

# Smarter Monte Carlo

Today we will explore ways to change the transition probability in MCMC to allow faster convergence.

- Metropolis in MCMC
- Heat bath MC
- Preferential MC
- Smart MC
- Force Bias MC

# Recall: The “Classic” Metropolis method

*Metropolis-Rosenbluth<sup>2</sup> -Teller<sup>2</sup> (1953) method for sampling the Boltzmann distribution is:*

- Move from  $s$  to  $s'$  with probability  $T(s \rightarrow s') = \text{constant}$
- Accept with move with probability:

$$A(s \rightarrow s') = \min [ 1 , \exp (-\beta[E(s') - E(s)]) ]$$

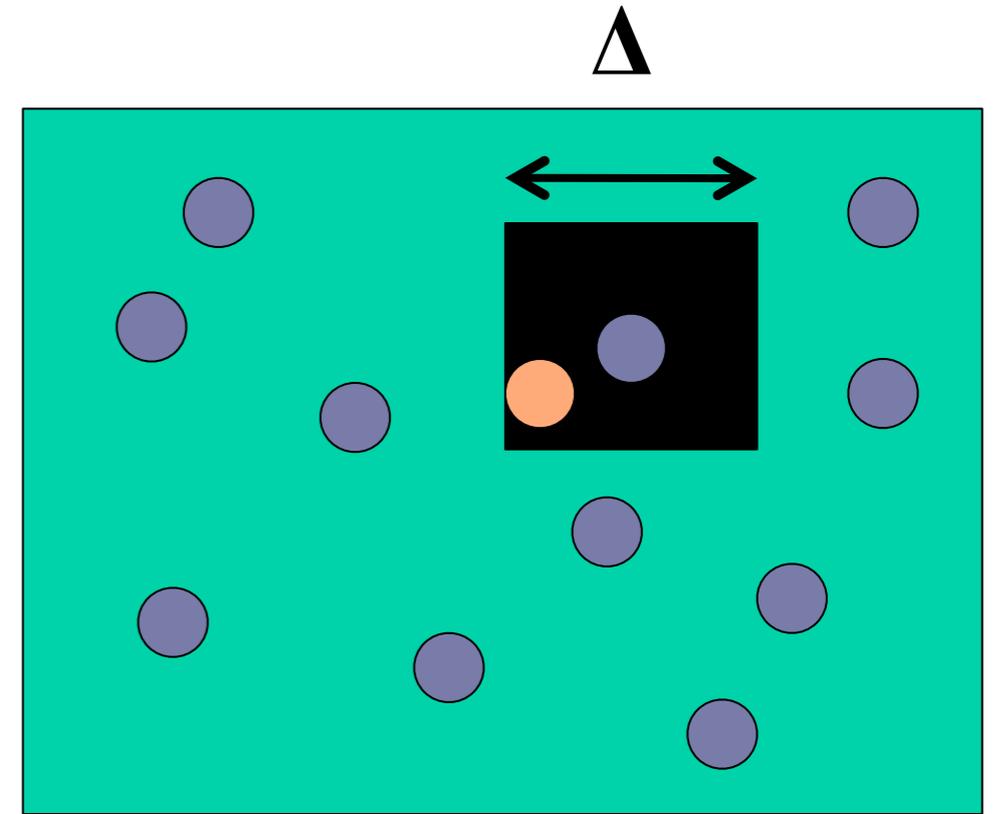
- Repeat many times

- Given ergodicity, the *distribution of  $s$*  will be the canonical distribution:  $\pi(s) = \exp(-E(s)/k_B T) / Z$ .
- **Convergence is guaranteed but the rate is not!**

# Recall: How to sample

$$S_{\text{new}} = S_{\text{old}} + \Delta \cdot (\text{sprng} - 0.5)$$

Uniform distribution in a cube of side " $\Delta$ ".



**Note:** It is more efficient to **move one particle at a time** because only the energy of that particle comes in and the acceptance ratio will be larger.

$$\begin{aligned} A(s \rightarrow s') &= \exp[-\beta(V(s') - V(s))] \\ &= \exp\left[-\beta \sum_{j \neq i} (v(r'_i - r_j) - v(r_i - r_j))\right] \end{aligned}$$

For  $V$  with cut-off range, difference is local.

# Recall: Rejection Method

Metropolis achieves detailed balance by *rejecting* moves.

