

Comment:

Consider this vector identity: $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{v}) = 0$ (G, #9)

Let's apply it to Ampere's law: $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \mu_0 \vec{\nabla} \cdot \vec{J} = -\mu_0 \frac{\partial \rho}{\partial t}$$

This implies that **Ampere's law must be modified** when we get away from the static situation (*i.e.*, when $\frac{\partial \rho}{\partial t} \neq 0$). We'll deal with this later.

Magnetic Vector Potential (5.4)

Here we are now (in the time independent situation):

$$\begin{array}{ll} \vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} & \vec{\nabla} \times \vec{E} = 0 \\ \text{Gauss} & \\ \vec{\nabla} \cdot \vec{B} = 0 & \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \\ & \text{Ampere} \end{array}$$

This is a complete description of electro- and magneto-statics. (You can go home now.)

Of course, there are concepts that make life much simpler, and problem solving much easier. One of these is conservation of energy: $\vec{\nabla} \times \vec{E} = 0 \Rightarrow \vec{E} = -\vec{\nabla} V$
The potential energy of a charge is $U = qV$.

The magnetic field does no work, so potential energy isn't useful.
In any case, because the curl is not zero in general, we can't usually define V_B .

Can we take advantage of $\vec{\nabla} \cdot \vec{B} = 0$?

It turns out that we can.

Our ability to define $\vec{E} = -\vec{\nabla} V$ follows from this vector identity: $\vec{\nabla} \times (\vec{\nabla} V) = 0$

Another vector identity: $\vec{\nabla} \cdot (\vec{\nabla} \times \vec{A}) = 0$ tells us that if we define $\vec{B} \equiv \vec{\nabla} \times \vec{A}$ we are guaranteed to satisfy the divergence equation.

A is called the magnetic vector potential.

The definition of \mathbf{A} is only useful if we have a way to calculate it from the current distributions, akin to our calculation of V :

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{r} dVol'$$

$$\vec{A}(\vec{r}) = ?$$

The connection between \mathbf{A} and \mathbf{J} is given by Ampere's law:

$$\begin{aligned} \vec{\nabla} \times \vec{B} &= \mu_0 \vec{J} \\ = \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) &= \vec{\nabla} (\vec{\nabla} \cdot \vec{A}) - \vec{\nabla}^2 \vec{A} \end{aligned}$$

↔
Vector identity #11

The boxed equation looks a bit messy. Fortunately, we can simplify it.

Remember our freedom of choice with the scalar potential. The fact that it is defined in terms of its derivative, $\vec{E} = -\vec{\nabla}V$, means that we can add any constant to V without affecting the physics. We can pick $V = 0$ anywhere we want.

There is a similar freedom of choice with \mathbf{A} .

\mathbf{A} is defined by its derivative: $\vec{B} = \vec{\nabla} \times \vec{A}$

This means that we can add to \mathbf{A} any vector field, \mathbf{X} , that has $\vec{\nabla} \times \vec{X} = 0$.

In particular, any $\vec{X} = \vec{\nabla} \lambda$ will work, because $\vec{\nabla} \times (\vec{\nabla} \lambda) = 0$.
Identity #10

That is, suppose we transform \mathbf{A} : $\vec{A}' = \vec{A} + \vec{\nabla} \lambda$.

Then, $\vec{\nabla} \times \vec{A}' = \vec{\nabla} \times \vec{A}$, and we have the same \mathbf{B} .

This freedom is called
“gauge invariance”.
 \mathbf{A} to \mathbf{A}' is called a
“gauge transformation”.

How can we use this freedom to simplify the problem?

We have: $\mu_0 \vec{J} = \vec{\nabla} (\vec{\nabla} \cdot \vec{A}) - \vec{\nabla}^2 \vec{A}$

We'd like to eliminate this term.

If we can find an \mathbf{A}' such that $\vec{\nabla} \cdot \vec{A}' = 0$, then we'll have reduced the problem to Poisson's equation (and, in current-free regions, to Laplace's equation). We want to find a λ that accomplishes this. We want:

$$0 = \vec{\nabla} \cdot \vec{A}' = \vec{\nabla} \cdot \vec{A} + \underbrace{\vec{\nabla} \cdot (\vec{\nabla} \lambda)}_{=\nabla^2 \lambda} \Rightarrow \nabla^2 \lambda = -\vec{\nabla} \cdot \vec{A} \quad (\text{Poisson's equation})$$

This equation always has a solution, but I don't want to solve it.

I don't need to. Once we know that \mathbf{A}' exists, we can solve for it directly:

$$\mu_0 \vec{J} = -\vec{\nabla}^2 \vec{A}'$$

Choosing $\vec{\nabla} \cdot \vec{A}' = 0$ is the equivalent of picking $V = 0$ where we want.

$\vec{\nabla}^2 \vec{A}' = -\mu_0 \vec{J}$ is three Poisson equations, one for each component.
Therefore, the solutions look just like the solutions for the scalar potential:

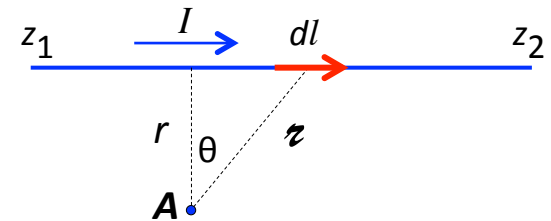
$$\nabla^2 V = -\frac{\rho}{\epsilon_0} \Rightarrow V = \frac{1}{4\pi\epsilon_0} \int \frac{\rho}{r} dVol$$

$$\nabla^2 \vec{A} = -\mu_0 \vec{J} \Rightarrow \vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{J}}{r} dVol$$

Remember: These solutions are only valid for localized charge and current distributions.

Example: The vector potential produced by a finite wire:

$$\vec{A} = \frac{\mu_0}{4\pi} \int \frac{I \hat{z}}{r} dz = \frac{\mu_0 I}{4\pi} \hat{z} \int \frac{dz}{(z^2 + r^2)^{1/2}} dz = \frac{\mu_0 I}{4\pi} \ln \left[\frac{z_2 + (z_2^2 + r^2)^{1/2}}{z_1 + (z_1^2 + r^2)^{1/2}} \right] \hat{z}$$



Does this make sense? Calculate \vec{B} :

$$\vec{B} = \vec{\nabla} \times \vec{A} = -\frac{\partial A_z}{\partial r} \hat{\phi} = \frac{\mu_0 I}{4\pi r} \left[\frac{z_2}{(z_2^2 + r^2)^{1/2}} - \frac{z_1}{(z_1^2 + r^2)^{1/2}} \right]$$

$\sin\theta_2$ $\sin\theta_1$

Comments:

- \vec{A} is poorly behaved when z_1 or z_2 go to ∞ .
- To get this, you must complete the square.

This is the answer we obtained the other day.

End 10/18/13