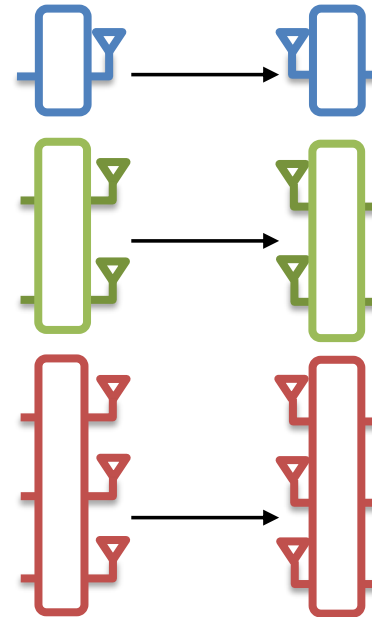


## MU-MIMO Beamforming

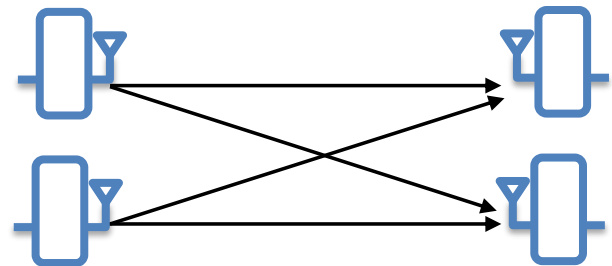


# This Lecture

## Heterogeneous # of antennas (Interference Nulling/Alignment)



## Distributed MIMO





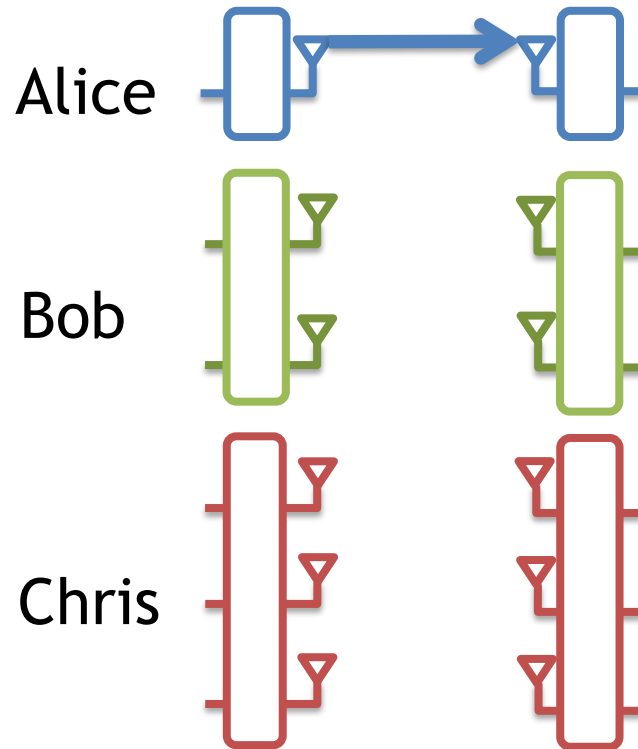
1-antenna devices

2-antenna devices

3-antenna devices

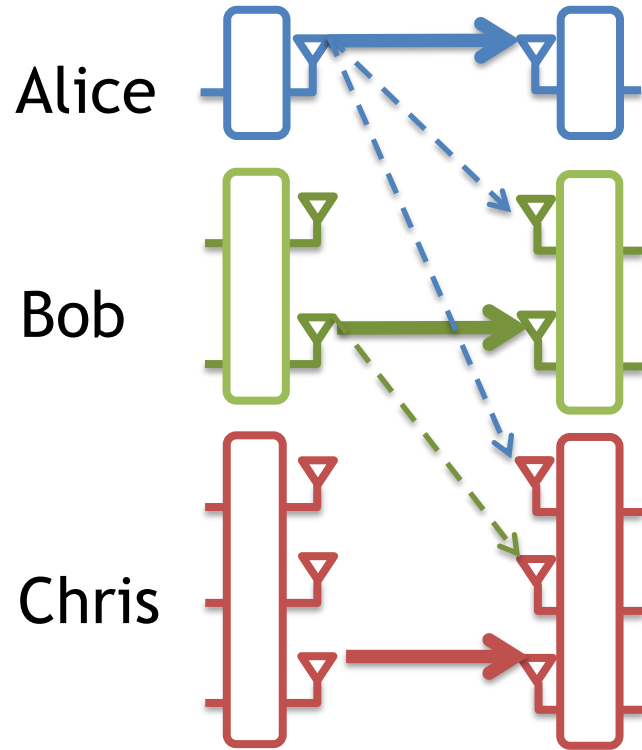
Wireless nodes increasingly have  
**heterogeneous numbers of antennas**

Consider a scenario with Tx-Rx pairs that have a different number of antennas

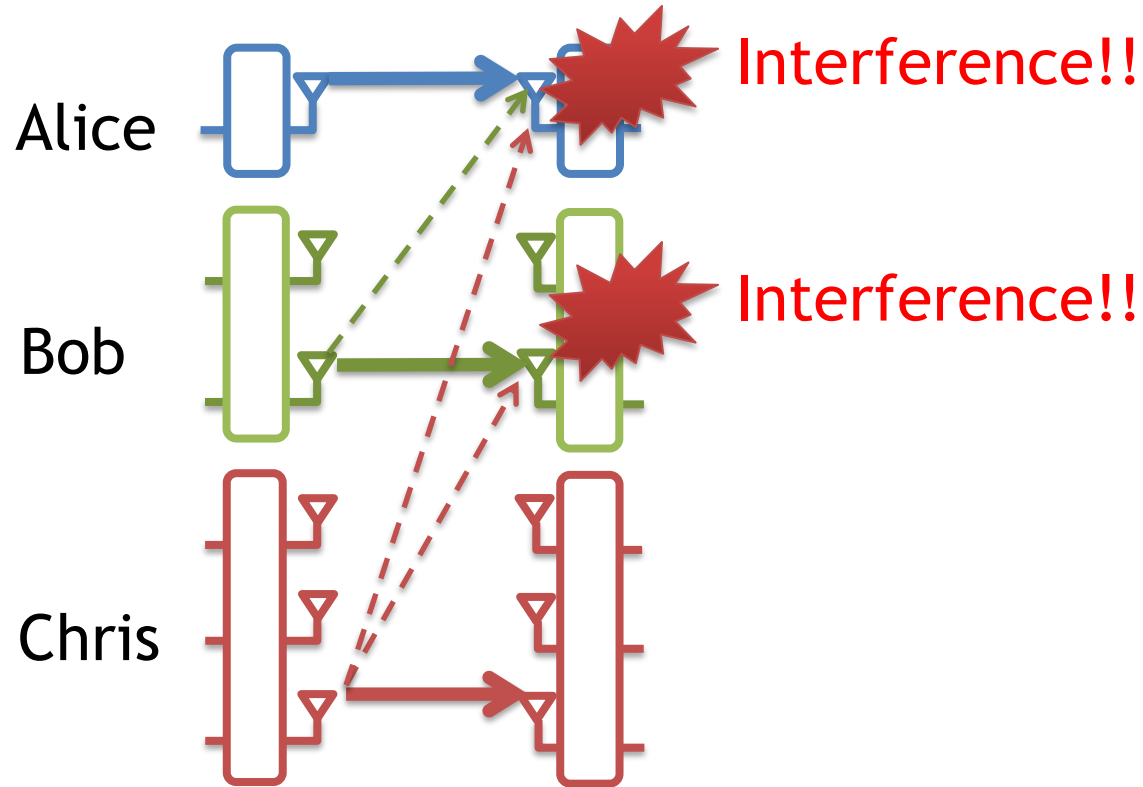


When a single-antenna node transmits,  
multi-antenna nodes refrain from transmitting

# But, MIMO Nodes Can Receive Multiple Concurrent Streams

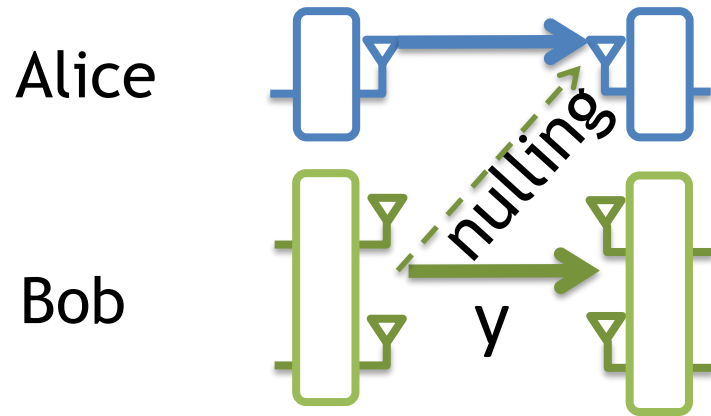


# It's Not That Simple



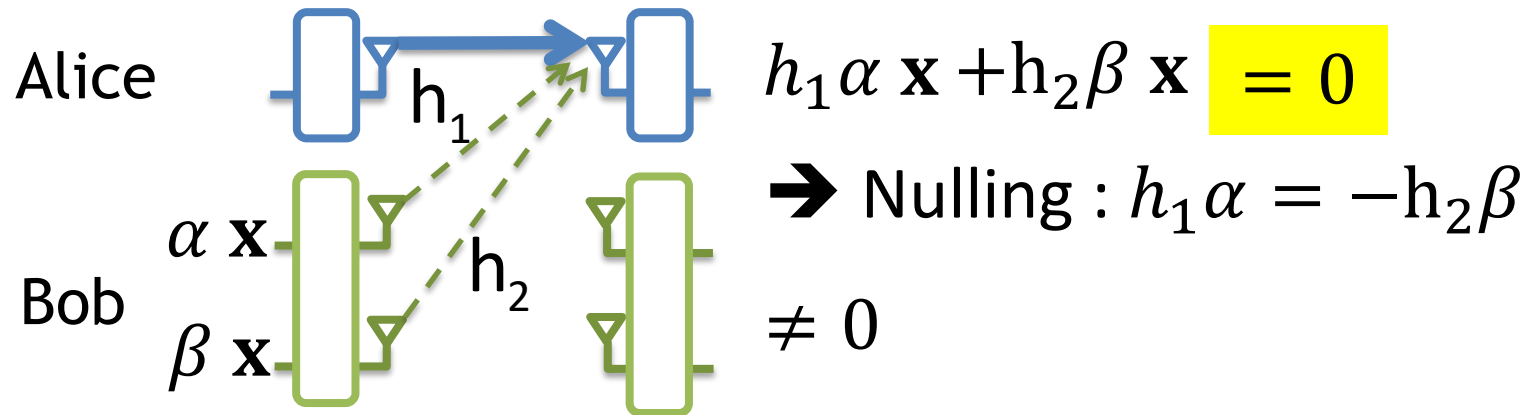
But, how do we transmit without interfering at receivers with fewer antennas?

# Interference Nulling



- Signals cancel each other at Alice's receiver

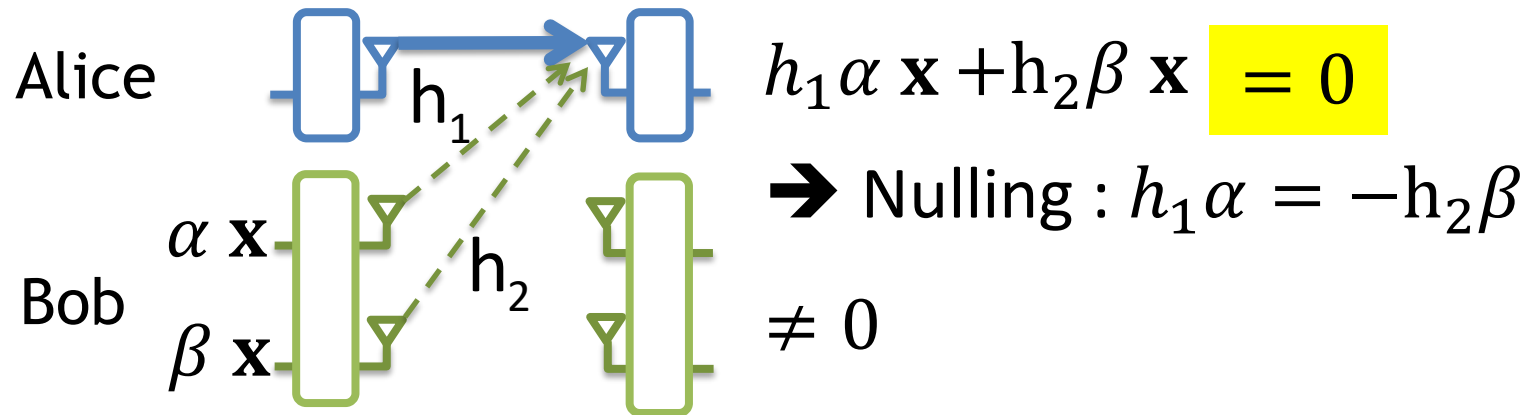
# Interference Nulling



- Signals cancel each other at Alice's receiver
- Signals don't cancel each other at Bob's receiver
  - ▶ Because channels are different
- Bob's sender learns channels either by feedback from Alice's receiver or via reciprocity

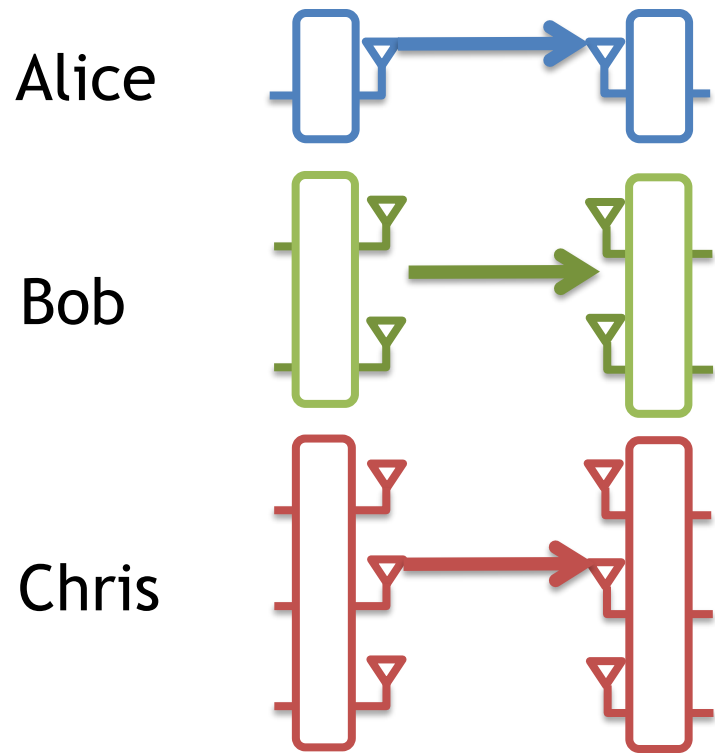


# Interference Nulling

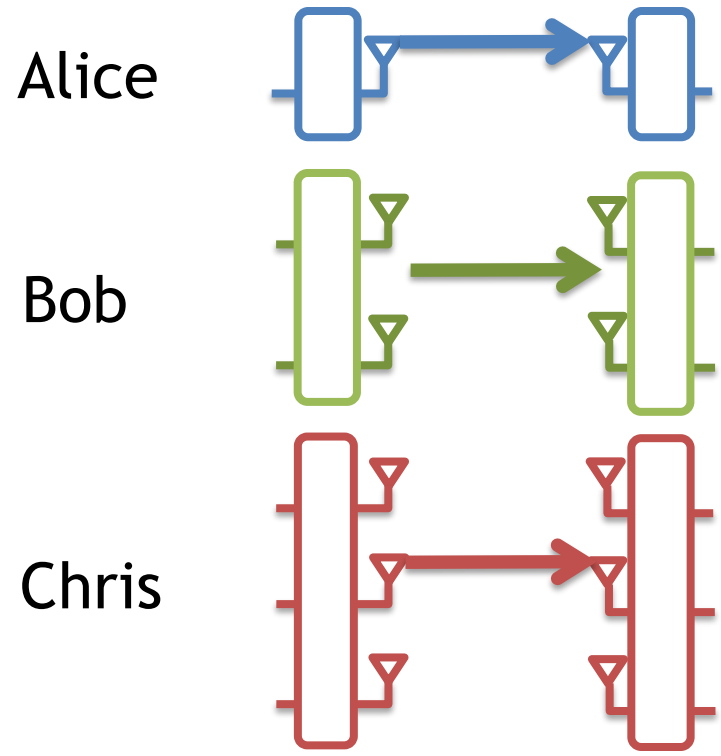


Q: How to transmit without interfering with receivers with fewer antennas?

