

Lecture 7 | Reminder: HW 1 is due 9/18 11:59pm  
Derek's office hrs tomorrow 3pm

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Recap: Space groups  $G < E(3)$  rigid symmetries  
of crystals

$$V(\vec{x}) = V(g^{-1}\vec{x}) \quad \text{for all } g \in G$$

Every space group contains a Bravais lattice  $T \trianglelefteq G$

$$T = \{ \{E | \sum n_i \vec{e}_i\}, n_i \in \mathbb{Z} \} \quad \vec{e}_1, \vec{e}_2, \vec{e}_3 \text{ primitive lattice vectors}$$

$$\text{Irreps of } T: \chi_{\vec{k}}(\{E | \vec{t}\}) = e^{-i\vec{k} \cdot \vec{t}}$$

$\vec{b}_i$  - primitive reciprocal lattice vectors  $\vec{b}_i \cdot \vec{e}_j = 2\pi \delta_{ij}$

$\leadsto$  crystal momentum  $\vec{k} = \sum_i \alpha_i \vec{b}_i$   $\alpha_i \in (-\frac{1}{2}, \frac{1}{2}]$  - 1st Brillouin zone

On electronic wavefunctions  $u_{\vec{k}} = e^{-i \frac{\vec{p}}{\hbar} \cdot \vec{r}}$   $\vec{p} = -i \nabla_{\vec{r}}$

Hamiltonian invariant under translations  $[H, u_{\vec{k}}] = 0$  for all  $\vec{k} \in T$

So say we find  $|\Psi_{\vec{k}}\rangle, |\Phi_{\vec{k}'}\rangle$

transforming as  $\rho_{\vec{k}}^{\lambda}, \rho_{\vec{k}'}^{\lambda'}$

Schur's lemma  $\langle \Psi_{\vec{k}} | H | \Phi_{\vec{k}'} \rangle = 0$  if  $\vec{k}$  and  $\vec{k}'$

label different irreps

→ We can diagonalise  $H$  by finding translation eigenstates

Bloch's Theorem

$$\begin{cases} U_{\vec{t}} |\Psi_{n\vec{k}}\rangle = e^{-i\vec{k}\cdot\vec{t}} |\Psi_{n\vec{k}}\rangle & \textcircled{1} \leftarrow \text{transform in the irrep } \rho_{\vec{k}} \text{ of } T \\ H |\Psi_{n\vec{k}}\rangle = E_{n\vec{k}} |\Psi_{n\vec{k}}\rangle & \textcircled{2} \end{cases}$$

$$\langle \vec{r} | \Psi_{n\vec{k}} \rangle = \Psi_{n\vec{k}}(\vec{r})$$

$$\textcircled{1}: \langle \vec{r} | U_{\vec{t}} | \Psi_{n\vec{k}} \rangle = \Psi_{n\vec{k}}(\vec{r} - \vec{t}) = e^{-i\vec{k}\cdot\vec{t}} \Psi_{n\vec{k}}(\vec{r})$$

define  $u_{n\vec{k}}(\vec{r}) = e^{-i\vec{k}\cdot\vec{r}} \Psi_{n\vec{k}}(\vec{r})$

$u_{nk}(\vec{r}-t) = u_{nk}(\vec{r})$  is periodic

②  $H \psi_{nk}(\vec{r}) = E_{nk} \psi_{nk}(\vec{r})$

What other transformations  $g = \{R | \vec{d}\}$  can appear in  $G$   
 $\in \mathbb{R}^3$

Remember  $T \trianglelefteq G$  every pure translation  $\{E | \vec{t}\} \in G$   
should be in  $T$

Suppose  $g = \{R | \vec{d}\} \in G \Rightarrow g^{-1} = \{R^{-1} | -R^{-1}\vec{d}\}$

$$T \trianglelefteq G \ni g \{E|\vec{e}\} g^{-1} \in G$$

$$\begin{aligned} & (\{R|\vec{d}\} \{E|\vec{e}\}) \{R^{-1}|-R^{-1}\vec{d}\} \\ & \approx \{R|\vec{d}+R\vec{e}\} \{R^{-1}|-R^{-1}\vec{d}\} \\ & = \{E|\vec{d}+R\vec{e}-\vec{d}\} = \{E|R\vec{e}\} \in T \end{aligned}$$

$$\begin{aligned} & \{R_1|\vec{d}_1\} \{R_2|\vec{d}_2\} \\ & \approx \{R_1 R_2 |\vec{d}_1 + R_1 \vec{d}_2\} \end{aligned}$$

If  $g = \{R|\vec{d}\} \in G$  then  $R\vec{e} \in T$  for every  $\vec{e} \in T$

