

Lecture 11

Reminder: HW 2 due Thursday

$$G_k = \{ \{ \vec{g} | \vec{0} \} \in G \mid \vec{g}k \equiv k \text{ modulo } \Gamma \}$$

set of elements that leave fixed the representation $\vec{k}$ of the Bravais lattice

$$\begin{aligned} \textcircled{1} \quad G_k \text{ is symmetric} \rightarrow e_k(\{ \vec{g} | \vec{t} \}) &= e_k(\{ \vec{E} | \vec{t} \}) e_k(\{ \vec{g} | \vec{0} \}) \\ &= e^{-i\vec{k} \cdot \vec{t}} e_k(\{ \vec{g} | \vec{0} \}) \end{aligned}$$

phase factor

representation of $\bar{G}_k = G_k \setminus \Gamma$

$$\textcircled{2} \quad G_k \text{ is nonsymmetric}$$

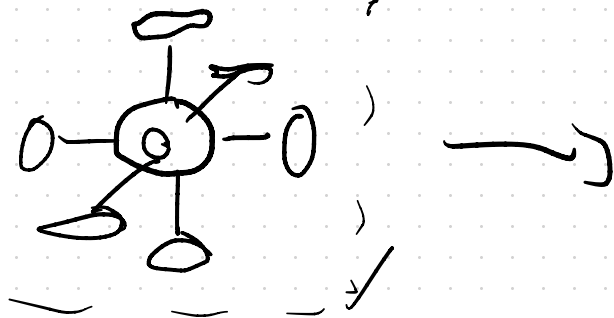
Case 1 example P432

$\vec{k} = \vec{0}$ (Γ point)

$G_T = 432$, $\bar{G}_T = 432$

Character table

	1	4	2 ₁	3	2 ₁₁₀
A ₁	1	1	1	1	1
A ₂	1	-1	1	1	-1
E	2	0	2	-1	0
T ₂	3	-1	-1	0	1
T ₁	3	1	-1	0	-1



↓ Valence electrons
 $\{ |d \text{ orbitals}\rangle \}$
 $|l=2, m\rangle$

Absent other
atoms, states

$$\rho_{l=2}(\hat{n}, \theta) = e^{-\hat{n} \cdot \hat{J} \theta}$$

transform

$\rho_{l=2}$ of $SO(3)$

$$J_z = \begin{pmatrix} 2 & 1 & 0 \\ 1 & 0 & -1 \\ 0 & -1 & 2 \end{pmatrix}$$

$$J_x = \frac{1}{2} \begin{pmatrix} 0 & 2 & 0 \\ 2 & 0 & \sqrt{6} \\ 0 & \sqrt{6} & 0 \\ 0 & \sqrt{6} & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$J_y = \frac{1}{2i} \begin{pmatrix} 0 & 2 & 0 \\ -2 & 0 & \sqrt{6} \\ \sqrt{6} & 0 & 0 \\ 0 & -\sqrt{6} & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$h_{mm'}(k=0) = \langle l=2 m | H | l=2 m' \rangle$$

→ How does {Valence states} decompose into irreps of 432

$432 \subset SO(5) \subset \rho_{l=2}$ is a representation of $SO(3)$

Given a representation of $SO(3)$ $\rho: SO(3) \rightarrow U(V)$

we can construct $\eta: \mathbb{R}^3 \rightarrow U(V)$ by restriction

$$\eta(g \in \mathbb{R}^3) = \rho_{\ell=2}(g) \quad \text{for } g \in \mathbb{R}^3$$

$$\Rightarrow \eta = \rho \downarrow_{\mathbb{R}^3}$$

5d
reducible
rep of $\mathbb{R}^3$

irreducible
5-d rep of $SO(3)$

We can use characters to find how η reduces

$$\chi_{\eta}(g) = \text{tr}[\eta(g)] = \text{tr}[\rho_{\ell=2}(g)]$$

$$\eta(E) = e^{i0} = \begin{pmatrix} 1 & & \\ & 1 & \\ & & 1 \end{pmatrix} \rightarrow \chi_\eta(E) = 5$$

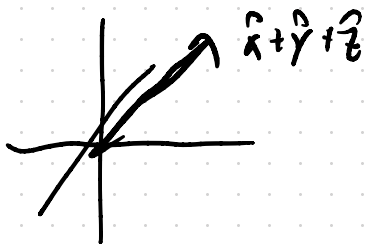
$$\eta(C_{4z}) = e^{-i\frac{\pi}{2}J_z} = \begin{pmatrix} -1 & & \\ & -i & \\ & & 1 & \\ & & & i & \\ & & & & -1 \end{pmatrix} \rightarrow \chi_\eta(C_{4z}) = -1$$

$$\eta(C_{2z}) = e^{-i\pi J_z} = \begin{pmatrix} 1 & & \\ & -1 & \\ & & 1 & \\ & & & -1 & \\ & & & & 1 \end{pmatrix} \rightarrow \chi_\eta(C_{2z}) = +1$$