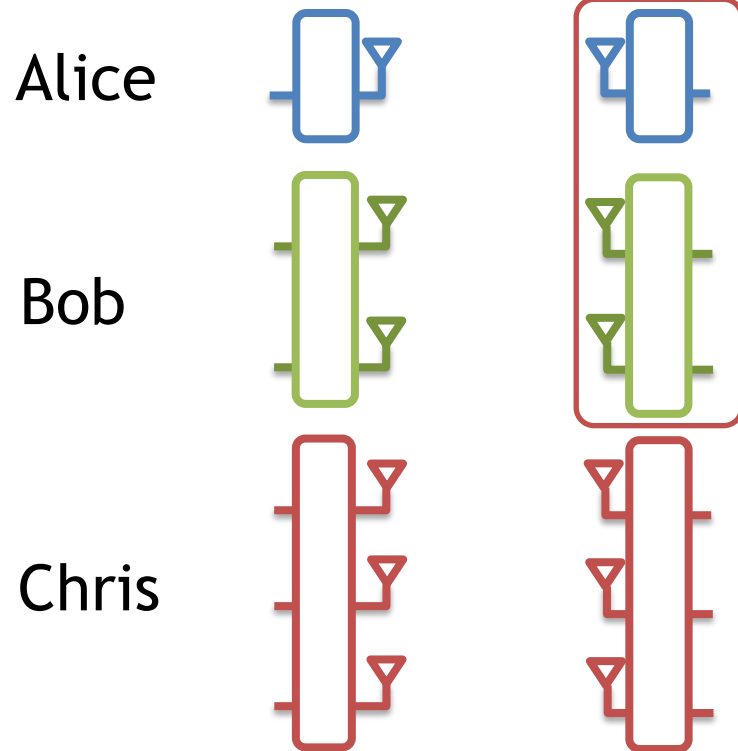
A: Nulling



# Is Nulling Alone Enough?

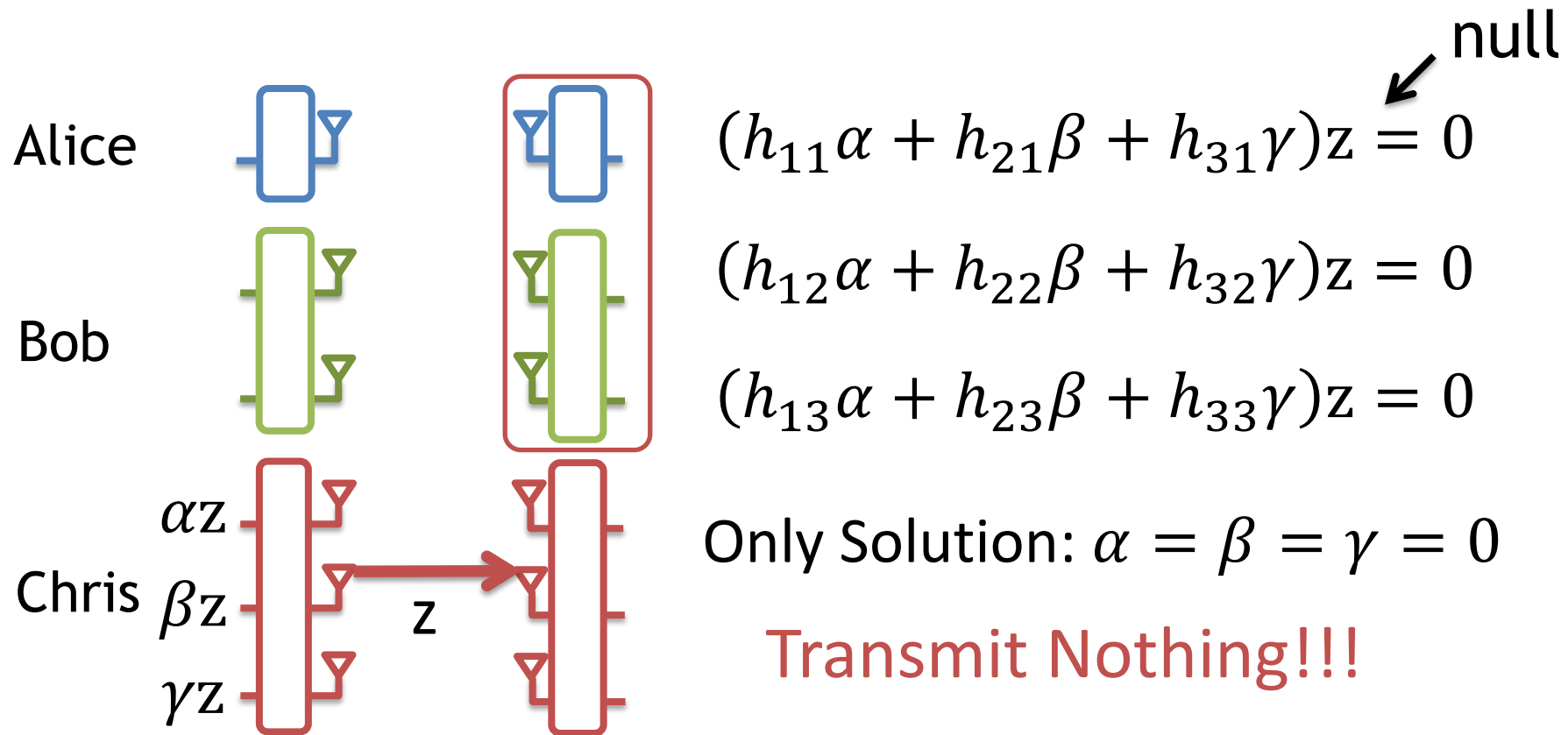


# Is Nulling Alone Enough?



Chris needs to null at  
three antennas

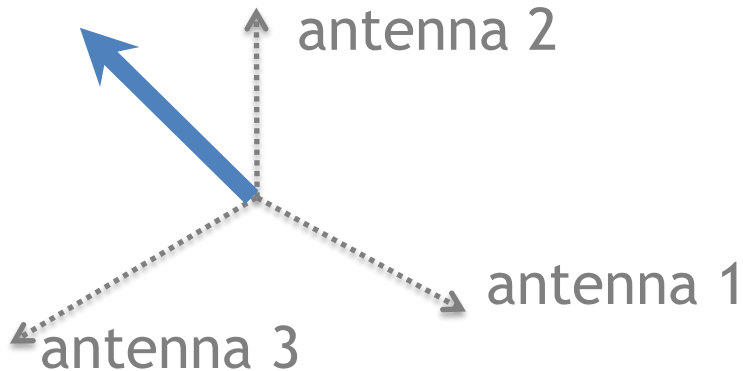
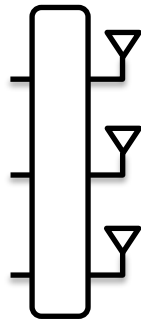
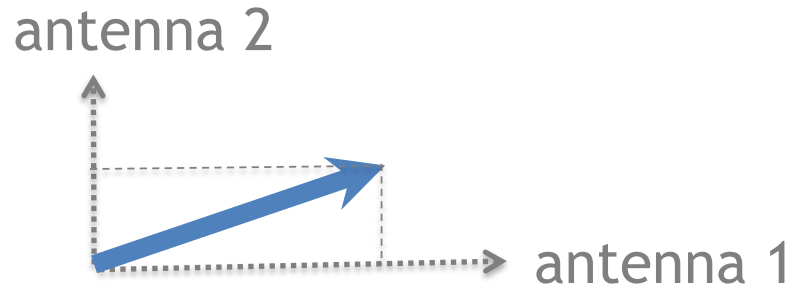
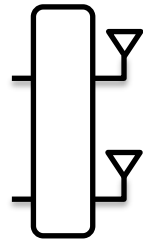
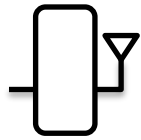
# Is Nulling Alone Enough? **NO!**



Are we doomed?

# MIMO Recap

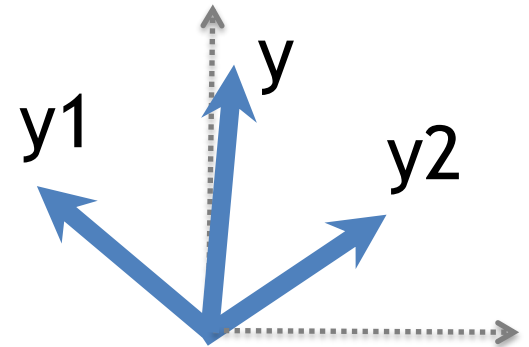
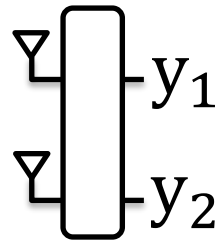
1. N-antenna node receives in N-dimensional space



# MIMO Recap

1. N-antenna node receives in N-dimensional space
2. N-antenna receiver can decode N signals

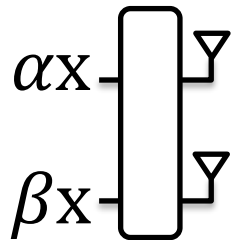
2-antenna RX



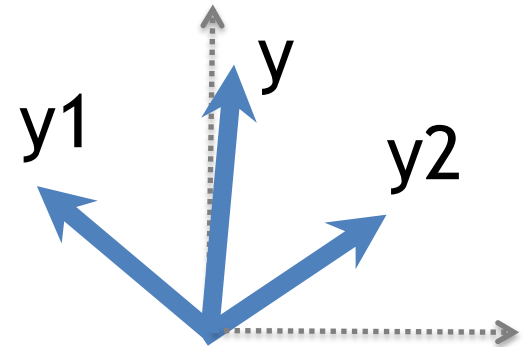
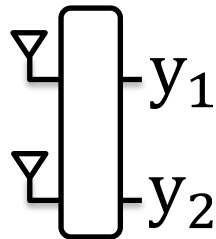
# MIMO Recap

1. N-antenna node receives in N-dimensional space
2. N-antenna receiver can decode N signals
3. Transmitter can rotate the received signal

2-antenna TX



2-antenna RX



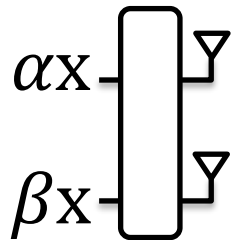
$x$  is the sender's symbol,  $(y_1, y_2)$  is the received symbol,  $(\alpha, \beta)$  is the pre-coding vector, and  $H$  is the channel matrix



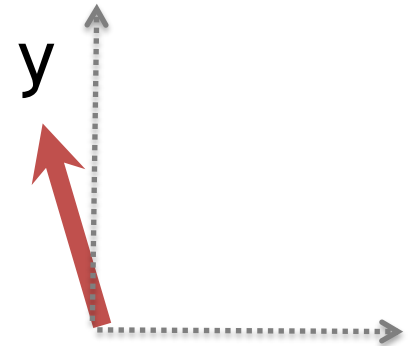
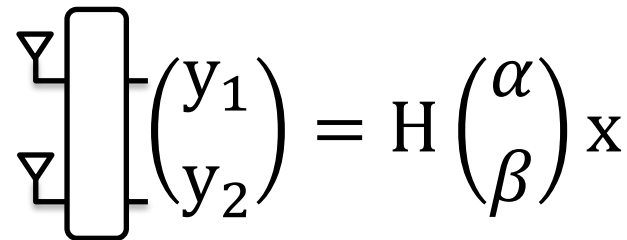
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2-antenna RX

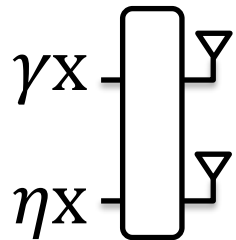


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# MIMO Recap

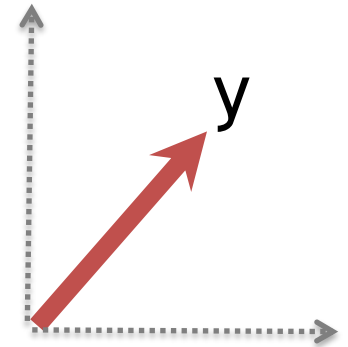
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2. N-antenna receiver can decode N signals
3. Transmitter can rotate the received signal

2-antenna TX



2-antenna RX

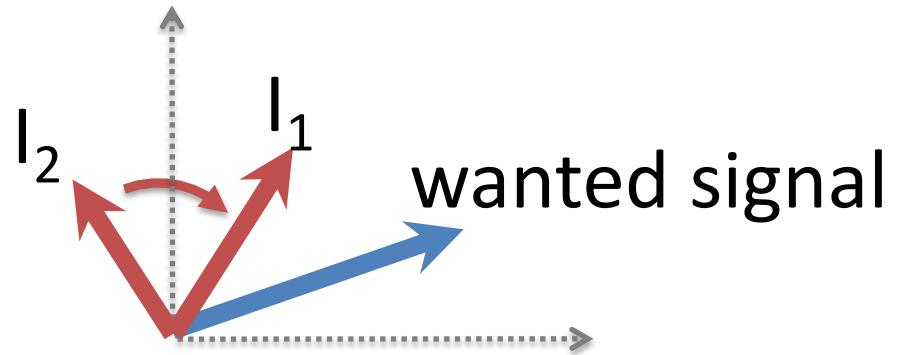
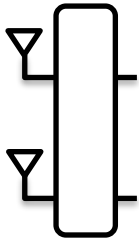
$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = H \begin{pmatrix} \gamma \\ \eta \end{pmatrix} x$$



Sender can rotate the received symbol by multiplying with a different pre-coding vector; However to align along a particular direction, sender needs to know  $H$

# Interference Alignment

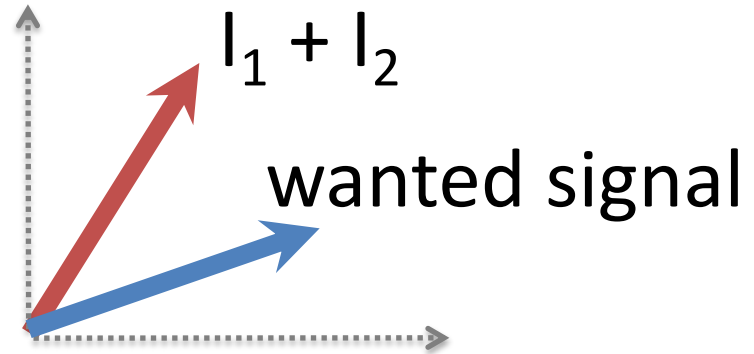
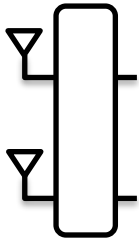
2-antenna receiver



If  $I_1$  and  $I_2$  are aligned,

# Interference Alignment

2-antenna receiver

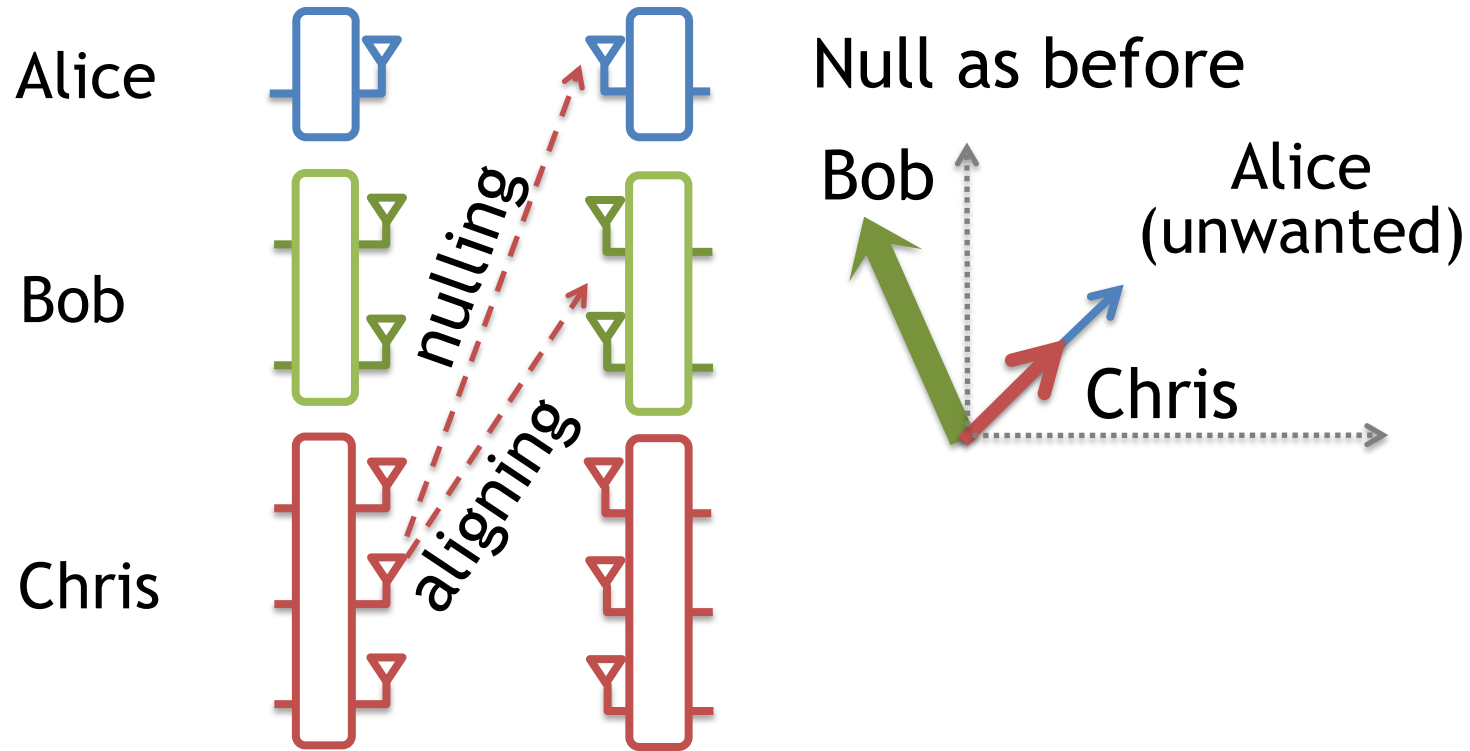


If  $I_1$  and  $I_2$  are aligned,

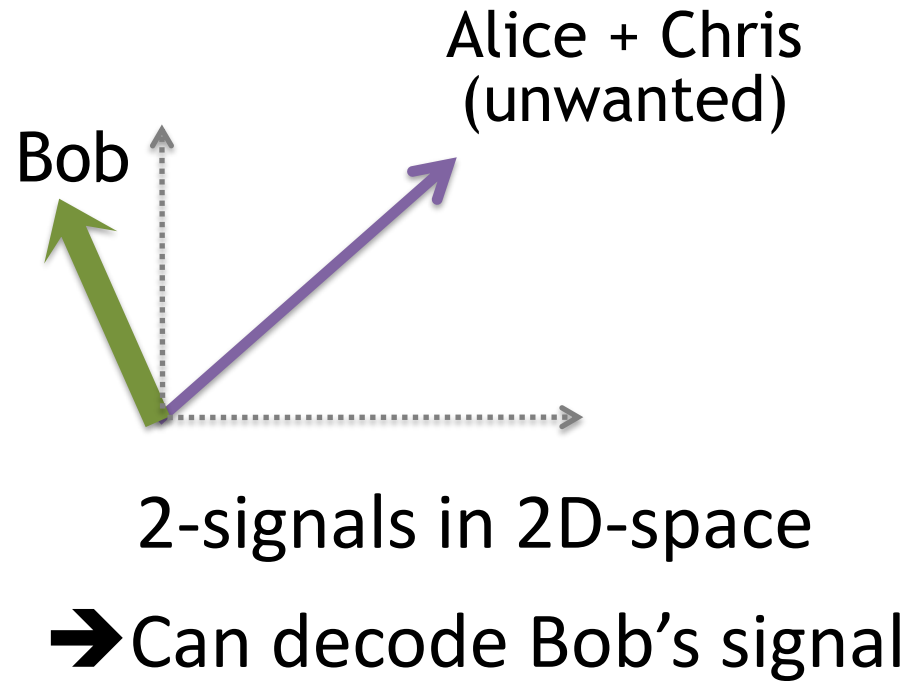
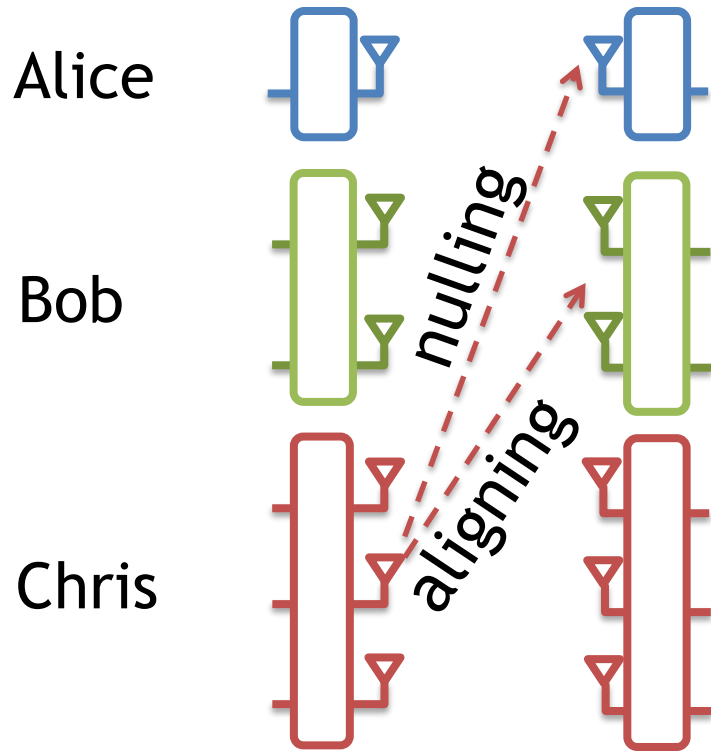
→ appear as one interferer

