

AC Measurement of Magnetic Susceptibility

Episode 1 – Ferromagnetism and Hysteresis

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Physics 401

Spring 2020



Key Goals of this Lab

Combine the tools and techniques we've learned to characterize **magnetic properties of materials**

- Magnetization and (complex) **magnetic susceptibility**
- Ferromagnetism and **hysteresis**
- Thermal effects and the **Curie temperature**

This is the **first week** of a **three-week** lab
Counts as your **final exam**



Outline

Combine the tools and techniques we've learned to characterize **magnetic properties of materials**

- Ferromagnetism
- Measuring magnetic properties of materials
- Lab setup and measurements
- Analysis notes

This is the **first week** of a **three-week** lab

Next week: Temperature dependence of magnetic properties



Reminder: Magnetic Response of Materials

Two things are often called the “magnetic field”: **B** and **H**

B

Magnetic induction
Magnetic flux density

Determines forces **on**
moving *free* charges
via **Lorentz force law**:

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$

M

Magnetization
Magnetic polarization

Field created only **by**
moving *bound* charges,
i.e. magnetic response
of the medium

H

Magnetic field intensity
Magnetizing field

Field created only **by**
moving *free* charges.

In vacuum, $B = \mu_0 H$.

Reminder: Magnetic Response of Materials

$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$

Since many materials have approximately linear response, we define the **magnetic susceptibility**:

$$\vec{M} = \chi \vec{H}$$

$$\vec{B} = \mu_0 (1 + \chi) \vec{H} = \mu_0 \mu_r \vec{H} = \mu \vec{H}$$

$$\mu = \mu_0 \mu_r = \frac{\partial B}{\partial H}$$

$$\mu_r = 1 + \chi = \frac{1}{\mu_0} \frac{\partial B}{\partial H}$$

In general, susceptibility... :

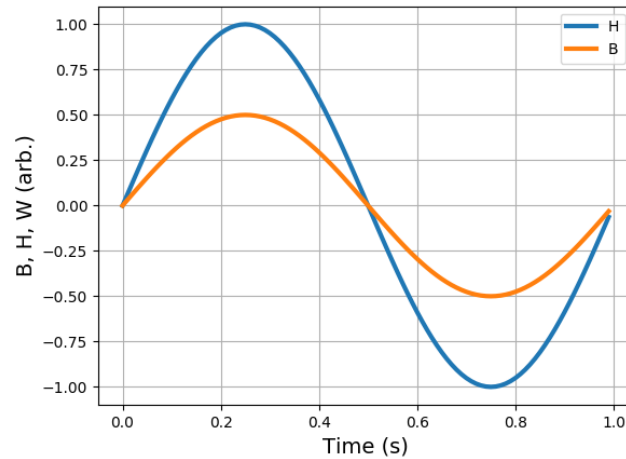
1. ... is a function $\chi(H)$ (**nonlinearity**)
2. ... is a 2nd-rank **tensor** (*matrix*) (scalar for **isotropic** materials)
3. ... may be **complex** (*phase lag, loss*) $\chi = \chi' - i\chi''$
4. ... may have history dependence (**hysteresis**) not captured by this expression (*see below!*)

Aside: Loss from Complex Permeability

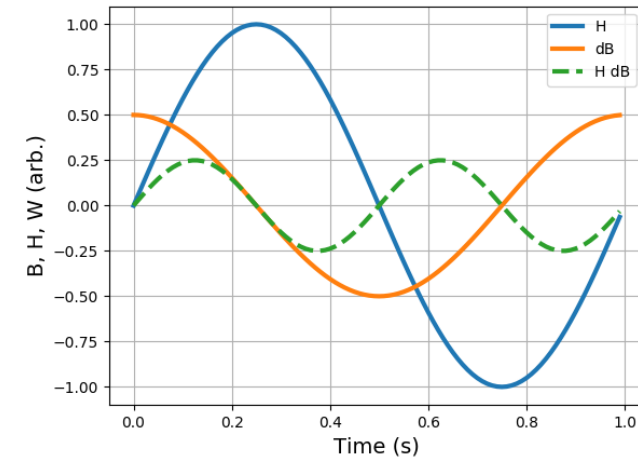
$$\vec{B} = \mu_0(\vec{H} + \vec{M}) = (\mu' - i\mu'')\vec{H}$$

Why is a material with complex permeability ($\mu'' \neq 0$) lossy?

Real μ :

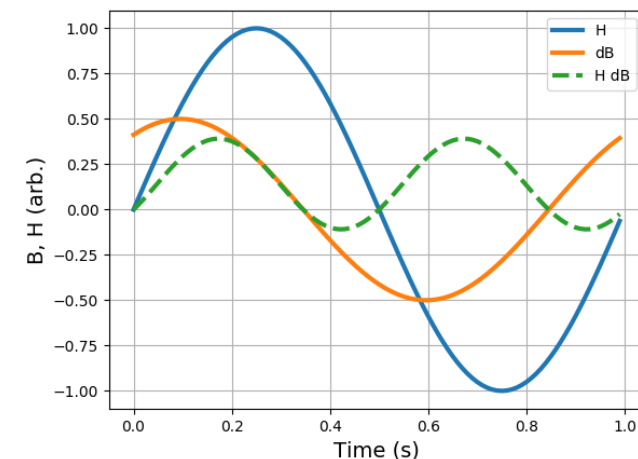
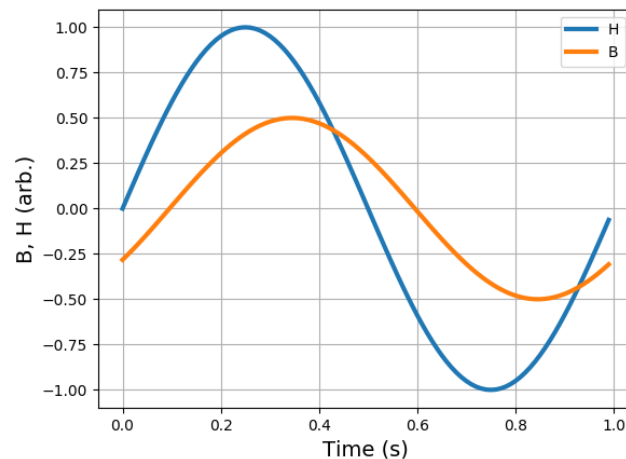


In analogy with
 $dW = F dx$,
we have
 $dW = H dB$



Zero
integral

Complex μ :



Nonzero
integral!



Reminder: Magnetic Response of Materials

$$\vec{B} = \mu_0(\vec{H} + \vec{M}) = \mu_0(1 + \chi)\vec{H} = \mu_0\mu_r\vec{H}$$

We classify materials into three major categories:

Diamagnetic	$\chi < 0$	$\mu_r < 1$	Weakly repelled
Paramagnetic	$\chi > 0$	$\mu_r > 1$	Weakly attracted
Ferromagnetic	$\chi \gg 0$	$\mu_r \gg 1$	Strongly attracted

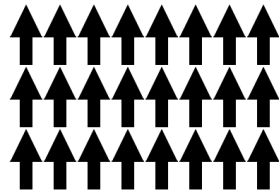
More next time on these... for now, **ferromagnetism!**

What is Ferromagnetism?

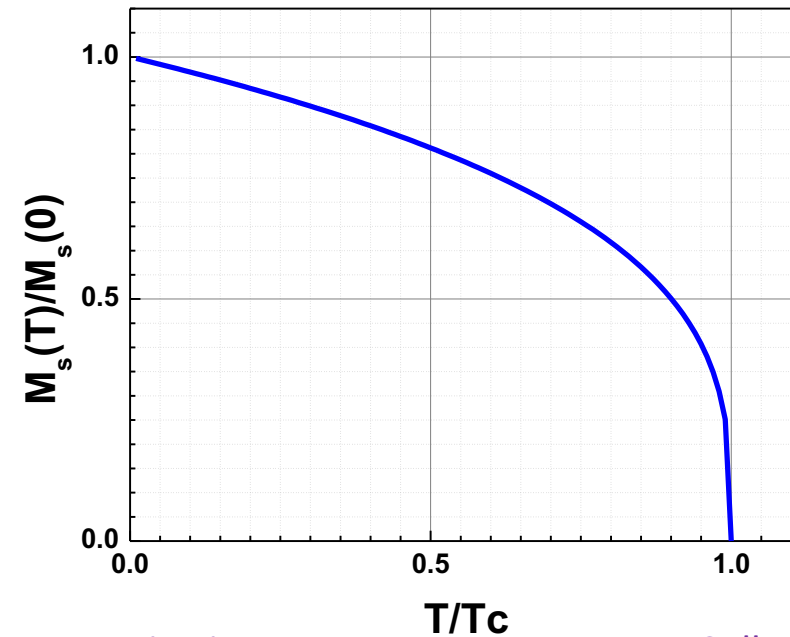
Some materials experience **spontaneous magnetic ordering** in the absence of an applied field.

Happens when aligning interactions among neighboring atomic/molecular dipoles (typically from Pauli exclusion, **exchange interactions**) exceed magnetic dipole anti-alignment forces and thermal randomization.

This ordering occurs only below some transition temperature, the **Curie temperature (T_c)**.



Some materials exhibit spontaneous anti-alignment of neighbors: *antiferromagnetism, ferrimagnetism*.



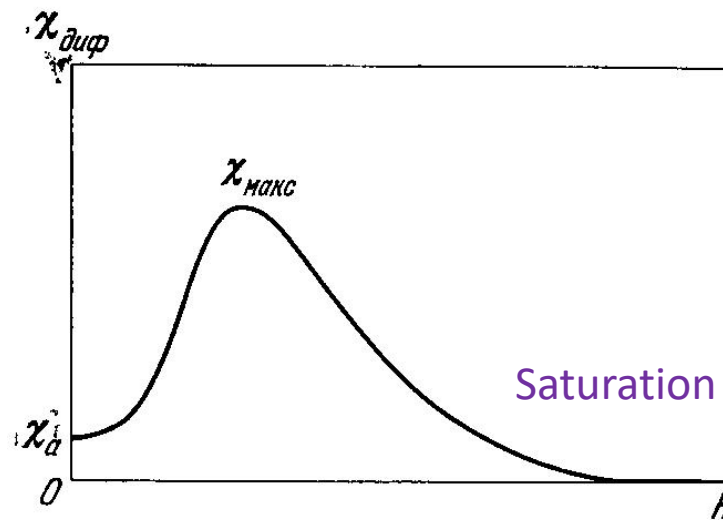
Typical spontaneous magnetization versus temperature

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Ferromagnetic Materials

Material	Curie temp. (K)
Co	1388
Fe	1043
Fe ₂ O ₃ *	948
FeOFe ₂ O ₃ *	858
NiOFe ₂ O ₃ *	858
MgOFe ₂ O ₃ *	713
MnBi	630
Ni	627
MnSb	587
MnOFe ₂ O ₃ *	573
Y ₃ Fe ₅ O ₁₂ *	560
CrO ₂	386
MnAs	318
Gd	292



“Stoletov” curve

$$\chi = \frac{dM}{dH}$$



Aleksandr Stoletov
(1839 – 1896)

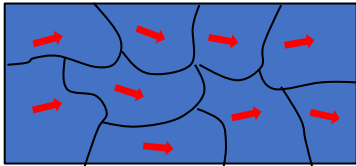
* = Ferrimagnetic (local anti-alignment, but unbalanced – acts like a ferromagnet)

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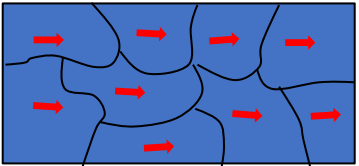


Domains and Hysteresis

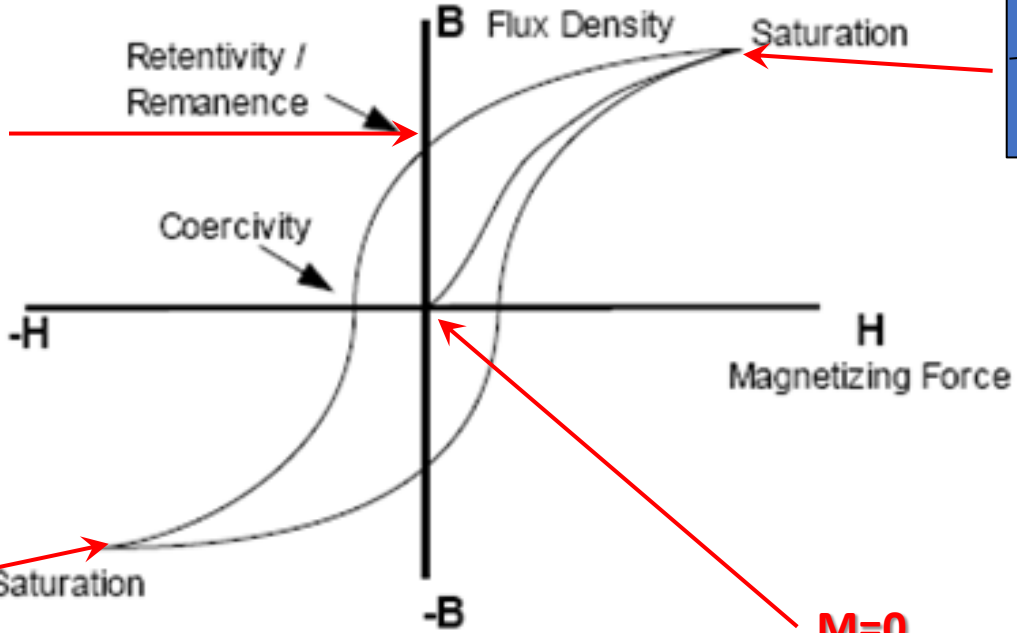
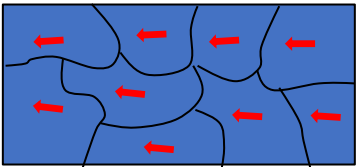
3. Internal fields retain partial alignment without external field



