

Let us investigate the effect of a change of variables in the $N \times N$ real & symmetric “**covariance matrix**” aka the “**variance matrix**” aka the “**error matrix**” $\hat{V}_{\underline{x}} \equiv E[\underline{R}_{\underline{x}} \underline{R}_{\underline{x}}^T] \equiv E[(\underline{x} - \hat{\underline{x}})(\underline{x} - \hat{\underline{x}})^T]$:

$$\hat{V}_{\underline{x}} \equiv E[\underline{R}_{\underline{x}} \underline{R}_{\underline{x}}^T] \equiv E[(\underline{x} - E[\underline{x}])(\underline{x} - E[\underline{x}])^T] \equiv E[(\underline{x} - \hat{\underline{x}})(\underline{x} - \hat{\underline{x}})^T] = \begin{pmatrix} \sigma_{x_1}^2 & \text{cov}(x_1, x_2) & \dots & \text{cov}(x_1, x_N) \\ \text{cov}(x_2, x_1) & \sigma_{x_2}^2 & \dots & \text{cov}(x_2, x_N) \\ \vdots & \vdots & \ddots & \vdots \\ \text{cov}(x_N, x_1) & \text{cov}(x_N, x_2) & \dots & \sigma_{x_N}^2 \end{pmatrix}$$

Define:

$$\begin{aligned} u_1 &\equiv u_1(x_1, x_2, \dots, x_N) \\ u_2 &\equiv u_2(x_1, x_2, \dots, x_N) \\ &\vdots \\ u_k &\equiv u_k(x_1, x_2, \dots, x_N) \end{aligned} \quad (\text{n.b. for now, we do not **require** that } k \equiv N)$$

We can generically define the **collection** of u_i vectors as a $k \times 1$ matrix:

$$\underline{u} \equiv \underline{u}(\underline{x}) = \underbrace{\begin{pmatrix} u_1(x_1, x_2, \dots, x_N) \\ u_2(x_1, x_2, \dots, x_N) \\ \vdots \\ u_k(x_1, x_2, \dots, x_N) \end{pmatrix}}_{\substack{k \times 1 \\ \text{matrix}}}$$

Let us assume that we can expand each $u_i(x_1, x_2, \dots, x_N)$ vector in a Taylor series about $\hat{\underline{x}}$ and also assume that 2nd order (and all higher order) terms can (safely) be neglected. Then:

$$u_i(x_1, x_2, \dots, x_N) \cong u_i(\hat{x}_1, \hat{x}_2, \dots, \hat{x}_N) + \sum_{j=1}^N \left. \frac{\partial u_i(x_1, x_2, \dots, x_N)}{\partial x_j} \right|_{x_j=\hat{x}_j} (x_j - \hat{x}_j)$$

which we can also symbolically abbreviate as: $\underline{u}(\underline{x}) \cong \underline{u}(\hat{\underline{x}}) + \frac{\partial \underline{u}}{\partial \hat{\underline{x}}}(\underline{x} - \hat{\underline{x}}) = \underline{u}(\hat{\underline{x}}) + \frac{\partial \underline{u}}{\partial \hat{\underline{x}}} \underline{R}_x$

Explicitly writing this out:

$$\underbrace{\begin{pmatrix} u_1(x_1, x_2, \dots, x_N) \\ u_2(x_1, x_2, \dots, x_N) \\ \vdots \\ u_k(x_1, x_2, \dots, x_N) \end{pmatrix}}_{\substack{k \times 1 \\ \text{matrix}}} = \underbrace{\begin{pmatrix} u_1(\hat{x}_1, \hat{x}_2, \dots, \hat{x}_N) \\ u_2(\hat{x}_1, \hat{x}_2, \dots, \hat{x}_N) \\ \vdots \\ u_k(\hat{x}_1, \hat{x}_2, \dots, \hat{x}_N) \end{pmatrix}}_{\substack{k \times 1 \\ \text{matrix}}} + \underbrace{\left(\underbrace{\begin{pmatrix} \left. \frac{\partial u_1(\hat{x}_1, \hat{x}_2, \dots, \hat{x}_N)}{\partial x_1} \right|_{\underline{x}=\hat{\underline{x}}} & \dots & \left. \frac{\partial u_1(\hat{x}_1, \hat{x}_2, \dots, \hat{x}_N)}{\partial x_N} \right|_{\underline{x}=\hat{\underline{x}}} \\ \vdots & \ddots & \vdots \\ \left. \frac{\partial u_k(\hat{x}_1, \hat{x}_2, \dots, \hat{x}_N)}{\partial x_1} \right|_{\underline{x}=\hat{\underline{x}}} & \dots & \left. \frac{\partial u_k(\hat{x}_1, \hat{x}_2, \dots, \hat{x}_N)}{\partial x_N} \right|_{\underline{x}=\hat{\underline{x}}} \end{pmatrix}}_{\substack{k \times N \\ \text{matrix}}} \underbrace{\begin{pmatrix} x_1 - \hat{x}_1 \\ \vdots \\ x_N - \hat{x}_N \end{pmatrix}}_{\substack{N \times 1 \\ \text{matrix}}} \right)_{\substack{k \times 1 \\ \text{matrix}}}$$

The expectation value of $\underline{u} = \underline{u}(\underline{x})$ is also $E[\underline{u}] = E[\underline{u}(\underline{x})] = \underline{u}(E[\underline{x}]) = \underline{u}(\hat{\underline{x}}) \equiv \hat{\underline{u}}$, as we expect.