→ 2-antenna receiver can decode the wanted signal

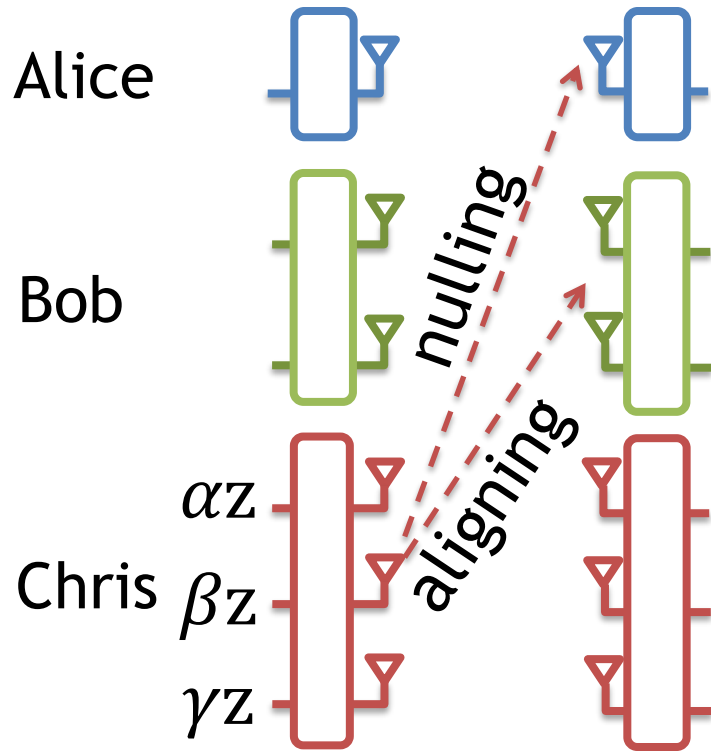
# Use Nulling and Alignment



# Use Nulling and Alignment



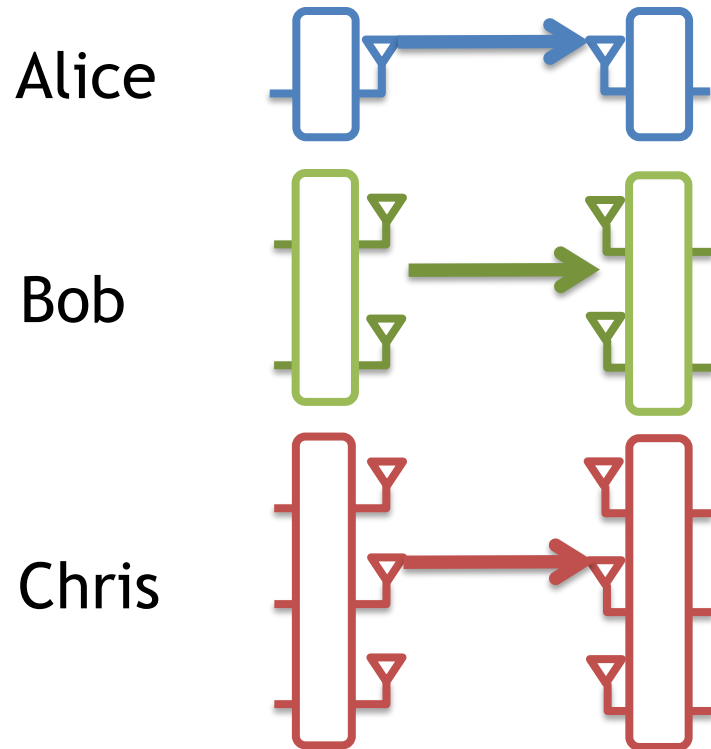
# Use Nulling and Alignment



$$(h_{11}\alpha + h_{21}\beta + h_{31}\gamma)z = 0$$

$$\begin{pmatrix} h_{12}\alpha + h_{22}\beta + h_{32}\gamma \\ h_{13}\alpha + h_{23}\beta + h_{33}\gamma \end{pmatrix} \propto \begin{pmatrix} h_{a1} \\ h_{a2} \end{pmatrix}$$

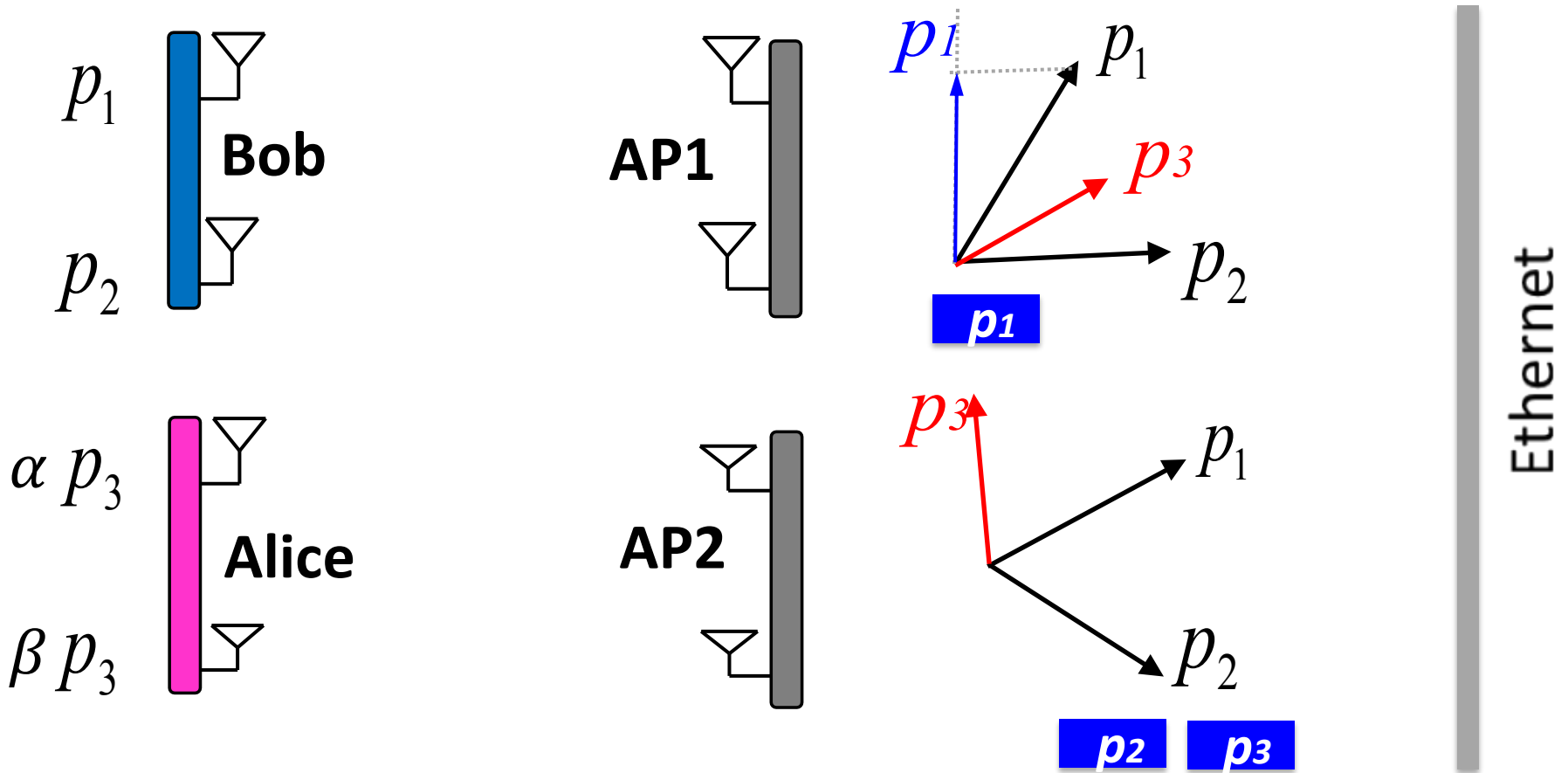
# Use Nulling and Alignment



3 packets though  
receivers have fewer  
than 3 antennas



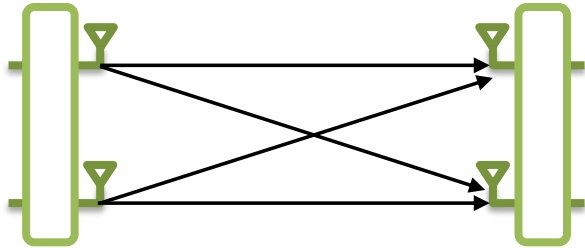
# Interference Alignment and Cancellation (IAC)



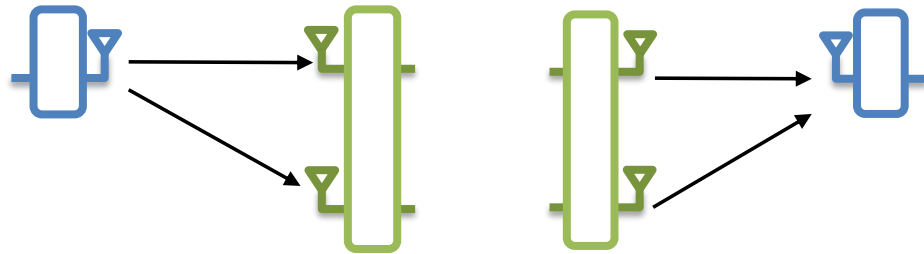
- **Align**  $P_3$  with  $P_2$  at AP1  $\rightarrow$  AP1 decodes  $P_1$  to its bits
- AP1 broadcasts  $P_1$  on Ethernet
- AP2 subtracts/ **Cancels**  $P_1 \rightarrow$  decodes  $P_2, P_3$

# Last Lecture

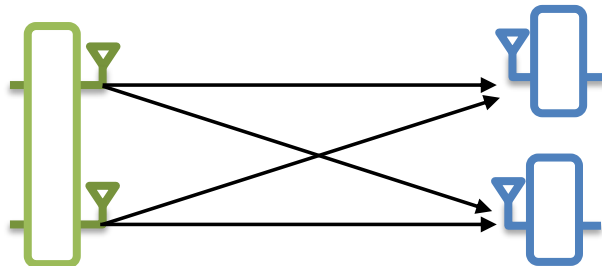
## MIMO Multiplexing Gain



## MIMO TX/RX Diversity Gain

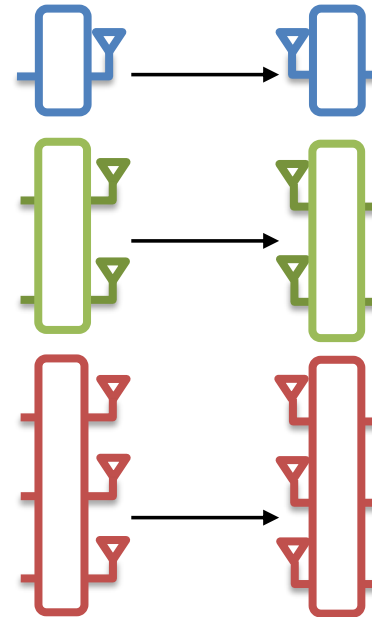


## MU-MIMO Beamforming

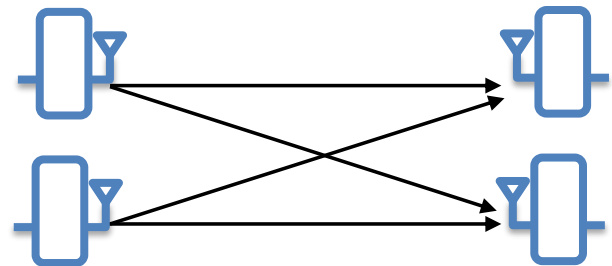


# This Lecture

## Heterogeneous # of antennas (Interference Nulling/Alignment)



## Distributed MIMO

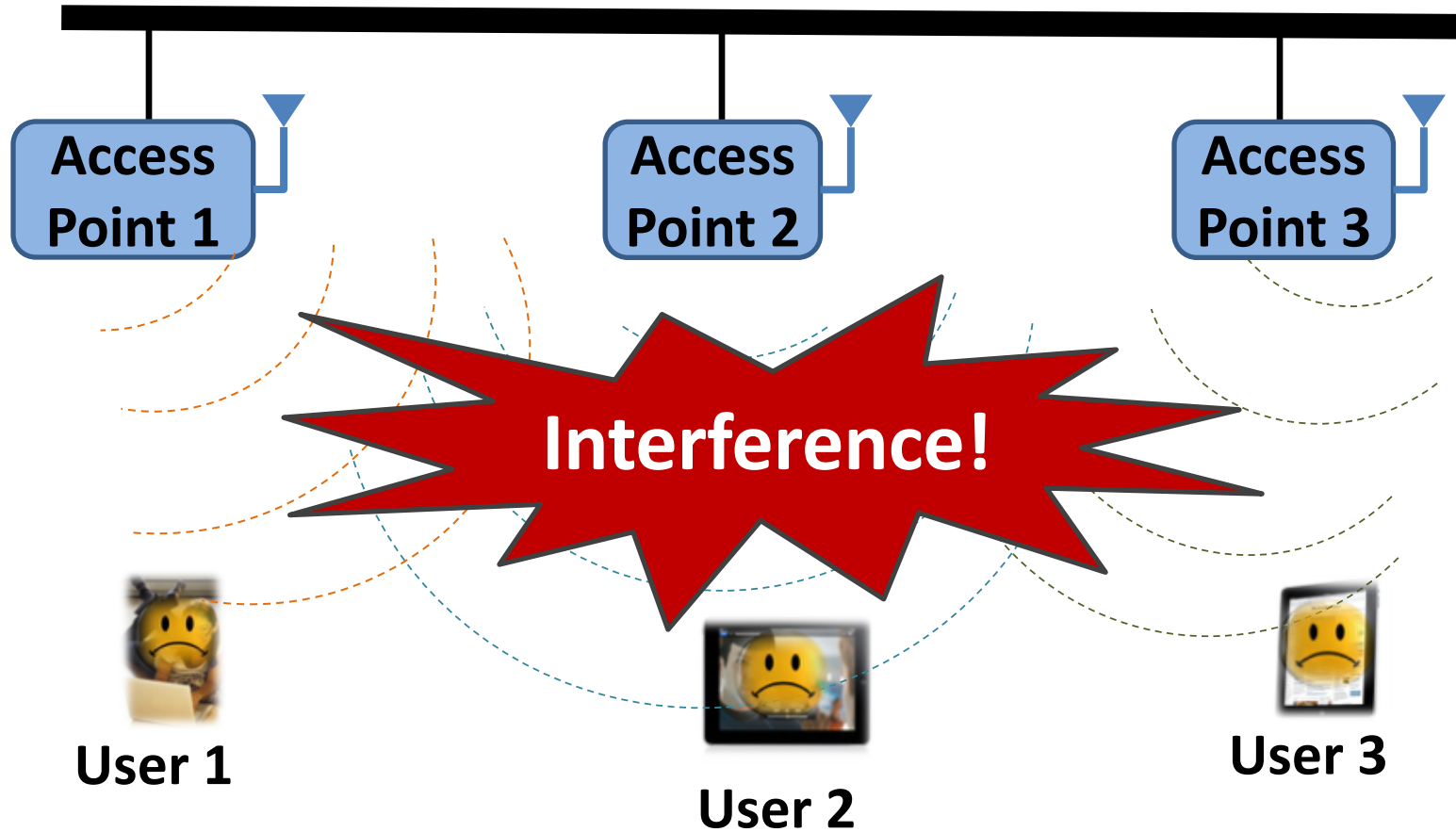


MegaMIMO:

