The Speed of Light *c* in vacuum is the same for all inertial observers, independent of the motion of the source.

$$\beta \equiv \frac{v}{c} \quad \gamma \equiv \frac{1}{\sqrt{1 - \beta^2}}$$

- Time Dilation: moving clocks tick slower by factor γ
- Length Contraction: moving objects are shorter by factor γ along direction of motion
- Loss of Simultaneity: events that occur at the same time but different positions in one frame are not simultaneous in another frame



Principle of Relativity: The laws of physics are the same in all inertial frames.

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Lorentz Boosts





- Convention: S' moves at speed $v=\beta c$ in +x direction relative to S.
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- Synch S,S' origins \rightarrow drop Δ 's

Invariant
Interval
$$I = (c\Delta t)^2 - (\Delta x)^2 - (\Delta y)^2 - (\Delta z)^2$$
is invariant under boosts

- Timelike $I_{A-B} > 0$
- object can travel from A-B
- boost can change Δx_{AB} sign
- Spacelike I_{A-B} < 0
 cannot travel from A-B
 boost can change Δt_{AB} sign

The **proper time** interval $\Delta \tau_{AB} \equiv \sqrt{I_{AB}}/c$ is the "**watch-time**" that elapses on the wristwatch of an inertial observer who travels from A to B.

Causality: Causal relationships exist where "event A causes event B", implying that A must occur *before* B



Nothing – even information – can travel faster than c.

- worldline: path of an object in (*ct*,*x*) diagram
- **boost hyperbola**: locus of coordinates $(t,x)_{\rm B}$ in all possible inertial frames relative to $(t,x)_{\rm A}$ at (0,0); defined by $I = (c\Delta t)^2 - (\Delta x)^2$

Minkowski Diagrams



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4



Lorentz Boosts and 4-Vectors S S' • Convention: S' speed rel. to S is $v = \beta c$ in +x direction. v • **Inverse**: swap $S \leftrightarrow S'$ by changing the sign of β . • Synch origins to drop Δ 's х $\Delta x'^{\mu} = \Lambda \ \Delta x^{\mu}$ 0 0 $\Lambda \equiv$ $x^{\mu} \equiv (ct, x, y, z)$ 0 0 1 5 • Boost velocity: • Boost frequency of light ray (parallel case) $u_x = \frac{u'_x + v}{1 + u'_x v / c^2}$ $\frac{f'}{f} = \sqrt{\frac{1-\beta}{1+\beta}}$ $u_{y,z} = \frac{u'_{y,z}}{\gamma(1 + u'_{,v} v / c^2)}$ Invariant $I = (c\Delta t)^2 - (\Delta x)^2 - (\Delta y)^2 - (\Delta z)^2$ Interval is invariant under boosts Timelike $I_{A-B} > 0$ Spacelike $I_{A-B} < 0$ • object can travel from A-B • cannot travel from A-B • boost can change Δx_{AB} sign • boost can change Δt_{AB} sign The **proper time** interval $\Delta \tau_{AB} \equiv \sqrt{I_{AB}/c}$ is the "watch-time" that elapses on the wristwatch of an

inertial observer who travels from A to B.

Dynamics

$$\vec{F} = \frac{d\vec{p}}{dt} \quad W = \int \vec{F} \cdot d\vec{l} = \Delta E$$

$$\vec{p} = m\vec{v} \qquad E = mc^{2}$$

$$\vec{\psi} \quad \vec{6}$$

$$\vec{E} = \sqrt{(pc)^{2} + (m_{0}c^{2})^{2}}$$

$$\vec{p} = \gamma m_{0}\vec{v} \qquad E = \gamma m_{0}c^{2} \qquad m = \gamma m_{0}$$

$$KE \equiv E - m_{0}c^{2} \qquad \beta = \frac{pc}{E}$$

Causality: Causal relationships exist where "event A causes event B", implying that A must occur before B

Nothing - even information can travel faster than *c*.

- worldline: path of an object in (ct,x) diagram
- boost hyperbola: locus of coordinates $(t,x)_{\rm B}$ in all possible inertial frames relative to $(t,x)_A$ at (0,0); defined by $I = (c\Delta t)^2 - (\Delta x)^2$

Minkowski Diagrams

• tilted axes: *ct* and *x* axes plotted in S-frame are tilted and stretched rel to *ct*, *x* axes

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Dynamics $\vec{F} = \frac{d\vec{p}}{dt}$ $W = \int \vec{F} \cdot d\vec{l} = \Delta E$ $m_{\text{inert}} = \gamma m_0 \quad \vec{p} = m_{\text{inert}} \vec{v} \quad E = m_{\text{inert}} c^2$ $E = \sqrt{(pc)^2 + (m_0 c^2)^2}$ $\vec{p} = \gamma m_0 \vec{v}$ $E = \gamma m_0 c^2$ $\beta = \frac{pc}{F}$ $KE \equiv E - m_0 c^2$ **E,p conserved** • (Rest) mass not conserved, can be converted \leftrightarrow energy • **photon**: $m_0=0$, γ equ's useless Causality: Causal relationships exist Nothing – even information – can travel faster than *c*. • worldline: path of an object Minkowski Diagrams in (ct,x) diagram • boost hyperbola: locus of coordinates $(t,x)_{\rm B}$ in all possible inertial frames relative to $(t,x)_A$ at (0,0); defined by $I = (c\Delta t)^2 - (\Delta x)^2$ • tilted axes: *ct* and *x* axes

plotted in S-frame are tilted and stretched rel to *ct*, *x* axes