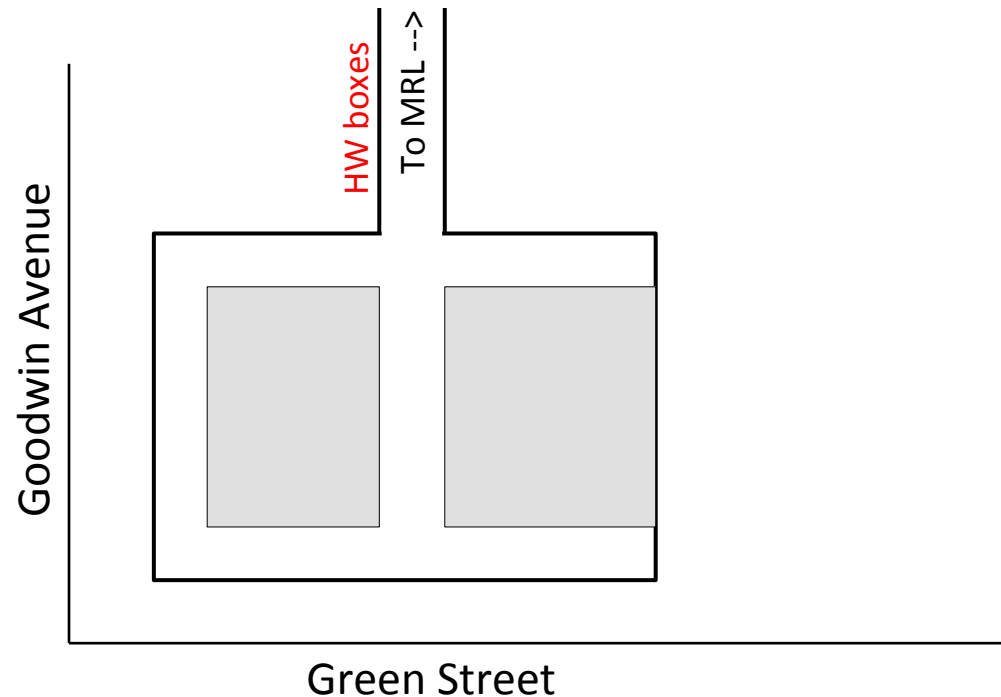


Announcement

Homework:

- Homework is due at **5 PM** on Friday.
- Put your homework in the **P435 HW box**, which is in the 2nd floor passage between Loomis and MRL:



Today's Topic: The Electric Field

Griffiths, 2.1 and 2.2

Empirically, we have Coulomb's law: $\vec{E}(\vec{r}) = \frac{Q}{4\pi\epsilon_0} \frac{\hat{r}}{r^2}$, where $\vec{r} = \vec{r} - \vec{r}_Q$

The force on a charge, q , at \vec{r} is: $\vec{F} = q\vec{E}(\vec{r}) = \frac{qQ}{4\pi\epsilon_0} \frac{\hat{r}}{r^2}$ (or $\frac{\vec{r}}{r^3}$)

Notes:

- $\vec{F} \propto q$ If that weren't true, it would not be possible to talk about an electric field independent of q .

- $\vec{E} \propto Q$ This is **superposition**. More generally, if we have several charges, the total \vec{E} is the sum of each charge's field.

$$\vec{E}_{\text{tot}}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_i \frac{Q_i \hat{r}_i}{r_i^2}$$

If we have a continuous distribution of charge, the sum becomes an integral, Q_i becomes $\rho(\vec{r}')$, and $\vec{r} = \vec{r} - \vec{r}'$.

These aren't really independent. Swap the roles of q and Q , and remember Newton's 3rd law.

Standard notation:

- 1-dimensional (line) density: $\lambda(x)$
- 2-dimensional (surface) density: $\sigma(x,y)$
- 3-dimensional (volume) density: $\rho(x,y,z)$

Example: (G 2.7, p. 64)

Calculate E due to a **uniform spherical surface charge**, density $= \sigma$.