We can then determine the $k \times k$ **covariance** matrix $\hat{\underline{V}}_{\underline{u}}$ associated with the set of variables

$\underline{u} \equiv \underline{u}(\underline{x})$, defined analogously to those we defined for $\hat{\underline{V}}_{\underline{x}}$:

$$\hat{\underline{V}}_{\underline{u}} \equiv E[\underline{R}_{\underline{u}} \underline{R}_{\underline{u}}^T] \equiv E[(\underline{u} - E[\underline{u}])(\underline{u} - E[\underline{u}])^T] \equiv E[(\underline{u} - \hat{\underline{u}})(\underline{u} - \hat{\underline{u}})^T] = \begin{pmatrix} \sigma_{u_1}^2 & \text{cov}(u_1, u_2) & \dots & \text{cov}(u_1, u_k) \\ \text{cov}(u_2, u_1) & \sigma_{u_2}^2 & \dots & \text{cov}(u_2, u_k) \\ \vdots & \vdots & \ddots & \vdots \\ \text{cov}(u_k, u_1) & \text{cov}(u_k, u_2) & \dots & \sigma_{u_k}^2 \end{pmatrix}$$

where the $k \times 1$ ***u-residual*** vector $\underline{R}_{\underline{u}}$ is defined analogously to that for $\underline{R}_{\underline{x}} \equiv \underline{x} - \hat{\underline{x}}$, i.e. $\underline{R}_{\underline{u}} \equiv \underline{u} - \hat{\underline{u}}$.

The details:

$$\underline{R}_{\underline{u}} \equiv \underbrace{\underline{u}(\underline{x})}_{k \times 1} - \underbrace{E[\underline{u}(\underline{x})]}_{k \times 1} = \underbrace{\underline{u}(\underline{x})}_{k \times 1} - \underbrace{\underline{u}(E[\underline{x}])}_{k \times 1} = \underbrace{\underline{u}(\underline{x})}_{k \times 1} - \underbrace{\underline{u}(\hat{\underline{x}})}_{k \times 1} = \underbrace{\left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}} \right)}_{k \times N} \underbrace{(\underline{x} - \hat{\underline{x}})}_{N \times 1} = \underbrace{\hat{\underline{D}}_{\underline{u}/\underline{x}}}_{k \times N} \underbrace{\underline{R}_{\underline{x}}}_{N \times 1}$$

where we have also defined the $k \times N$ **derivative** matrix $\hat{\underline{D}}_{\underline{u}/\underline{x}}$ and its $N \times k$ transpose $\hat{\underline{D}}_{\underline{u}/\underline{x}}^T$ as:

$$\hat{\underline{D}}_{\underline{u}/\underline{x}} \equiv \left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}} \right) = \underbrace{\begin{pmatrix} \left. \frac{\partial u_1}{\partial x_1} \right|_{\hat{\underline{x}}} & \left. \frac{\partial u_1}{\partial x_2} \right|_{\hat{\underline{x}}} & \dots & \left. \frac{\partial u_1}{\partial x_N} \right|_{\hat{\underline{x}}} \\ \left. \frac{\partial u_2}{\partial x_1} \right|_{\hat{\underline{x}}} & \left. \frac{\partial u_2}{\partial x_2} \right|_{\hat{\underline{x}}} & \dots & \left. \frac{\partial u_2}{\partial x_N} \right|_{\hat{\underline{x}}} \\ \vdots & \vdots & \ddots & \vdots \\ \left. \frac{\partial u_k}{\partial x_1} \right|_{\hat{\underline{x}}} & \left. \frac{\partial u_k}{\partial x_2} \right|_{\hat{\underline{x}}} & \dots & \left. \frac{\partial u_k}{\partial x_N} \right|_{\hat{\underline{x}}} \end{pmatrix}}_{k \times N} \quad \text{and} \quad \hat{\underline{D}}_{\underline{u}/\underline{x}}^T \equiv \left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}} \right)^T = \underbrace{\begin{pmatrix} \left. \frac{\partial u_1}{\partial x_1} \right|_{\hat{\underline{x}}} & \left. \frac{\partial u_2}{\partial x_1} \right|_{\hat{\underline{x}}} & \dots & \left. \frac{\partial u_k}{\partial x_1} \right|_{\hat{\underline{x}}} \\ \left. \frac{\partial u_1}{\partial x_2} \right|_{\hat{\underline{x}}} & \left. \frac{\partial u_2}{\partial x_2} \right|_{\hat{\underline{x}}} & \dots & \left. \frac{\partial u_k}{\partial x_2} \right|_{\hat{\underline{x}}} \\ \vdots & \vdots & \ddots & \vdots \\ \left. \frac{\partial u_1}{\partial x_N} \right|_{\hat{\underline{x}}} & \left. \frac{\partial u_2}{\partial x_N} \right|_{\hat{\underline{x}}} & \dots & \left. \frac{\partial u_k}{\partial x_N} \right|_{\hat{\underline{x}}} \end{pmatrix}}_{N \times k}$$

n.b. The $k \times N$ **derivative** matrix $\hat{\underline{D}}_{\underline{u}/\underline{x}}$ and its $N \times k$ transpose $\hat{\underline{D}}_{\underline{u}/\underline{x}}^T$ are **not symmetric** matrices!

\Rightarrow For $k \times k$ matrices, in general $\hat{\underline{D}}_{\underline{u}/\underline{x}}^T \neq \hat{\underline{D}}_{\underline{u}/\underline{x}}$.