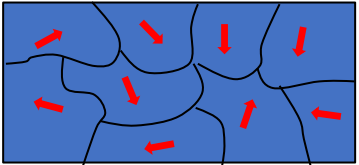
2. Strong external field maximally aligns domains



4. Strong external field maximally aligns domains



$M=0$

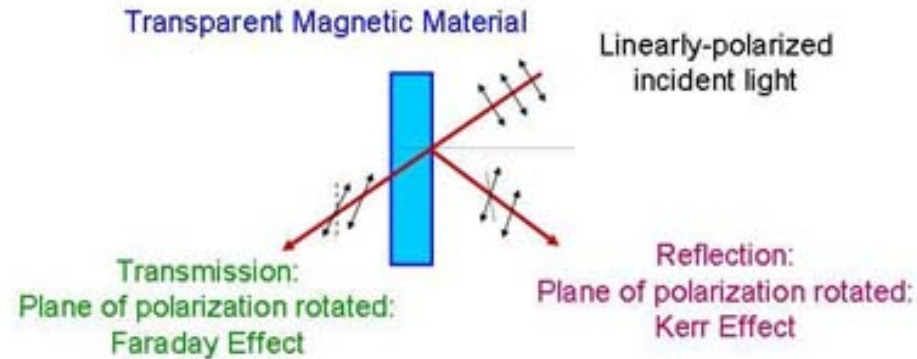


1. Initially, dipoles are ordered within a domain, but domains are random

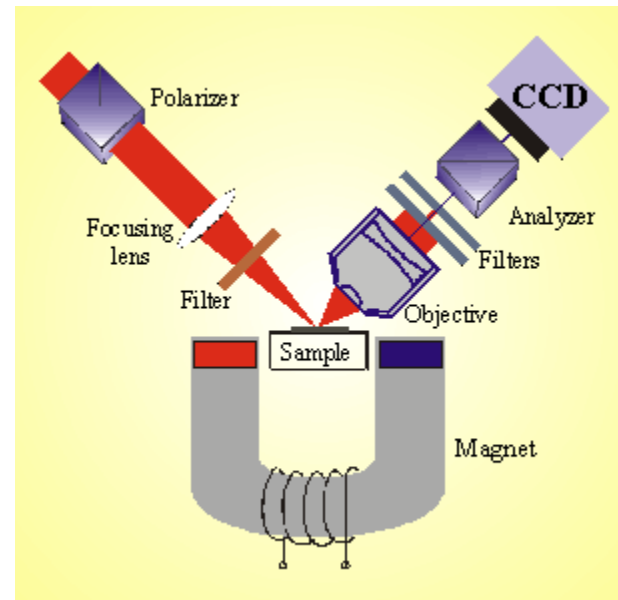


Visualizing Magnetic Domains

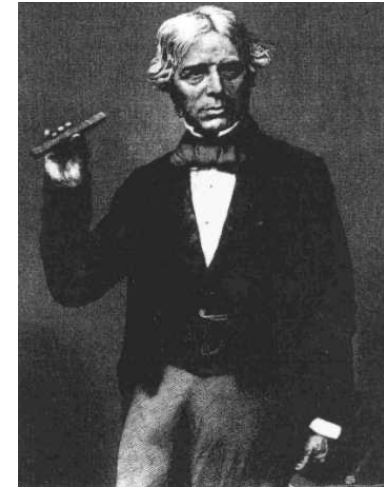
Faraday Rotation: Rotation of polarized light passing through a transparent magnetic material



Magneto-Optic Kerr Effect (MOKE): Rotation of polarized light reflected from a magnetic material



Typical Kerr microscope
Radboud Univ., Nijmegen, the
Netherlands



Michael Faraday
1791 – 1867

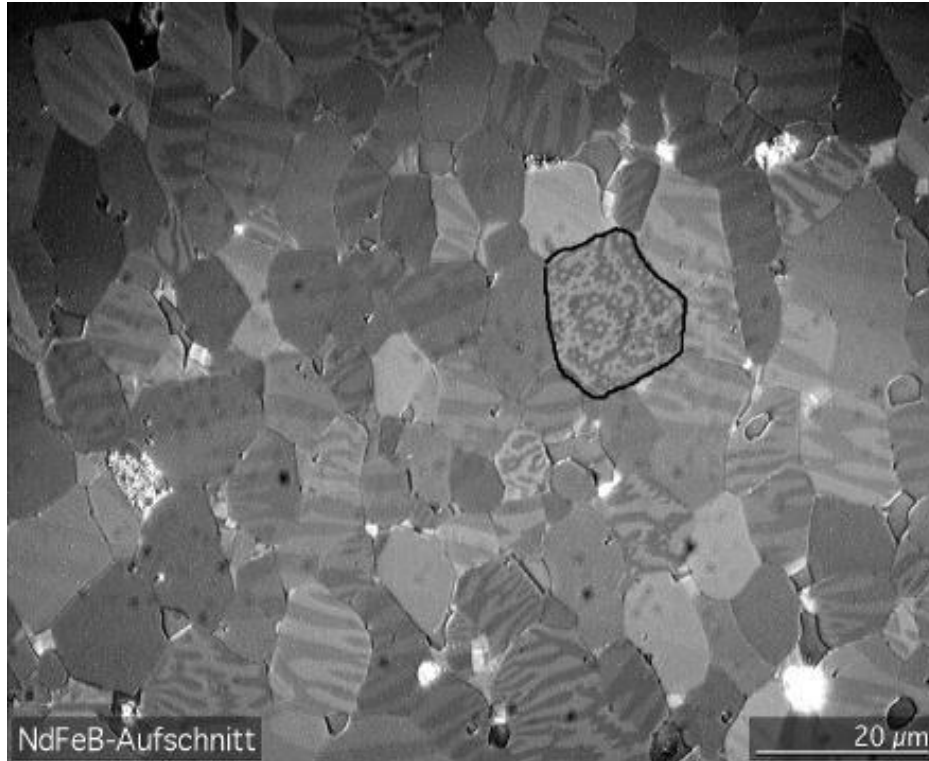


John Kerr
1824 – 1907

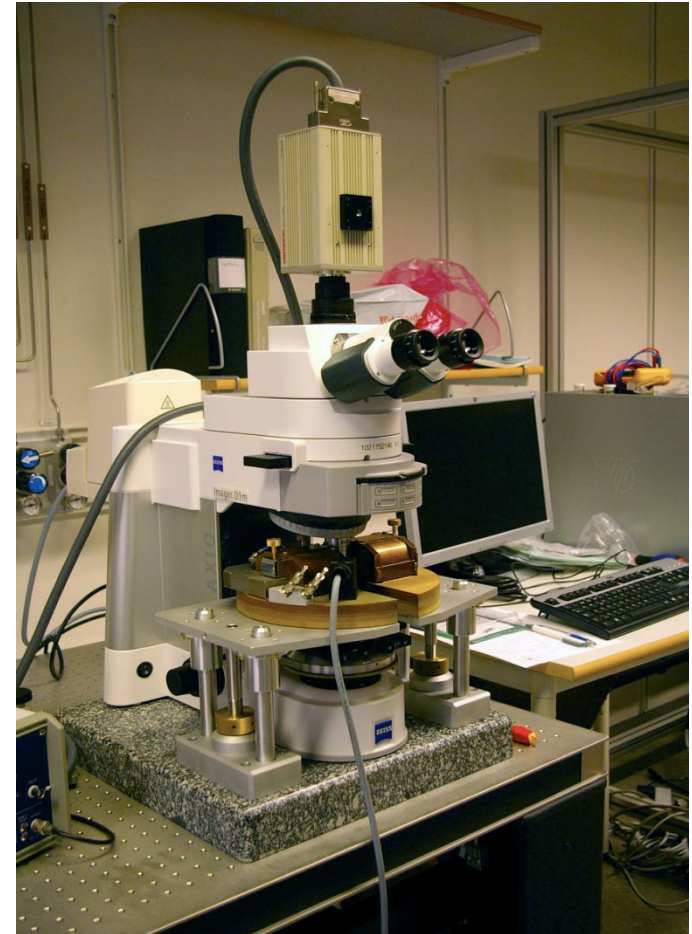
E.V. Colla



Visualizing Magnetic Domains



Kerr microscope image of a NdFeB sample, showing domains



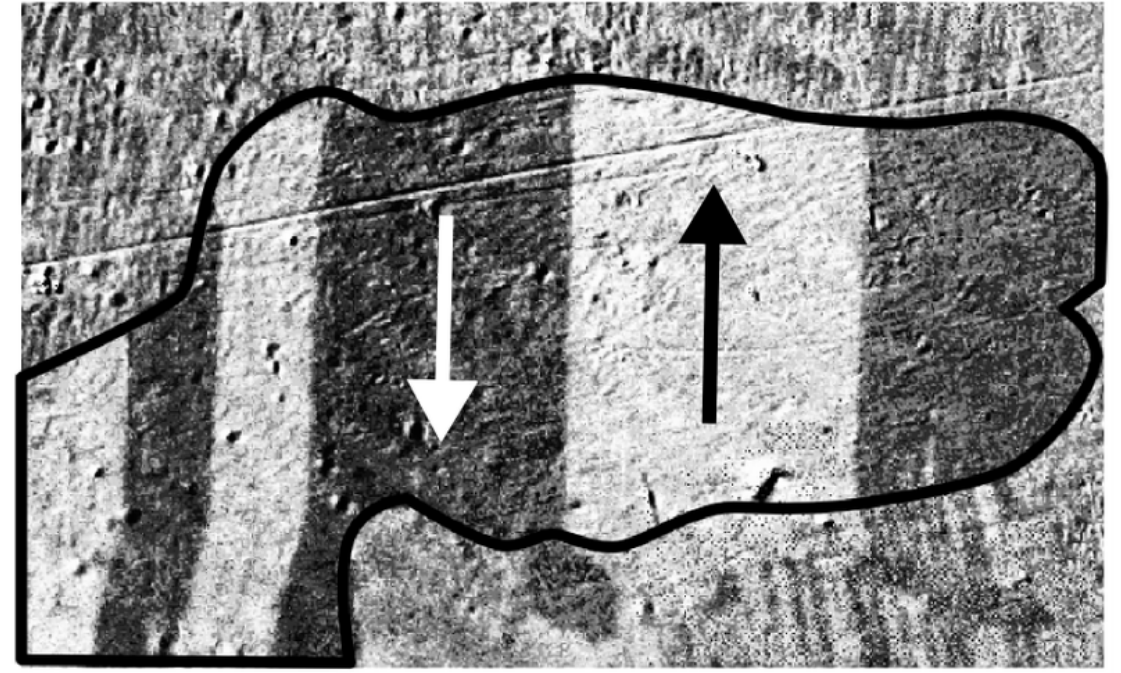
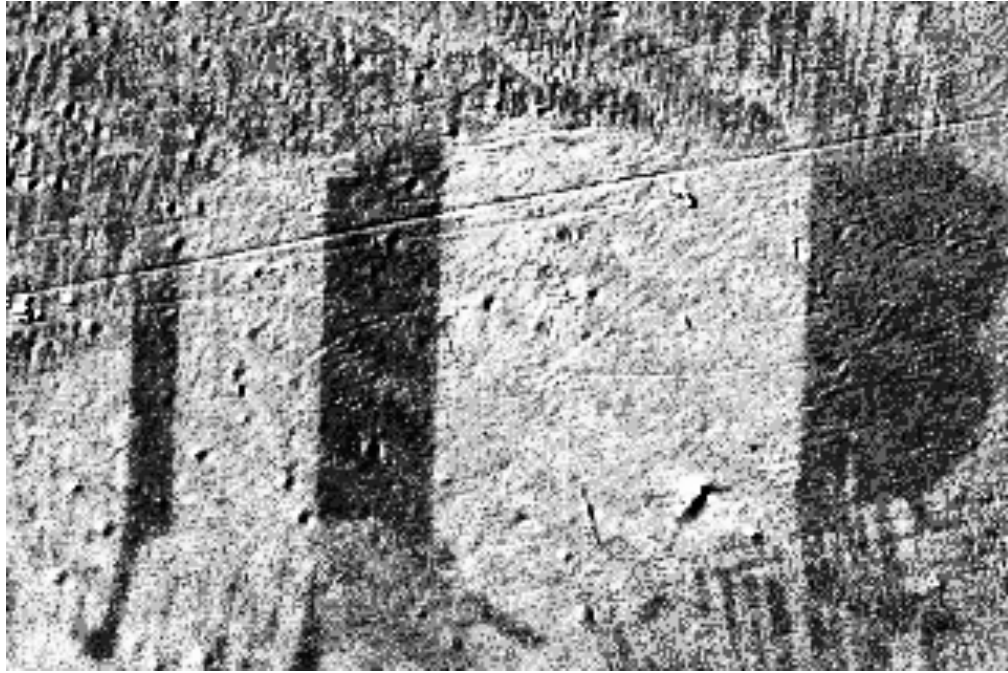
Kerr microscope
University of Uppsala, Sweden

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Wikipedia

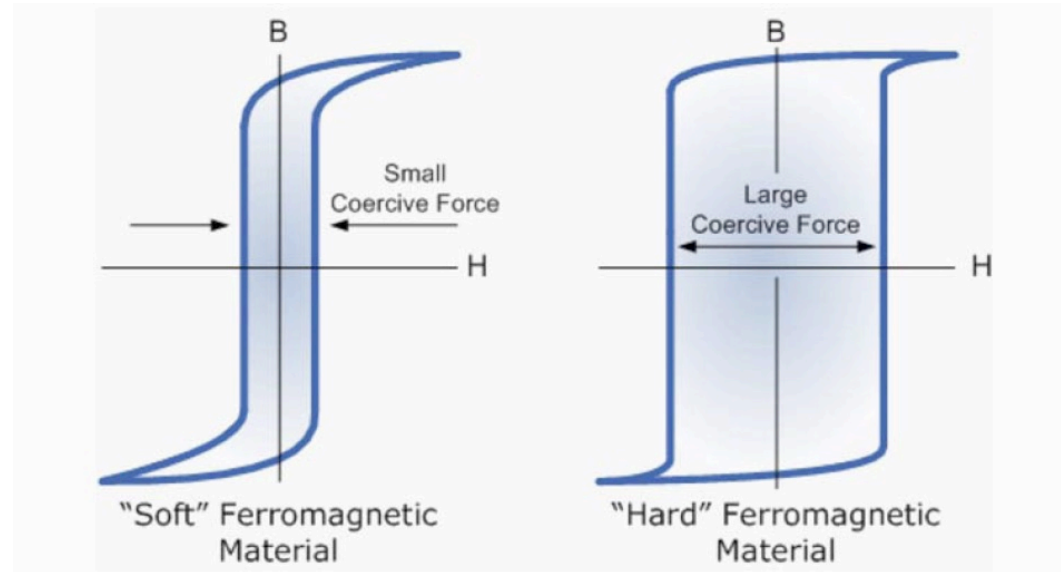


Visualizing Magnetic Domains



Domain walls in a grain of silicon steel, moving as the external magnetic field is increased

Hysteresis and Coercivity



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Hysteresis necessarily involves energy losses from re-magnetization.
If the domains are “sticky”, we need to do work to overcome that.