Spherical symmetry lets us evaluate \mathbf{E} on the z -axis, where it points in the \mathbf{z} direction. We must consider both $z > R$ and $z < R$.

$$\vec{r} = (0, 0, z)$$

$$\vec{r}' = R(\sin\theta \cos\phi, \sin\theta \sin\phi, \cos\theta) \quad |\vec{r}'| = R$$

$$r^2 = R^2 + z^2 - 2Rz \cos\theta \quad \text{Law of cosines}$$

$$r_z = z - R \cos\theta$$

$$\text{So, } E_z = \frac{\sigma}{4\pi\epsilon_0} \oint \frac{r_z}{r^3} dA = \sigma R^2 \int_0^{2\pi} \int_0^\pi \frac{z - R \cos\theta}{(R^2 + z^2 - 2Rz \cos\theta)^{\frac{3}{2}}} \sin\theta d\theta d\phi$$

$$= \frac{2\pi R^2 \sigma}{4\pi\epsilon_0 z^2} \left[\frac{z - R}{|z - R|} + \frac{z + R}{|z + R|} \right]$$

$$= 0 \text{ if } z < R$$

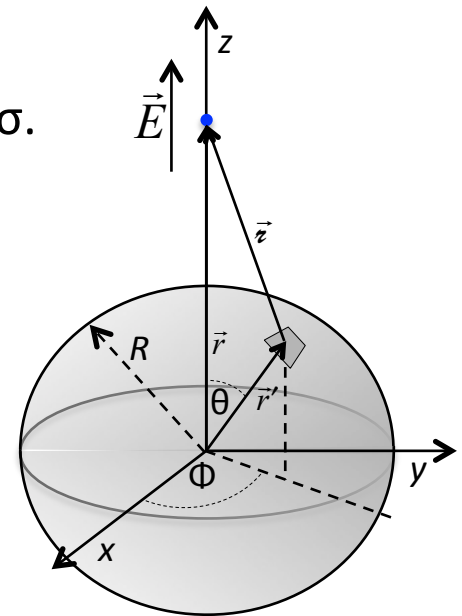
$$= 2 \text{ if } z > R$$

This is obtained using a trig substitution and partial fractions.

$$\text{Note: } 4\pi R^2 \sigma = Q_{\text{tot.}}$$

Note: This problem, for gravity, led Newton to develop calculus.

He needed to verify that the force falls off as $1/r^2$ for a spherical (not point) mass.



I suggest:

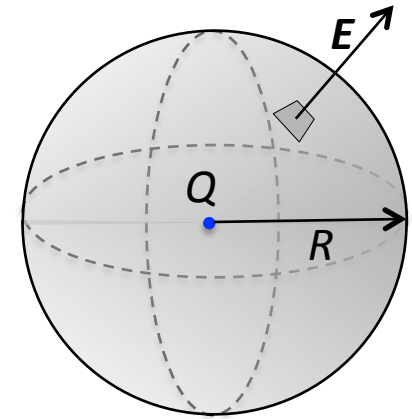
Do Griffiths problems
2.4, 2.5, and 2.6.
(2.3 will be a
HW problem.)

Divergence and Curl of E

Griffiths, 2.2

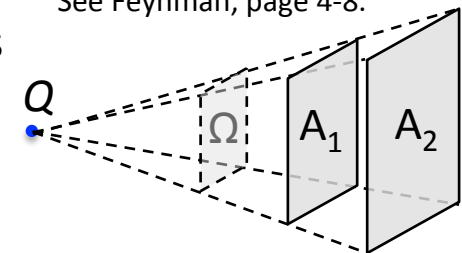
Coulomb's law: $\vec{E} \propto 1/r^2$ is the reason that we can draw **electric field lines** that start on a + charge and end on a - charge.

Consider a point charge surrounded by a spherical surface of radius R :
Because $A \propto R^2$ the total flux through the sphere is independent of R .
Flux = Q/ϵ_0 . The electric field lines don't end in empty space.