Then:

$$\begin{aligned} \underbrace{\underline{R}_{\underline{u}}}_{k \times 1} \underbrace{\underline{R}_{\underline{u}}^T}_{1 \times k} &\equiv \underbrace{\{\underline{u}(\underline{x}) - E[\underline{u}(\underline{x})]\}}_{k \times 1} \underbrace{\{\underline{u}(\underline{x}) - E[\underline{u}(\underline{x})]\}^T}_{1 \times k} = \underbrace{\{\underline{u}(\underline{x}) - \underline{u}(\hat{\underline{x}})\}}_{k \times 1} \underbrace{\{\underline{u}(\underline{x}) - \underline{u}(\hat{\underline{x}})\}^T}_{1 \times k} \\ &= \underbrace{\left\{ \left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}} \right) (\underline{x} - \hat{\underline{x}}) \right\}}_{k \times 1} \underbrace{\left\{ \left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}} \right) (\underline{x} - \hat{\underline{x}}) \right\}^T}_{1 \times k} = \underbrace{\left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}} \right)}_{k \times N} \underbrace{(\underline{x} - \hat{\underline{x}})}_{N \times 1} \underbrace{(\underline{x} - \hat{\underline{x}})^T}_{1 \times N} \underbrace{\left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}} \right)^T}_{N \times k} \\ &= \underbrace{\hat{\underline{D}}_{\underline{u}/\underline{x}} \underline{R}_{\underline{x}}}_{k \times 1} \underbrace{(\hat{\underline{D}}_{\underline{u}} \underline{R}_{\underline{x}})^T}_{1 \times k} = \underbrace{\hat{\underline{D}}_{\underline{u}/\underline{x}} \underline{R}_{\underline{x}} \underline{R}_{\underline{x}}^T \hat{\underline{D}}_{\underline{u}/\underline{x}}^T}_{k \times k} = \text{a } k \times k \text{ matrix.} \end{aligned}$$

where: $\underline{R}_{\underline{u}} \equiv \hat{\underline{D}}_{\underline{u}/\underline{x}} \underline{R}_{\underline{x}}$ and: $\underline{R}_{\underline{u}}^T \equiv (\hat{\underline{D}}_{\underline{u}/\underline{x}} \underline{R}_{\underline{x}})^T = \underline{R}_{\underline{x}}^T \hat{\underline{D}}_{\underline{u}/\underline{x}}^T$.

n.b. Recall from linear algebra that the **transpose of the product of two matrices A and B** is $(AB)^T = B^T A^T$.

The $k \times k$ **covariance** matrix \hat{V}_u associated with the $\underline{u} \equiv \underline{u}(\underline{x})$ variables can thus be written as:

$$\begin{aligned}\hat{V}_u &\equiv E[\underline{R}_u \underline{R}_u^T] = E[\hat{\underline{D}}_{u/x} \underline{R}_x \{\hat{\underline{D}}_{u/x} \underline{R}_x\}^T] = E[\hat{\underline{D}}_{u/x} \underline{R}_x \underline{R}_x^T \hat{\underline{D}}_{u/x}^T] = \hat{\underline{D}}_{u/x} E[\underline{R}_x \underline{R}_x^T] \hat{\underline{D}}_{u/x}^T \\ &\equiv E\left[(\underline{u} - E[\underline{u}])(\underline{u} - E[\underline{u}])^T\right] \equiv E\left[(\underline{u} - \hat{\underline{u}})(\underline{u} - \hat{\underline{u}})^T\right] \\ &= E\left[\underbrace{\left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}}\right)}_{k \times N} \underbrace{(\underline{x} - \hat{\underline{x}})}_{N \times 1} \underbrace{(\underline{x} - \hat{\underline{x}})^T}_{1 \times N} \underbrace{\left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}}\right)^T}_{N \times k}\right] = \underbrace{\left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}}\right)}_{k \times N} E\left[\underbrace{(\underline{x} - \hat{\underline{x}})(\underline{x} - \hat{\underline{x}})^T}_{N \times N}\right] \underbrace{\left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}}\right)^T}_{N \times k} \\ &= \begin{pmatrix} \sigma_{u_1}^2 & \text{cov}(u_1, u_2) & \dots & \text{cov}(u_1, u_k) \\ \text{cov}(u_2, u_1) & \sigma_{u_2}^2 & \dots & \text{cov}(u_2, u_k) \\ \vdots & \vdots & \ddots & \vdots \\ \text{cov}(u_k, u_1) & \text{cov}(u_k, u_2) & \dots & \sigma_{u_k}^2 \end{pmatrix} = \text{a } k \times k \text{ matrix.}\end{aligned}$$

Note that in the last step of the 1st and 3rd rows above, we took advantage of the fact that the $k \times N$ **derivative** matrix $\hat{\underline{D}}_{u/x} \equiv \left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}}\right) = \left(\frac{\partial \underline{u}}{\partial \underline{x}}\right)_{x=\hat{\underline{x}}}$ and its $N \times k$ transpose $\hat{\underline{D}}_{u/x}^T \equiv \left(\frac{\partial \underline{u}}{\partial \hat{\underline{x}}}\right)^T = \left(\frac{\partial \underline{u}}{\partial \underline{x}}\right)_{x=\hat{\underline{x}}}^T$ are just sets of **numbers** (constants!), i.e. they are no longer **functions** of the random variables x_i .