*General Approach:*

1. Choose distribution to sample, e.g.,  $\pi(s) = \exp[-\beta H(s)]/Z$

2. Impose detailed balance on transition:  $K(s \rightarrow s') = K(s' \rightarrow s)$

where  $K(s \rightarrow s') = \pi(s) P(s \rightarrow s')$

*(probability of being at  $s$ ) \* (transition probability of going to  $s'$ ).*

3. Break up transition probability into sampling and acceptance:

$$P(s \rightarrow s') = T(s \rightarrow s') A(s \rightarrow s')$$

*(probability of generating  $s'$  from  $s$ ) \* (probability of accepting move)*

The optimal acceptance probability that gives detailed balance is:

$$A(s \rightarrow s') = \min \left\{ 1, \frac{T(s' \rightarrow s)\pi(s')}{T(s \rightarrow s')\pi(s)} \right\} = \min \left\{ 1, \frac{\pi(s')}{\pi(s)} \right\}$$

*If T is constant!*

**IMPORTANTLY** Normalization of  $\pi(s)$  is not needed or used!

We want to choose **T** to maximize the acceptance probability.

# Detailed balance

Three key concepts:

1. Sample by using an ergodic random walk.
2. Determine equilibrium state by using detailed balance.
3. Achieve detailed balance by using rejections.

**Detailed balance:**  $\pi(\mathbf{s}) P(\mathbf{s} \rightarrow \mathbf{s}') = \pi(\mathbf{s}') P(\mathbf{s}' \rightarrow \mathbf{s})$ .

*Rate balance from  $s$  to  $s'$ .*

- If  $P(\mathbf{s} \rightarrow \mathbf{s}')$  is ergodic,  $\pi(\mathbf{s})$  is unique steady state solution.
- Detailed balance is **not** required
  - **Balance** will suffice:  $\pi(\mathbf{s}) = \sum_{\mathbf{s}'} \pi(\mathbf{s}') P(\mathbf{s}' \rightarrow \mathbf{s})$ .
  - Example: **menu of moves**

# Menu of Moves

Suppose we have moves of type A and B, either of which satisfy detailed balance alone.

- We can either:
  - 1. Randomly choose* from (A,B).
  - 2. Cycle deterministically* (A,B,A,B,A,B,...)
- Either will give the correct distribution even though choice 2 does not really satisfy detailed balance.
  - ✓ **Theorem**: If each menu item individually satisfies detailed balance, then desired state is the unique stationary state.
- **EX: in classic Metropolis**, *instead of randomly choosing the particle to be moved, then one can go through them sequentially*. After one *pass*, all particles are attempted once. This is correct and might be faster.

# Preferential Sampling

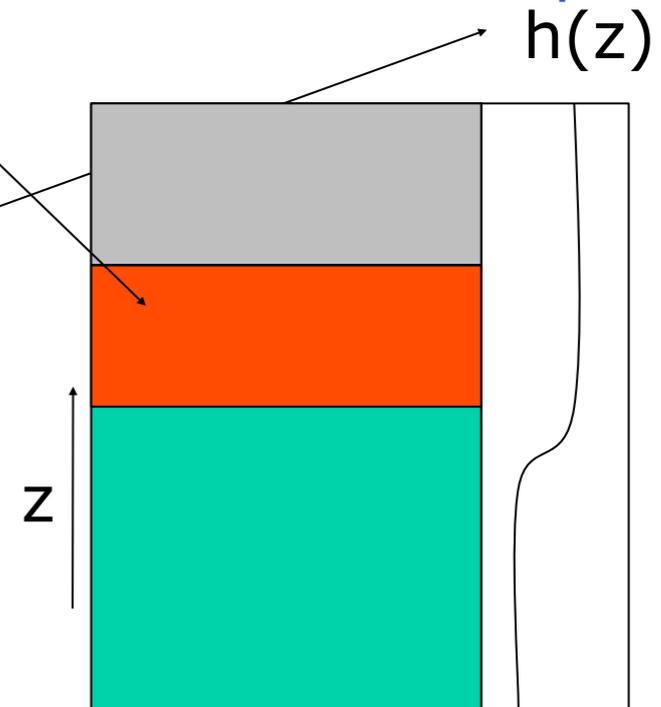
Sometimes it is not the overall acceptance ratio one wants to optimize.

