Transients in a Torsional Oscillator

• Electrical RLC circuits
• Torsional Oscillator
  • Damping
  • Data Analysis
Transients in RLC circuit.

\[ V_R + V_L + V_C = V(t) \]

If \( V(t) = 0 \)

Damping term. Reflects energy dissipation in the resistor

\[ L \frac{d^2 q(t)}{dt^2} + R \frac{dq(t)}{dt} + \frac{q(t)}{C} = 0, \quad \frac{q(t)}{C} = V_0 \]
\[ a = \frac{R}{2L}, \quad b = \sqrt{\left(\frac{R}{2L}\right)^2 - \left(\frac{1}{LC}\right)} \]

\[ b^2 < 0 \quad \text{under-damped solution} \]

\[ b^2 > 0 \quad \text{over-damped solution} \]

\[ b^2 = 0 \quad \text{critically-damped solution} \]
The Torsional Oscillator.

Momentum of Inertia $I$ for disk with radius $R$ and mass $M$:

$$I = \frac{MR^2}{2}$$
Wires 1 and 2 exert the torques $\tau_1$ and $\tau_2$ on the disk of mass $M$.

$$\tau = \tau_1 + \tau_2 = -K_1\theta - K_2\theta = -K\theta$$

$\theta$ : angular deflection of the disk
$r$ : radius of the wires
$L_i$ : length of the wire $i$
$G$ : shear modulus of the wire

$$K_1 = \frac{\pi Gr^4}{2L_1}$$

$$K = K_1 + K_2 = G\frac{\pi}{2}r^4\left(\frac{1}{L_1} + \frac{1}{L_2}\right)$$

$K$ – torsional spring constant

A typical shear modulus for steel is $8.3 \times 10^{10}$ N/m$^2$. 

10/3/2016

Physics 401
The Data Acquisition Setup and Program

Program can accept only 10000 points. If sampling rate is 50Hz – the maximum time of data collection is 200s!

10/3/2016
Measuring of the Torsional Spring constant.

\[ \vec{\tau}_1 + \vec{\tau}_2 = 0 \quad \text{K}\theta = mgR \]

\[ \theta = \frac{gR}{K}m \quad K = \frac{gR}{\text{slope}} \]

g = 9.81\text{m/s}^2
Slope = 51.3\text{rad/kg}
K = 0.00971\text{Nm/rad}
Measuring of the Torsional Spring constant. Possible problems.

Rope is too short!

\[ \tau = R \times F \]

Avoid the over damping of the pendulum motion and any extra sources of friction.
Torsional Pendulum. Scientific application.

Measuring of the electrostatic forces.

\[ \vec{\tau}_1 + \vec{\tau}_2 = 0 \]

\[ K\theta = FL; \]

Where \( F \) is electrostatic force and \( L \) is the length of the balance beam.

Charles-Augustin de Coulomb
1736-1806

Coulomb's law

\[ F = k_e \frac{q_1 q_2}{r^2}; \quad k_e = \frac{1}{4\pi\epsilon_0} \]

Coulomb's torsion balance.
Courtesy of Wikipedia
Measuring of the gravitational forces.

$$\vec{t}_1 + \vec{t}_2 = 0$$

$$K\theta = FL;$$

Where $F$ is gravitational force and $L$ is the length of the balance beam.

Cavendish's result

$$F = \frac{GmM}{r^2}$$

Currently accepted value

$$G = 6.74 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2},$$

$$6.67428 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2}.$$
The Torsional Oscillator. “No damping”.

\[ \tau = \tau_1 + \tau_2 = -K_1 \theta - K_2 \theta = -K \theta \]

\[
K_1 = \frac{\pi G r^4}{2 L_1}; \quad K = K_1 + K_2 = \frac{\pi G r^4}{2} \left( \frac{1}{L_1} + \frac{1}{L_2} \right)
\]

Solution: \( \theta = \theta_0 \sin(\omega_0 t + \phi) \) with \( \omega_0 = \sqrt{\frac{K}{I}} \)

If there is no dissipation:
\[
I \frac{d^2 \theta}{dt^2} = -K \theta
\]

If we know \( I \) we can calculate \( K \)

From time trace \( \theta(t) \) we can find \( \omega_0 \) it can be done by measuring period but better (and faster!) to perform the nonlinear fitting.
The Torsional Oscillator. “No damping”. Fitting

“No damping” is not realistic situation fitting should be done to SineDamp function

\[ y = y_0 + A \exp \left( \frac{-x}{t_0} \right) \sin \left( \pi \frac{x-x_c}{w} \right) \]

\[ \omega_0 = \frac{\pi}{w} \]

\[ \frac{\omega_0}{2l} \approx 1.12 \times 10^{-2} \text{Nm/\text{rad}} \]
The Torsional Oscillator. “No damping”. Fitting.

\[ \omega_0 = \frac{\pi}{w} \quad f_0 = \frac{1}{2w} \]

From “SineDamp fitting \( f_0 = 0.497 \)Hz

Resonance frequency can be also found by applying FFT on the raw data.
Viscous (magnetic) damping.