Now, since the $N \times N$ **covariance matrix** $\hat{V}_x \equiv E[\underline{R}_x \underline{R}_x^T] \equiv E[(\underline{x} - \hat{\underline{x}})(\underline{x} - \hat{\underline{x}})^T]$ is:

$$\begin{aligned}\hat{V}_x &\equiv E[\underline{R}_x \underline{R}_x^T] \equiv E[(\underline{x} - E[\underline{x}])(\underline{x} - E[\underline{x}])^T] \equiv E[(\underline{x} - \hat{\underline{x}})(\underline{x} - \hat{\underline{x}})^T] \\ &= \begin{pmatrix} \sigma_{x_1}^2 & \text{cov}(x_1, x_2) & \dots & \text{cov}(x_1, x_N) \\ \text{cov}(x_2, x_1) & \sigma_{x_2}^2 & \dots & \text{cov}(x_2, x_N) \\ \vdots & \vdots & \ddots & \vdots \\ \text{cov}(x_N, x_1) & \text{cov}(x_N, x_2) & \dots & \sigma_{x_N}^2 \end{pmatrix}\end{aligned}$$

The $k \times k$ **covariance matrix** \hat{V}_u can then be compactly written as:

$$\hat{V}_u \equiv E[\underline{R}_u \underline{R}_u^T] = E[\hat{\underline{D}}_{u/x} \underline{R}_x \{\hat{\underline{D}}_{u/x} \underline{R}_x\}^T] = E[\hat{\underline{D}}_{u/x} \underline{R}_x \underline{R}_x^T \hat{\underline{D}}_{u/x}^T] = \hat{\underline{D}}_{u/x} \underbrace{E[\underline{R}_x \underline{R}_x^T]}_{\equiv \hat{V}_x} \hat{\underline{D}}_{u/x}^T = \hat{\underline{D}}_{u/x} \hat{V}_x \hat{\underline{D}}_{u/x}^T$$

Important note:

In various probability & statistics textbooks, the covariance matrix equation is instead written as $\hat{V}_u = \hat{\underline{D}}_{u/x}' \hat{V}_x \hat{\underline{D}}_{u/x}'$. A detailed comparison of $\hat{V}_u = \hat{\underline{D}}_{u/x}' \hat{V}_x \hat{\underline{D}}_{u/x}'$ with the above derivation of $\hat{V}_u = \hat{\underline{D}}_{u/x} \hat{V}_x \hat{\underline{D}}_{u/x}^T$ shows that the two seemingly different/contradictory relations **are** indeed equivalent, because $\hat{\underline{D}}_{u/x} = \hat{\underline{D}}_{u/x}'$ and $\hat{\underline{D}}_{u/x}^T = \hat{\underline{D}}_{u/x}'$! The origin of the two differing conventions can be traced back to the respective **definitions** of the **residual** matrices as a **column** vector ($N \times 1$ matrix) $\underline{R}_x \equiv (\underline{x} - \hat{\underline{x}})$ vs. a **row** vector ($1 \times N$ matrix) $\underline{R}_x' \equiv (\underline{x} - \hat{\underline{x}})$ in the formation of the **outer product** for the $N \times N$ covariance matrix $\hat{V}_x \equiv E[\underline{R}_x \underline{R}_x^T] = E[\underline{R}_x'^T \underline{R}_x']$, i.e. $\underline{R}_x = \underline{R}_x'^T$ and $\underline{R}_x^T = \underline{R}_x'$.

Explicitly writing out this relation, long-hand, it is:

$$\hat{\underline{V}}_{\underline{u}} = \underbrace{\begin{pmatrix} \sigma_{u_1}^2 & \text{cov}(u_1, u_2) & \dots & \text{cov}(u_1, u_k) \\ \text{cov}(u_2, u_1) & \sigma_{u_2}^2 & \dots & \text{cov}(u_2, u_k) \\ \vdots & \vdots & \ddots & \vdots \\ \text{cov}(u_k, u_1) & \text{cov}(u_k, u_2) & \dots & \sigma_{u_k}^2 \end{pmatrix}}_{k \times k} \underbrace{\begin{pmatrix} \sigma_{x_1}^2 & \text{cov}(x_1, x_2) & \dots & \text{cov}(x_1, x_N) \\ \text{cov}(x_2, x_1) & \sigma_{x_2}^2 & \dots & \text{cov}(x_2, x_N) \\ \vdots & \vdots & \ddots & \vdots \\ \text{cov}(x_N, x_1) & \text{cov}(x_N, x_2) & \dots & \sigma_{x_N}^2 \end{pmatrix}}_{N \times N} \underbrace{\begin{pmatrix} \frac{\partial u_1}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_1}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_1}{\partial x_N} \Big|_{\hat{x}} \\ \frac{\partial u_2}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_2}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_2}{\partial x_N} \Big|_{\hat{x}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial u_k}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_k}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_k}{\partial x_N} \Big|_{\hat{x}} \end{pmatrix}}_{k \times N} \underbrace{\begin{pmatrix} \frac{\partial u_1}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_1}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_1}{\partial x_N} \Big|_{\hat{x}} \\ \frac{\partial u_2}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_2}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_2}{\partial x_N} \Big|_{\hat{x}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial u_k}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_k}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_k}{\partial x_N} \Big|_{\hat{x}} \end{pmatrix}}_{N \times k}^T$$

For the common case of N **independent** variables x_1, x_2, \dots, x_N **and** N **functions** u_1, u_2, \dots, u_N all of the **covariances** vanish, thus things simplify, and we then have, in explicit, long-hand notation:

$$\hat{\underline{V}}_{\underline{x}} = \underbrace{\begin{pmatrix} \sigma_{x_1}^2 & 0 & \dots & 0 \\ 0 & \sigma_{x_2}^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_{x_N}^2 \end{pmatrix}}_{N \times N}$$