- Consider a layered system:
- Suppose we are only interested in the top.
- Sample particles with probability  $h(z_i)/H$ .

$$H = \sum_{i=1}^N h(z_i)$$

- Then acceptance probability:

$$A(r \rightarrow r') = \frac{h(z_i)}{H} \frac{H'}{h(z'_i)} e^{-\beta(V(r')-V(r))}$$



- We focus the CPU time on *interesting degrees of freedom* (it will lower overall acceptances but increase efficiency of what we want to calculate.)

# Optimizing the moves

- (Ergodicity) Any transition rule is allowed as long as you can go anywhere in phase space with a finite number of steps.
- Try to find a  $T(s \rightarrow s') \approx \pi(s')/C$ .

$$A(s \rightarrow s') = \min \left\{ 1, \frac{T(s' \rightarrow s)\pi(s')}{T(s \rightarrow s')\pi(s)} \right\} = 1$$

- If you can the acceptance ratio will be 1.
- But this would be "direct sampling". Normally very difficult.
- Heat bath corresponds to making this choice in a limited neighborhood (for lattice models).

# Heat Bath

Sample a neighborhood of a given point so that it is in "local equilibrium."

$$T(s \rightarrow s') = \frac{\pi(s')}{C(s)} \quad \text{with} \quad C(s) = \sum_{s'' \in N(s)} \pi(s'')$$

Then the acceptance probability will be:

$$A(s \rightarrow s') = \min \left\{ 1, \frac{C(s)}{C(s')} \right\}$$

- ✓ Can be used **only** if it is possible to quickly compute the normalization ratio.
- ✓ Acceptance ratio=1 if  $C(s)$  is independent of  $s$ .

# Force-Bias MC

We can use forces to push the walk in the right direction.

– Taylor expand about the current point.

$$V(r') = V(r) - F(r) \cdot (r' - r)$$

– Set  $T(s \rightarrow s') \approx \exp[-\beta(V(r) - aF(r) \cdot (r' - r))]$ .

- We can sample this distribution using the mapping method if we assume a limited domain such as a cube.
- This is *Force-Bias Monte Carlo* (see notes and textbook for details).
- Idea is to move preferentially in direction of higher probability, thereby reducing rejections and increasing how far you can move.
- Does it work in practice?

Force bias has higher acceptance ratio than classic Metropolis. Does it lead to faster convergence?

