

Maxwell's Equations in Matter (7.3.5)

Remember that \mathbf{B} and \mathbf{E} are sourced by all the current and charge, while the curl of \mathbf{H} and the divergence of \mathbf{D} respond to the free currents and charges.

We just wrote Maxwell's equations using \mathbf{B} and \mathbf{E} only, but that is not always the most convenient notation. When there are polarizable materials, we want to take into account χ_M and χ_E . (or, \mathbf{P} and \mathbf{M}).

What do Maxwell's equations look like in this case?

A complication – there is another way to produce bound current,

Because the bound charges move around if $\frac{\partial \vec{P}}{\partial t} \neq 0$.

Recall that $\rho_b = -\vec{\nabla} \cdot \vec{P}$. So, with time dependence,

$$\frac{\partial \rho_b}{\partial t} = -\frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{P}) = -\vec{\nabla} \cdot \left(\frac{\partial \vec{P}}{\partial t} \right) \equiv -\vec{\nabla} \cdot \vec{J}_p$$

\vec{J}_p is the current that results from $\frac{\partial \vec{P}}{\partial t}$.

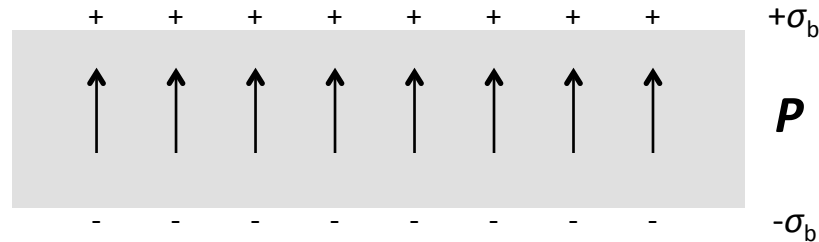
$\vec{J}_p = \frac{\partial \vec{P}}{\partial t}$ is the contribution to bound current from time dependence.

There may be $\vec{\nabla} \times \vec{M}$ at the same time.

End 11/19/14

The physical picture:

$$\sigma_b = -\vec{P} \cdot \hat{n}$$



If \mathbf{P} is changing, a bound current must be flowing to charge up the surfaces.

We must include \mathbf{J}_p in the total current flow:
$$\vec{J} = \vec{J}_f + \vec{\nabla} \times \vec{M} + \frac{\partial \vec{P}}{\partial t}$$

We can now rewrite Maxwell's equations:

1: $\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \Rightarrow \vec{\nabla} \cdot \vec{E} = \frac{1}{\epsilon_0} (\rho_f - \vec{\nabla} \cdot \vec{P}) \Rightarrow \vec{\nabla} \cdot \vec{D} = \rho_f$ (not changed by time dependence)

2: $\vec{\nabla} \cdot \vec{B} = 0$

3: $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

} No ρ or \mathbf{J} , so no changes here.

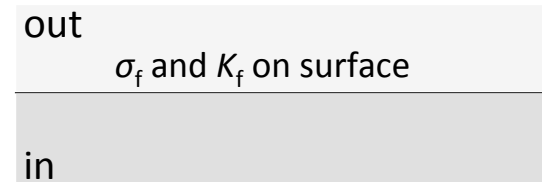
4: $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \mu_0 \left(\vec{J}_f + \vec{\nabla} \times \vec{M} + \frac{\partial \vec{P}}{\partial t} \right) + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

Use: $\vec{B} = \mu_0 (\vec{H} + \vec{M})$ and $\vec{D} = \vec{P} + \epsilon_0 \vec{E}$, to obtain $\vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$

This is useful if you know: $\mathbf{P} = \epsilon_0 \chi_E \mathbf{E}$ and $\mathbf{M} = \chi_M \mathbf{H}$.