So:

$$\hat{\underline{V}}_{\underline{u}} = \underbrace{\begin{pmatrix} \sigma_{u_1}^2 & \text{cov}(u_1, u_2) & \dots & \text{cov}(u_1, u_N) \\ \text{cov}(u_2, u_1) & \sigma_{u_2}^2 & \dots & \text{cov}(u_2, u_N) \\ \vdots & \vdots & \ddots & \vdots \\ \text{cov}(u_N, u_1) & \text{cov}(u_N, u_2) & \dots & \sigma_{u_N}^2 \end{pmatrix}}_{N \times N} \underbrace{\begin{pmatrix} \sigma_{x_1}^2 & 0 & \dots & 0 \\ 0 & \sigma_{x_2}^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_{x_N}^2 \end{pmatrix}}_{N \times N} \underbrace{\begin{pmatrix} \frac{\partial u_1}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_1}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_1}{\partial x_N} \Big|_{\hat{x}} \\ \frac{\partial u_2}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_2}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_2}{\partial x_N} \Big|_{\hat{x}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial u_k}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_k}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_k}{\partial x_N} \Big|_{\hat{x}} \end{pmatrix}}_{N \times N} \underbrace{\begin{pmatrix} \frac{\partial u_1}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_1}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_1}{\partial x_N} \Big|_{\hat{x}} \\ \frac{\partial u_2}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_2}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_2}{\partial x_N} \Big|_{\hat{x}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial u_k}{\partial x_1} \Big|_{\hat{x}} & \frac{\partial u_k}{\partial x_2} \Big|_{\hat{x}} & \dots & \frac{\partial u_k}{\partial x_N} \Big|_{\hat{x}} \end{pmatrix}}_{N \times N}^T$$

For the case of N **independent** random variables x_1, x_2, \dots, x_N **and** N **functions** u_1, u_2, \dots, u_N the $N \times N$ **covariance** matrix $\hat{\underline{V}}_u$ has diagonal elements of the form:

$$\left(\hat{\underline{V}}_u\right)_{kk} = \text{cov}(u_k, u_k) = \text{var}(u_k) = \sigma_{u_k}^2 = \sum_{i=1}^N \left(\left. \frac{\partial u_k(x_i)}{\partial x_i} \right|_{x_i=\hat{x}_i} \right)^2 \sigma_{x_i}^2 \quad \text{for } k=1, 2, \dots, N$$

which agrees with the corresponding Taylor series derivation on p. 5 of P598AEM Lect. Notes 5.

In addition, the $N \times N$ **covariance** matrix $\hat{\underline{V}}_u$ **also** has non-zero **off**-diagonal elements of the form:

$$\left(\hat{\underline{V}}_u\right)_{k\ell} = \text{cov}(u_k, u_\ell) = \sum_{i=1}^N \left(\left. \frac{\partial u_k(x_i)}{\partial x_i} \right|_{x_i=\hat{x}_i} \right) \sigma_{x_i}^2 \left(\left. \frac{\partial u_\ell(x_i)}{\partial x_i} \right|_{x_i=\hat{x}_i} \right) \quad \text{for } k \neq \ell = 1, 2, \dots, N$$

which need **not** be zero! The transformation from $x \rightarrow u$ has **induced** correlations between the **new** random variables u_i even though the **original** x_i variables were **independent**!!!

A simple example of $\hat{\underline{V}}_u = \hat{\underline{D}}_{u/x} \hat{\underline{V}}_x \hat{\underline{D}}_{u/x}^T = \left(\frac{\partial \underline{u}}{\partial \underline{\hat{x}}} \right) \hat{\underline{V}}_x \left(\frac{\partial \underline{u}}{\partial \underline{\hat{x}}} \right)^T$:

Let x_1 and x_2 be **independent** random variables. Let $u_1 \equiv \frac{1}{\sqrt{2}}(x_1 - x_2)$ and $u_2 \equiv \frac{1}{\sqrt{2}}(x_1 + x_2)$.

Assume that we are given the \underline{x} -basis **covariance** matrix $\hat{\underline{V}}_x = \begin{pmatrix} \sigma_{x_1}^2 & 0 \\ 0 & \sigma_{x_2}^2 \end{pmatrix}$

Then: $\hat{\underline{D}}_{u/x} = \left(\frac{\partial \underline{u}}{\partial \underline{\hat{x}}} \right) = \begin{pmatrix} \left. \frac{\partial u_1}{\partial x_1} \right|_{\hat{x}_1} & \left. \frac{\partial u_1}{\partial x_2} \right|_{\hat{x}_2} \\ \left. \frac{\partial u_2}{\partial x_1} \right|_{\hat{x}_1} & \left. \frac{\partial u_2}{\partial x_2} \right|_{\hat{x}_2} \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$

And: $\hat{\underline{D}}_{u/x}^T = \left(\frac{\partial \underline{u}}{\partial \underline{\hat{x}}} \right)^T = \begin{pmatrix} \left. \frac{\partial u_1}{\partial x_1} \right|_{\hat{x}_1} & \left. \frac{\partial u_1}{\partial x_2} \right|_{\hat{x}_2} \\ \left. \frac{\partial u_2}{\partial x_1} \right|_{\hat{x}_1} & \left. \frac{\partial u_2}{\partial x_2} \right|_{\hat{x}_2} \end{pmatrix}^T = \begin{pmatrix} \left. \frac{\partial u_1}{\partial x_1} \right|_{\hat{x}_1} & \left. \frac{\partial u_2}{\partial x_1} \right|_{\hat{x}_1} \\ \left. \frac{\partial u_1}{\partial x_2} \right|_{\hat{x}_2} & \left. \frac{\partial u_2}{\partial x_2} \right|_{\hat{x}_2} \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} = \left(\frac{\partial \underline{u}}{\partial \underline{\hat{x}}} \right)^T \neq \hat{\underline{D}}_u \text{ (here)}$