Consider  $\varphi(\{R|\vec{d}\}) = R \in O(3)$   $\varphi: G \rightarrow O(3)$

$$\ker \varphi = \{ \{E|\vec{e}\} \in G \} = T$$

$$O(3) > \text{In } \varphi = \{ R \mid \{ R \vec{d} \} \in G \}$$

1st Isomorphism theorem  $G/T \cong \text{In } \varphi = \overline{G} \leftarrow \begin{array}{l} \text{point} \\ \text{group} \\ \text{of } G \end{array}$

$\overline{G} < O(3)$  all the rotation and reflection parts of space group elements

$$R \in \overline{G} \Rightarrow R \vec{t} \in T \text{ for all } \vec{t} \in T$$

Important result: Crystallographic Restriction Theorem

let  $T$  be a Bravais lattice,  $R \in SO(3)$  a rotation  
then if  $R \vec{t} \in T$  for all  $\vec{t} \in T$  then:

$R$  is a rotation by either

|           |             |                      |                     |                     |
|-----------|-------------|----------------------|---------------------|---------------------|
| $0^\circ$ | $180^\circ$ | $\pm 120^\circ$      | $\pm 90^\circ$      | $\pm 60^\circ$      |
| $0$       | $\pi$       | $\pm \frac{2\pi}{3}$ | $\pm \frac{\pi}{2}$ | $\pm \frac{\pi}{3}$ |
| 1-fold    | 2-fold      | 3-fold               | fourfold            | sixfold             |

Proof: let's pick primitive lattice vectors  $\vec{e}_1, \vec{e}_2, \vec{e}_3$

let's pick primitive reciprocal lattice vectors  $\vec{b}_1, \vec{b}_2, \vec{b}_3$   $\vec{b}_i \cdot \vec{e}_j = \delta_{ij}$

$$R \vec{e}_i = \sum_j \vec{e}_j \eta_{ji} \quad \eta_{ji} \in \mathbb{Z}$$

$\eta_{ji} = (\vec{b}_j \cdot R \vec{e}_i) \frac{1}{2\pi i} \equiv R_{ji}$  is a  $3 \times 3$  matrix of integers  
matrix elements of  $R$  in the primitive lattice basis

$$(\hat{x}, \hat{y}, \hat{z}) \xrightarrow{V} (\vec{e}_1, \vec{e}_2, \vec{e}_3)$$

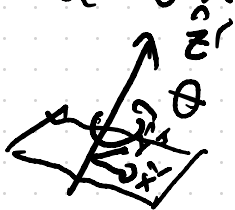
$V$  - change of Basis

$$(\hat{x}, \hat{y}, \hat{z}) \xrightarrow{V^{-1}} \frac{1}{\sqrt{n}} (\vec{b}_1, \vec{b}_2, \vec{b}_3)$$

$$R_{ij} = \underbrace{V[R]V^{-1}}_{\text{Cartesian basis}} \rightarrow \sum_i R_{ji} = \text{tr}[R]$$

$$\textcircled{1} \quad \text{tr} R = \text{tr}[R] = \sum_i R_{ii} \in \mathbb{Z}$$

$\textcircled{2}$  if we go to a basis aligned w/ the axis of rotation



$$R = \begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\text{tr } R = 1 + 2\cos\theta$$

$$\Rightarrow 1 + 2\cos\theta \in \mathbb{Z}$$

$$\Rightarrow 2\cos\theta \in \mathbb{Z}$$

$$\cos\theta = 0, \pm \frac{1}{2}, \pm 1 \rightarrow 0, \pi$$

$$\theta = \pm \frac{\pi}{2} \quad \pm \frac{\pi}{6} \text{ or } \pm \frac{2\pi}{3}$$

$\Rightarrow$  There are only 10 subgroups of  $O(3)$  consistent w/ this theorem [10 are point groups of 2-D lattices]

| Group                 | Hermann-Mauguin | Schönflies Notation |
|-----------------------|-----------------|---------------------|
| trivial group $\{E\}$ | 1               | $C_1$               |
| $\langle C_2 \rangle$ | 2               | $C_2$               |
| $\langle C_3 \rangle$ | 3               | $C_3$               |
| $\langle C_4 \rangle$ | 4               | $C_4$               |
| $\langle C_6 \rangle$ | 6               | $C_6$               |

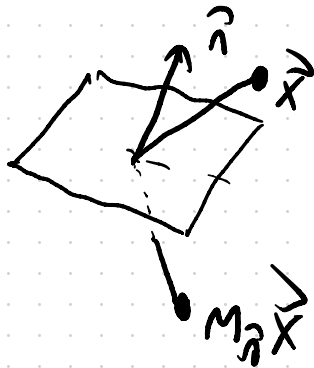
$C_n \hat{r}$  - rotation by angle  $\frac{2\pi}{n}$  about axis  $\hat{r}$

$$(C_n \hat{r})^n = E$$

$\langle \dots \rangle$  - the group generated by ...