Boundary Conditions in Matter (7.3.6)

Each of Maxwell's equations gives a boundary condition at an interface:



$$\vec{\nabla} \cdot \vec{D} = \rho_f \quad \Rightarrow \quad D_{\perp}(\text{out}) = D_{\perp}(\text{in}) \quad \text{if } \sigma_f = 0.$$

$$\vec{\nabla} \cdot \vec{B} = 0 \quad \Rightarrow \quad B_{\perp}(\text{out}) = B_{\perp}(\text{in})$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad \Rightarrow \quad E_{\parallel}(\text{out}) = E_{\parallel}(\text{in}) \quad \text{because } \frac{\partial \vec{B}}{\partial t} \text{ is finite.}$$

$$\vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t} \quad \Rightarrow \quad H_{\parallel}(\text{out}) = H_{\parallel}(\text{in}) \quad \text{if } K_f = 0.$$

Neither $\frac{\partial \vec{E}}{\partial t}$, nor $\frac{\partial \vec{B}}{\partial t}$ affects surface boundary conditions.

Example: Meissner effect and magnetic levitation by a superconductor

There was a homework problem last year (HW14) to show that the current must reside on the surface of a superconductor. This is a consequence of the fact that $\mathbf{B} = 0$ inside a superconductor (the Meissner effect). It's a QM effect, so I can't derive it here. However, there is a phenomenological description that is very interesting.

We have learned that the vector potential, \mathbf{A} , is not uniquely determined:

$$\vec{B} = \vec{\nabla} \times \vec{A} \Rightarrow \vec{A}' = \vec{A} + \vec{\nabla} \lambda \text{ also works. This is called "gauge invariance".}$$

However, Fritz and Heinz London discovered (1935) that

the Meissner effect requires that \mathbf{A} be fixed to a specific value:

$$\vec{A} = -\frac{m}{q^2 n} \vec{j}$$

m is the mass of the current carriers ($\sim 2m_e!!$)
 q is the charge of the current carriers ($= 2e!$)
 n is the number density of current carriers ($\sim n_e/2$).

This loss of gauge invariance is another example of “spontaneous symmetry breaking” that was mentioned in the discussion of ferromagnetism.

Let's see how this gives the Meissner effect.

Meissner effect:

Consider a magnetic field outside the superconductor:

Inside:

$$\vec{\nabla} \times \vec{J} = -\frac{q^2 n}{m} \vec{\nabla} \times \vec{A} = -\frac{q^2 n}{m} \vec{B} \quad \text{London's condition}$$

$$\mu_0 (\vec{\nabla} \times \vec{J}) = \vec{\nabla} \times (\vec{\nabla} \times \vec{B}) \quad \text{Maxwell}$$

$$= \vec{\nabla} (\underbrace{\nabla \cdot \vec{B}}_{=0}) - \nabla^2 \vec{B} \quad \text{Math identity}$$

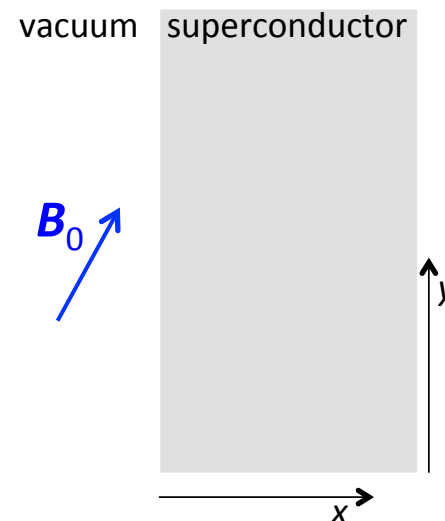
So:

$$\nabla^2 \vec{B} = +k \vec{B} \quad k = \frac{\mu_0 q^2 n}{m}$$

$$\vec{B} = \vec{B}_0 e^{\pm \sqrt{k} x}$$

There is no y or z dependence.

$\frac{1}{\sqrt{k}}$ is called the penetration depth, λ_L .



λ_L is typically a few tens of nanometers.

End 11/21/14