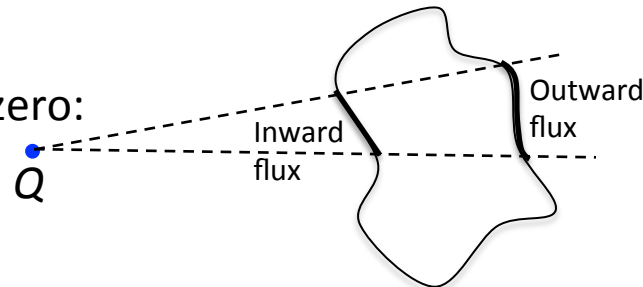


Gauss' law is a generalization of this to the situation where the charge is not at the center and where the surface is not a sphere. Because the field lines are radial, the flux through surfaces A_1 and A_2 depends only on the solid angle, Ω , that they subtend. This works even if the surfaces are tilted. So, **Flux** = Q/ϵ_0 is universally true.

See Feynman, page 4-8.



If Q is outside the surface, the total flux is zero:



Superposition lets us generalize Gauss' law to continuous charge distributions.

Gauss' law follows from Coulomb's law and superposition:

$$\oint_{\text{Surface}} \vec{E} \cdot \hat{n} dA = \frac{Q_{in}}{\epsilon_0} = \frac{1}{\epsilon_0} \int_{\text{Volume}} \rho(\vec{r}) dV$$

However, this is an **integral equation**, not so easy to solve, except in special cases. We can convert it into a **differential equation** using a math identity, the **divergence theorem**: (**v** is any differentiable vector function)

$$\oint_{\text{Surface}} \vec{v} \cdot \hat{n} dA = \int_{\text{Volume}} \vec{\nabla} \cdot \vec{v} dV \quad \leftarrow \text{No physics here !!}$$

Letting **v** be **E**, we immediately see that (because the volume is arbitrary), the two volume integrands must be equal:

$$\boxed{\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}} \quad \text{Gauss' law in differential form.}$$

This tells us the local behavior of the electric field due to the charge density at a given point.

Note: The divergence theorem is the fundamental theorem of calculus in 3-D. If you Google “divergence theorem proof” (no quotes), you’ll find innumerable proofs on the web.

Calculation (and Use) of Divergence

Example:

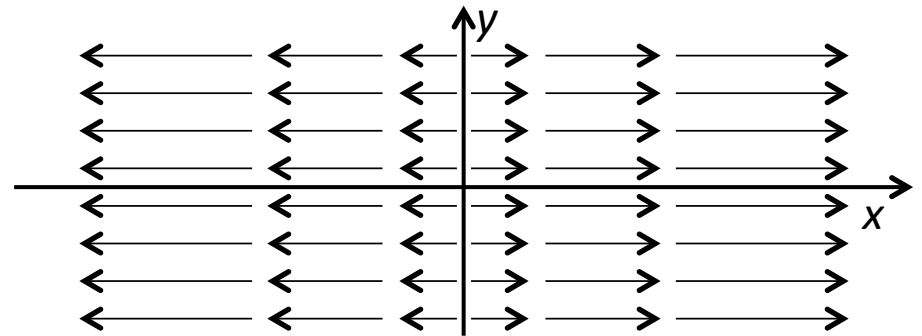
Suppose we want to create an electric field with the behavior shown. What charge density is required?

$$\vec{E} = ax\hat{x} = (ax, 0, 0)$$

In Cartesian coordinates:

$$\vec{\nabla} \cdot \vec{E} = \frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z} = a$$

So, $\rho = a\epsilon_0$. Is that reasonable?



How can a uniform charge density pick out a preferred direction and position?

Look at the differential equation more closely. For $\rho = a\epsilon_0$, an electric field of the form, $\vec{E} = a_1x\hat{x} + a_2y\hat{y} + a_3z\hat{z} + \vec{E}_0$, is a solution for any $a_1 + a_2 + a_3 = a$, and for any \vec{E}_0 .

The parameters, a_1 , a_2 , a_3 , and \vec{E}_0 are determined by the **boundary conditions** that we have imposed on the problem.

Question: What does \vec{E} look like if $a_1 = a_2 = a_3 = a/3$?

Spherical Coordinates

Sometimes, problems are simpler to understand and solve if we use other coordinate systems.

Spherical coordinates are most useful when there is spherical symmetry (*i.e.*, the problem looks the same in any orientation).