Under damped case

The solutions are exactly the same as in case of RLC circuit (three solutions)

$$I \frac{d^2 \theta}{dt^2} + K \theta + R \frac{d\theta}{dt} = 0$$

Damping term

Model SineDamp
Equation $$y = y_0 + A \exp(-x/t_0) \sin(\pi(x-x_c)/w)$$
Reduced Chi-Sqr 2.34732E-5
Adj. R-Square 0.99926

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Physics 401
Viscous damping. Logarithmic decrement.

\[ I \frac{d^2 \theta}{dt^2} + K\theta + R \frac{d\theta}{dt} = 0 \]

\[ \delta = \ln\left(\frac{\theta_{n+1}}{\theta_n}\right); \]

For viscous damping \( \delta = \frac{T}{t_0} \);

where

\( T \) – period and \( t_0 \) – characteristic decay time*

from SineDamp fitting function

\( T=2w \) and \( \delta = \frac{2w}{t_0} \)

\( \delta=0.640 \pm 0.002 \)

From SineDamp fitting exponential decay term is

\[ \exp\left(\frac{-t}{t_0}\right) \]

*\( a=\frac{1}{t_0} \) (write up)
We can find the amplitudes of the wave using Peak Analyzer.

Peaks coordinates are saved in the worksheet and can be used for analysis.

$$\ln\left(\frac{A_{n+1}}{A_n}\right)$$

$$\delta = 0.63 \pm 0.02$$
1. Fitting to damp exponential decay function. Outcome: resonance frequency and decrement coefficient.


3. Using Origin Peak Analyzer we can find amplitudes and positions of the damped sine wave maximum end then plot the envelope.

4. You can directly obtain the envelope of the damped sine wave by using Origin (optional).
Coulomb damping. Theory

\[ I \ddot{\theta} + K \theta + \tau_{\text{Coulomb}} = 0 \]

\[ \tau_{\text{Coulomb}} = C \frac{\dot{\theta}}{\dot{\theta}} \]

\[ \theta(t) = +\frac{C}{K} + (\theta_0 - (4n - 1)\frac{C}{K}) \cos(\omega t) \]

\( (n - \frac{1}{2})T \leq t \leq nT \quad n = 1, 2, \ldots \)

\[ \theta(t) = +\frac{C}{K} + (\theta_0 - (4n - 3)\frac{C}{K}) \cos(\omega t) \]

\( (n - 1)T \leq t \leq (n - \frac{1}{2})T \quad n = 1, 2, \ldots \)

Amplitude decreases by \( 4C/K \) per period linearly!
Coulomb damping. Experiment

Amplitude decreases by 4C/K per period linearly!
Coulomb damping. Experiment

\[ |\tau_{\text{Coulomb}}| = C \]

\[ K\theta \sim \theta \]

if \( K\theta \leq C \)

pendulum stops

\[ \theta_{\text{off}} \]
Turbulent damping. Theory

\[ I \ddot{\theta} + K \dot{\theta} + \tau_{\text{Turb}} = 0 \]

\[ \tau_{\text{turb}} = C_t \text{sgn}(\dot{\theta}) |\dot{\theta}|^n \]

In case of \( n=1 \) → viscous damping

Logarithmic decrement in case of turbulent damping is no more constant and in case \( n=2 \) can be calculated as

\[ \delta = \frac{8C_3}{3l} \dot{\theta}_0 \]

Expected result – decrement decreases with decreasing of the amplitude
Turbulent damping. Experiment

Analyzing the envelope of the damped oscillating time record we can calculate the log decrement factor.
Turbulent damping. Experiment.

\[ \theta \text{ (rad)} \]

\[ \delta \text{ (log decrecment)} \]

\[ \Theta \text{ (rad)} \]
Data analysis. Finding the peaks.

Raw data.
Our goal: find the positions and amplitudes of the peaks

$X_i, Y_i$

1st Technique: using “FindPeaks” option
Local Maximum works well for not noisy oscillating dependencies.
Data analysis. Finding the peaks.

New plot + labels as a result of finding the peaks

“Peaks” data can be found in a Worksheet and using this data you can plot the dependence of amplitude on time

“Positive” peaks

“Negative” peaks
Data analysis. Finding the peaks.