Trick for the remaining two

$$\chi_\eta(g) = \text{tr}[\rho_{\text{e=2}}(g)] \quad g \in 432$$

$$= \text{tr} \left[\rho_{\ell=2}(g') \rho_{\ell=2}(g) \rho_{\ell=2}(g') \right] \quad \begin{matrix} 30432 \\ g' \in \text{SO}(3) \end{matrix}$$



Fun fact - all rotations by angle θ are conjugate in $\text{SO}(3)$

$$\Rightarrow \text{tr} \left[\rho_{\ell=2}(C_{3, \theta}) \right] = \text{tr} \left[\rho_{\ell=2}(C_{3, \pi/3}) \right]$$

$$= \text{tr} \left[\begin{pmatrix} e^{-4i\pi/3} & & & \\ & e^{-2i\pi/3} & & \\ & & 1 & \\ & & & e^{2i\pi/3} \\ & & & & e^{4i\pi/3} \end{pmatrix} \right] = 1 + 2\cos\frac{2\pi}{3} + 2\cos\frac{4\pi}{3} = -1$$

$$\chi_{\eta}(C_{2, \hat{x}+\hat{y}}) = \chi_{\eta}(C_{2, z}) = +1$$

$$\chi_\eta = \begin{pmatrix} 1 & 4 & 2_{100} & 3 & 2_{110} \\ 5 & -1 & 1 & -1 & 1 \end{pmatrix}$$

Inner product

$$\langle \chi_\eta, \chi_i \rangle = \frac{1}{24} \sum_{g \in G} \chi_\eta^*(g) \chi_i(g)$$

	1	4	2 ₁	3	2 ₁₁₀
A ₁	1	1	1	1	1
A ₂	1	-1	1	1	-1
E	2	0	2	-1	0
T ₂	3	-1	-1	0	1
T ₁	3	1	-1	0	-1

$$\begin{aligned} &= \frac{1}{24} \left[\chi_\eta^*(E) \chi_i(E) + 6 \chi_\eta^*(C_{4z}) \chi_i(C_{4z}) + 3 \chi_\eta^*(C_{2z}) \chi_i(C_{2z}) \right. \\ &\quad \left. + 8 \chi_\eta^*(C_{3z}) \chi_i(C_{3z}) + 6 \chi_\eta^*(C_{2110}) \chi_i(C_{2110}) \right] \end{aligned}$$

$$\langle \chi_\eta, \chi_{A_1} \rangle = \frac{1}{24} (6 + (-6) + 3 - 8 + 6) = 0$$

$$\langle \chi_{\eta}, \chi_{A_2} \rangle = 0$$

$$\langle \chi_{\eta}, \chi_E \rangle = \frac{1}{24} (10 + 6 + 8) = 1$$

$$\langle \chi_{\eta}, \chi_{T_2} \rangle = \frac{1}{24} (15 + 6 - 3 + 6) = 1$$

$$\chi_{\eta} = \chi_E + \chi_{T_2}$$

$$\gamma = \bigoplus_{l=2} \downarrow 432 \cong E \oplus T_2$$

$$\{ |l=2, m\rangle \} \xrightarrow{\text{basis trans}} \{ |1_E\rangle, |2_E\rangle, |1_{T_2}\rangle, |2_{T_2}\rangle \}$$

$$|3T_2\rangle$$

in this basis

$$\eta(g) = \begin{pmatrix} \begin{matrix} 1_E & 2_E \\ \rho_E(g) \end{matrix} & \begin{matrix} 1_{T_2} & 2_{T_2} & 3_{T_2} \\ 0 \end{matrix} \\ \begin{matrix} 0 \end{matrix} & \begin{matrix} \rho_{T_2}(g) \end{matrix} \end{pmatrix} \begin{matrix} 1_E \\ 2_E \\ 1_{T_2} \\ 2_{T_2} \\ 3_{T_2} \end{matrix}$$

$$\langle a_E | H | b_E \rangle = (\epsilon_0 + \epsilon_E) \delta_{ab}$$

$$\langle a_{T_2} | H | b_{T_2} \rangle = (\epsilon_0 + \epsilon_{T_2}) \delta_{ab}$$

Handwritten matrix representation of the Hamiltonian H in the basis of states $|E\rangle, |E_L\rangle, |E_T\rangle, |E_R\rangle$. The matrix is partitioned into four quadrants by a horizontal and vertical line.