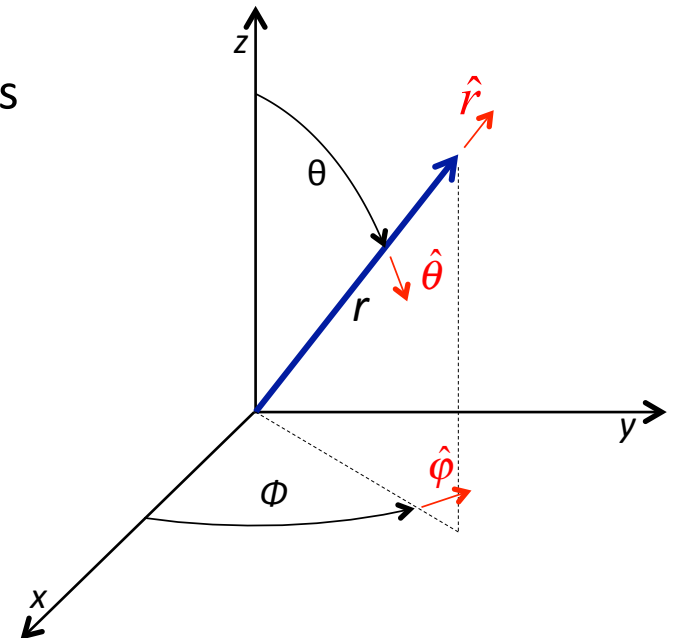
The Cartesian components of the spherical unit vectors are:

$$\hat{r} = (\sin\theta \cos\varphi, \sin\theta \sin\varphi, \cos\theta)$$

$$\hat{\theta} = (\cos\theta \cos\varphi, \cos\theta \sin\varphi, -\sin\theta)$$

$$\hat{\phi} = (-\sin\varphi, \cos\varphi, 0)$$

Each tells us the (x,y,z) motion when only that particular component changes. One important feature of spherical (and other curvilinear) coordinates is that **the directions of the unit vectors are not constant**, so that taking derivatives in those coordinate systems is more complicated.



Divergence in Spherical Coordinates

Contrary to intuition, this expression is not correct:

No! $\vec{\nabla} \cdot \vec{E} = \frac{\partial E_r}{\partial r} + \frac{\partial E_\theta}{\partial \theta} + \frac{\partial E_\phi}{\partial \phi}$ No! It fails, because \hat{r} , $\hat{\theta}$, and $\hat{\phi}$ are functions of position.

Instead, we have:

$$\vec{\nabla} \cdot \vec{E} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 E_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta E_\theta) + \frac{1}{r \sin \theta} \frac{\partial E_\phi}{\partial \phi}$$

This form is useful in problems with spherical symmetry.

Let's calculate the divergence of the Coulomb field, $\vec{E} = a \frac{\hat{r}}{r^2}$. Simple:

$$E_\theta = 0. \quad E_\phi = 0. \quad E_r = a/r^2, \text{ so } \partial(r^2 E_r) / \partial r = 0.$$

Therefore, $\vec{\nabla} \cdot \vec{E} = 0$ everywhere !! ??

Beware of this word.
It's usually a trap.

We know this is wrong, because there is charge at the origin. The problem is that \vec{E} is not well behaved at the origin – its derivatives are not defined at the singularity.

How can we deal with this?

Singularities and the Dirac δ -function

See Griffiths, 1.5

We have a point charge at the origin. ρ is zero everywhere except there, where it is infinite. That's the singularity.

We know how to deal with it, because the total charge is Q . That means that if we integrate $\int_{Volume} \rho dV$ over any volume that contains the origin, we obtain Q . If the volume does not contain the origin, we obtain 0.

A function, in this case, $\rho(\mathbf{r})$, that is zero everywhere except at one point, but that has a finite (non-zero) integral, is called a Dirac δ -function.

Comments:

- δ -functions are defined in 1, 2, and 3 dimensions.
- I won't discuss them more now, but they appear now and again.
In particular, they are important in the development of Green's functions solutions to differential equations.

Graphically, a δ -function is a “needle”:

Disclaimer: Mathematically inclined students will complain that I'm being sloppy. That's true ...