Scaling Wireless Throughput with the  
Number of Users

# Today's Wireless Networks

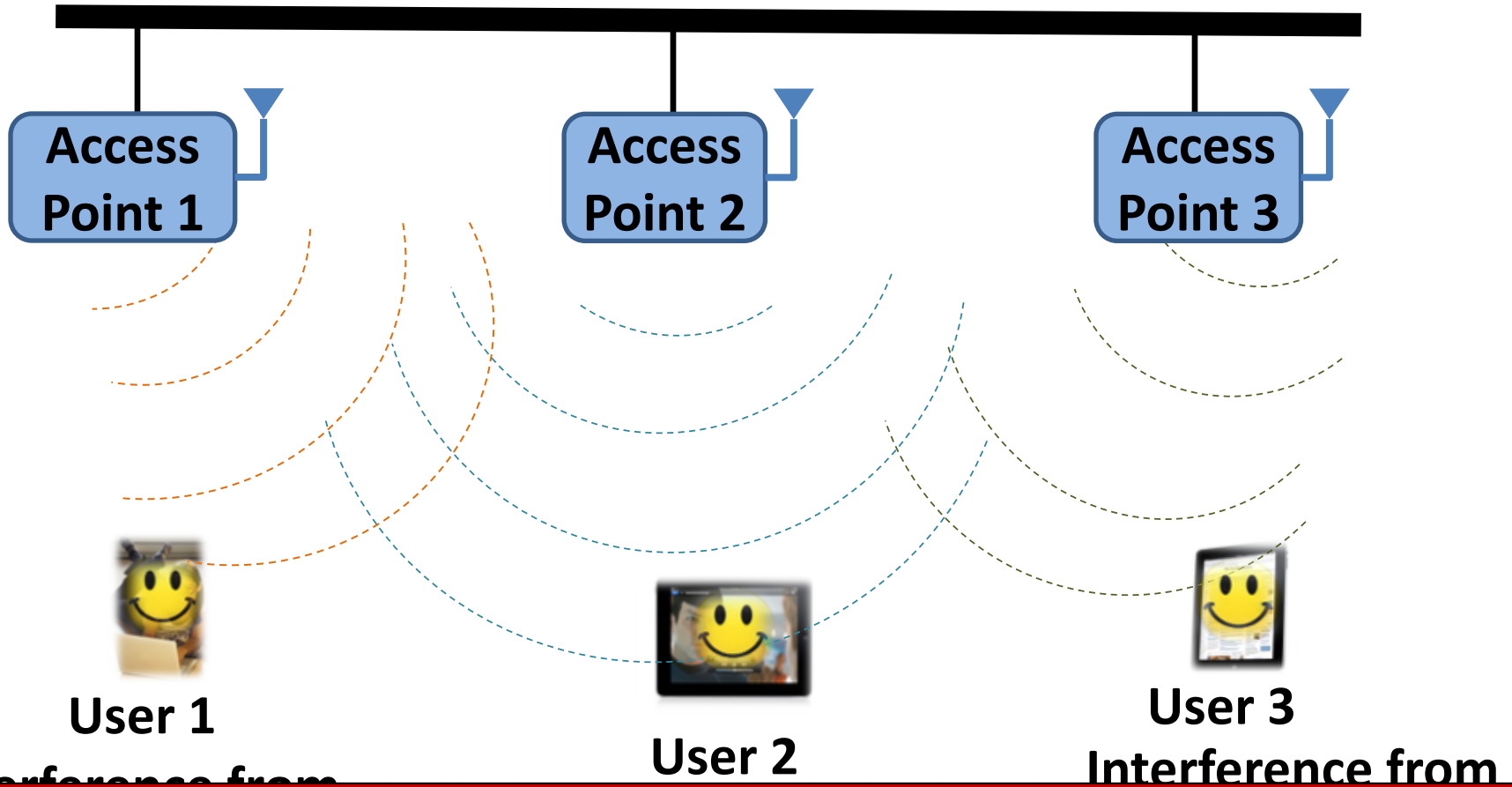
## Ethernet



Access Points Can't Transmit Together in the Same Channel

# MegaMIMO

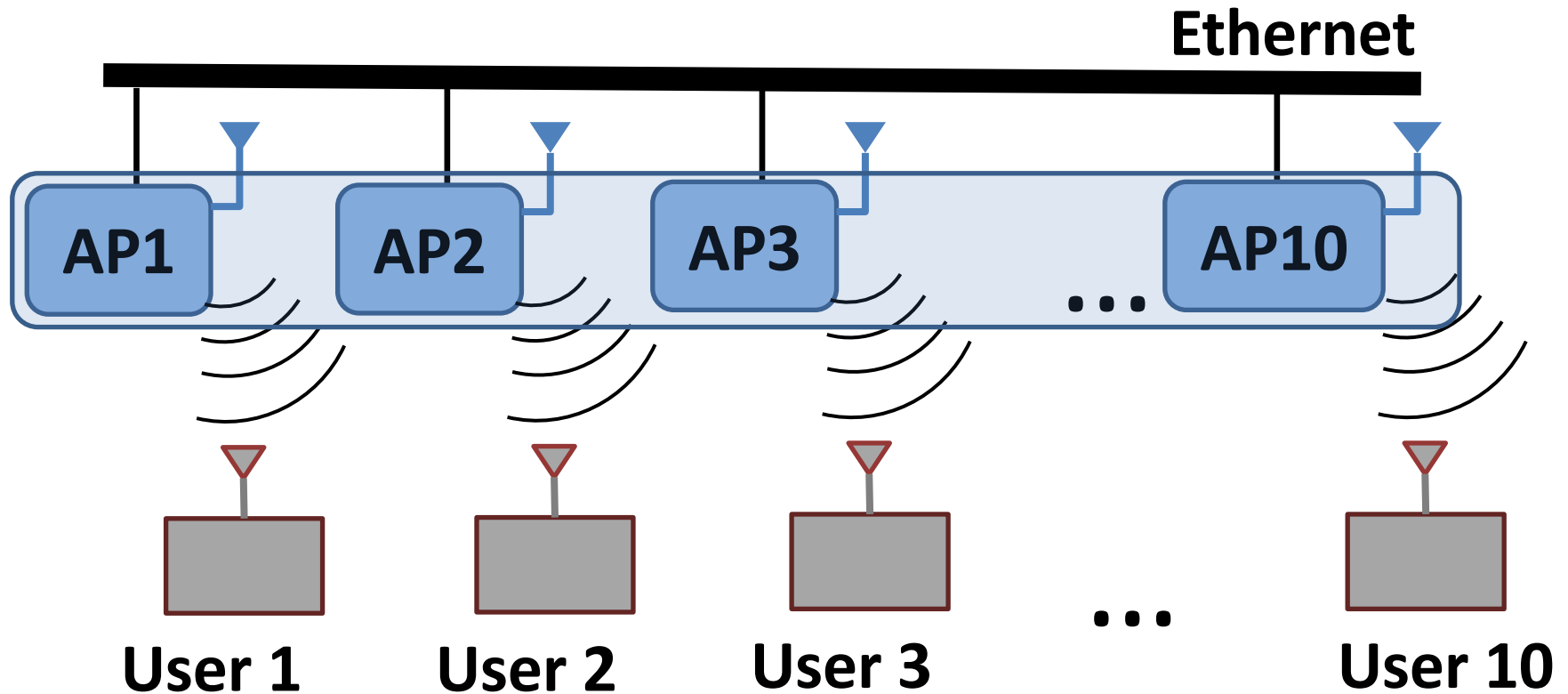
## Ethernet



**Enables senders to transmit together without interference**

# MegaMIMO = Distributed MIMO

Distributed protocol for APs to act as a huge MIMO transmitter with sum of antennas



**10 APs → 10x higher throughput**

# Transmitting Without Interference



Wants  $x_1$   
Receives  $y_1$  **cli 1**

Wants  $x_2$   
Receives  $y_2$  **cli 2**

$$y_1 = d_1 x_1$$

$$y_2 = d_2 x_2$$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} d_1 & 0 \\ 0 & d_2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

# Transmitting Without Interference



Wants  $x_1$   
Receives  $y_1$



Wants  $x_2$   
Receives  $y_2$



**Diagonal Matrix  $\rightarrow$  Non-Interference**

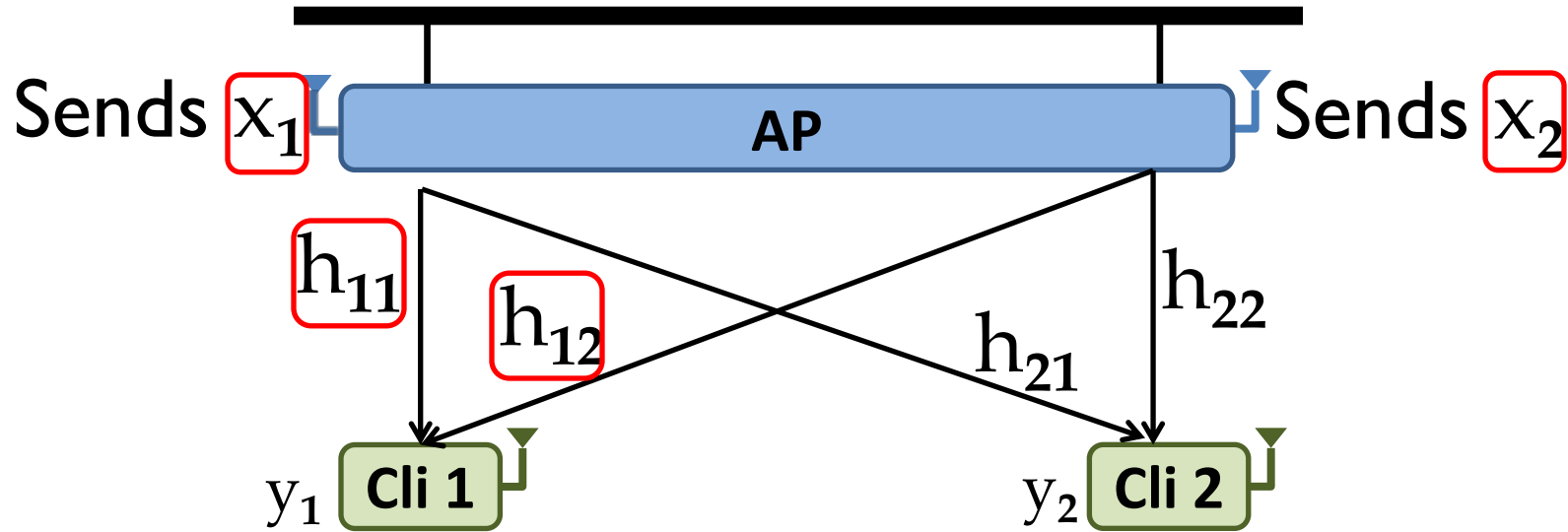
**Goal: Make the effective channel matrix diagonal**



# On-Chip MIMO

- All antennas on the MIMO sender are synchronized in time to within nanoseconds of each other.
- All antennas on a MIMO sender have exactly the same oscillator, i.e., no frequency offset.

# On-Chip MIMO



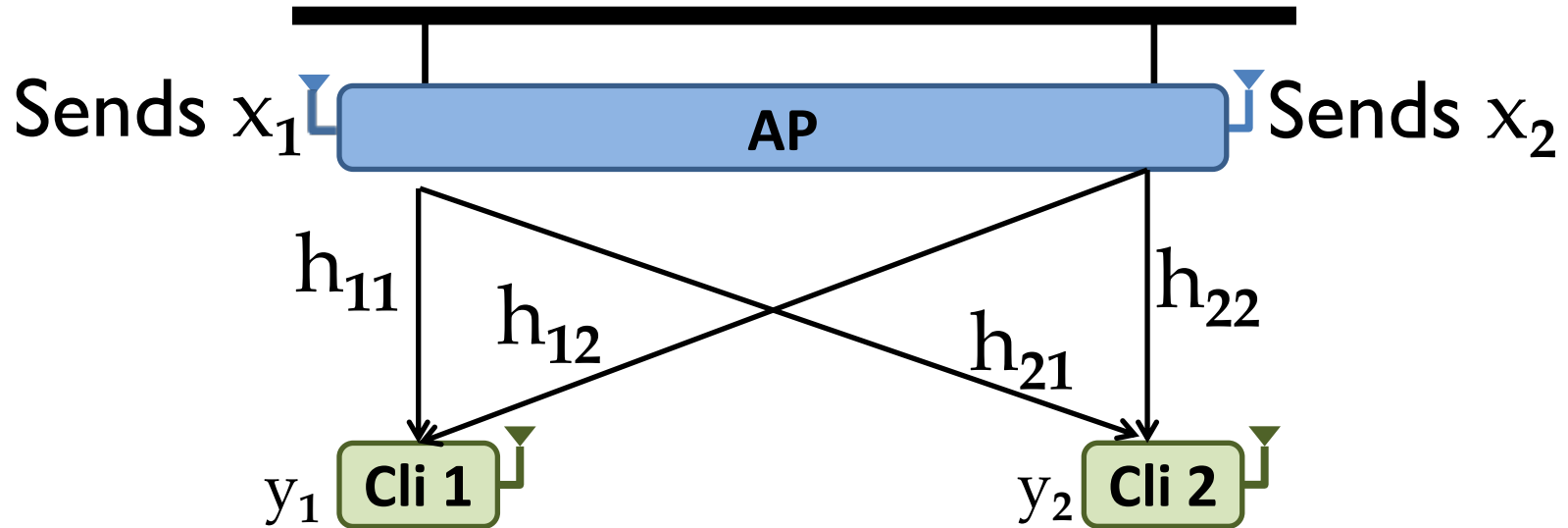
$$y_1 = h_{11} x_1 + h_{12} x_2$$

$$y_2 = h_{21} x_1 + h_{22} x_2$$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Non-diagonal  
Matrix  $\rightarrow$   
Interference

# On-Chip MIMO

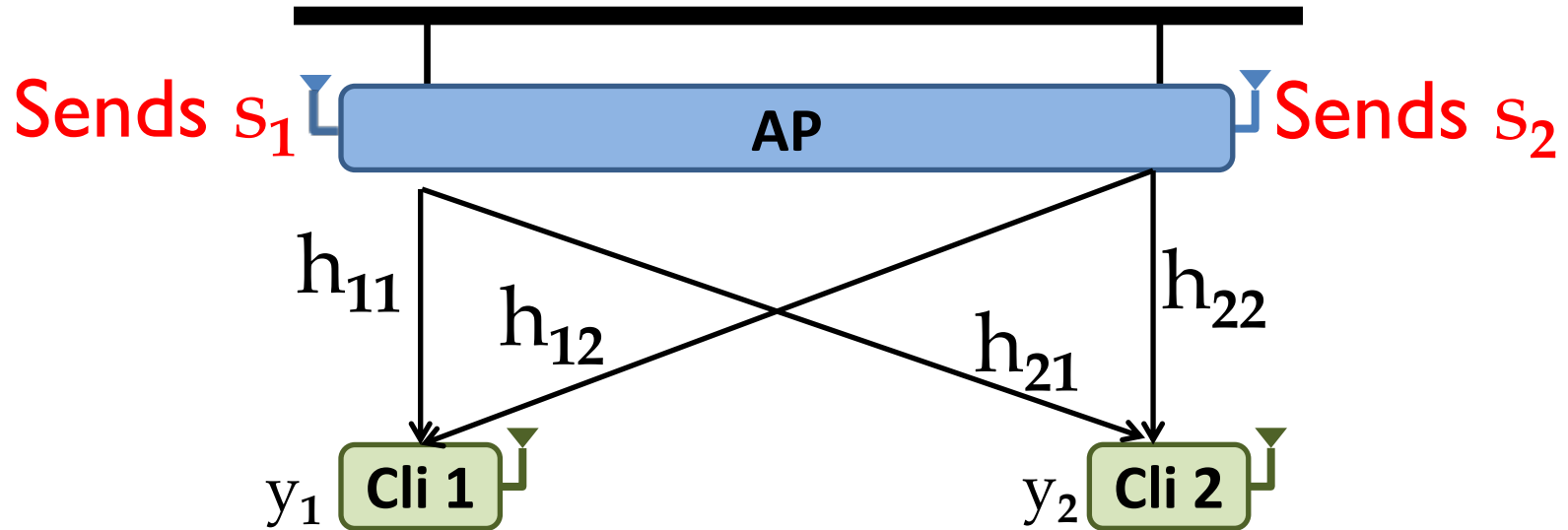


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# On-Chip MIMO

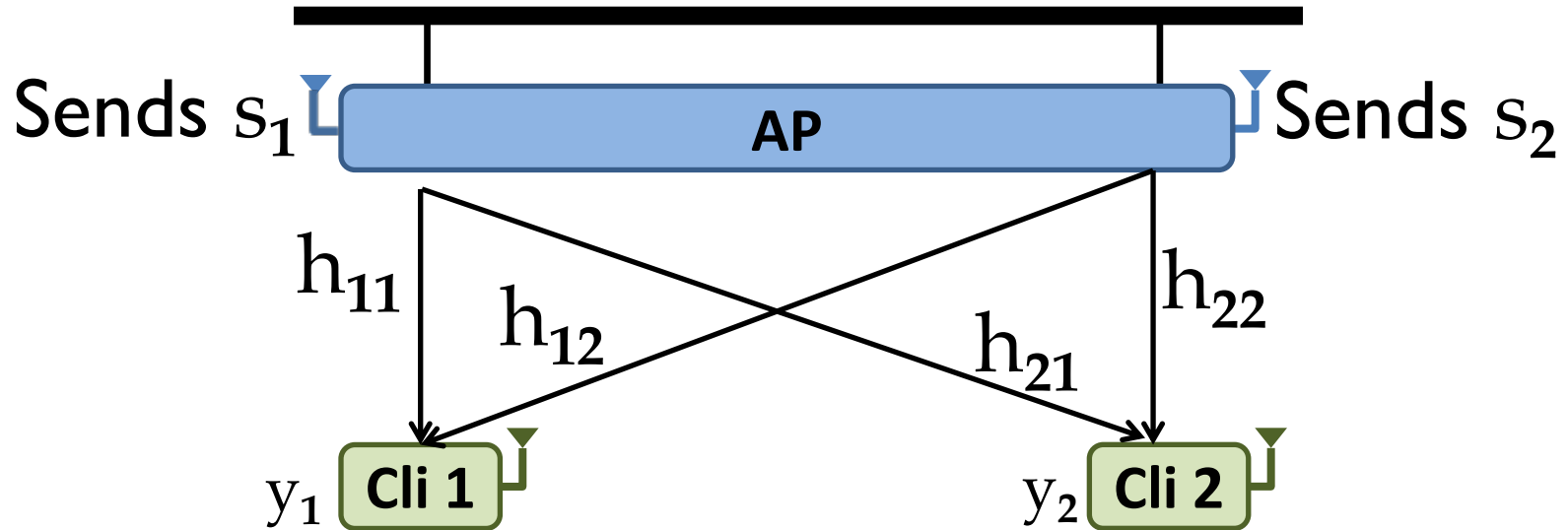


$$y_1 = h_{11} s_1 + h_{12} s_2$$

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$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} s_1 \\ s_2 \end{bmatrix}$$

# On-Chip MIMO

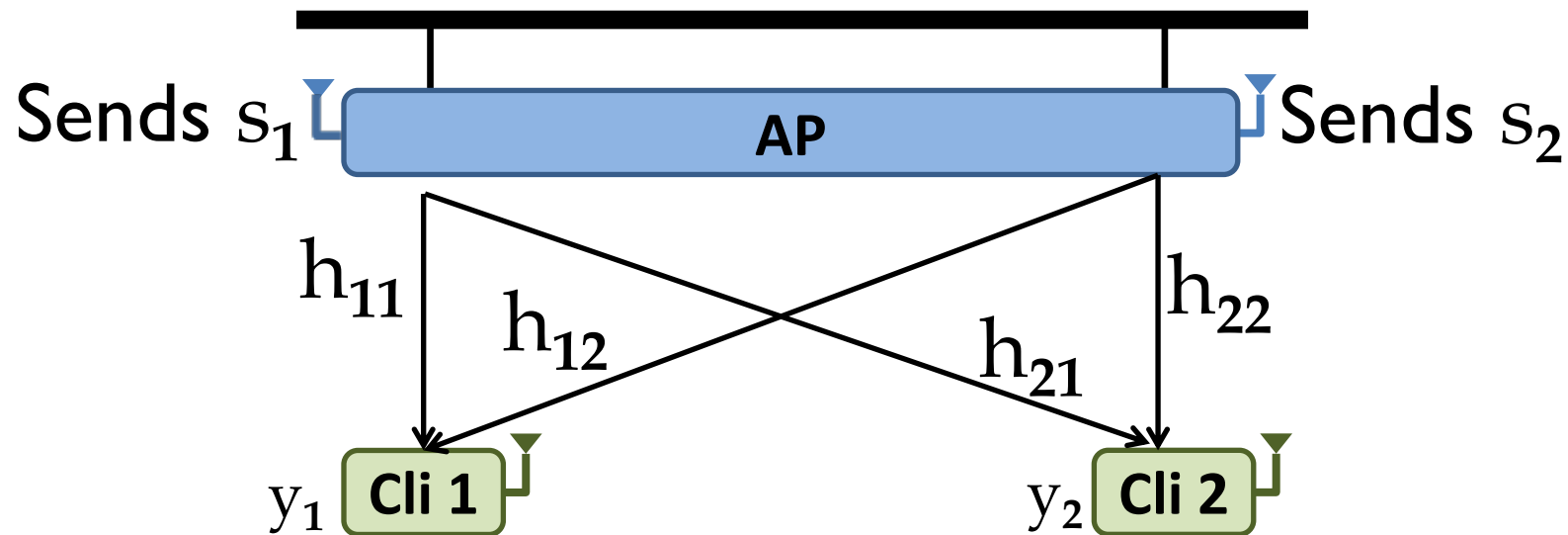


$$y_1 = h_{11} s_1 + h_{12} s_2$$

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$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \mathbf{H} \begin{bmatrix} s_1 \\ s_2 \end{bmatrix}$$