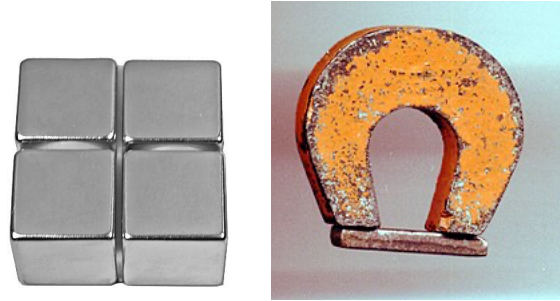
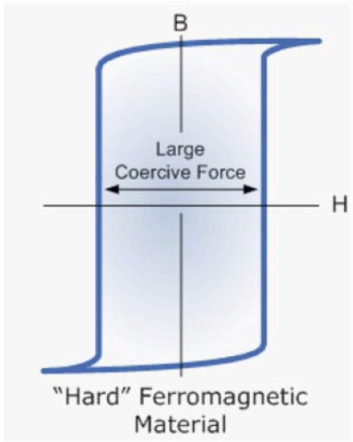
$$W = V \int \vec{H} \cdot d\vec{B}$$

For uniform fields over volume V
(analogous to $dW = F dx$)

$$W_{loop} = V \oint \vec{H} \cdot d\vec{B} = V * A_{loop}$$

Applications of Magnetic Materials

“Hard” Materials

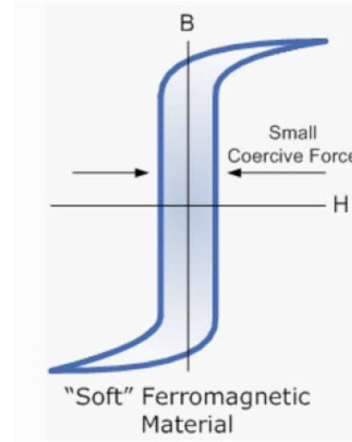


Permanent magnets

Data storage media



“Soft” Materials

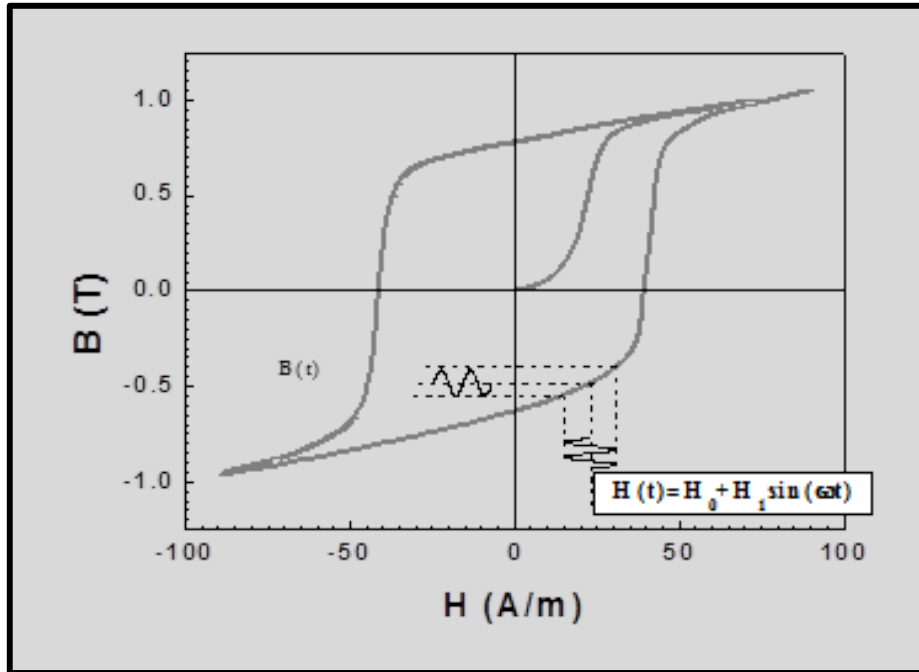


Cores for inductors, electromagnets, power transformers...

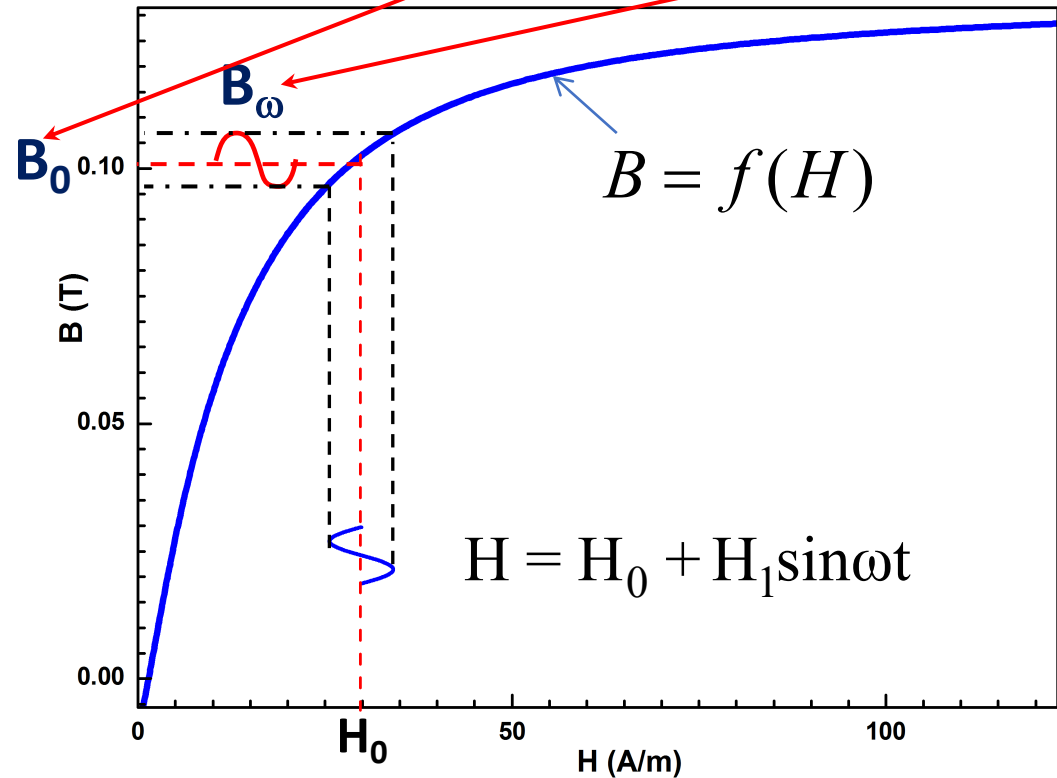


AC Measurement of Magnetic Permeability

Apply a small modulation to H to measure the derivative of the B-H hysteresis loop



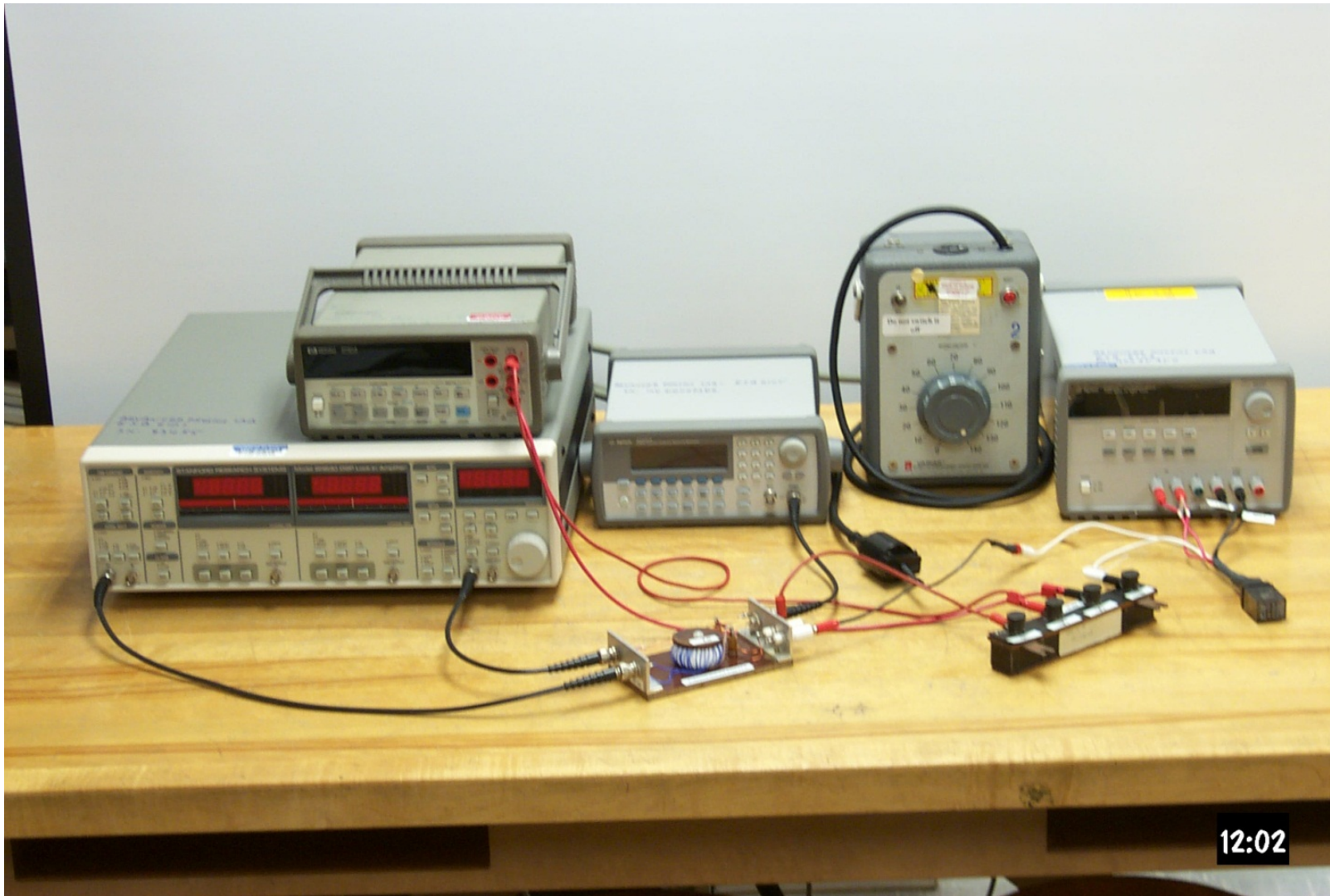
$$B = f(H_0 + H_1 \sin \omega t) = f(H_0) + \frac{df}{dH} H_1 \sin \omega t + \dots$$



$$\mu(H_0, \omega) = \mu_0 (1 + \chi(H_0, \omega)) = \left. \frac{dB}{dH} \right|_{H_0, \omega}$$