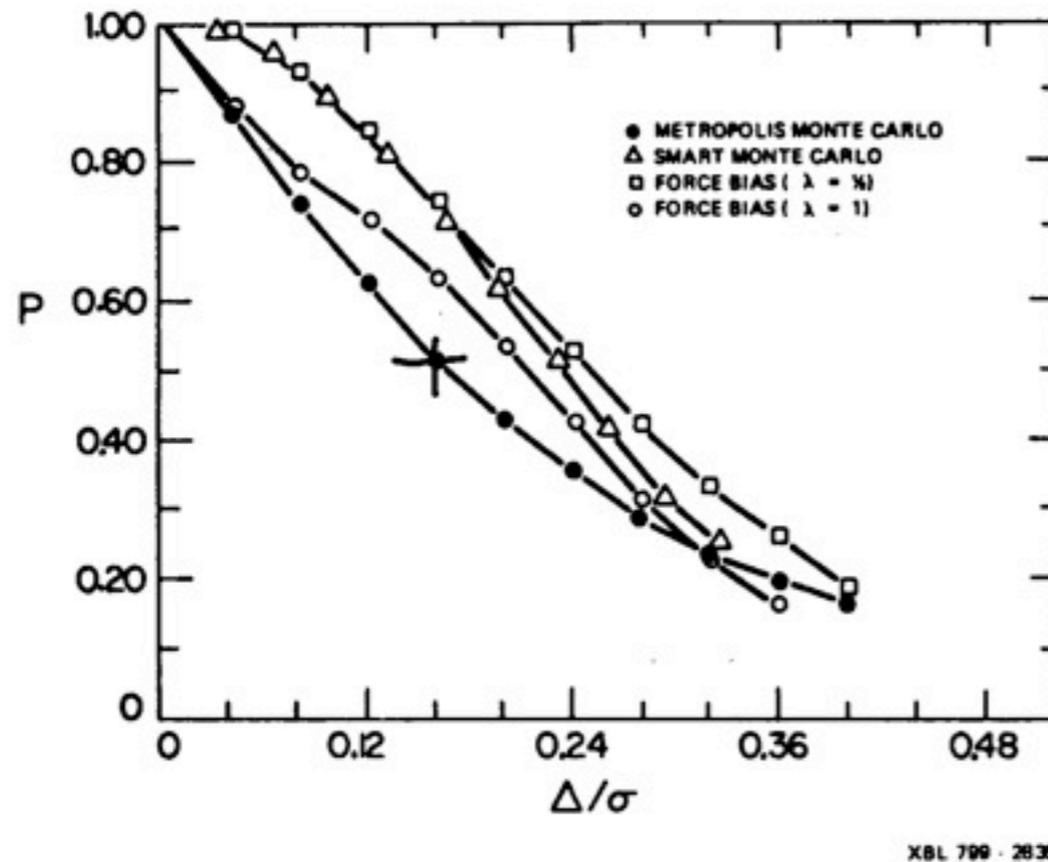


Fig. 1. Average acceptance probability.

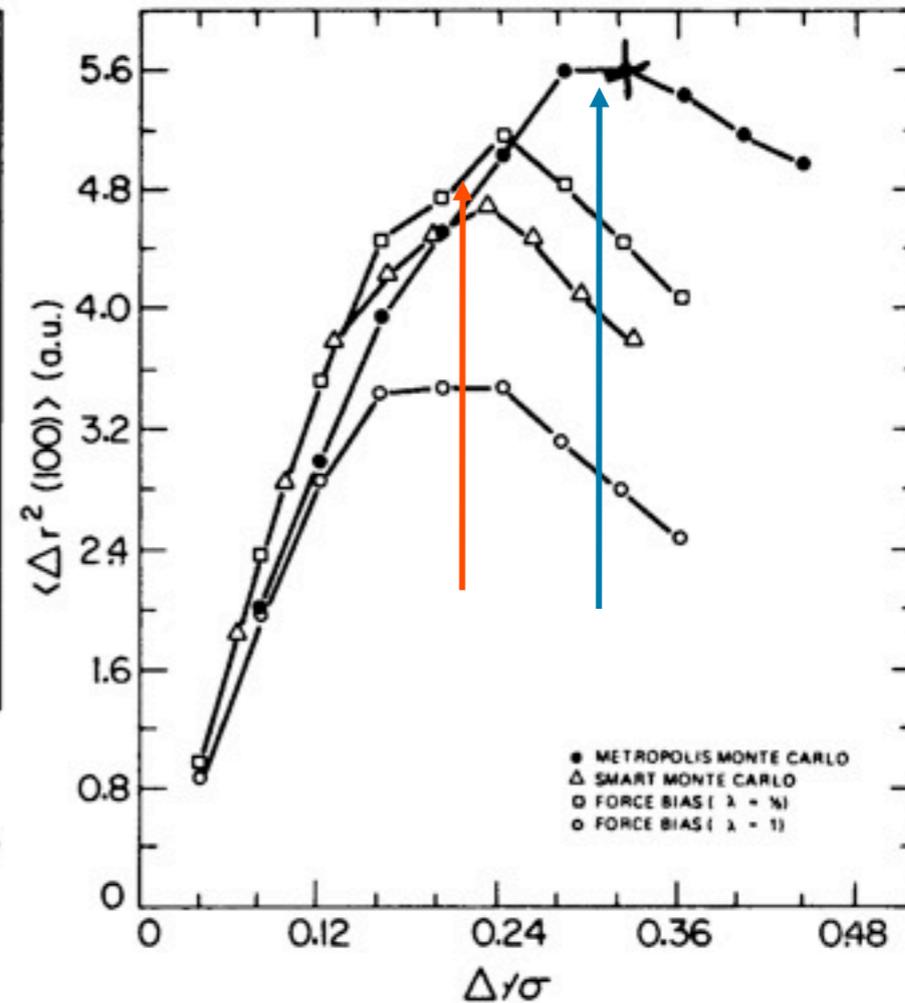


Fig. 3.  $\langle (\vec{r}(i) - \vec{r}(i + 100))^2 \rangle$   
 $\vec{r}(i) = 3n$  vector of argon positions at step  $i$ .

Variance of energy (local quantity) is not as sensitive to step size. MC is a robust method!