So:

$$\begin{aligned} \hat{\underline{V}}_u &= \hat{\underline{D}}_{u/x} \hat{\underline{V}}_x \hat{\underline{D}}_{u/x}^T = \left(\frac{\partial \underline{u}}{\partial \underline{\hat{x}}} \right) \hat{\underline{V}}_x \left(\frac{\partial \underline{u}}{\partial \underline{\hat{x}}} \right)^T = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \sigma_{x_1}^2 & 0 \\ 0 & \sigma_{x_2}^2 \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \\ &= \frac{1}{2} \begin{pmatrix} \sigma_{x_1}^2 + \sigma_{x_2}^2 & \sigma_{x_1}^2 - \sigma_{x_2}^2 \\ \sigma_{x_1}^2 - \sigma_{x_2}^2 & \sigma_{x_1}^2 + \sigma_{x_2}^2 \end{pmatrix} = \begin{pmatrix} \frac{1}{2}(\sigma_{x_1}^2 + \sigma_{x_2}^2) & \frac{1}{2}(\sigma_{x_1}^2 - \sigma_{x_2}^2) \\ \frac{1}{2}(\sigma_{x_1}^2 - \sigma_{x_2}^2) & \frac{1}{2}(\sigma_{x_1}^2 + \sigma_{x_2}^2) \end{pmatrix} = \begin{pmatrix} \sigma_{u_1}^2 & \text{cov}(u_1, u_2) \\ \text{cov}(u_2, u_1) & \sigma_{u_2}^2 \end{pmatrix} \end{aligned}$$

Thus in **general** u_1 and u_2 are **not independent** {b/c $\text{cov}(u_1, u_2) = \frac{1}{2}(\sigma_{x_1}^2 - \sigma_{x_2}^2) \neq 0$ } **unless** $\sigma_{x_1} \equiv \sigma_{x_2}$.

A Numerical Example:

Suppose the **1-sigma uncertainty** on x_1 is $\sigma_{x_1} = 5$ and the **1-sigma uncertainty** on x_2 is $\sigma_{x_2} = 3$.

The 2×2 **covariance** matrix associated with the transformation $u_1 \equiv \frac{1}{\sqrt{2}}(x_1 - x_2)$, $u_2 \equiv \frac{1}{\sqrt{2}}(x_1 + x_2)$ is:

$$\hat{V}_{\underline{u}} = \begin{pmatrix} \sigma_{u_1}^2 & \text{cov}(u_1, u_2) \\ \text{cov}(u_2, u_1) & \sigma_{u_2}^2 \end{pmatrix} = \begin{pmatrix} \frac{1}{2}(\sigma_{x_1}^2 + \sigma_{x_2}^2) & \frac{1}{2}(\sigma_{x_1}^2 - \sigma_{x_2}^2) \\ \frac{1}{2}(\sigma_{x_1}^2 - \sigma_{x_2}^2) & \frac{1}{2}(\sigma_{x_1}^2 + \sigma_{x_2}^2) \end{pmatrix} = \begin{pmatrix} \frac{1}{2}(25+9) & \frac{1}{2}(25-9) \\ \frac{1}{2}(25-9) & \frac{1}{2}(25+9) \end{pmatrix} = \begin{pmatrix} 17 & 8 \\ 8 & 17 \end{pmatrix}$$

Thus the **1-sigma uncertainty** on $u_1 = \frac{1}{\sqrt{2}}(x_1 - x_2)$ is: $\sigma_{u_1} = \sqrt{17} = 4.1231$

and the **1-sigma uncertainty** on $u_2 = \frac{1}{\sqrt{2}}(x_1 + x_2)$ is: $\sigma_{u_2} = \sqrt{17} = 4.1231 = \sigma_{u_1}$

However, even though (here) $\sigma_{u_1} \equiv \sigma_{u_2} = \sqrt{17} = 4.1231$, the random variables u_1 and u_2 are **not** independent – they are (positively) correlated with each other, because:

$$\text{cov}(u_1, u_2) = \text{cov}(u_2, u_1) = \frac{1}{2}(\sigma_{x_1}^2 - \sigma_{x_2}^2) = 8 > 0$$

or, equivalently:

$$\rho(u_1, u_2) = \frac{\text{cov}(u_1, u_2)}{\sigma_{u_1} \sigma_{u_2}} = \frac{8}{17} = 0.4706.$$

Undoing the Error Propagation:

Inverting this transformation, we have: $x_1 \equiv \frac{1}{\sqrt{2}}(u_1 + u_2)$ and $x_2 \equiv \frac{1}{\sqrt{2}}(-u_1 + u_2)$.

Let us (temporarily) pretend to **ignore** correlations, i.e. treat u_1 and u_2 as if they **were** independent.

We **would** then obtain:

$$\sigma_{x_1}^2 = \left(\frac{\partial x_1}{\partial u_1} \right)^2 \sigma_{u_1}^2 + \left(\frac{\partial x_1}{\partial u_2} \right)^2 \sigma_{u_2}^2 = \frac{1}{2} \cdot 17 + \frac{1}{2} \cdot 17 = 17 \Rightarrow \sigma_{x_1} = \sqrt{17} = 4.1231$$

$$\sigma_{x_2}^2 = \left(\frac{\partial x_2}{\partial u_1} \right)^2 \sigma_{u_1}^2 + \left(\frac{\partial x_2}{\partial u_2} \right)^2 \sigma_{u_2}^2 = \frac{1}{2} \cdot 17 + \frac{1}{2} \cdot 17 = 17 \Rightarrow \sigma_{x_2} = \sqrt{17} = 4.1231 = \sigma_{x_1}$$

These results are clearly wrong !!! (Since we initially stated that $\sigma_{x_1} = 5$ and $\sigma_{x_2} = 3$!!!)