Setup #1: Mapping the Hysteresis Loops



Setup #1: Mapping the Hysteresis Loops

$$H_0 + H_1 \sin \omega t$$

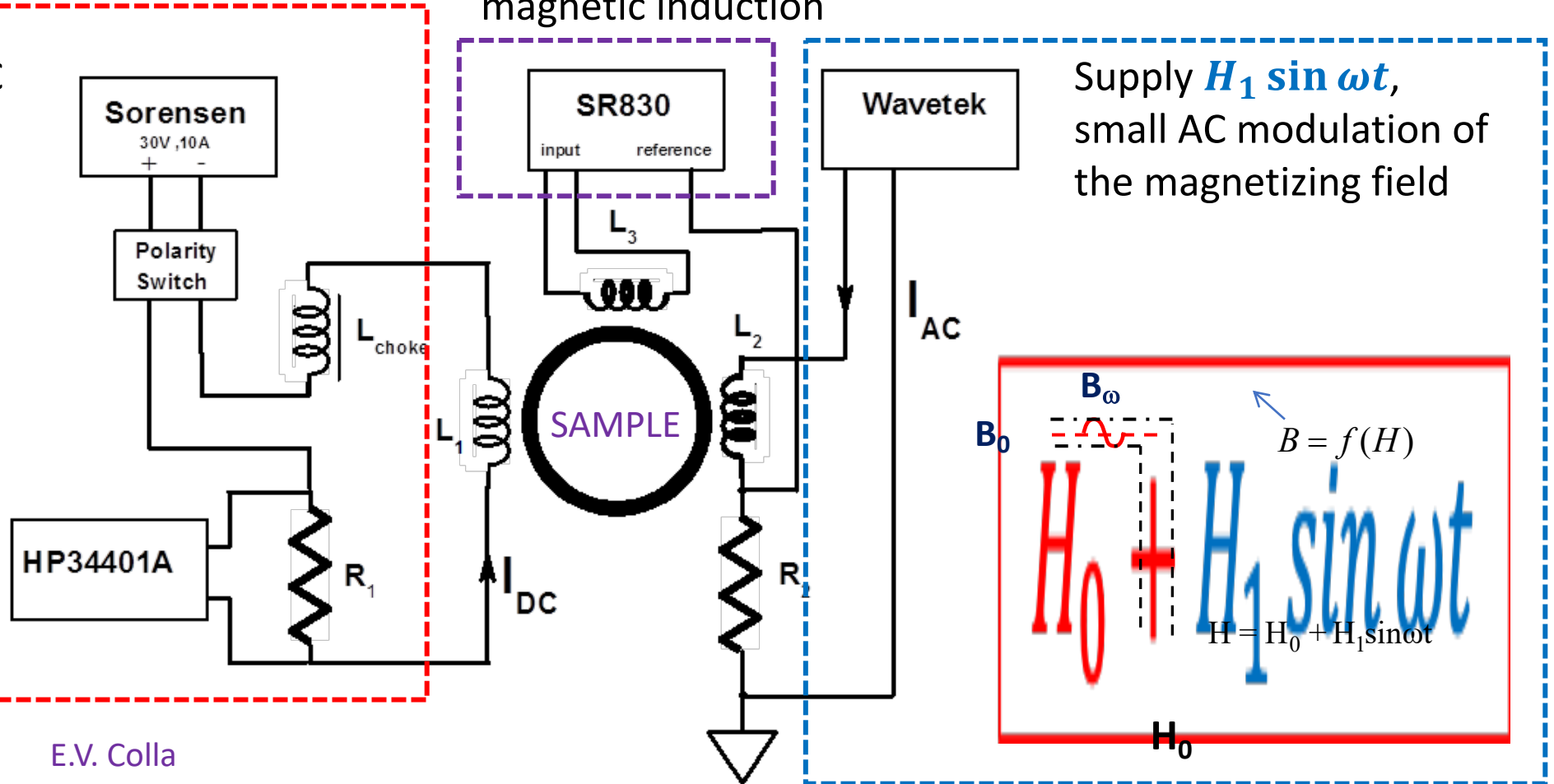
Measure B_ω , resulting modulation of the magnetic induction

Supply $H_1 \sin \omega t$, small AC modulation of the magnetizing field

Supply H_0 , DC magnetizing field

$$H = \frac{N_p I_p}{2\pi r}$$

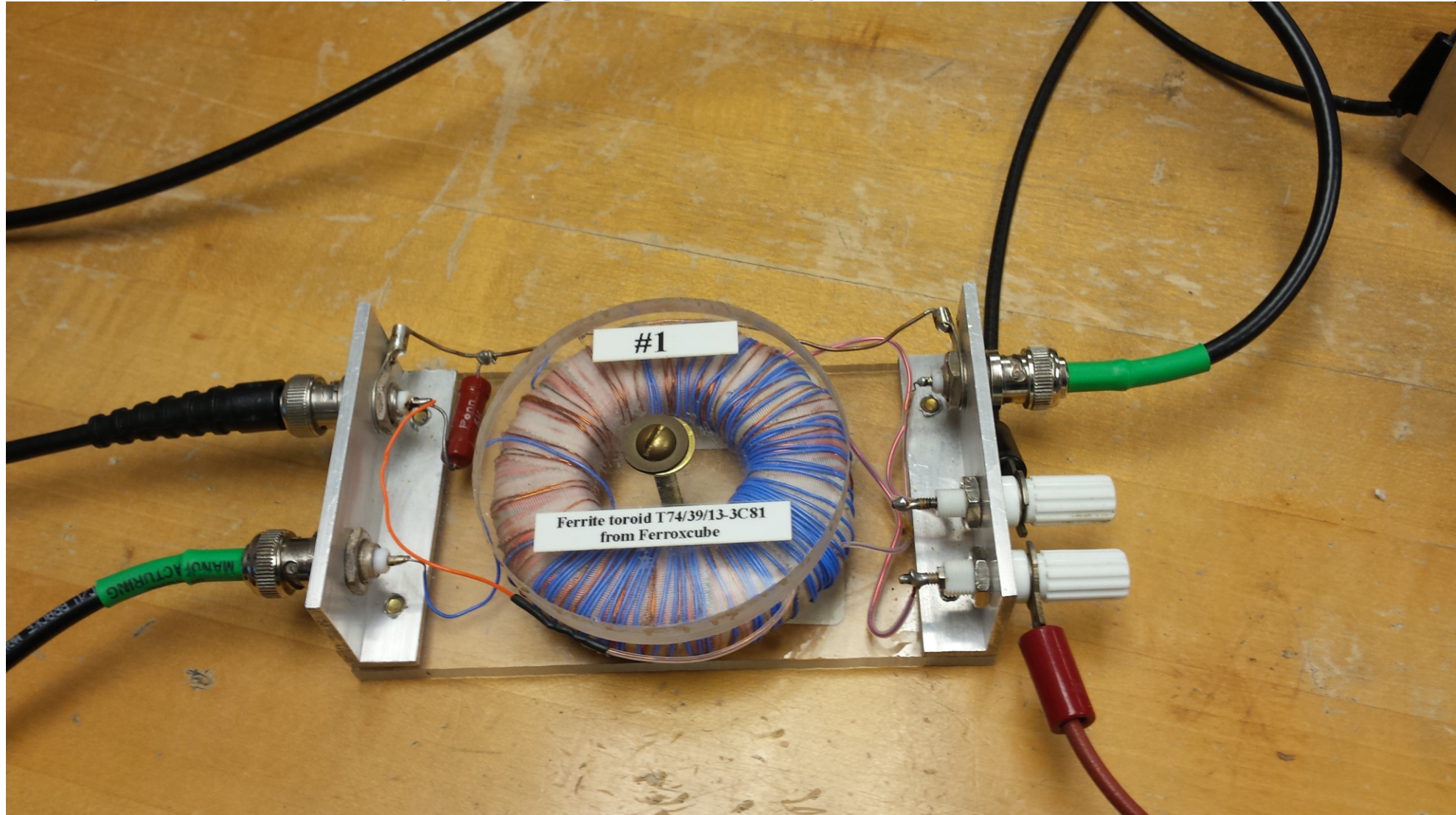
DMM to monitor H_0



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Setup #1: Mapping the Hysteresis Loops

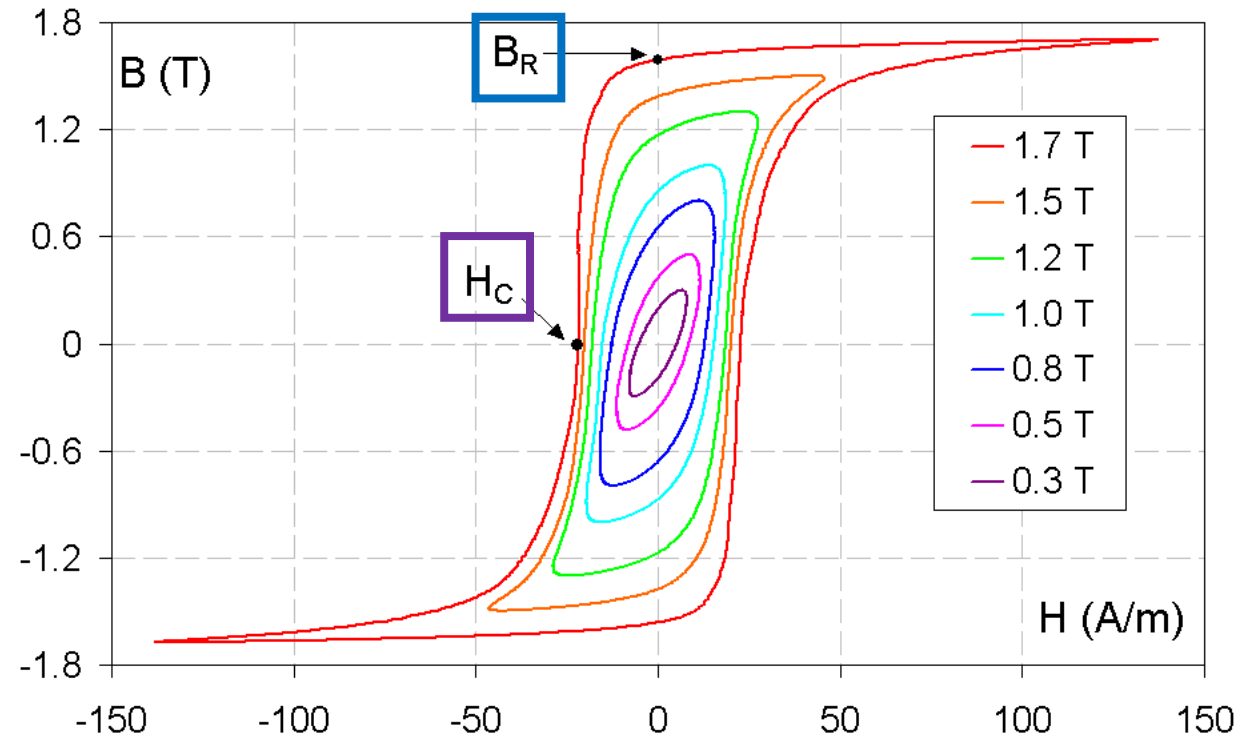


More on Hysteresis Loops

There isn't just one hysteresis curve!

Key values for saturation curve:

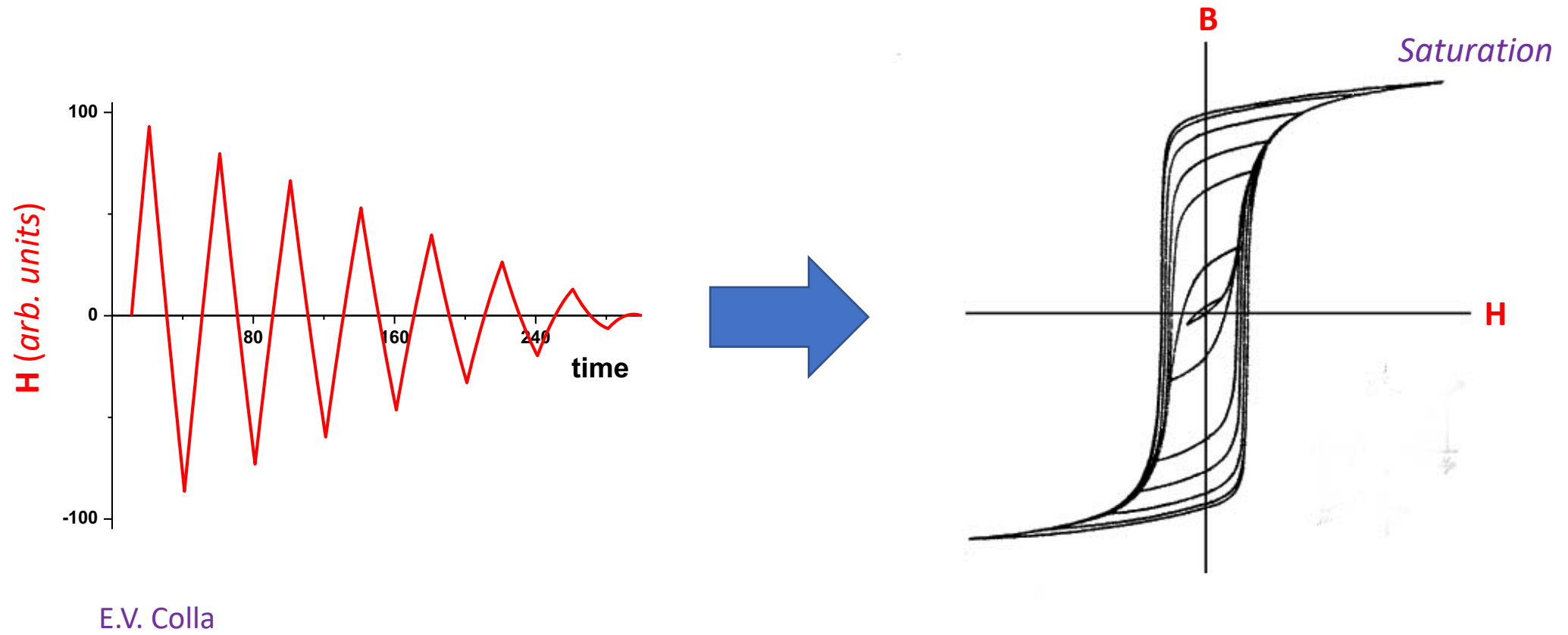
- B_R is the **saturation remanence**: the maximum residual magnetism at zero applied field
- H_C is the **coercivity**: the applied field required to demagnetize a sample that has been saturated.