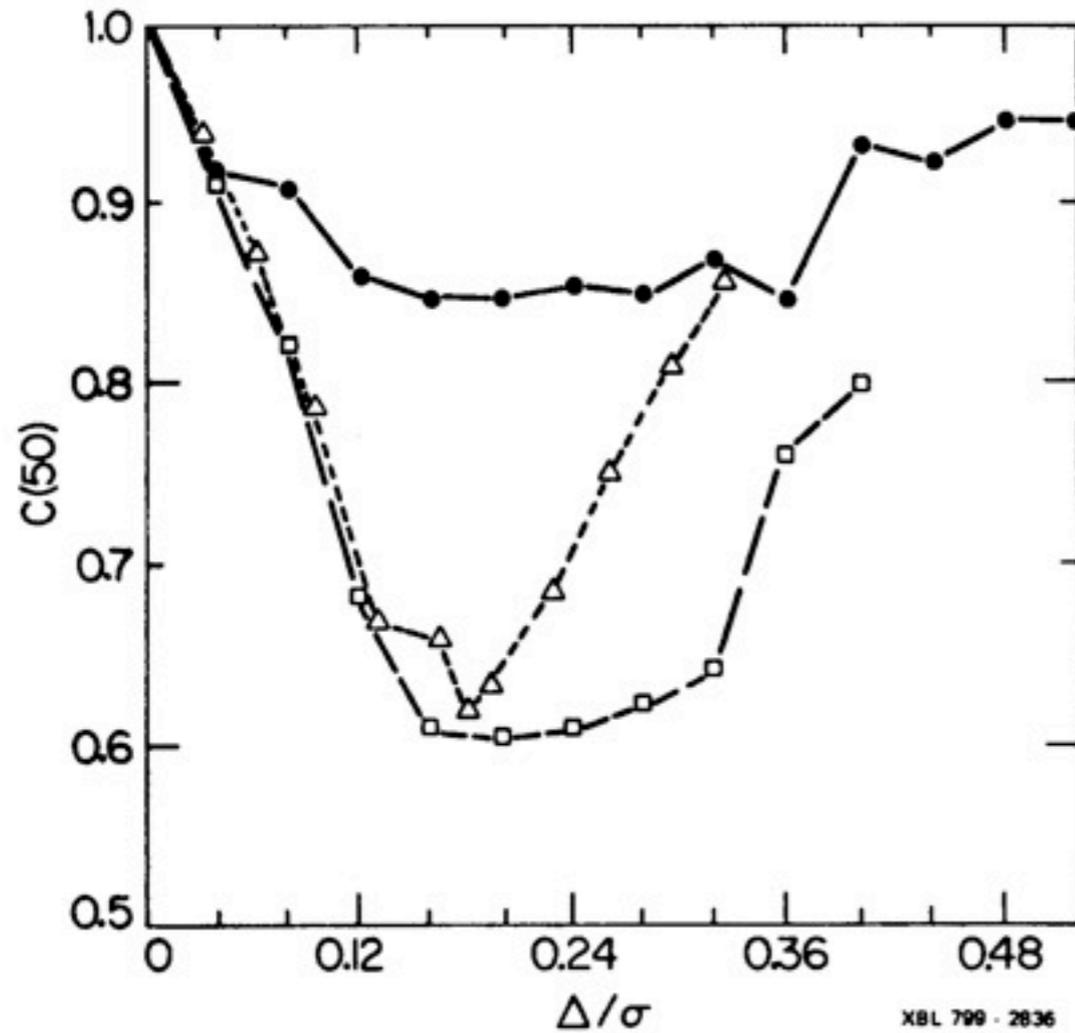


Fig. 2.  $\frac{\langle \Delta V(i) \Delta V(i + 50) \rangle}{\langle \Delta V(i)^2 \rangle}$

where  $i$  = step number and  $\Delta V$  is the deviation of potential energy from the mean.

Acceptable range of efficiency.