Top-Left Quadrant ($|E\rangle, |E_L\rangle$ basis):

- Row 1: $E_0 + E_E$, 0
- Row 2: 0 , $E_0 + E_E$

Top-Right Quadrant ($|E\rangle, |E_L\rangle$ basis vs $|E_T\rangle, |E_R\rangle$ basis):

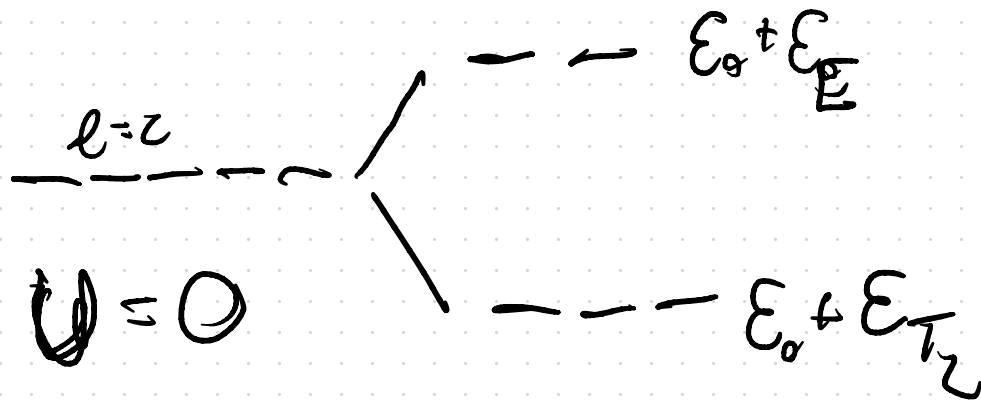
- Row 1: E

Bottom-Left Quadrant ($|E_T\rangle, |E_R\rangle$ basis vs $|E\rangle, |E_L\rangle$ basis):

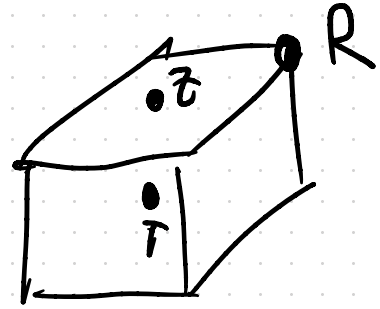
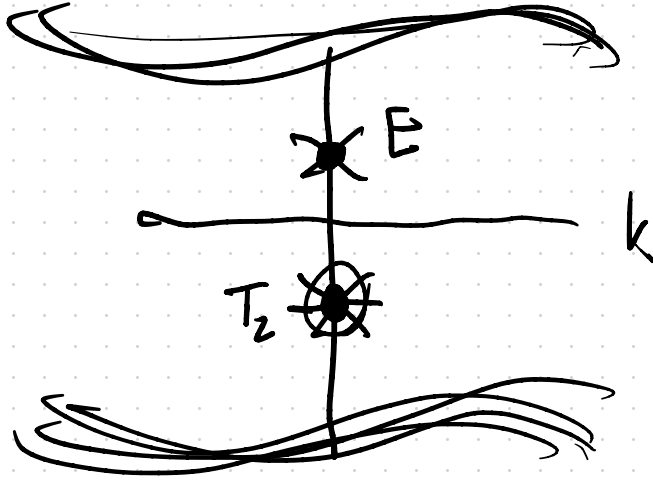
- Row 1: E

Bottom-Right Quadrant ($|E_T\rangle, |E_R\rangle$ basis):

- Row 1: $E_0 + E_T$, 0 , 0
- Row 2: 0 , $E_0 + E_T$, 0
- Row 3: 0 , 0 , $E_0 + E_T$



"Crystal field splitting"