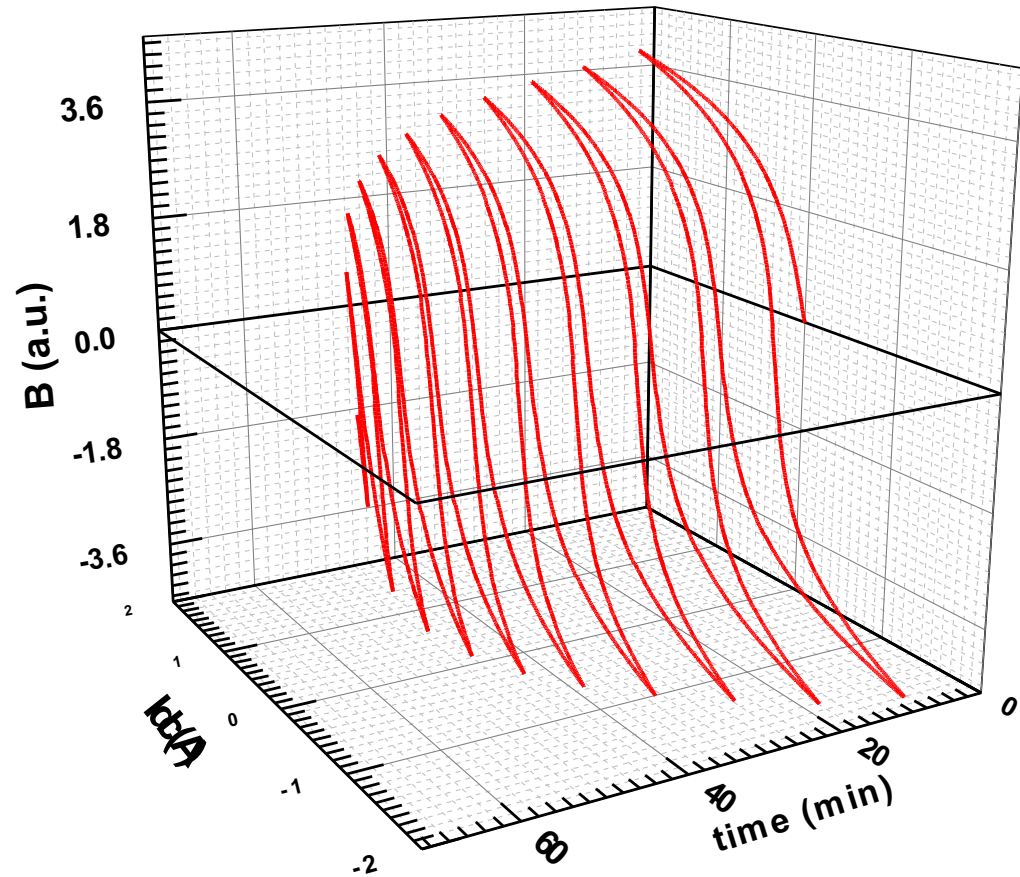
A family of AC hysteresis loops for grain-oriented electrical steel
([Wikipedia:Remanence](#))

Demagnetizing the Core

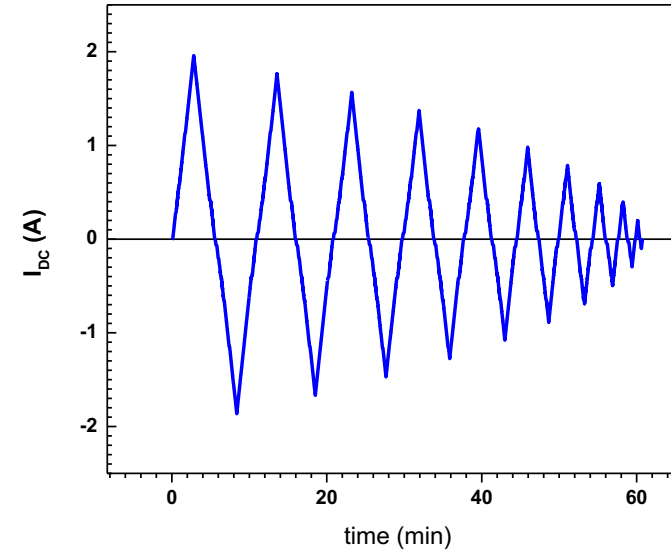
Clear the sample's unknown residual field (**remanence**) by imposing a slowly-decaying AC H-field



Demagnetizing the Core

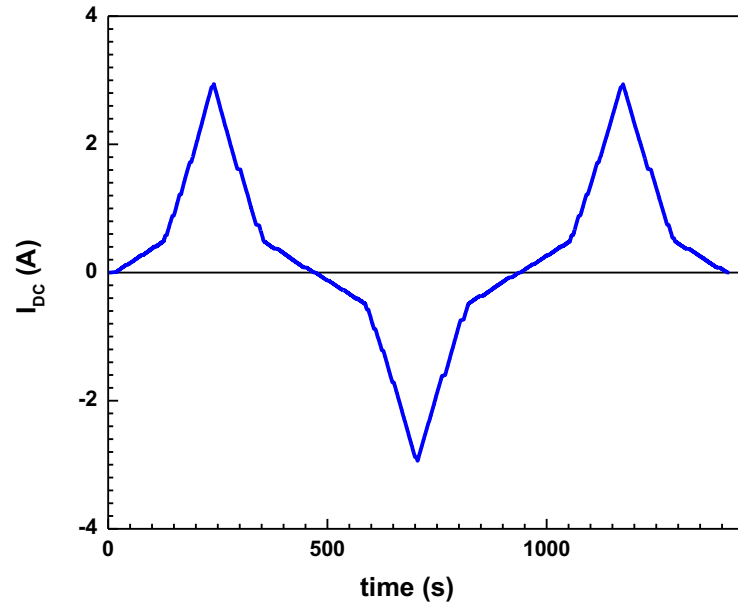


Example: Demagnetization of 4C65 toroid from Ferroxcube

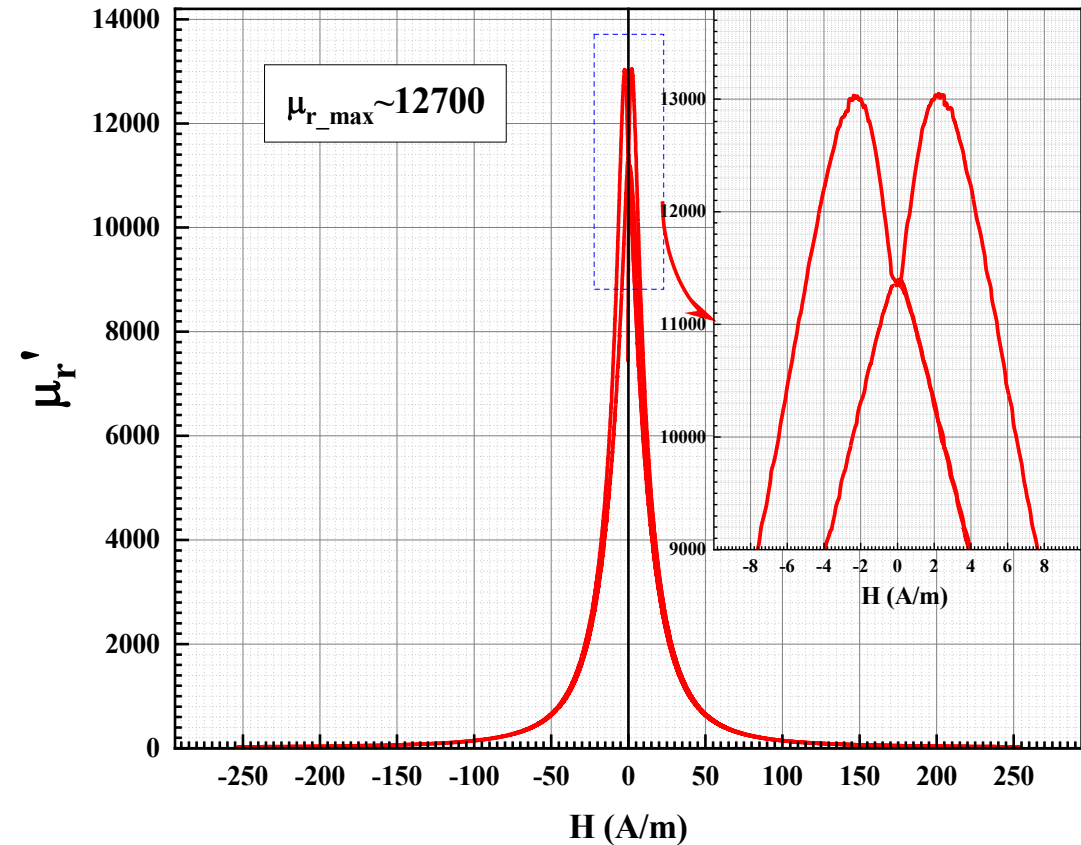


Data and plots by E.V. Colla

Measuring the Magnetic Permeability



Example: DC current profile and magnetic permeability of Magnetics ZW44715TC



Data and plots by E.V. Colla

From Permeability to Hysteresis Loop

ECE Storeroom unknown material sample #5

How to get a good data set for an unknown sample?

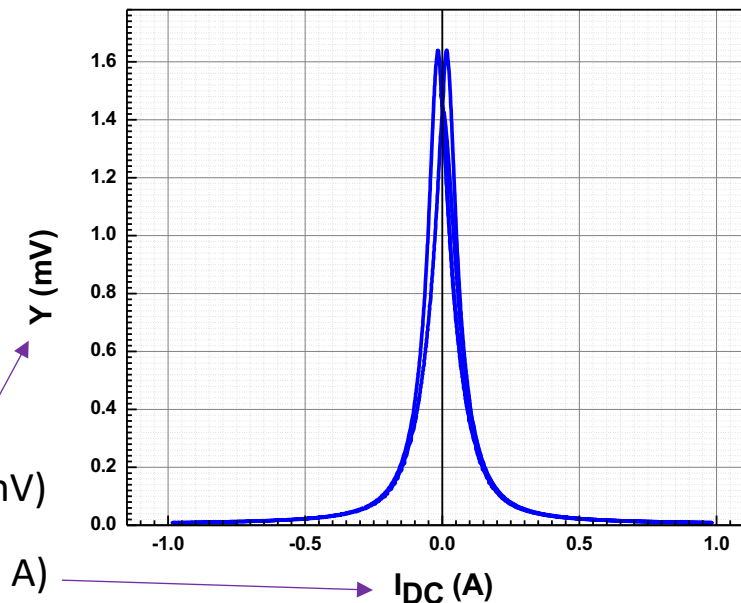
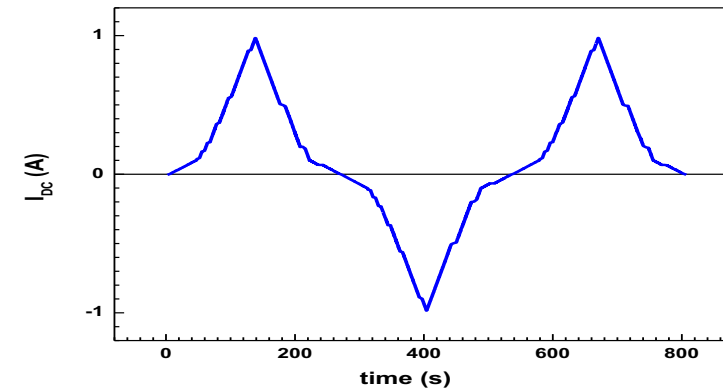
1. Perform one **coarse** (i.e., *fast*) **scan** over I_{DC} (that is, H_0) to find the required **dynamic range**.

How wide a range must we cover?

How small a step size is needed for detail?

Based upon this data set...

2. Perform a **precision scan** for data analysis



Y : amplitude measured by SR830 (in mV)

I_{DC} : current in primary coil (in A)

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From Permeability to Hysteresis Loop

3. **Calibration:** relating what you measure to what you want to know

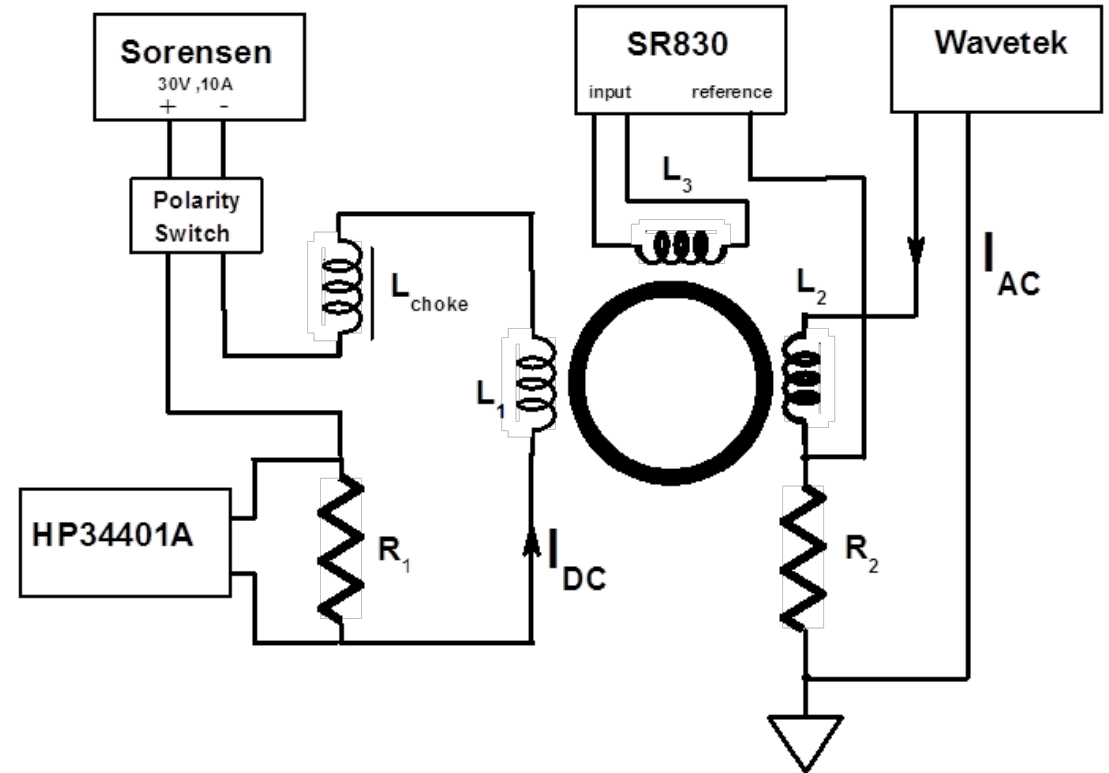
What does the lock-in amplifier actually measure?