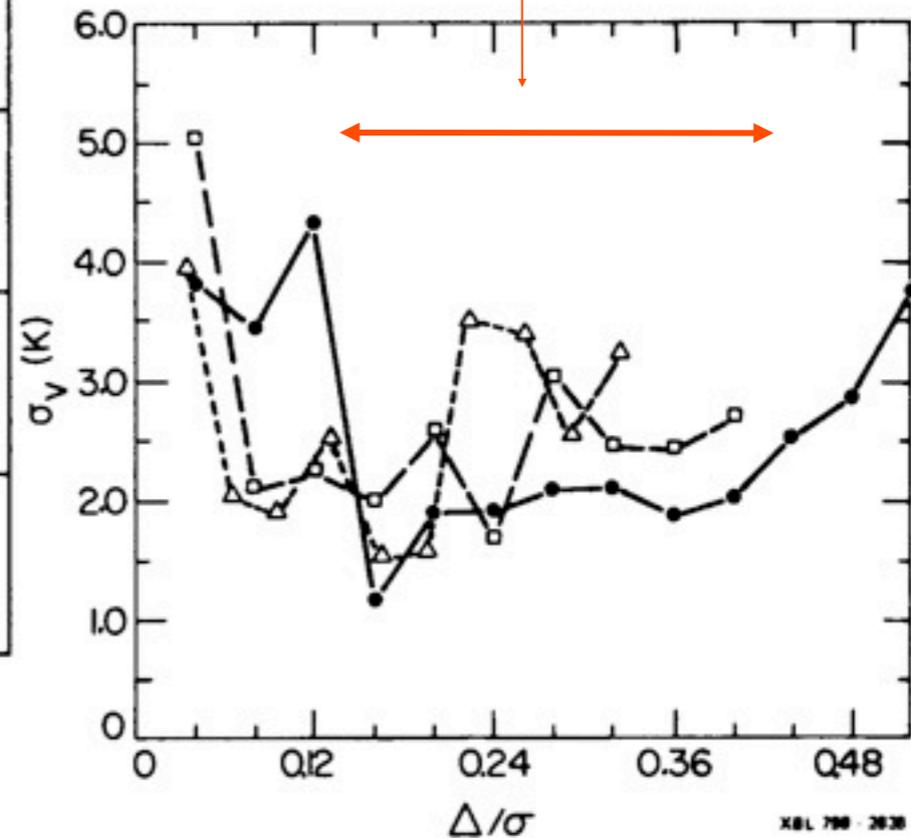


Fig. 4. The variance of the total potential energy for calculations with the same number of steps.

# Smart Monte Carlo

Same idea but sample from a *displaced Gaussian pdf*.

$$T(r \rightarrow r') = \frac{1}{(4\pi\tau)^{3/2}} \exp \left[ -\frac{(\vec{r}' - \vec{r} - \tau\beta\vec{F}(\vec{r}))^2}{4\tau} \right]$$

with trial displacement:  $\vec{\Delta r} = \tau\beta\vec{F}(\vec{r}) + \vec{\delta}$  where  $\langle \delta \rangle = 0$  and  $\langle \delta^2 \rangle = 2\tau$

- Also moves in the direction of increased probability
- Acceptance rate  $A$  will be:

$$A(r \rightarrow r') = \exp \left\{ -\beta \left[ V(\vec{r}') - V(\vec{r}) + \frac{\vec{F}(\vec{r}') + \vec{F}(\vec{r})}{2} \cdot \left( \vec{r}' - \vec{r} + \tau\beta \frac{\vec{F}(\vec{r}') - \vec{F}(\vec{r})}{2} \right) \right] \right\}$$

- $A=1$  in case the potential is linear in region sampled  $O(\tau^{1/2})$ .
- Note that sampling domain is infinite, in principle.
- There is a nice way of deriving this -- related to Brownian dynamics and quantum Monte Carlo.

# Brownian Dynamics

Consider a big molecule in a solvent. In the high-viscosity limit the “master equation” is:

$$\frac{\partial \rho(R, t)}{\partial t} = D \nabla^2 \rho(R, t) - \beta D \nabla \cdot (\vec{F}(R) \rho(R, t))$$

$$R(t + \tau) = R(t) + \tau \beta D \vec{F}(R(t)) + \vec{\eta}(t)$$

$$\langle \vec{\eta}(t) \rangle = 0 \quad \langle \eta^2(t) \rangle = 2\tau D$$

White noise  
Variance  $\sim D\tau$

**Enforce detailed balance by rejections!** (hybrid method)

$$T(R \rightarrow R') \propto \exp \left[ -\frac{(R' - R - \beta D \tau F(R))^2}{2D\tau} \right]$$

Also the equation for Diffusion Quantum Monte Carlo!