We can also look at groups w/ reflection symmetries  
(mirror)

$M_{\hat{n}}$  - reflection about the plane normal to  $\hat{n}$

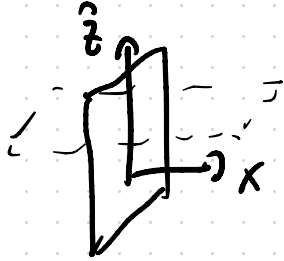


$$M_x: (x, y, z) \rightarrow (-x, y, z)$$

$$M_y: (x, y, z) \rightarrow (x, -y, z)$$

$$M_z: (x, y, z) \rightarrow (x, y, -z)$$

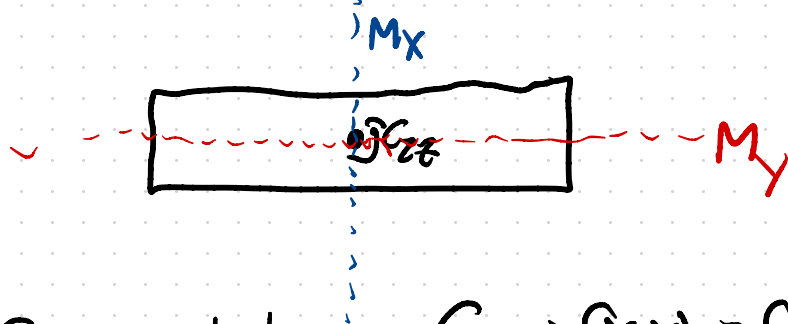
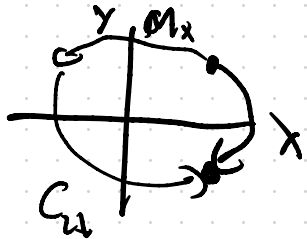
$$\langle M_x \rangle \quad | \quad M \quad | \quad C_s$$

|                               |     |                     |                                                                                   |
|-------------------------------|-----|---------------------|-----------------------------------------------------------------------------------|
| $\langle C_{2z}, M_x \rangle$ | 2mm | $C_{2v}$ "vertical" |  |
| $\langle C_{3z}, M_x \rangle$ | 3m  | $C_{3v}$            |                                                                                   |
| $\langle C_{4z}, M_x \rangle$ | 4mm | $C_{4v}$            |                                                                                   |
| $\langle C_{6z}, M_x \rangle$ | 6mm | $C_{6v}$            |                                                                                   |

# of ms : # of  
conjugacy classes of reflections

Ex: 2mm and 3m

$$2mm \quad \langle C_{2z}, M_x \rangle = \{E, C_{2z}, M_x, \underbrace{C_{2z} M_x = M_y}\}$$



$$C_2 = M_x M_y$$

$$M_y = C_2 M_x$$

$$M_x = C_2 M_y$$

Group is abelian

$$C_2: (x, y) \rightarrow (-x, -y)$$

$$M_x: (x, y) \rightarrow (-x, y)$$

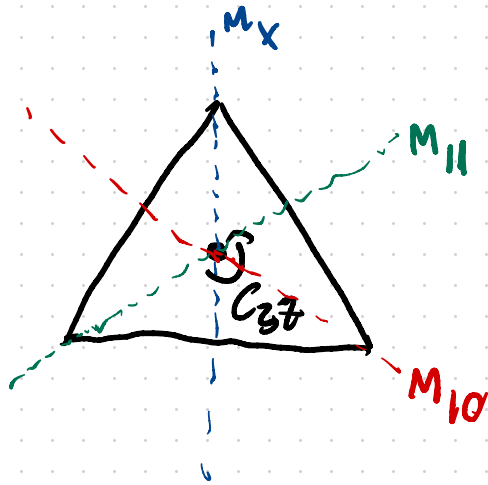
$$M_y: (x, y) \rightarrow (x, -y)$$

$$C_2 M_y C_2^{-1} = M_x$$

$$M_x M_y M_x^{-1} = M_y$$

$M_x$  and  $M_y$  are  
not conjugate to each  
other in  $2mm$

$3m_i$   $\langle C_{3z}, M_x \rangle$  = Symmetries of an equilateral triangle



This group not abelian