... the **EMF** imposed on the pickup coil

$$V_{lock-in} = -\frac{d\Phi}{dt} = -\frac{d}{dt}(\vec{B} \cdot \vec{S})$$

The AC current driven in primary coil L_2 is:

$$I_p = \frac{V_0 \sin \omega t}{R_2}$$



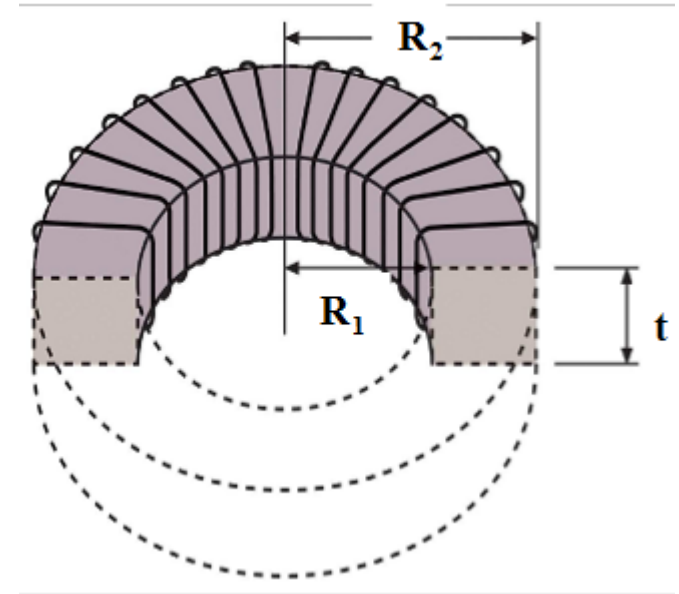
From Permeability to Hysteresis Loop

3. **Calibration:** relating what you measure to what you want to know

$$V_{\text{lock-in}} = -\frac{d\Phi}{dt} = -\frac{d}{dt}(\vec{B} \cdot \vec{S})$$
$$I_p = \frac{V_0 \sin \omega t}{R_2}$$

Primary coil is a **toroid** of N_p turns carrying a current I_p creates a magnetic field H , and thus adds a flux $d\Phi$:

$$H = \frac{N_p I_p}{2\pi r}$$
$$d\Phi = \mu \int \vec{H} \cdot d\vec{a} = \frac{\mu I N t}{2\pi} \int_{R_1}^{R_2} \frac{dr}{r} = \frac{\mu I N t}{2\pi} \ln \frac{R_2}{R_1}$$



From Permeability to Hysteresis Loop

3. **Calibration:** relating what you measure to what you want to know

$$V_{lock-in} = -\frac{d\Phi}{dt} = -\frac{d}{dt}(\vec{B} \cdot \vec{S})$$

Total flux detected by the pickup coil:

$$\Phi = N_{pickup} d\Phi = \frac{\mu N_{pickup} I_p N_p t}{2\pi} \ln \frac{R_2}{R_1}$$

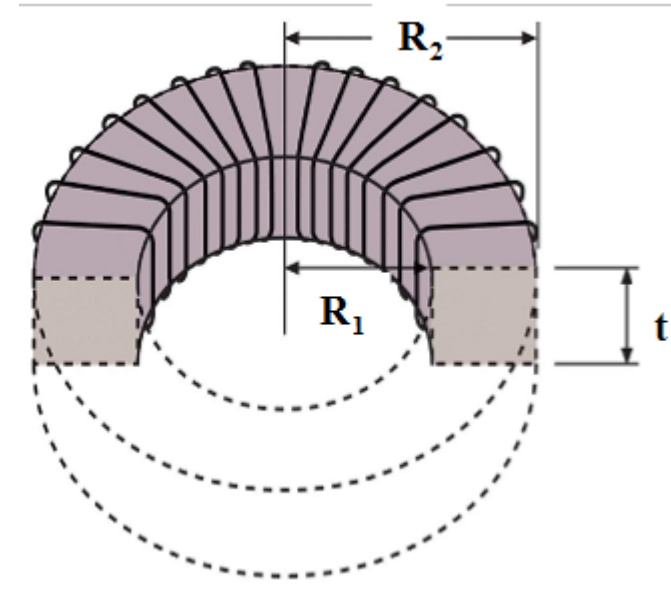
Careful about whether the lock-in is giving you amplitude or r.m.s.!

Toroid inductance:

$$L = \frac{\Phi}{I} = \mu_r L_0 = (\mu' - i\mu'') L_0$$

Geometric inductance in vacuum

$$L_0 = \frac{\mu_0 N_{pickup} N_p t}{2\pi} \ln \frac{R_2}{R_1}$$



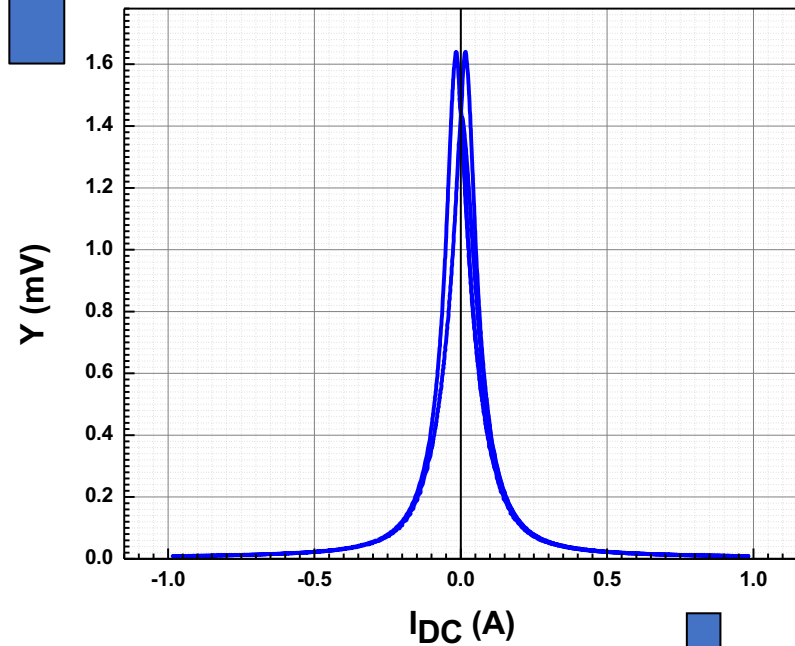
From Permeability to Hysteresis Loop

Signal generator:

$$\frac{dI_p}{dt} = \omega \frac{V_0}{R_2} \cos \omega t$$

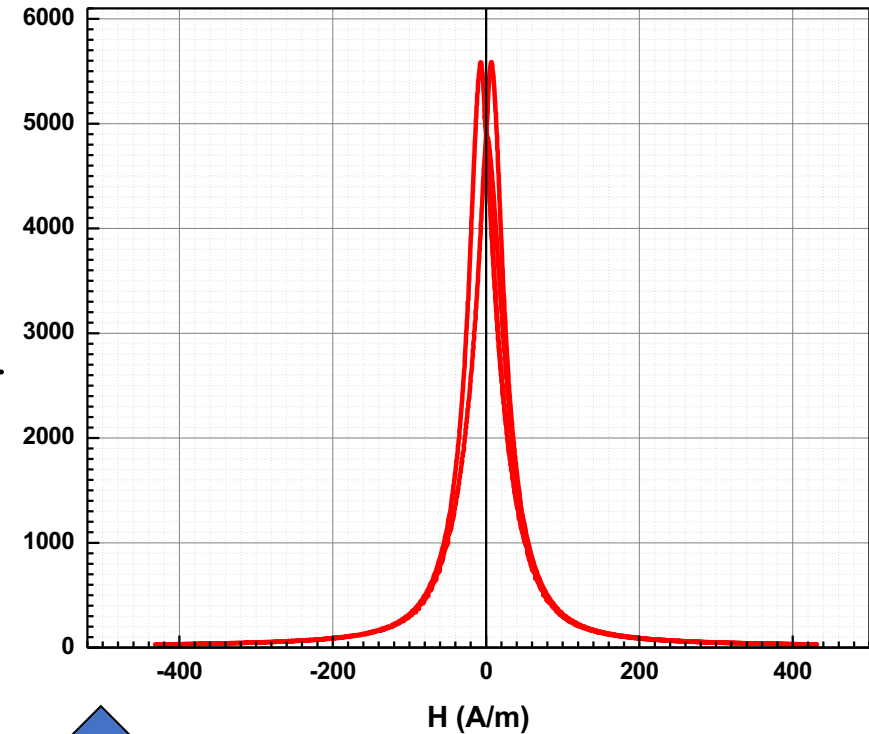
Note: proportional to ω !

$$V_{lock-in} = \mu_r L_0 \frac{dI_p}{dt}$$



$$\mu_r = \mu' - i \mu''$$

μ''



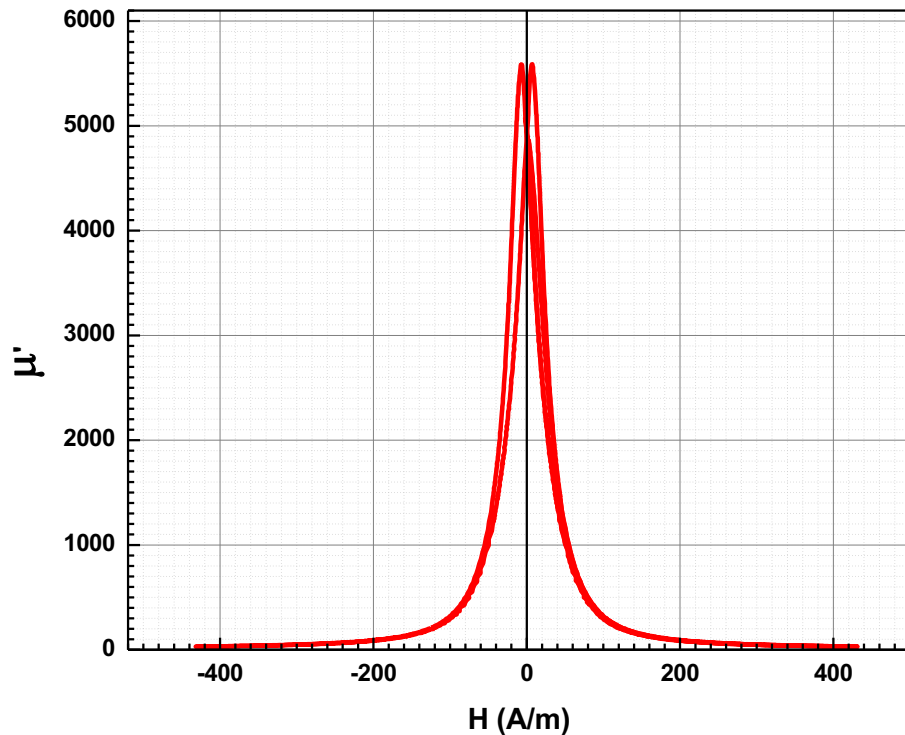
$$H_0 = \frac{N_p I_{DC}}{2\pi r}$$

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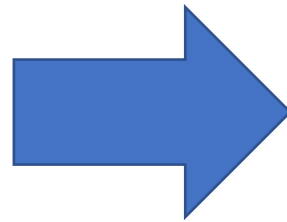


From Permeability to Hysteresis Loop

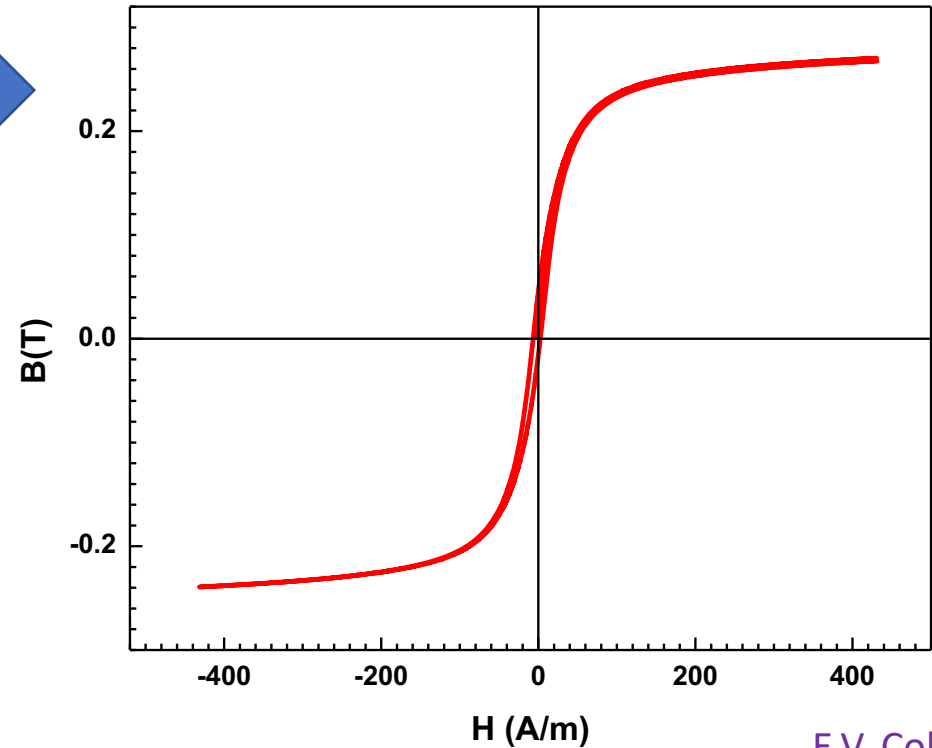
4. **Integration:** $\mu_r(H)$ is a local derivative, so we must integrate it to find $B(H)$