The (correct) **inverse** transformation, using matrices is: $\hat{V}_{\underline{x}} \equiv \underline{D}_{x/u} \hat{V}_{\underline{u}} \underline{D}_{x/u}^T \equiv \left(\frac{\partial \underline{x}}{\partial \underline{u}} \right) \hat{V}_{\underline{u}} \left(\frac{\partial \underline{x}}{\partial \underline{u}} \right)^T$

where:

$$\underline{D}_{x/u} \equiv \left(\frac{\partial \underline{x}}{\partial \underline{u}} \right) = \begin{pmatrix} \frac{\partial x_1}{\partial u_1} & \frac{\partial x_1}{\partial u_2} \\ \frac{\partial x_2}{\partial u_1} & \frac{\partial x_2}{\partial u_2} \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \Rightarrow \underline{D}_{x/u}^T \equiv \left(\frac{\partial \underline{x}}{\partial \underline{u}} \right)^T = \begin{pmatrix} \frac{\partial x_1}{\partial u_1} & \frac{\partial x_2}{\partial u_1} \\ \frac{\partial x_1}{\partial u_2} & \frac{\partial x_2}{\partial u_2} \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \neq \underline{D}_{x/u}$$

Then:

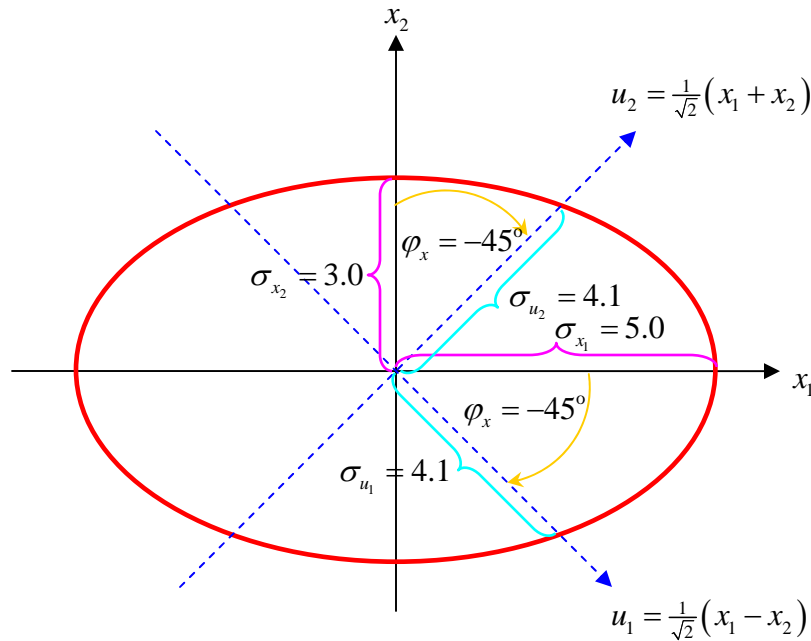
$$\begin{aligned}\hat{\underline{V}}_{\underline{x}} &= \underline{D}_{x/u} \hat{\underline{V}}_{\underline{u}} \underline{D}_{x/u}^T = \left(\frac{\partial \underline{x}}{\partial \underline{u}} \right) \hat{\underline{V}}_{\underline{u}} \left(\frac{\partial \underline{x}}{\partial \underline{u}} \right)^T = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 17 & 8 \\ 8 & 17 \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \\ &= \frac{1}{2} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 25 & -9 \\ 25 & 9 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 50 & 0 \\ 0 & 18 \end{pmatrix} = \begin{pmatrix} 25 & 0 \\ 0 & 9 \end{pmatrix} = \begin{pmatrix} \sigma_{x_1}^2 & 0 \\ 0 & \sigma_{x_2}^2 \end{pmatrix}\end{aligned}$$

Thus, we see via the use of the above matrix formalism, that we indeed (correctly) recover the original $\sigma_{x_1} = 5$ and $\sigma_{x_2} = 3$, i.e. the random variables x_1 and x_2 **are independent**.

The above simple example(s) of a change of (**orthonormal**) variables can be easily understood as a simple change of **orthonormal basis vectors** – from the **independent** random variables x_1 and x_2 to the **non-independent** random variables u_1 and u_2 via the **orthonormal transformation** $u_1 \equiv \frac{1}{\sqrt{2}}(x_1 - x_2)$, $u_2 \equiv \frac{1}{\sqrt{2}}(x_1 + x_2)$ and/or the **inverse orthonormal transformation** $x_1 \equiv \frac{1}{\sqrt{2}}(u_1 + u_2)$, $x_2 \equiv \frac{1}{\sqrt{2}}(-u_1 + u_2)$.

(n.b. both of these orthonormal transformations are from RH \rightarrow RH coordinate systems...)