# Making Effective Channel Matrix Diagonal

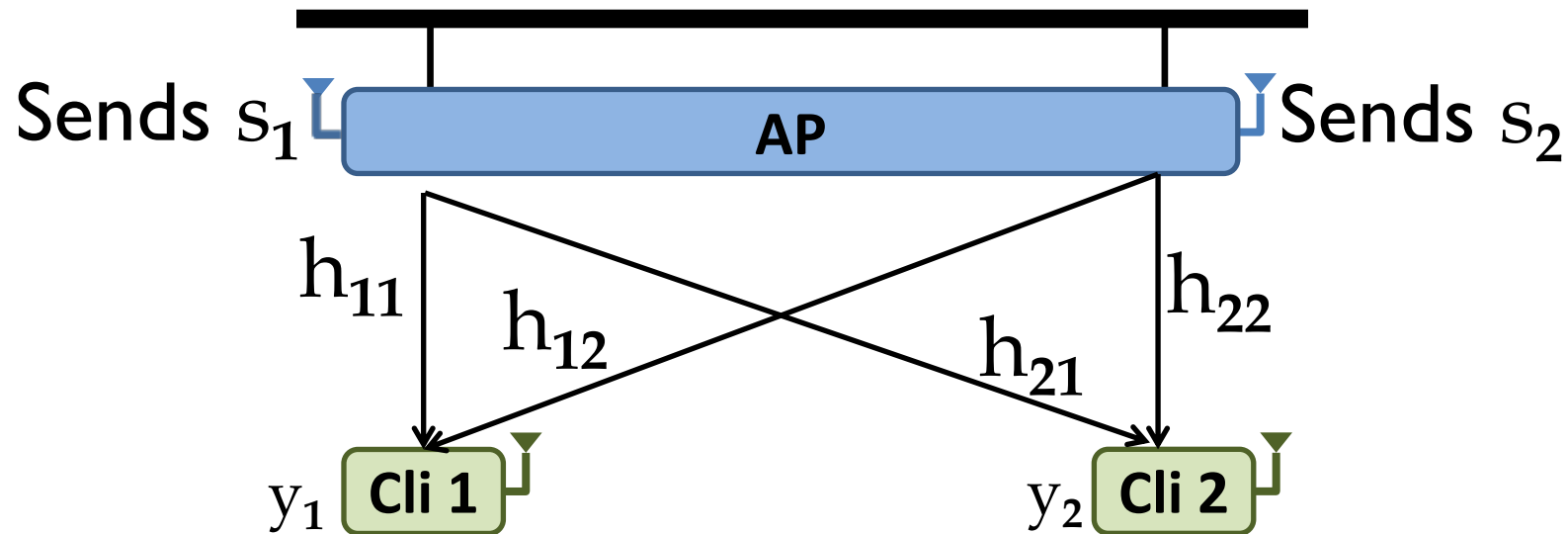


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# Making Effective Channel Matrix Diagonal



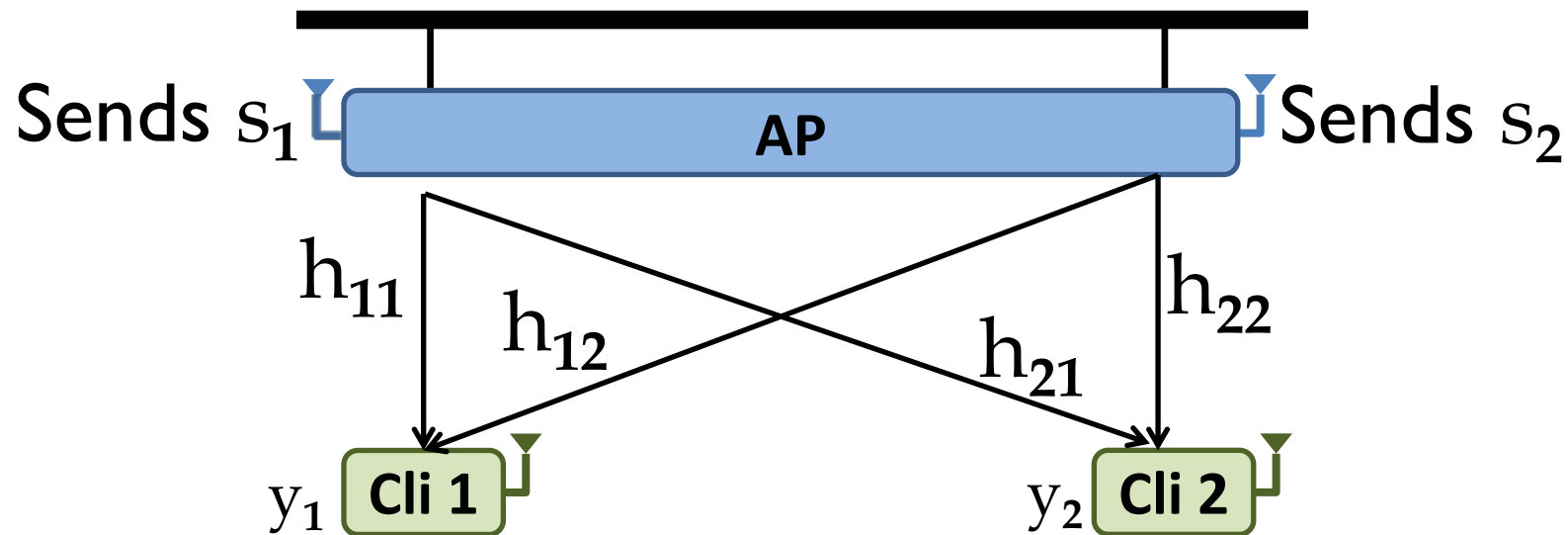
$$y_1 = h_{11} s_1 + h_{12} s_2$$

$$y_2 = h_{21} s_1 + h_{22} s_2$$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \mathbf{H} \begin{bmatrix} s_1 \\ s_2 \end{bmatrix}$$

A callout box with a purple border and a light orange background contains the equation  $\mathbf{H}^{-1} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ . A purple arrow points from the callout box to the  $\begin{bmatrix} s_1 \\ s_2 \end{bmatrix}$  vector in the main equation above.

# Making Effective Channel Matrix Diagonal



$$y_1 = h_{11} s_1 + h_{12} s_2$$

$$y_2 = h_{21} s_1 + h_{22} s_2$$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \mathbf{H} \mathbf{H}^{-1} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Effective  
channel is  
diagonal



# Beamforming System Description

## Channel Measurement:

- Measure channels from sending antennas to clients
- Clients report measured channels back to APs

## Data Transmission:

- MIMO sender computes its beamformed signal  $s_i$  using the equation  $\vec{s} = \mathbf{H}^{-1} \vec{x}$
- Clients 1 and 2 decode  $x_1$  and  $x_2$  independently

# Distributed Transmitters Are Different

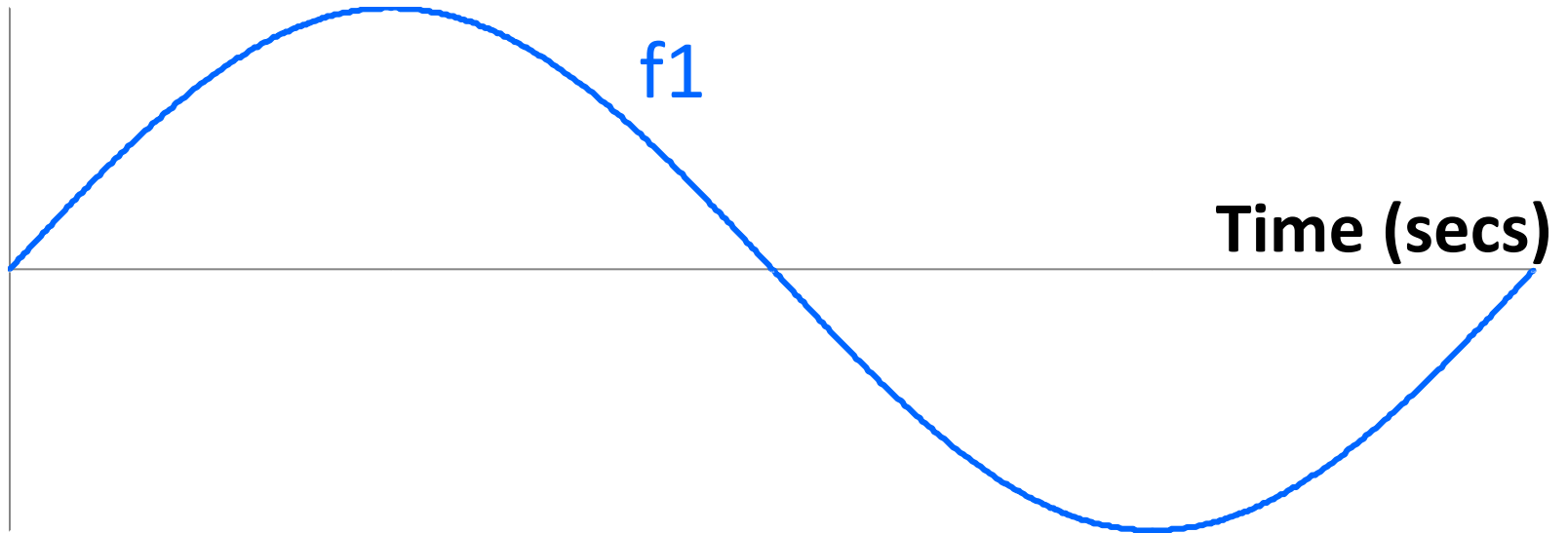
- Nodes are not synchronized in time.
  - We use SourceSync to synchronize senders within 10s of ns
  - Works for OFDM based systems like Wi-Fi, LTE etc.
- Oscillators are not synchronized and have frequency offsets relative to each other.

# Synchronize Time Across APs

- Lead AP starts transmitting; Follower APs use the packet detection time to synchronize
- Challenge: Follower APs do not detect the packet at exactly the same time (difference in propagation delay, etc.)
- Solution: Each follower AP estimates the delay between its detection of the packet and the time the lead AP sent the first symbol in the packet... but How?

# Estimating Packet Detection Delay in SourceSync

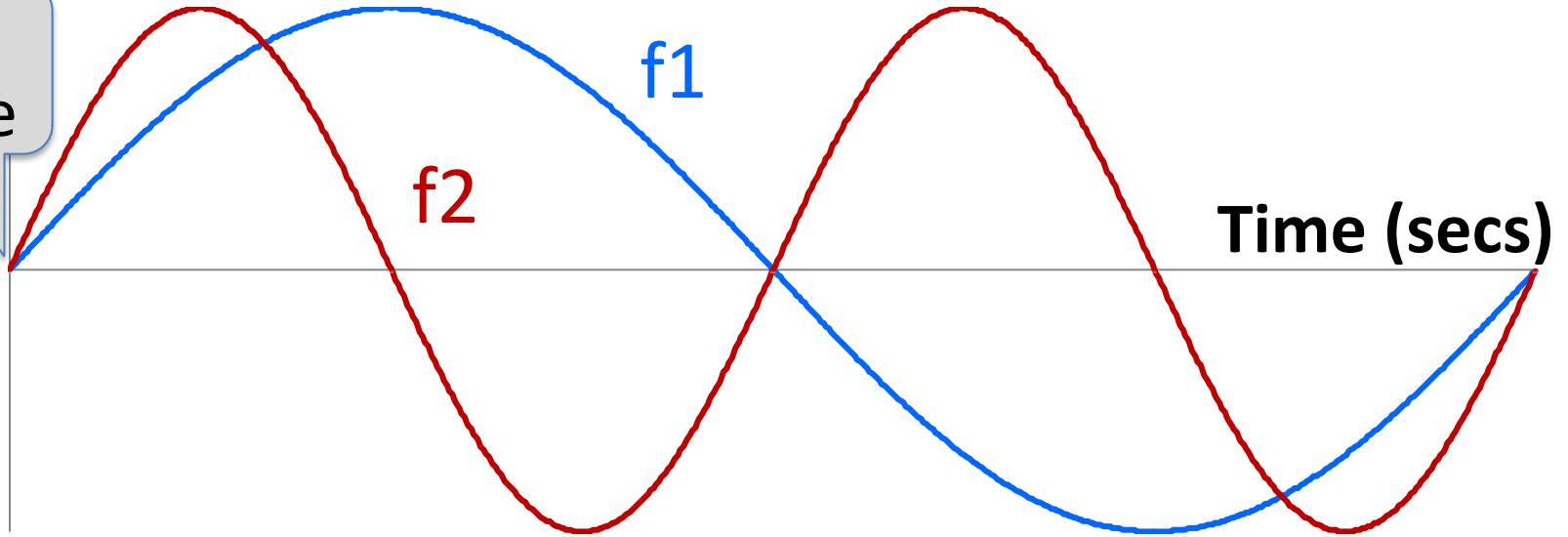
OFDM transmits signal over multiple frequencies