$$\mu(H_0) = \mu_0 \mu_r(H_0) = \left. \frac{dB}{dH} \right|_{H_0}$$



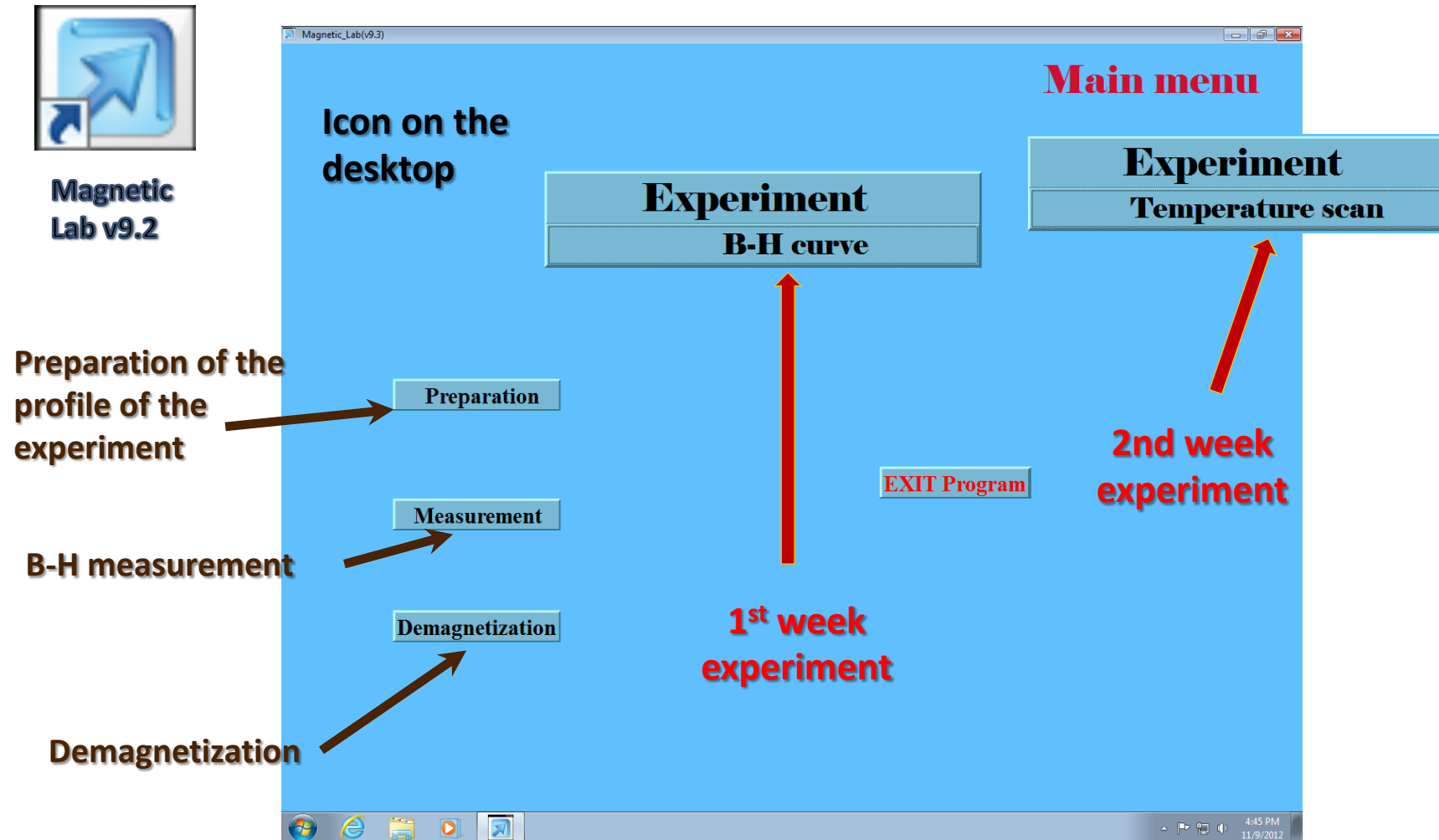
$$B(H) = \mu_0 \int \mu_r(H) dH$$



E.V. Colla



Using the Acquisition Software – E.V. Colla



Using the Acquisition Software – E.V. Colla

Preparing the measurement profile and using the profile template

The screenshot shows the Magnet Lab software interface. The main window is titled "B-H PROFILE" and contains the following text:

There is no saved parameters set or is damaged. Start to prepare new profile or open saved one.

The shown profile is a saved one from the previous experiment.

You can use it, load saved profile or create a new one.

The graph displays I_{dc} (A) on the y-axis (ranging from -1 to 1) versus time (s.n) on the x-axis (ranging from 0 to 2000). The graph shows a flat line at 0 A.

Below the graph, there are three input fields: I_{start} (A), I_{stop} (A), and $Step$ (A).

On the left side, there are four buttons: "Open a new file", "Create a new file", "Save file", and "Exit". These buttons are highlighted with a red rounded rectangle.

Three yellow callout boxes with red arrows point to the buttons:

- "Open a new file" points to the "Open a new file" button.
- "Create a new file" points to the "Create a new file" button.
- "Save prepared file for future use" points to the "Save file" button.



Using the Acquisition Software – E.V. Colla

Preparing the measurement profile and using the profile template

The screenshot shows the 'Magnetic_Lab(v10)' software interface. A file selection dialog box titled 'Enter File Name for T profile' is open, displaying a list of files in the 'Lectures Spring 2016' folder. The file 's1.par' is selected. The background shows a graph with 'time (a.u)' on the x-axis and a linear plot. Below the graph, there are buttons for 'Create a new file', 'Save file', and 'Exit'. A table with columns 'Step(A)', 'Istart(A)', 'Istop(A)', and 'Step(A)' is partially visible, showing values for steps 0, 1, and 2.

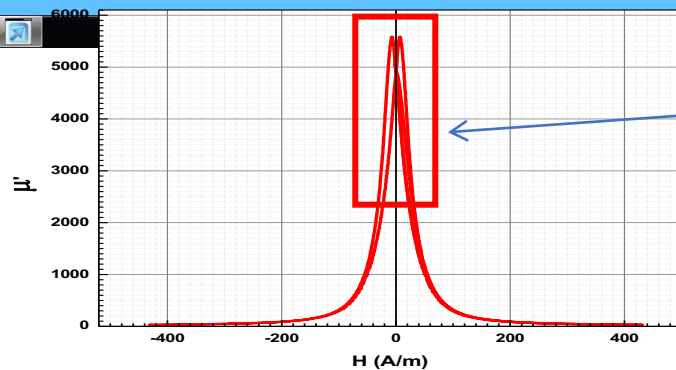
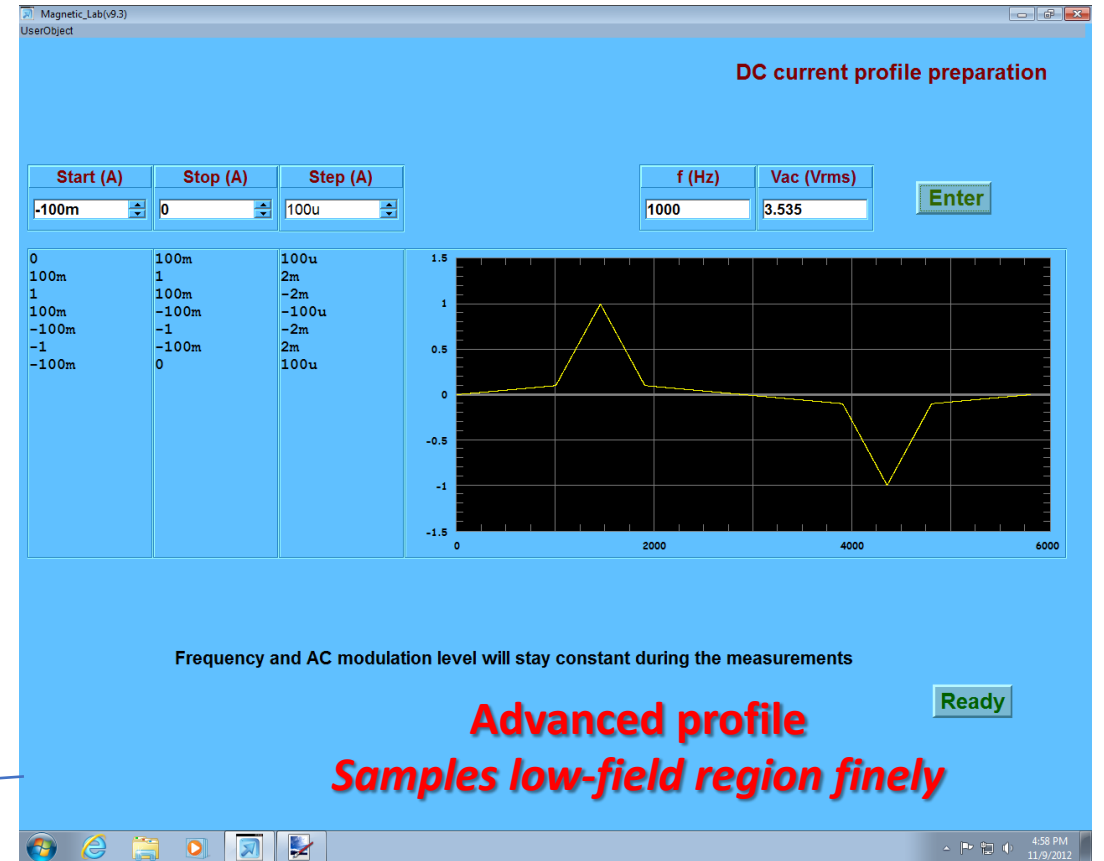
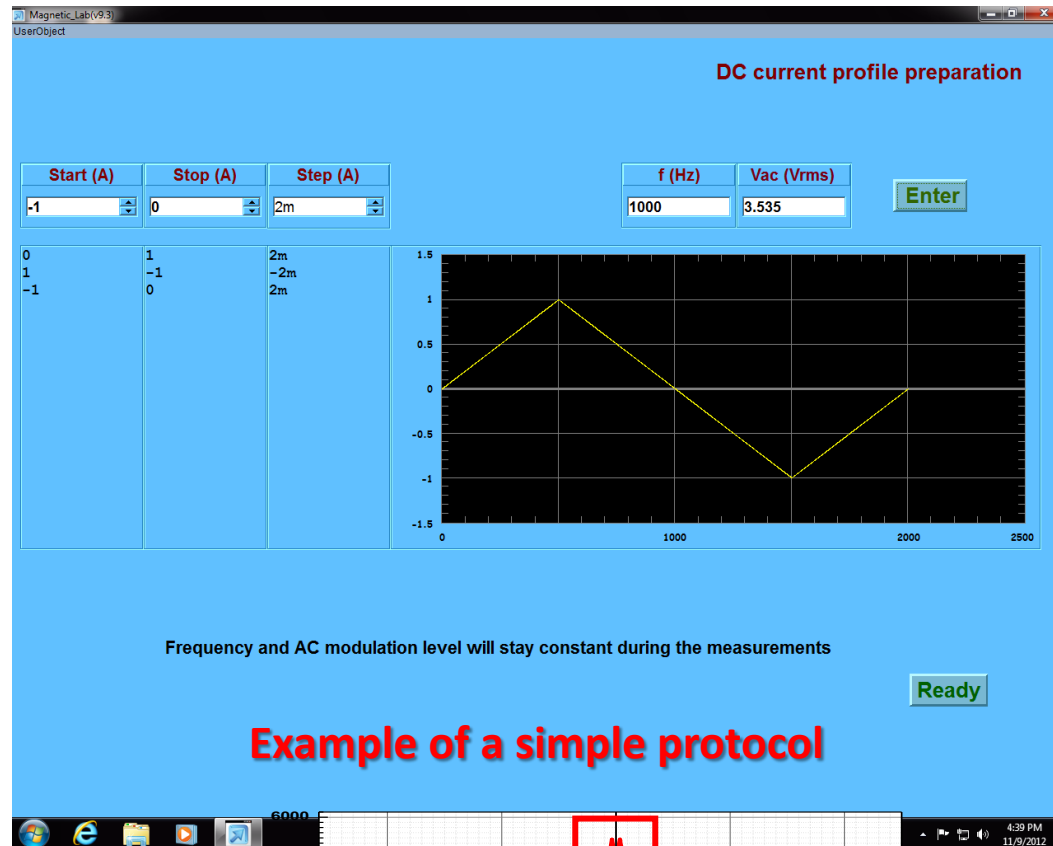
The screenshot shows the 'Magnetic_Lab(v10)' software interface. A graph titled 'B-H PROFILE' displays 'Idc (A)' on the y-axis and 'time (a.u)' on the x-axis. The graph shows a complex profile with multiple peaks and troughs. Below the graph, there are buttons for 'Open a new file', 'Create a new file', 'Save file', and 'Exit'. A table with columns 'Istart(A)', 'Istop(A)', and 'Step(A)' is displayed, showing values for steps 0 through 6.