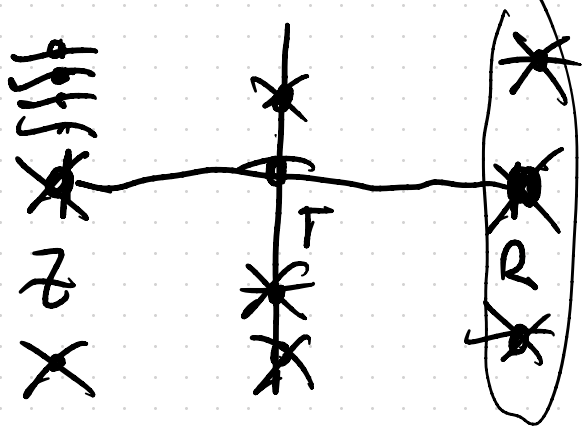


$$G_z \approx P422$$

$$\bar{G}_z = 422$$

ρ	dimension
A_1	1
A_2	1
B_1	1
B_2	1
E	2

can have 1 fold
or twofold degenerate
states



Group theory can fix
the degeneracies of states,
but not their energies

② G_k nonsymmorphic

$$G_k = \bigcup_{i=0}^{n-1} T\{\bar{g}_i | \vec{d}_i\}$$

$$\{\bar{g}_i, i=0, \dots, n-1\} = \bar{G}_k$$

at least one of $\vec{d}_i$ is a fraction of

a Bravais lattice translation

→ there is some $g_a = \{ \bar{g}_a | \vec{d}_a \}$, $\{ \bar{g}_b | \vec{d}_b \} = g_b$

$$g_a g_b = \{ \bar{g}_a \bar{g}_b | \vec{d}_a + \bar{g}_a \vec{d}_b \} = \{ E | \vec{t}_{ab} \} \{ \bar{g}_a \bar{g}_b | \vec{d}_{ab} \}$$

products of coset representative = (nonzero translation)

x another coset representative

Ex: $g_a = g_b = \{ C_{2z} | \frac{1}{2} \hat{z} \}$

$$g_a g_b = \{ E | \hat{z} \} \{ E | \vec{0} \}$$

↳ in any little group representation $e^{-ik \cdot \vec{t}_{ab}}$

$$\rho_k(g_a) \rho_k(g_b) = \rho_k(\{E | t_{ab}\}) \rho_k(\{\bar{g}_a \bar{g}_b | \vec{t}_{ab}\})$$

but in $\bar{G}_k$ $\eta(\bar{g}_a) \eta(\bar{g}_b) = \eta(\bar{g}_a \bar{g}_b)$

To accomodate this: still work $\bar{G}_k$ but generalize
our idea of representations

$$\rho_k: \bar{G}_k \rightarrow U(V)$$

$$\rho_k(\bar{g}_1) \rho_k(\bar{g}_2) = e^{iC(\bar{g}_1, \bar{g}_2)} \rho_k(\bar{g}_1 \bar{g}_2)$$

generalises the homomorphism rule

$$\left(\rho_k(\bar{g}_1) \rho_k(\bar{g}_2) \rho_k(\bar{g}_3) \right) \rightarrow \rho_k(\bar{g}_1) e^{iC(\bar{g}_2, \bar{g}_3)} \rho_k(\bar{g}_2 \bar{g}_3)$$

||

$$e^{iC(\bar{g}_1, \bar{g}_2) + iC(\bar{g}_1, \bar{g}_2 \bar{g}_3)} \rho_k(\bar{g}_1 \bar{g}_2 \bar{g}_3)$$

$$= e^{iC(\bar{g}_1, \bar{g}_2) + iC(\bar{g}_1 \bar{g}_2, \bar{g}_3)} \rho_k(\bar{g}_1 \bar{g}_2 \bar{g}_3)$$

$$C(\bar{g}_1, \bar{g}_2) + C(\bar{g}_1 \bar{g}_2, \bar{g}_3) - C(\bar{g}_2, \bar{g}_3) - C(\bar{g}_1, \bar{g}_2 \bar{g}_3) = 0 \pmod{2\pi}$$

"cocycle condition"

a map $\rho_k: \tilde{G}_k \rightarrow U(V)$ st. $\rho_k(\tilde{g}_1)\rho_k(\tilde{g}_2) = \rho_k(\tilde{g}_1\tilde{g}_2) \cdot \rho_k(\tilde{g}_1, \tilde{g}_2)$

w/ c satisfying the cocycle condition

is called a projective representation

For a nonsymmorphic little group

• Fix a set of coset representatives $\{\bar{g}_i | \vec{d}_i\}$
 $\{\bar{g}_i | \vec{d}_i\} \{\bar{g}_j | \vec{d}_j\} = \{\bar{g}_i \bar{g}_j | \vec{d}_i + \bar{g}_i \vec{d}_j\}$

$$= \{E | t_{ij}\} \{ \bar{g}_i, \bar{g}_j | \vec{d}_{ij} \}$$

$$\vec{t}_{ij} = \bar{g}_i \vec{d}_j + \vec{d}_i - \vec{d}_{ij}$$

$$C(\bar{g}_i, \bar{g}_j) = -k \cdot t_{ij}$$