# Estimating Packet Detection Delay in SourceSync

OFDM transmits signal over multiple frequencies

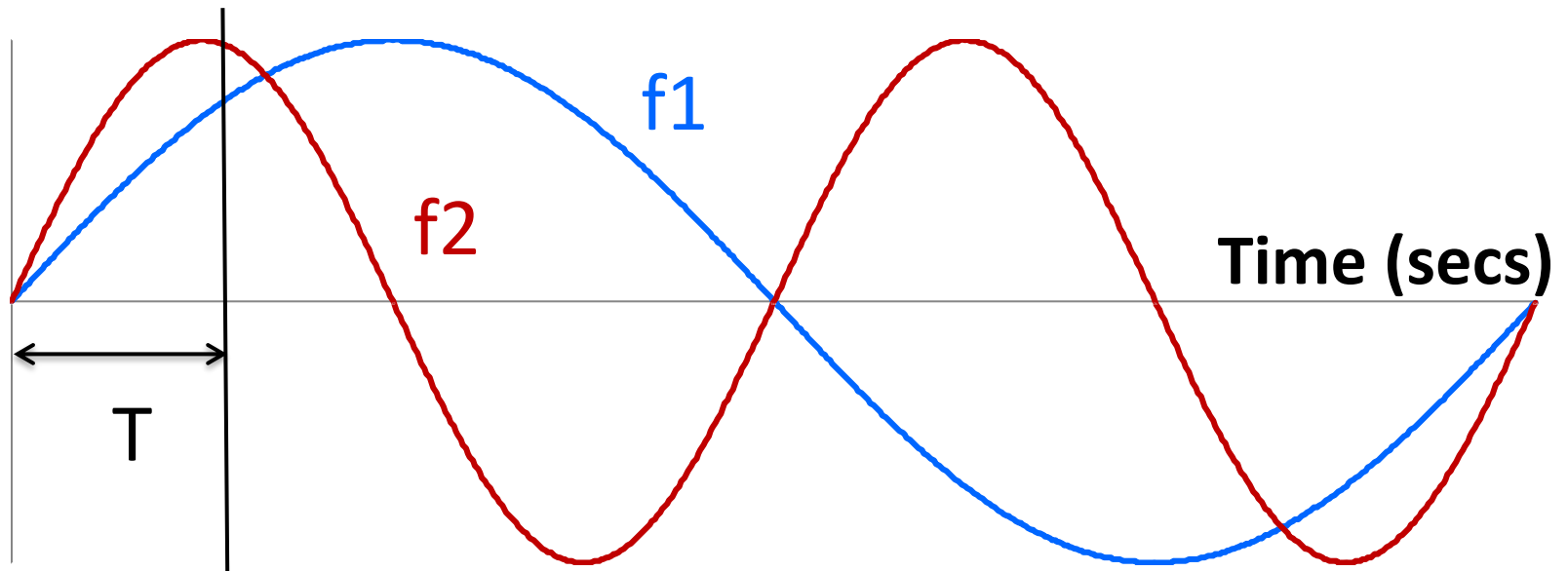
First  
Sample



Detect on first sample → Same phase

# Estimating Packet Detection Delay in SourceSync

OFDM transmits signal over multiple frequencies

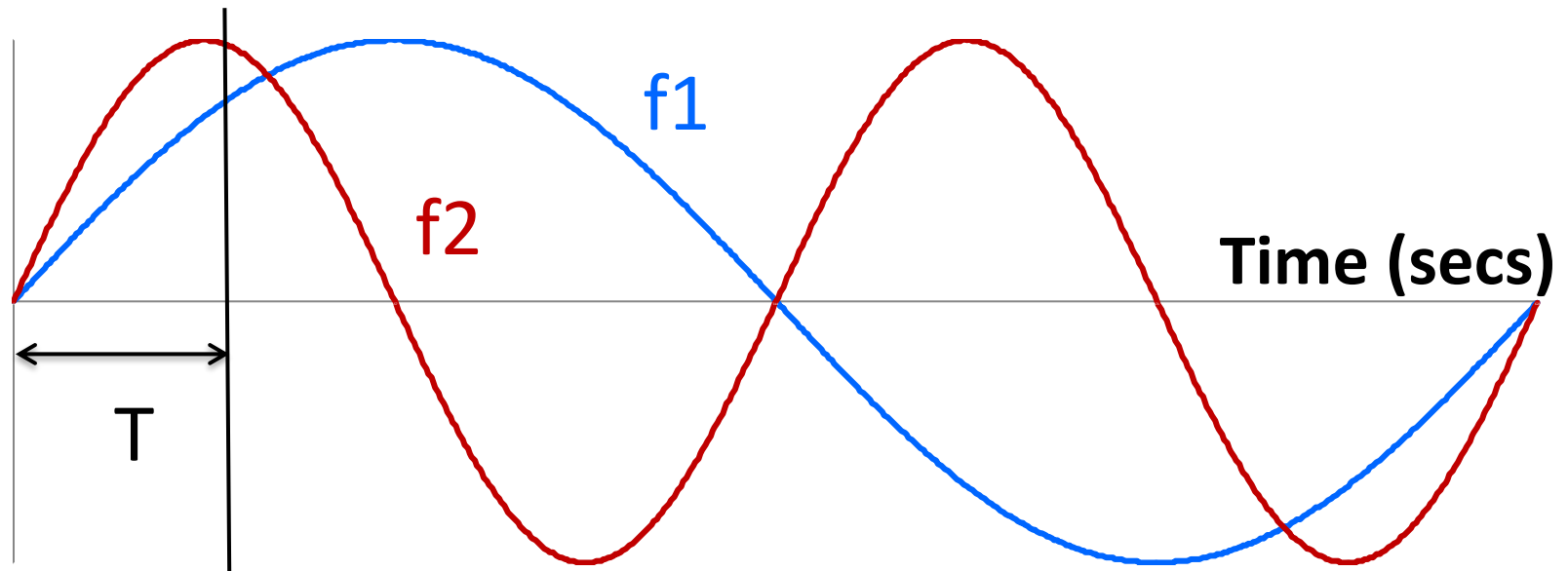


Detect after T

Frequencies rotate at different speeds

# Estimating Packet Detection Delay in SourceSync

OFDM transmits signal over multiple frequencies

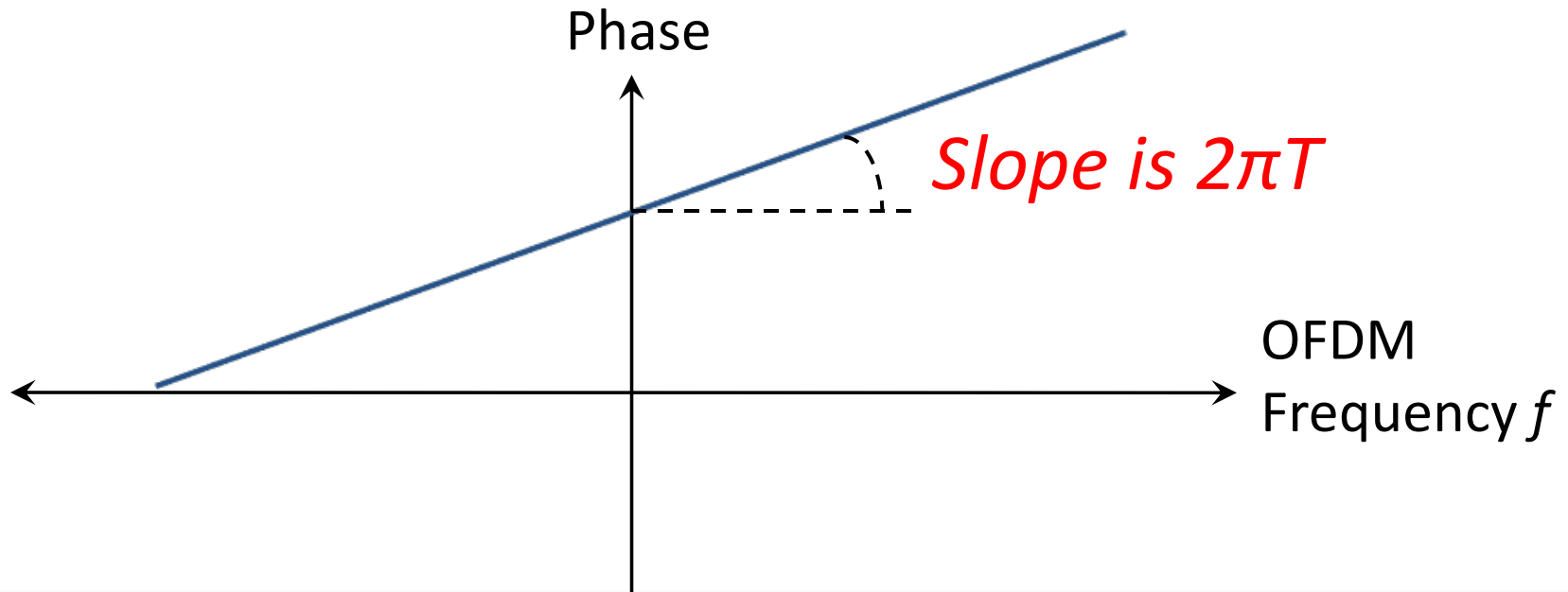


Detect after T

Different frequencies exhibit different phases

$$\text{Phase} = 2\pi fT$$

# Estimating Packet Detection Delay in SourceSync



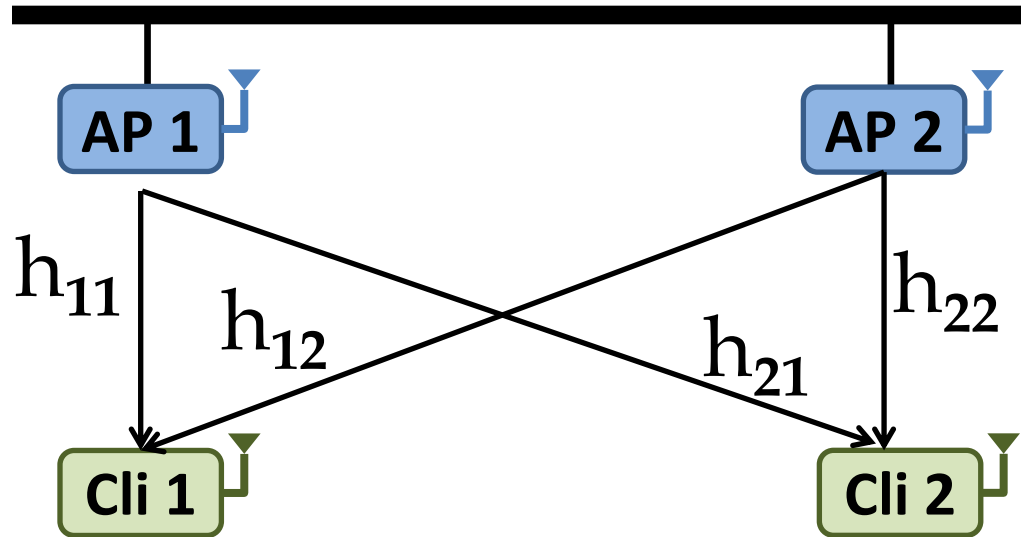
- Each AP estimates packet detection delay
- Estimate uses every symbol in packet → Robust to noise



# Distributed Transmitters Are Different

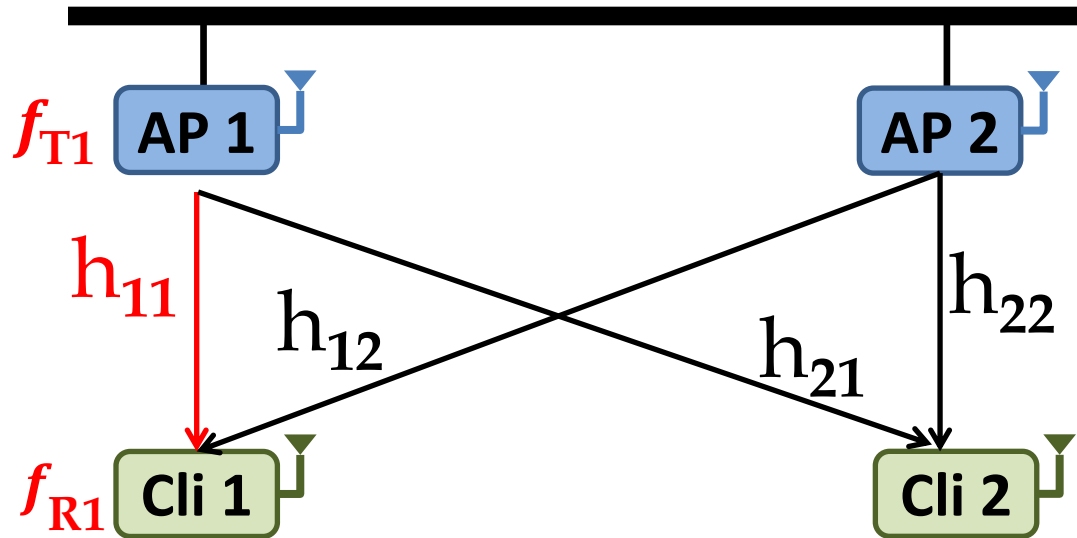
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- Oscillators are not synchronized and have frequency offsets relative to each other.

# What Happens with Independent Oscillators?



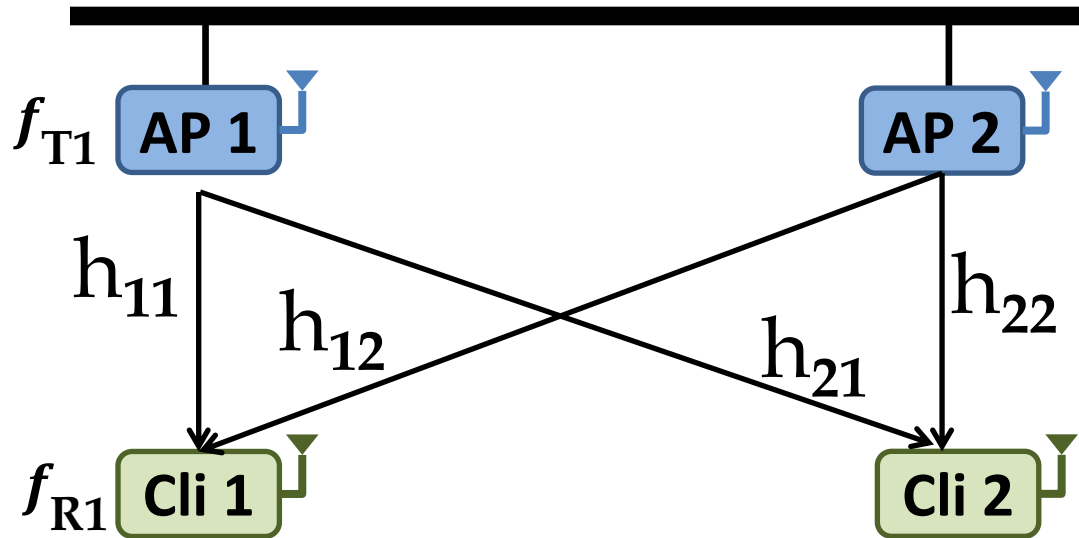
$$\begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix}$$

# What Happens with Independent Oscillators?



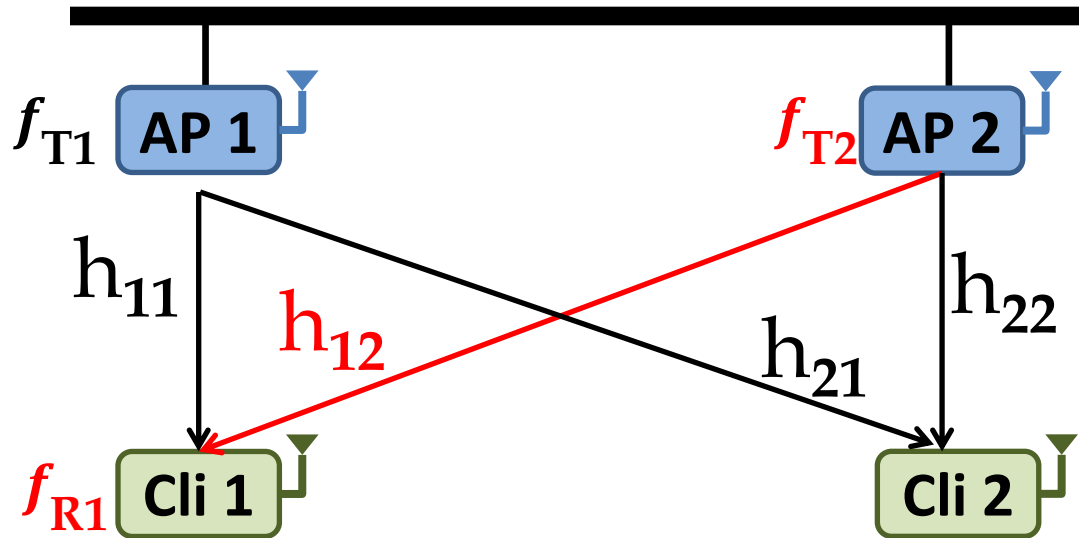
$$\begin{bmatrix} h_{11} e^{j2\pi(f_{T1} - f_{R1})t} & h_{12} \\ h_{21} & h_{22} \end{bmatrix}$$

# What Happens with Independent Oscillators?



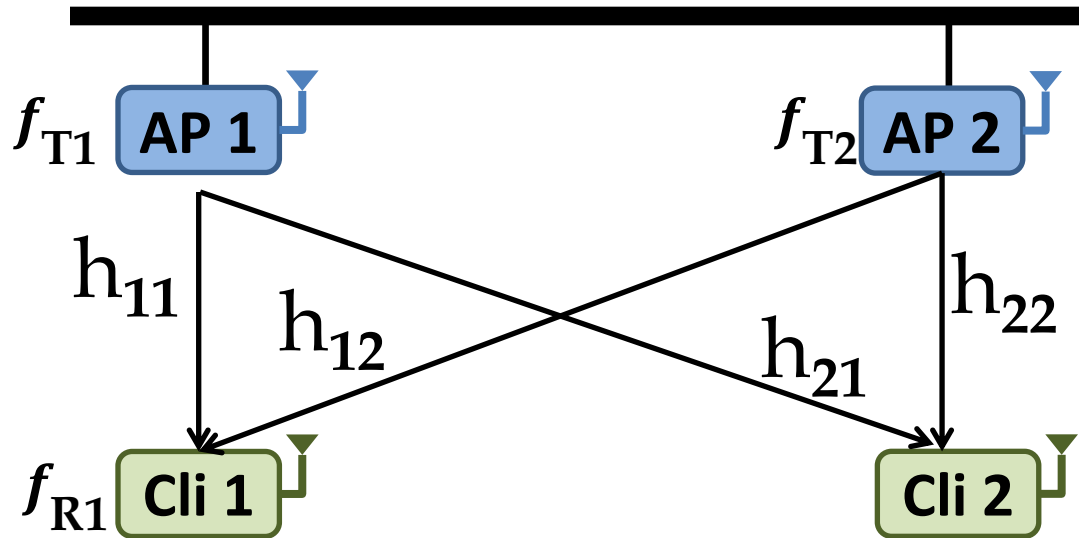
$$\begin{bmatrix} h_{11} e^{j2\pi(f_{T1} - f_{R1})t} & h_{12} \\ h_{21} & h_{22} \end{bmatrix}$$

# What Happens with Independent Oscillators?



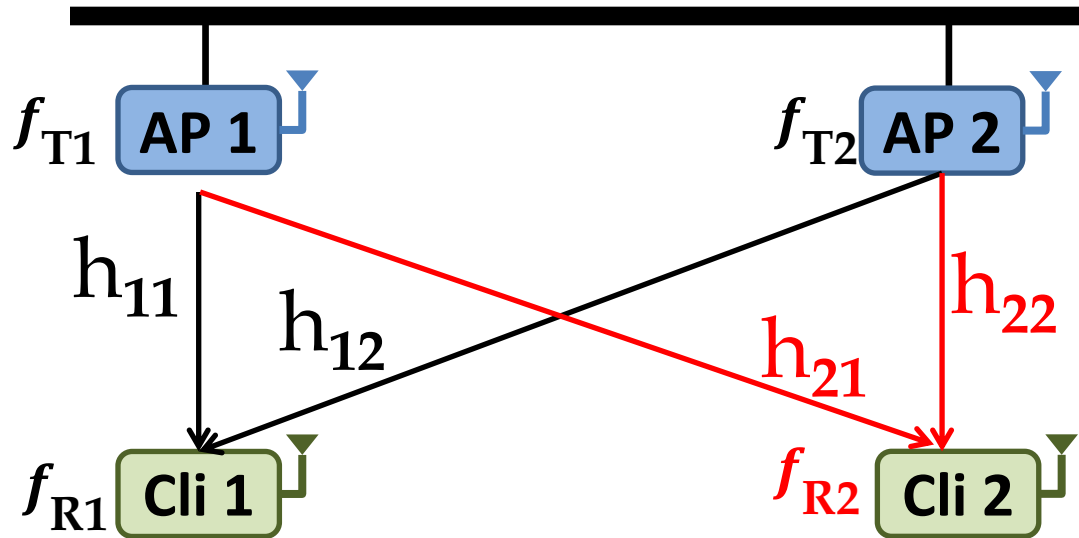
$$\begin{bmatrix} h_{11} e^{j2\pi (f_{T1} - f_{R1})t} & h_{12} e^{j2\pi (f_{T2} - f_{R1})t} \\ h_{21} & h_{22} \end{bmatrix}$$

# What Happens with Independent Oscillators?



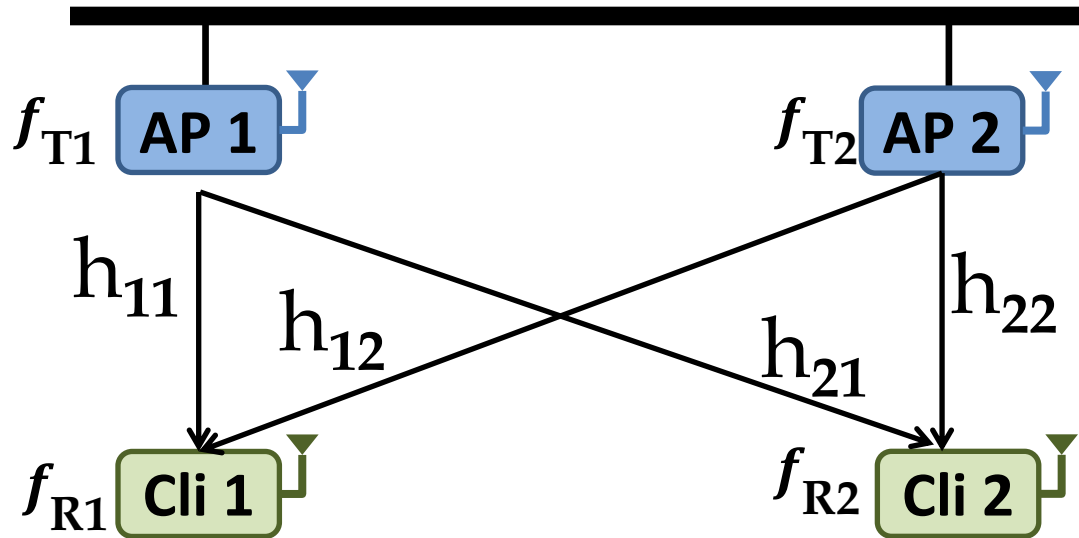
$$\begin{bmatrix} h_{11} e^{j2\pi (f_{T1} - f_{R1})t} & h_{12} e^{j2\pi (f_{T2} - f_{R1})t} \\ h_{21} & h_{22} \end{bmatrix}$$

# What Happens with Independent Oscillators?



$$\begin{bmatrix} h_{11} e^{j2\pi (f_{T1} - f_{R1})t} & h_{12} e^{j2\pi (f_{T2} - f_{R1})t} \\ h_{21} e^{j2\pi (f_{T1} - f_{R2})t} & h_{22} e^{j2\pi (f_{T2} - f_{R2})t} \end{bmatrix}$$

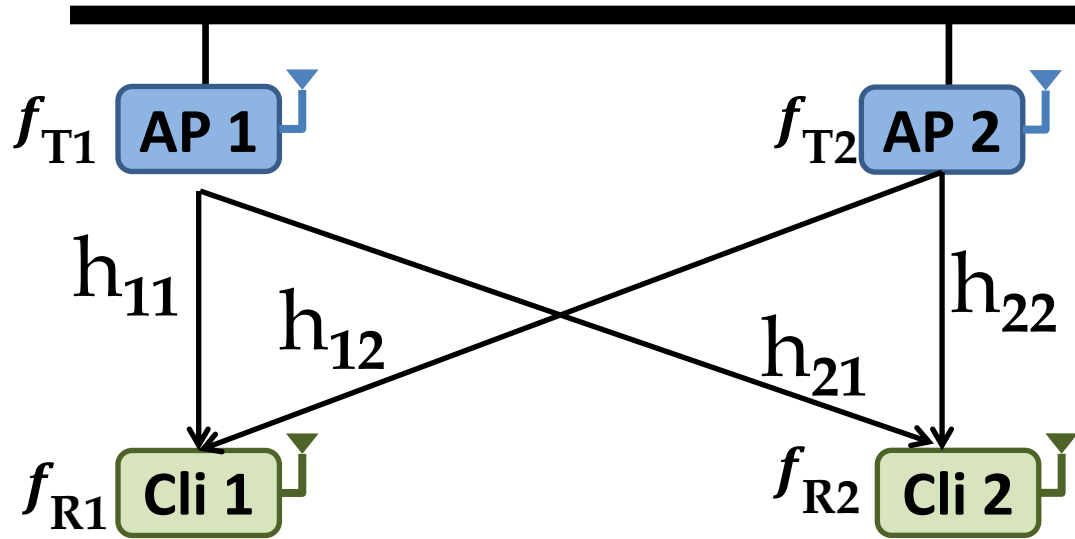
# What Happens with Independent Oscillators?