Istart(A)	Istop(A)	Step(A)
0:	1:	2:
0: 0	1	2m
1: 1	5	20m
2: 5	1	-20m
3: 1	-1	-2m
4: -1	-5	-20m
5: -5	-1	20m
6: -1	0	2m

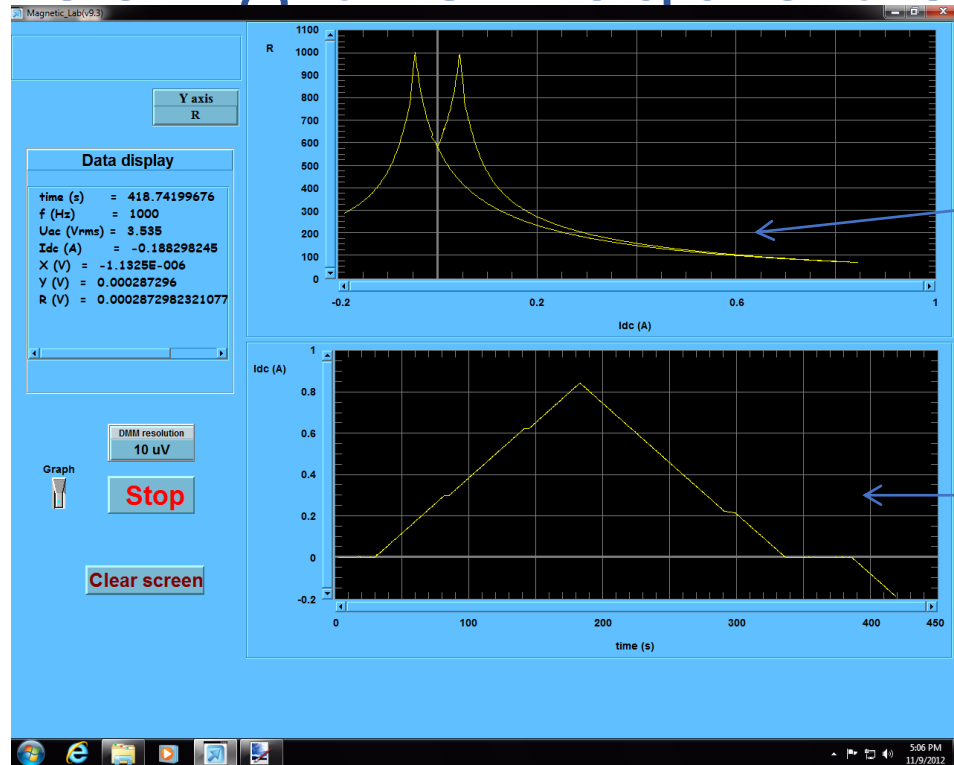


Using the Acquisition Software – E.V. Colla

Preparing the measurement profile



Using the Acquisition Software – E.V. Colla



Measurement Window

Lock-in amplifier response

The profile of the applied DC current

	times(X)	fHz(Y)	UacVrms(Y)	IdcA(Y)	XV(Y)	YV(Y)	RV(Y)
Long	time (s) =	f (Hz) =	Uac (Vrms)	Idc (A) =	X (V) =	Y (V) =	R (V) =
1	2.125	1000	3.535	0.00444	-1.31876E-	7.73077E-	7.73189E-
2	12.828	1000	3.535	0.00416	-1.16975E-	7.72332E-	7.72421E-
3	13.203	1000	3.535	0.00751	-1.1325E-6	7.67563E-	7.67647E-
4	13.578	1000	3.535	0.00988	-1.03564E-	7.65999E-	7.66069E-
5	13.938	1000	3.535	0.01205	-1.15485E-	7.62646E-	7.62733E-
6	14.313	1000	3.535	0.01395	-9.16425E-	7.59815E-	7.5987E-5
7	14.788	1000	3.535	0.01624	-1.22025E-	7.56765E-	7.56865E-

Structure of the data file (B-H experiment)

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To calculate the permeability, it's easiest to use the template :

\\engr-file-03\phyinst\APL Courses\PHYCS401\Common\Origin templates\AC magnetic Lab\MU_CALCULATION.otwu

It does not contain the equations – you have to write them!

	times(X)	fHz(Y)	UacVrms(Y)	IdcA(Y)	XV(Y)	YV(Y)	RV(Y)	A(L)	B(Y)	Lo(Y)	mu1(Y)	mu2(Y)	H(Y)
ng N	time (s)	f (Hz)	Uac (Vrms)	Idc (A)	X (V)	Y (V)	R (V)						a/m
Units								Parameters					
1	2.125	1000	3.535	0.00444	-1.31876E-6	7.73077E-5	7.73189E-5	Npickup	20	3.35179E-7	51.92141	0.88571	0.00789
2	12.828	1000	3.535	0.00416	-1.16975E-6	7.72332E-5	7.72421E-5	Nac primary	20	3.35179E-7	51.87137	0.78563	0.00739
3	13.203	1000	3.535	0.00751	-1.1325E-6	7.67563E-5	7.67647E-5	h(m)	0.00825	3.35179E-7	51.55108	0.76061	0.01335
4	13.578	1000	3.535	0.00988	-1.03564E-6	7.65999E-5	7.66069E-5	r2	22.35	3.35179E-7	51.44604	0.69556	0.01756
5	13.938	1000	3.535	0.01205	-1.15485E-6	7.62646E-5	7.62733E-5	r1	13.45	3.35179E-7	51.22084	0.77562	0.02143
6	14.313	1000	3.535	0.01395	-9.16425E-7	7.59815E-5	7.5987E-5	Ndc primary	100	3.35179E-7	51.03071	0.61549	0.0248
7	14.766	1000	3.535	0.01621	-1.22935E-6	7.5676E-5	7.5686E-5				50.82553	0.82566	0.02883
8	15.141	1000	3.535	0.01739	-1.26661E-6	7.51545E-5	7.51652E-5				50.47528	0.85068	0.03092
9	15.484	1000	3.535	0.01974	-8.12117E-7	7.50502E-5	7.50546E-5				50.40523	0.54543	0.0351
10	15.875	1000	3.535	0.02174	-1.1772E-6	7.47894E-5	7.47987E-5				50.23007	0.79063	0.03865
11	16.328	1000	3.535	0.02263	-1.09524E-6	7.46031E-5	7.46111E-5				50.10494	0.73559	0.04025
12	16.703	1000	3.535	0.02589	-9.76033E-7	7.43424E-5	7.43488E-5				49.92985	0.65552	0.04605
13	17.063	1000	3.535	0.02698	-1.15485E-6	7.37687E-5	7.37777E-5				49.54454	0.77562	0.04798



Raw data

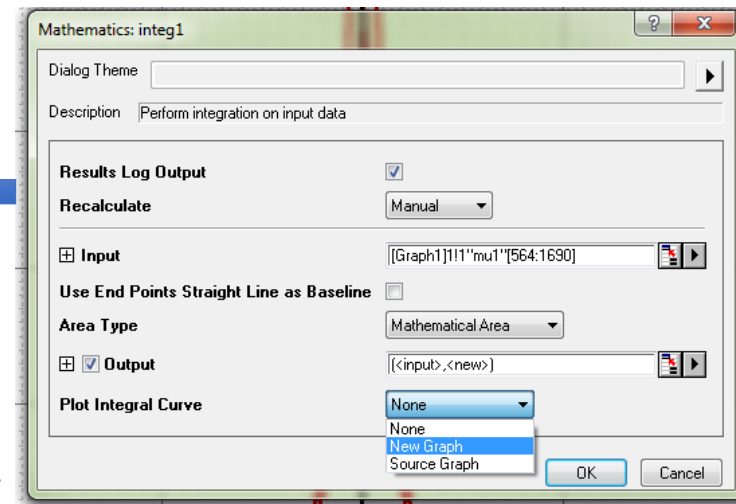
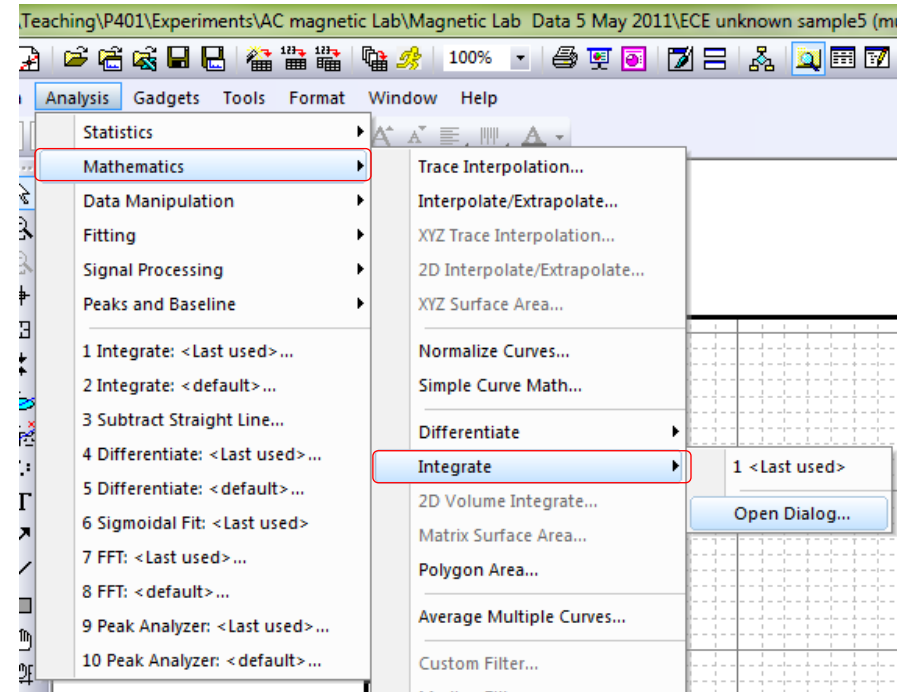
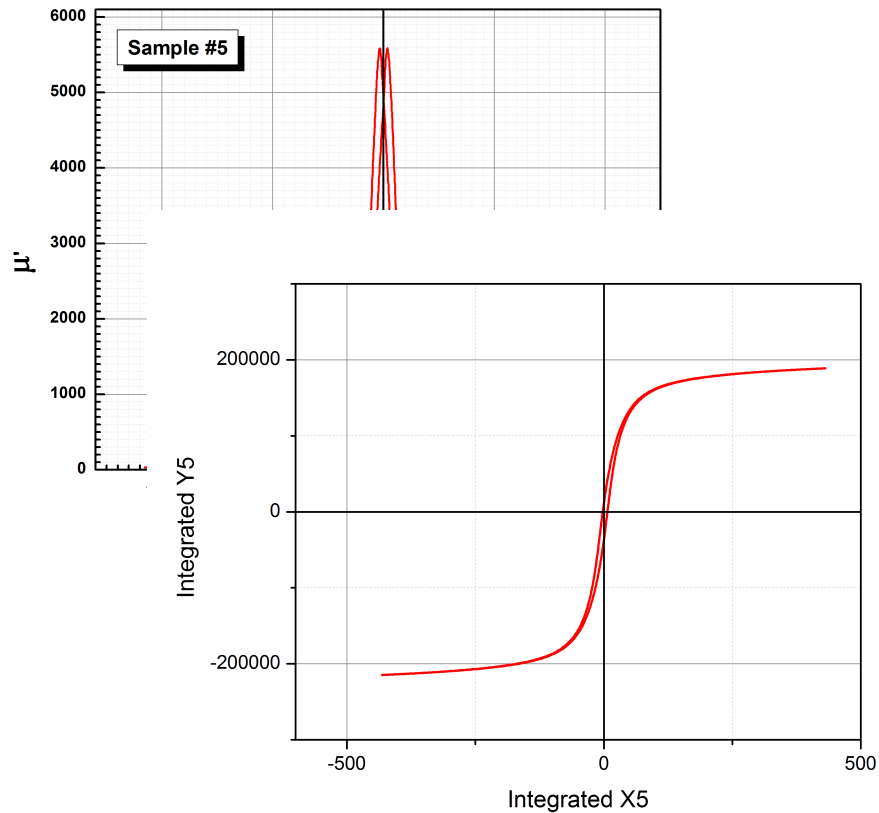
Parameters

Calculated results



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$$B(H) = \mu_0 \int \mu_r(H) dH$$

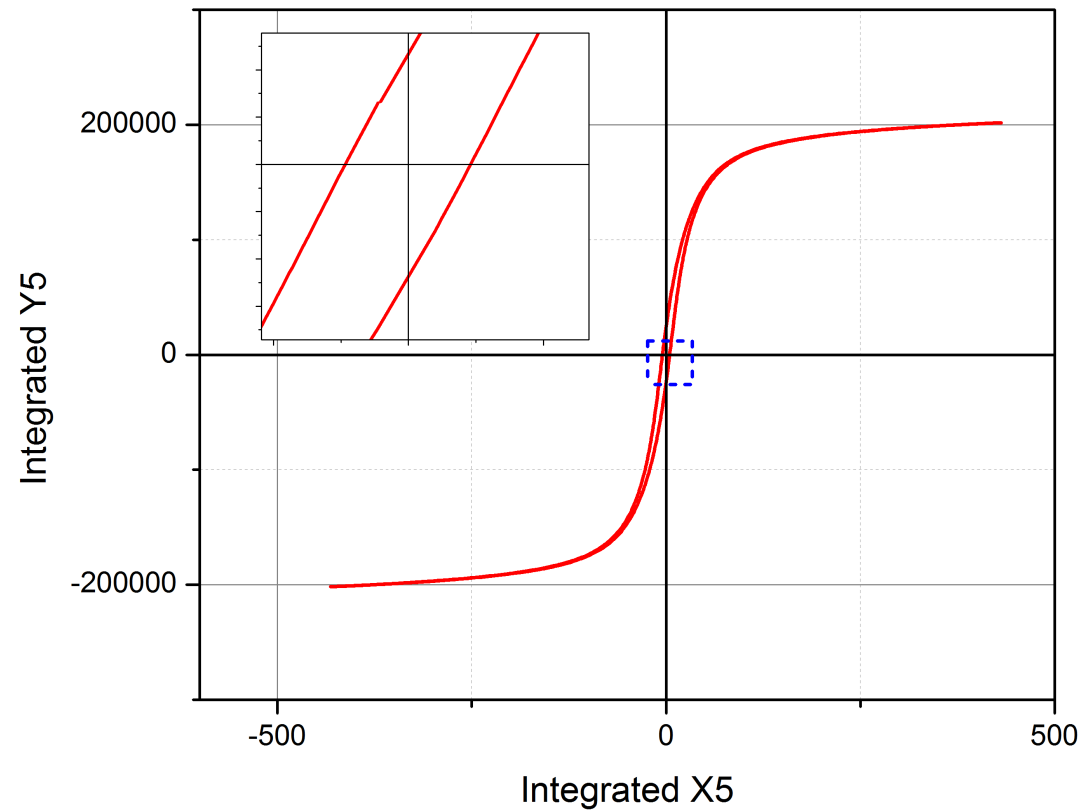


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$$B(H) = \mu_0 \int \mu_r(H) dH + offset$$



References

- Information about magnetic materials can be found in:
[\\engr-file-03\phyinst\APL Courses\PHYCS401\Experiments\AC_Magnetization\Magnetic Materials](#)
- SR830 (Lock-in Amplifier) manual
[\\engr-file-03\phyinst\APL Courses\PHYCS401\Common\EquipmentManuals\SR830m.pdf](#)