Original Data

Envelope

\[ \theta (\text{rad}) \]

\[ \theta_n (\text{rad}) \]

\[ \text{time (s)} \]
Data analysis. Finding the peaks.

2nd Technique: using “Envelope” option

Origin will create the worksheet with interpolated (defined for the same x’s as the raw data) “envelope” data
Data analysis. Finding the peaks.
Data analysis. FFT.

All these quasi periodic data can be analyzed using Fast Fourier Transform

Our goal: find the resonance frequency of the pendulum

Origin window
Data analysis. FFT.

The results of FFT you can find in the same Workbook which contains the raw data.

Click on corresponding graph and it will appear in separate window.

Magnitude vs. frequency plot.
Data analysis. FFT.

Spectrum better to present in log-log scale
Appendix. Some comments on oil drop experiment error analysis.

Result of measurement \( X_{\text{meas}} \) = Correct value \( X_{\text{true}} \) + Systematic error \( e_s \) + Random error \( e_r \)
Appendix. Some comments on oil drop experiment error analysis.

Systematic error

\[ X_{\text{meas}} = X_{\text{true}} + e_s + e_r \]

\[ Q = F \cdot S \cdot T = \left( \frac{1}{f_c^{3/2}} \right) \frac{9 \pi d}{V} \sqrt{\frac{2 \eta^3 x^3}{g \rho}} \cdot \frac{1}{\sqrt{t_g}} \left( \frac{1}{t_g} + \frac{1}{t_{\text{rise}}} \right) \]

\[
F = \frac{1}{f_c^{3/2}} \approx 1 - \left( \frac{t_g}{\tau_g} \right)^{1/2} \\
S = \frac{9 \pi d}{V} \sqrt{\frac{2 \eta^3 x^3}{g \rho}} \\
T = \frac{1}{\sqrt{t_g}} \left( \frac{1}{t_g} + \frac{1}{t_{\text{rise}}} \right) \\
\]

\[
\Delta Q = \sqrt{\left( \frac{dQ}{dF} \right)^2 (\Delta F)^2 + \left( \frac{dQ}{dS} \right)^2 (\Delta S)^2 + \left( \frac{dQ}{dT} \right)^2 (\Delta T)^2} \approx \sqrt{\left( \frac{dQ}{dS} \right)^2 (\Delta S)^2 + \left( \frac{dQ}{dT} \right)^2 (\Delta T)^2} \\
= \sqrt{(FT)^2 (\Delta S)^2 + (FS)^2 (\Delta T)^2} = Q \sqrt{\left( \frac{\Delta S}{S} \right)^2 + \left( \frac{\Delta T}{T} \right)^2} 
\]
Appendix. Some comments on oil drop experiment error analysis.

Systematic error

\[ X_{\text{meas}} = X_{\text{true}} + e_S + e_r \]

\[ \Delta Q \approx Q \sqrt{ \left( \frac{\Delta S}{S} \right)^2 + \left( \frac{\Delta T}{T} \right)^2 } \]

\[ \frac{\Delta S}{S} = \sqrt{ \left( \frac{\Delta d}{d} \right)^2 + \left( \frac{\Delta V}{V} \right)^2 + \left( \frac{3}{2} \frac{\Delta x}{x} \right)^2 + \left( \frac{3}{2} \frac{\Delta \eta}{\eta} \right)^2 + \left( \frac{1}{2} \frac{\Delta \rho}{\rho} \right)^2 + \left( \frac{1}{2} \frac{\Delta g}{g} \right)^2 } \approx \sqrt{ \left( \frac{\Delta d}{d} \right)^2 + \left( \frac{3}{2} \frac{\Delta x}{x} \right)^2 } \]

\[ \Delta T = \sqrt{ \left( \frac{3}{2} \frac{1}{t_g^{5/2}} + \frac{1}{2} \frac{1}{t_g^{3/2}} \frac{1}{t_{\text{rise}}} \right)^2 \Delta t_g^2 + \left( \frac{1}{t_g^{1/2}} \frac{1}{t_{\text{rise}}} \right)^2 \Delta t_{\text{rise}}^2 } \]
Appendix. Some comments on oil drop experiment error analysis.

Result of measurement: $X_{\text{meas}} = X_{\text{true}} + e_s + e_r$

Correct value

Systematic error

Random error

Mean of $\{x_i\}$

$\mu = \frac{1}{N} \sum_{i=0}^{N-1} x_i$

Standard deviation of $\{x_i\}$

$\sigma^2 = \frac{1}{N-1} \sum_{i=0}^{N-1} (x_i - \mu)^2$

Standard deviation of mean

$\sigma_X = \frac{\sigma}{\sqrt{N}}$