$$\begin{bmatrix} h_{11} \underline{e^{j2\pi (f_{T1} - f_{R1})t}} & h_{12} \underline{e^{j2\pi (f_{T2} - f_{R1})t}} \\ h_{21} \underline{e^{j2\pi (f_{T1} - f_{R2})t}} & h_{22} \underline{e^{j2\pi (f_{T2} - f_{R2})t}} \end{bmatrix} \text{Time Varying}$$

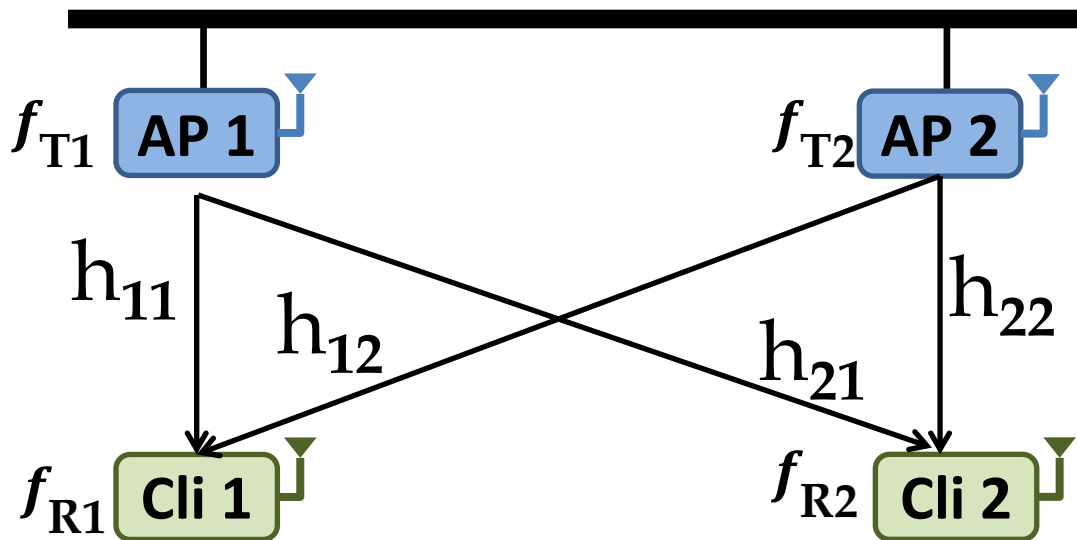


# Channel is Time Varying



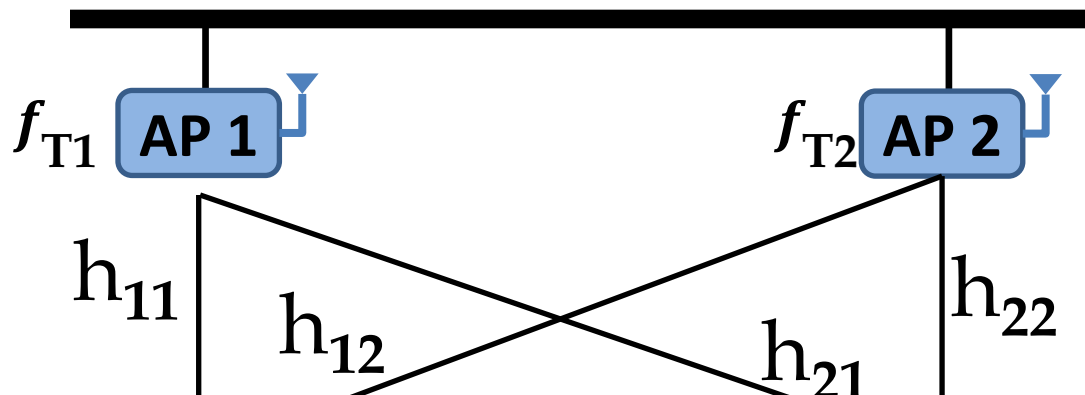
**H(t)**

# Does Traditional Beamforming Still Work?



$$\begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix} = \mathbf{H}(t) \begin{bmatrix} s_1(t) \\ s_2(t) \end{bmatrix}$$

# Does Traditional Beamforming Still Work?



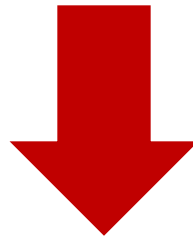
Beamforming does not work

$$\begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix} = \mathbf{H}(t) \mathbf{H}^{-1} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

Not Diagonal

# Challenge

Channel is Rapidly Time Varying



Relative Channel Phases of Transmitted Signals  
Changes Rapidly With Time

Prevents Beamforming

# Distributed Phase Synchronization

## **High Level Intuition:**

- Pick one AP as the lead
- All other APs are followers
  - Imitate the behavior of the lead AP by fixing the rotation of their oscillator relative to the lead.

# Decomposing $H(t)$

$$\begin{bmatrix} h_{11} e^{j2\pi (f_{T1} - f_{R1})t} & h_{12} e^{j2\pi (f_{T2} - f_{R1})t} \\ h_{21} e^{j2\pi (f_{T1} - f_{R2})t} & h_{22} e^{j2\pi (f_{T2} - f_{R2})t} \end{bmatrix}$$

$$\begin{bmatrix} e^{-j2\pi f_{R1}t} & 0 \\ 0 & e^{-j2\pi f_{R2}t} \end{bmatrix} \begin{bmatrix} h_{11} e^{j2\pi (f_{T1})t} & h_{12} e^{j2\pi (f_{T2})t} \\ h_{21} e^{j2\pi (f_{T1})t} & h_{22} e^{j2\pi (f_{T2})t} \end{bmatrix}$$

# Decomposing $\mathbf{H}(t)$

$$\begin{bmatrix} e^{-j2\pi f_{R1}t} & 0 \\ 0 & e^{-j2\pi f_{R2}t} \end{bmatrix} \begin{bmatrix} h_{11} e^{j2\pi(f_{T1})t} \\ h_{21} e^{j2\pi(f_{T1})t} \end{bmatrix} \begin{bmatrix} h_{12} e^{j2\pi(f_{T2})t} \\ h_{22} e^{j2\pi(f_{T2})t} \end{bmatrix}$$

# Decomposing $\mathbf{H}(t)$

$$\begin{bmatrix} e^{-j2\pi f_{R1}t} & 0 \\ 0 & e^{-j2\pi f_{R2}t} \end{bmatrix} \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} e^{j2\pi(f_{T1})t} & 0 \\ 0 & e^{j2\pi(f_{T2})t} \end{bmatrix}$$



# Decomposing $\mathbf{H}(t)$

$$\begin{bmatrix} e^{-j2\pi f_{R1}t} & 0 \\ 0 & e^{-j2\pi f_{R2}t} \end{bmatrix} \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} e^{j2\pi(f_{T1})t} & 0 \\ 0 & e^{j2\pi(f_{T2})t} \end{bmatrix}$$

# Decomposing $\mathbf{H}(t)$

$$\begin{bmatrix} e^{-j2\pi f_{R1}t} & 0 \\ 0 & e^{-j2\pi f_{R2}t} \end{bmatrix} \mathbf{H} \begin{bmatrix} e^{j2\pi(f_{T1})t} & 0 \\ 0 & e^{j2\pi(f_{T2})t} \end{bmatrix}$$

**Diagonal**

Devices cannot track their own oscillator phases...

# Decomposing $\mathbf{H}(t)$

$$e^{j2\pi(f_{T1})t} \begin{bmatrix} e^{-j2\pi f_{R1}t} & 0 \\ 0 & e^{-j2\pi f_{R2}t} \end{bmatrix} \mathbf{H} \begin{bmatrix} e^{j2\pi(f_{T1})t} & 0 \\ 0 & e^{j2\pi(f_{T2})t} \end{bmatrix} e^{-j2\pi(f_{T1})t}$$

# Decomposing $\mathbf{H}(t)$

$$\begin{bmatrix} e^{j2\pi (f_{T1} - f_{R1})t} & 0 \\ 0 & e^{j2\pi (f_{T1} - f_{R2})t} \end{bmatrix} \mathbf{H} \begin{bmatrix} 1 & 0 \\ 0 & e^{j2\pi (f_{T2} - f_{T1})t} \end{bmatrix}$$

$\mathbf{R}(t)$

$\mathbf{T}(t)$

Depends only on  
transmitters

# Decomposing $\mathbf{H}(t)$

$$\begin{bmatrix} e^{j2\pi (f_{T1} - f_{R1})t} & 0 \\ 0 & e^{j2\pi (f_{T1} - f_{R2})t} \end{bmatrix} \mathbf{H} \begin{bmatrix} 1 & 0 \\ 0 & e^{j2\pi (f_{T2} - f_{T1})t} \end{bmatrix}$$

$\mathbf{R}(t)$

$\mathbf{T}(t)$

$$\mathbf{H}(t) = \mathbf{R}(t) \cdot \mathbf{H} \cdot \mathbf{T}(t)$$

# Beamforming with Different Oscillators

$$\begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix} = \mathbf{R}(t) \cdot \mathbf{H} \cdot \mathbf{T}(t) \begin{bmatrix} s_1(t) \\ s_2(t) \end{bmatrix}$$

$$\begin{bmatrix} s_1(t) \\ s_2(t) \end{bmatrix} = \mathbf{T}(t)^{-1} \mathbf{H}^{-1} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

# Beamforming with Different Oscillators

$$\begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix} = \mathbf{R}(t) \cdot \mathbf{H} \cdot \mathbf{T}(t) \mathbf{T}(t)^{-1} \mathbf{H}^{-1} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

Diagonal

$$\begin{bmatrix} s_1(t) \\ s_2(t) \end{bmatrix} = \mathbf{T}(t)^{-1} \mathbf{H}^{-1} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

# Transmitter Compensation

$$\mathbf{T}(\mathbf{t}) = \begin{bmatrix} 1 & 0 \\ 0 & e^{j2\pi(f_{T2} - f_{T1})\mathbf{t}} \end{bmatrix}$$



# Transmitter Compensation

$$\mathbf{T}(t)^{-1} = \begin{bmatrix} 1 & 0 \\ 0 & e^{-j2\pi(f_{T2} - f_{T1})t} \end{bmatrix}$$

Follower AP imitates lead by multiplying each sample by oscillator rotation relative to lead

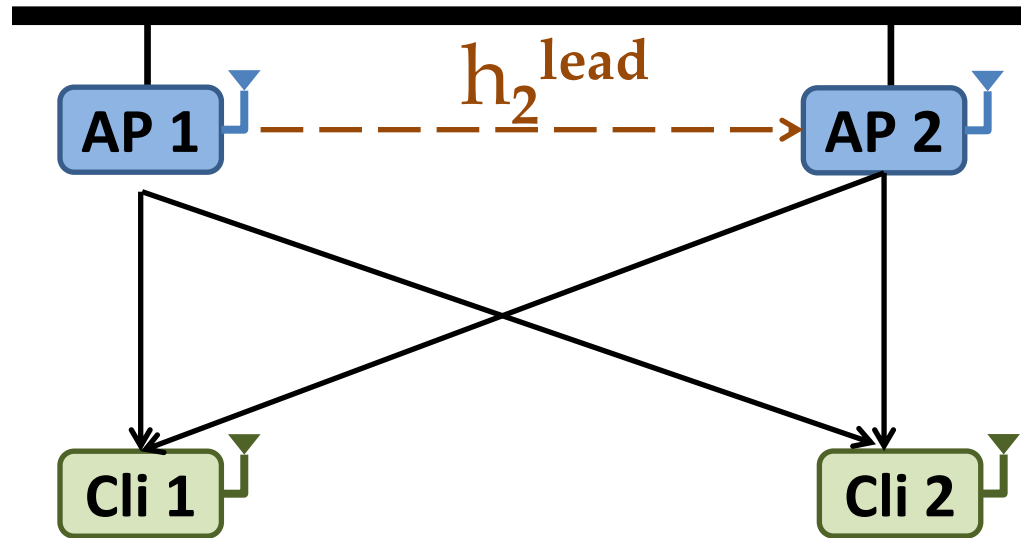
Requires only local information  $\rightarrow$  Fully distributed

# Measuring Phase Offset

- Multiply frequency offset by elapsed time
- Requires very accurate estimation of frequency offset
  - Error of 25 Hz (10 parts per BILLION) changes complete alignment to complete misalignment in 20 ms.

Need to keep resynchronizing to avoid error accumulation

# Resynchronization



$$h_2^{\text{lead}}(t) = h_2^{\text{lead}} e^{j2\pi(f_{T2} - f_{T1})t}$$

Directly compute phase at each follower AP by measuring channel from lead

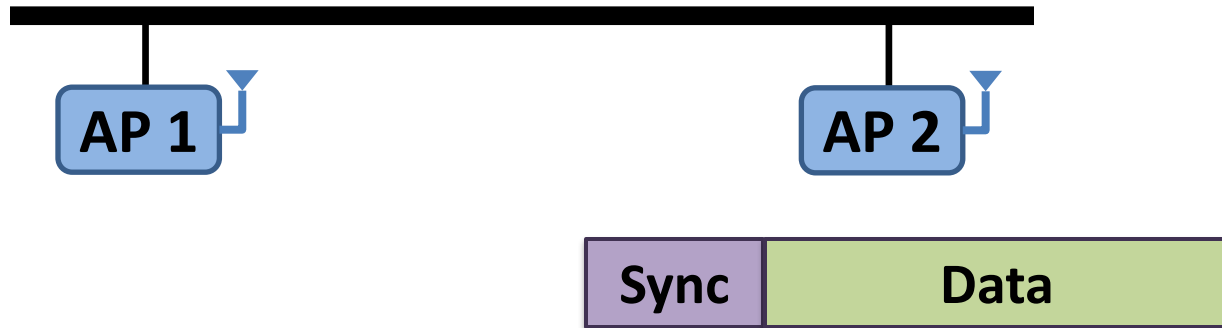
# Resynchronization



Lead AP:

- Prefixes data transmission with synchronization header

# Resynchronization



Follower AP:

- Receives Synchronization Header
- Corrects for change in channel phase from lead
- Transmits data

# Receiver Compensation

$$\begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix} = \mathbf{R}(t) \cdot \mathbf{H} \cdot \mathbf{T}(t)$$

$$\begin{bmatrix} s_1(t) \\ s_2(t) \end{bmatrix}$$

# Receiver Compensation

$$\begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix} = \mathbf{R}(t) \cdot \mathbf{H} \cdot \mathbf{T}(t) \mathbf{T}(t)^{-1} \mathbf{H}^{-1} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

$$\begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix} = \mathbf{R}(t)^{-1} \mathbf{R}(t) \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

# Receiver Compensation

$$\mathbf{R}(t) = \begin{bmatrix} e^{j2\pi (f_{T1} - f_{R1})t} & 0 \\ 0 & e^{j2\pi (f_{T1} - f_{R2})t} \end{bmatrix}$$

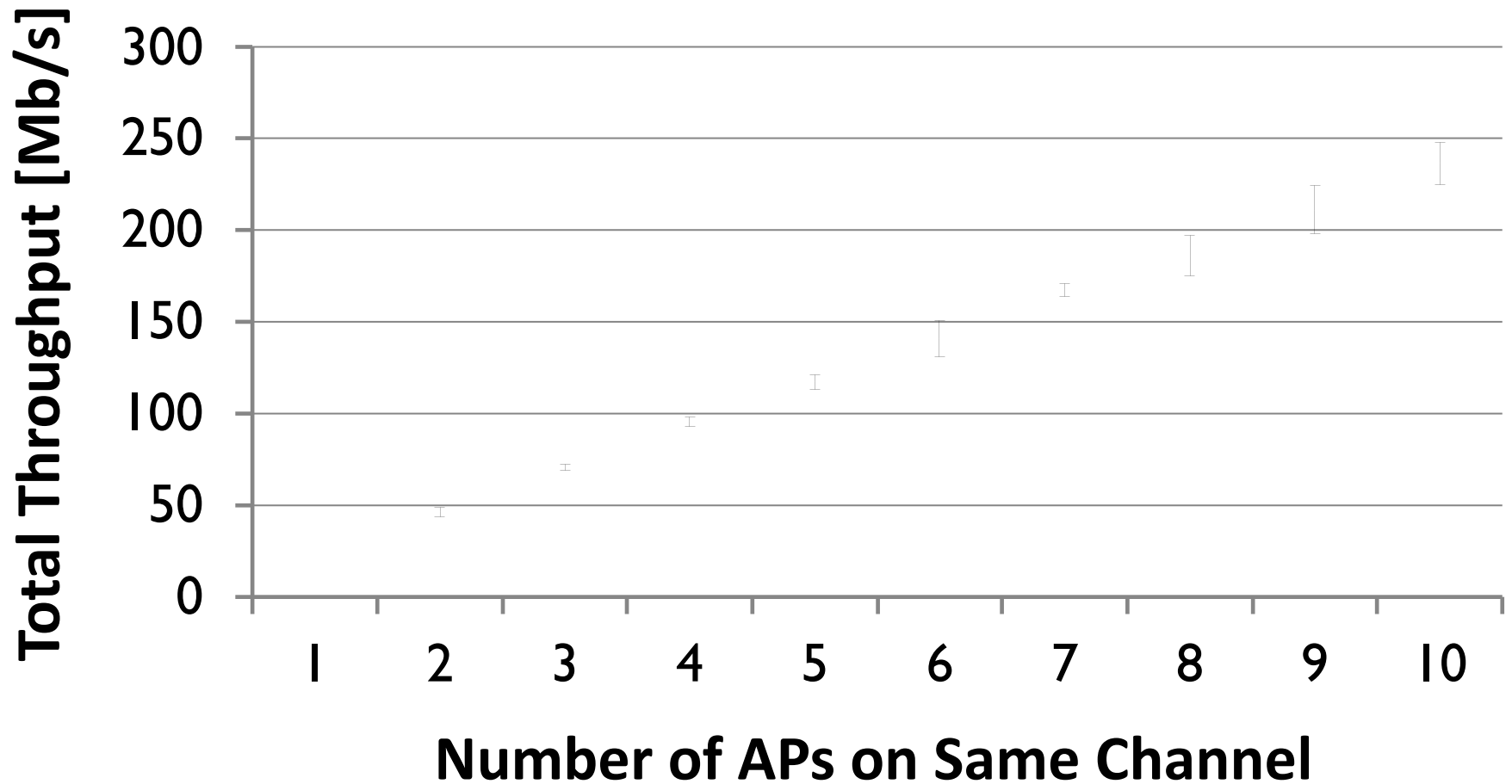


# Receiver Compensation

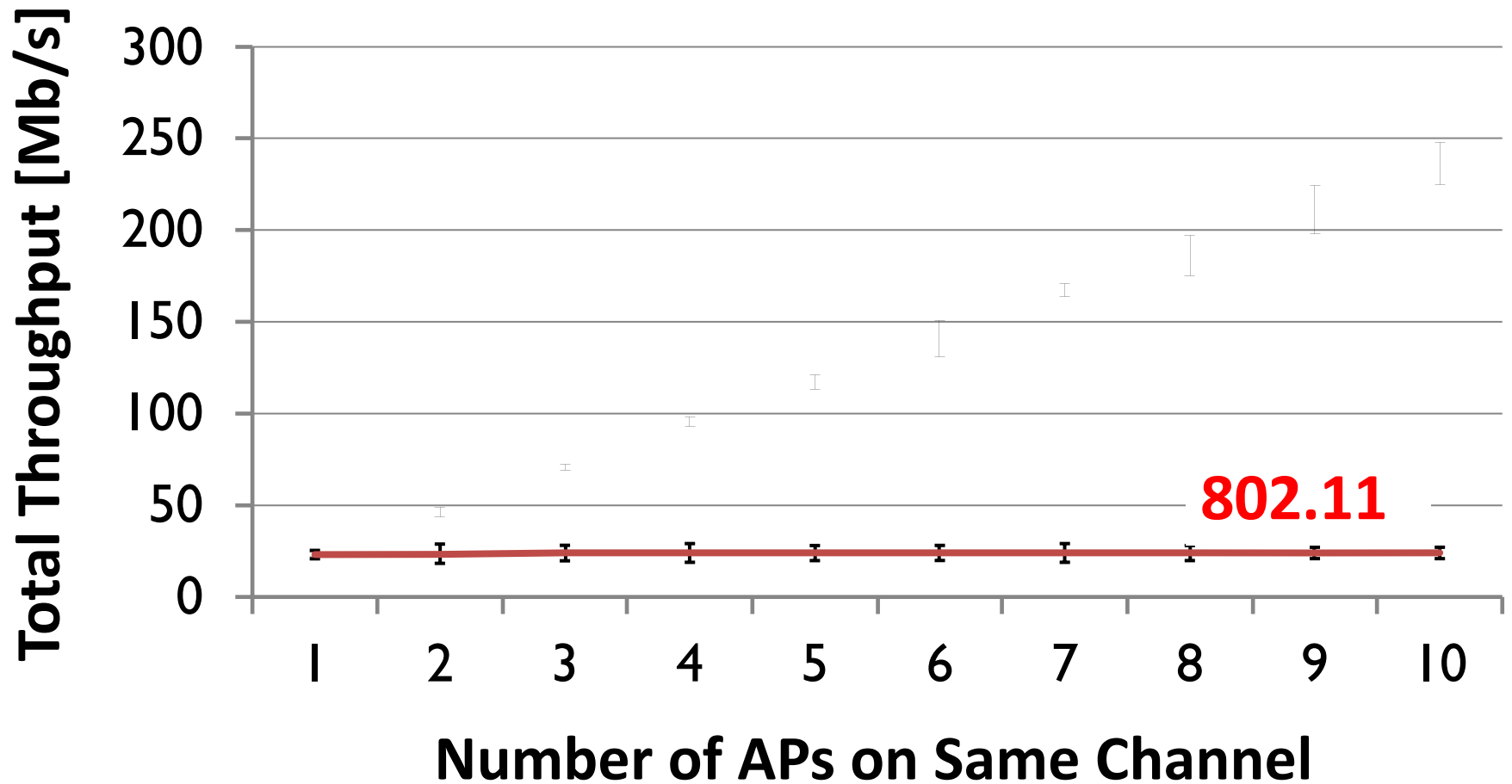
$$\mathbf{R}(t)^{-1} = \begin{bmatrix} e^{-j2\pi (f_{T1} - f_{R1})t} & 0 \\ 0 & e^{-j2\pi (f_{T1} - f_{R2})t} \end{bmatrix}$$

Receiver does what it does today –  
correct for oscillator offset from lead

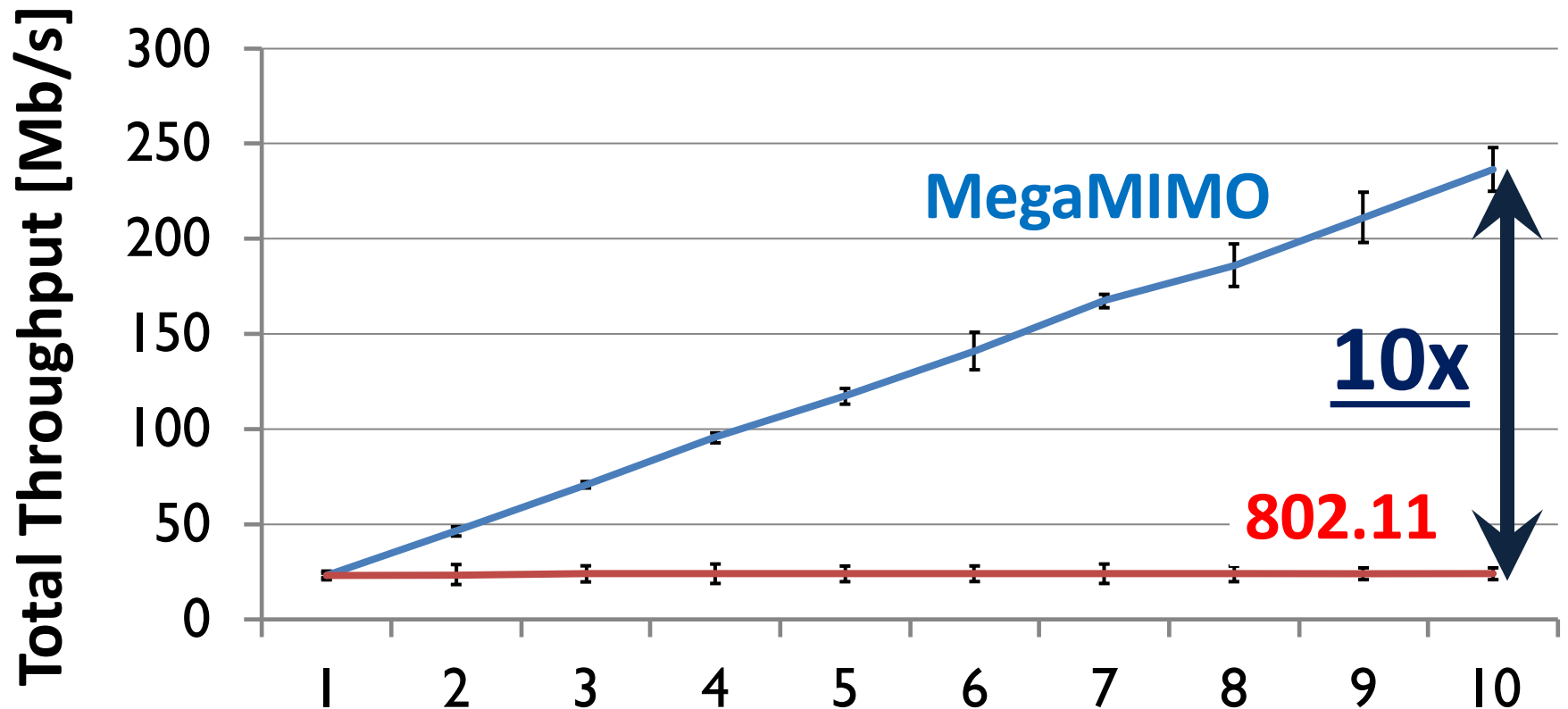
# Does MegaMIMO Scale Throughput with the Number of Users?



# Does MegaMIMO Scale Throughput with the Number of Users?



# Does MegaMIMO Scale Throughput with the Number of Users?



**10x throughput gain over existing Wi-Fi**

# AirShare

**transmits the reference clock over the air  
&  
eliminates CFO**

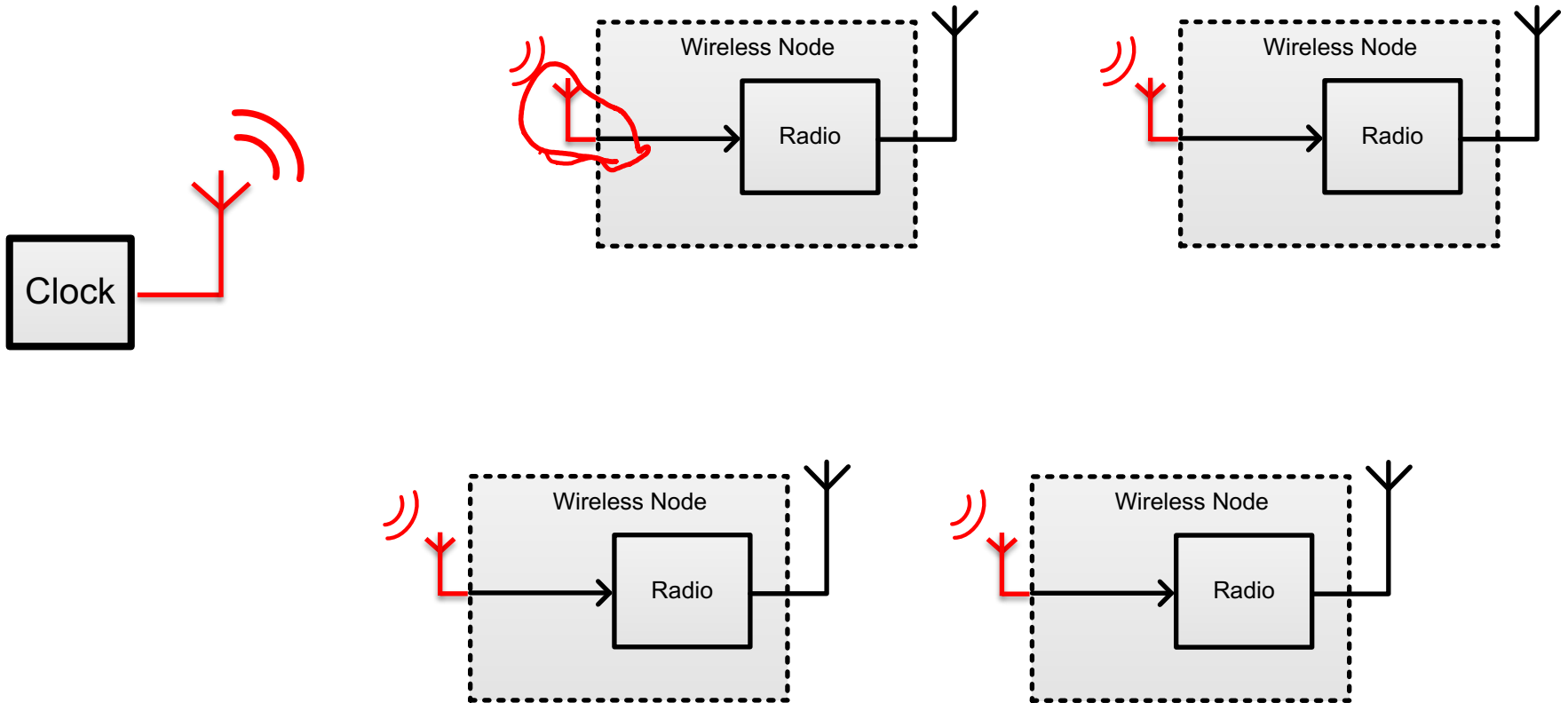
Protocol independent

Supports mobility

Cheap and Low-Power

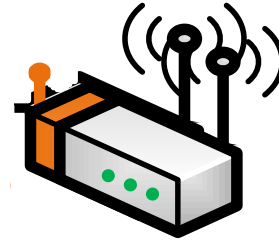
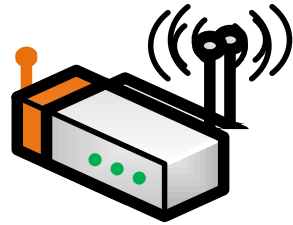
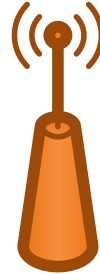
# Idea

Transmit a reference over-the-air

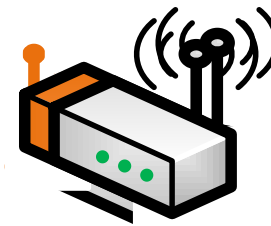
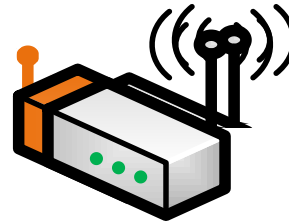
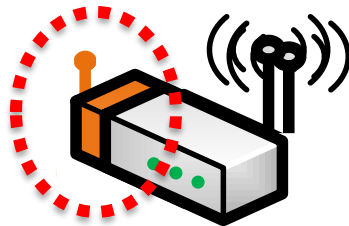


# AirShare Architecture

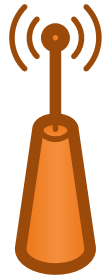
**Emitter**



**Recipient**



# Emitter



How can emitter transmit a clock?

Problem: Reference clocks are typically 10-40 MHz

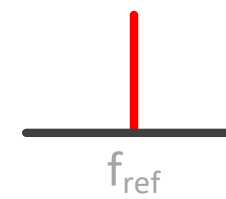
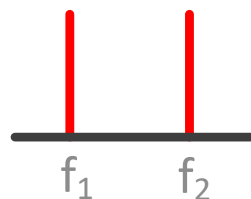
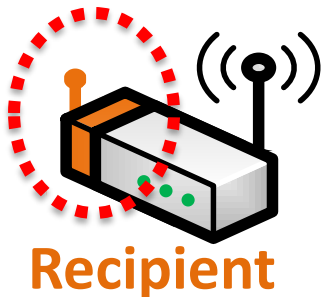
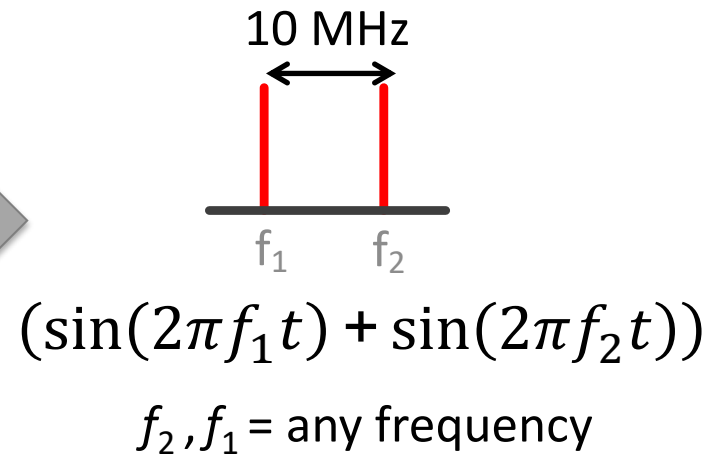
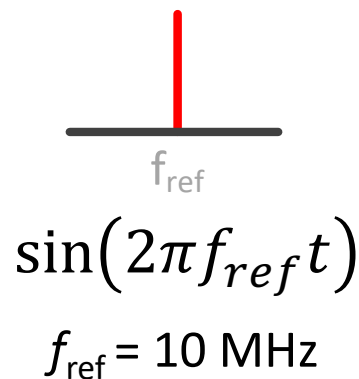
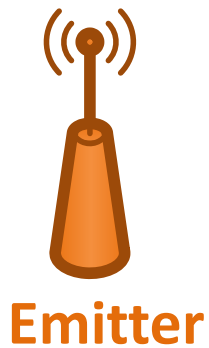
- FCC forbids transmitting such a low-frequency signal
- Requires large antennas



# Transmit a Differential-reference

Instead of transmitting a signal at the clock frequency (10 MHz)

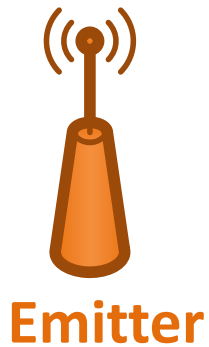
**Transmits two signals separated by the clock frequency**




# Transmit a Differential-reference

Instead of transmitting a signal at the clock frequency (10 MHz)

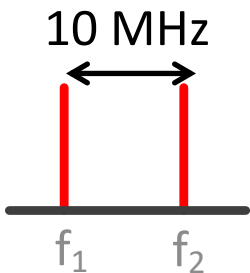
**Transmits two signals separated by the clock frequency**



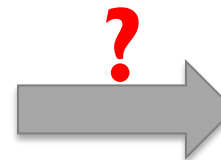
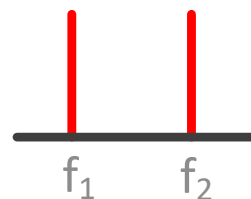
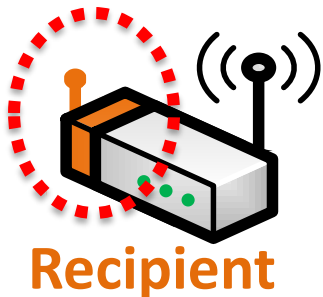


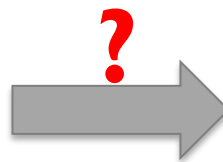
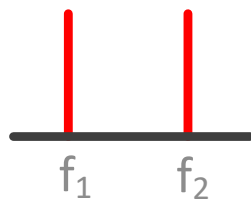
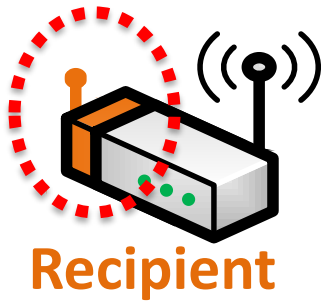
$\sin(2\pi f_{ref} t)$   
 $f_{ref} = 10 \text{ MHz}$



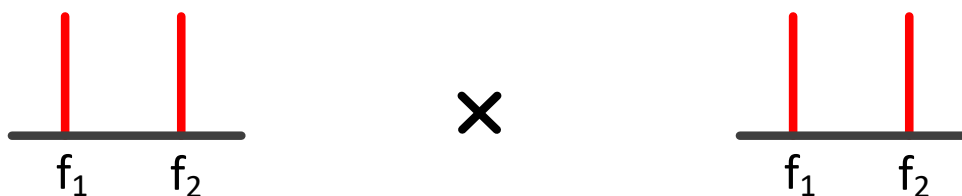


$(\sin(2\pi f_1 t) + \sin(2\pi f_2 t))$   
 $f_2, f_1 = \text{any frequency}$





receives the signal and multiplies the signal by itself



$$(\sin(2\pi f_1 t) + \sin(2\pi f_2 t)) \times (\sin(2\pi f_1 t) + \sin(2\pi f_2 t))$$

Using trigonometric identities:

$$\sin(\alpha) \times \sin(\beta) = \frac{1}{2} \cos(\alpha + \beta) + \frac{1}{2} \cos(\alpha - \beta)$$

AirShare transmits the reference clock  
without violating FCC regulations

# Conclusion

- Learned about Interference Nulling, IA, IAC and MegaMIMO
- In IA, the gains are lower, but
  - Transmitters need not be connected to the same Ethernet and exchange the packets
  - No need for phase synchronization
- IAC can bring additional gains in comparison to IA
  - Transmitters need not be connected to the same Ethernet and exchange the packets
  - No need for phase synchronization
- In MegaMIMO, the gains are linear with the total number of users
  - Need high speed Ethernet to connect the transmitters
  - Need tight phase synchronization between transmitters
- AirShare: Distributed phase synchronization