The $x \rightarrow u$ orthonormal transformation is a consequence of applying a $\varphi_x = -45^\circ$ (CW) rotation in the $x_1 - x_2$ plane, as shown by the red ellipse in the figure below:



n.b. we also see from the elliptical symmetry associated with the above figure that $\sigma_{u_1} = \sigma_{u_2} \cong 4.1$ simply because of the **specific** choice of the $\varphi = -45^\circ$ (CW) rotation in the 2-D $x_1 - x_2$ plane, resulting in the $u_1 - u_2$ basis vectors each having **equal** projections onto the $x_1 - x_2$ basis vectors. Had we instead chosen an **arbitrary** φ -rotation in the 2-D $x_1 - x_2$ plane, then in general $\sigma_{u_1} \neq \sigma_{u_2}$.

For an *arbitrary* φ_x -rotation of \underline{x} -basis vectors:

$$\begin{aligned} u_1 &= x_1 \cos \varphi_x + x_2 \sin \varphi_x \\ u_2 &= -x_1 \sin \varphi_x + x_2 \cos \varphi_x \end{aligned} \Rightarrow \underbrace{\begin{pmatrix} u_1 \\ u_2 \end{pmatrix}}_{\equiv \underline{u}} = \underbrace{\begin{pmatrix} x_1 \cos \varphi_x + x_2 \sin \varphi_x \\ -x_1 \sin \varphi_x + x_2 \cos \varphi_x \end{pmatrix}}_{\equiv \underline{R}_x} = \underbrace{\begin{pmatrix} \cos \varphi_x & \sin \varphi_x \\ -\sin \varphi_x & \cos \varphi_x \end{pmatrix}}_{\equiv \underline{R}_x} \underbrace{\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}}_{\equiv \underline{x}} \Rightarrow \underline{u} = \underline{R}_x \underline{x}$$

The *inverse* φ_u -rotation transformation of \underline{u} -basis vectors is (also) given by:

$$\begin{aligned} x_1 &= u_1 \cos \varphi_u + u_2 \sin \varphi_u \\ x_2 &= -u_1 \sin \varphi_u + u_2 \cos \varphi_u \end{aligned} \Rightarrow \underbrace{\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}}_{\equiv \underline{x}} = \underbrace{\begin{pmatrix} u_1 \cos \varphi_u + u_2 \sin \varphi_u \\ -u_1 \sin \varphi_u + u_2 \cos \varphi_u \end{pmatrix}}_{\equiv \underline{R}_u^{-1}} = \underbrace{\begin{pmatrix} \cos \varphi_u & \sin \varphi_u \\ -\sin \varphi_u & \cos \varphi_u \end{pmatrix}}_{\equiv \underline{R}_u^{-1}} \underbrace{\begin{pmatrix} u_1 \\ u_2 \end{pmatrix}}_{\equiv \underline{u}} \Rightarrow \underline{x} = \underline{R}_u^{-1} \underline{u}$$

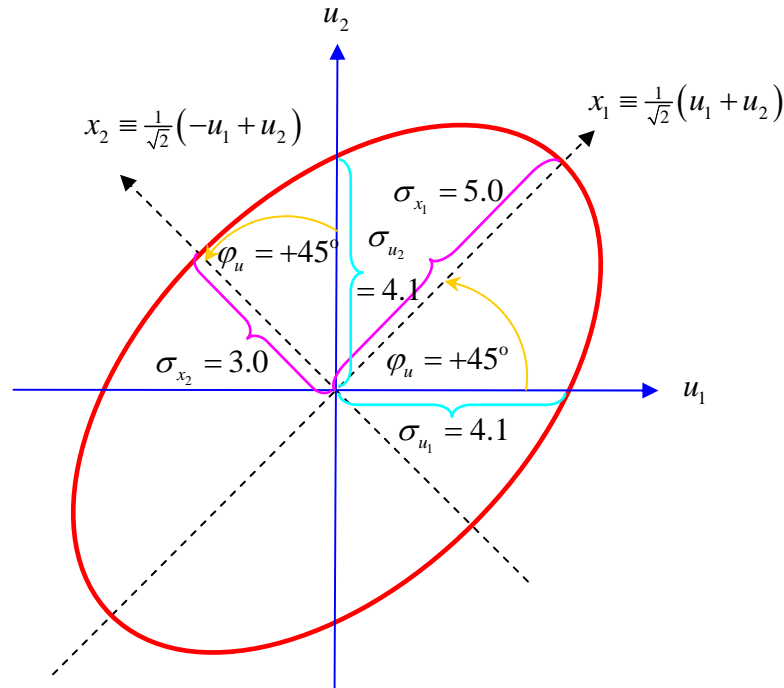
But note that $\varphi_u \equiv -\varphi_x$ ($= +45^\circ$ here), thus we can re-write the *inverse* φ_u -rotation transformation as:

$$\begin{aligned} x_1 &= u_1 \cos \varphi_x - u_2 \sin \varphi_x \\ x_2 &= u_1 \sin \varphi_x + u_2 \cos \varphi_x \end{aligned} \Rightarrow \underbrace{\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}}_{\equiv \underline{x}} = \underbrace{\begin{pmatrix} u_1 \cos \varphi_x - u_2 \sin \varphi_x \\ u_1 \sin \varphi_x + u_2 \cos \varphi_x \end{pmatrix}}_{\equiv \underline{R}_x^{-1}} = \underbrace{\begin{pmatrix} \cos \varphi_x & -\sin \varphi_x \\ \sin \varphi_x & \cos \varphi_x \end{pmatrix}}_{\equiv \underline{R}_x^{-1}} \underbrace{\begin{pmatrix} u_1 \\ u_2 \end{pmatrix}}_{\equiv \underline{u}} \Rightarrow \underline{x} = \underline{R}_x^{-1} \underline{u}$$

with:

$$\underline{R}_x \underline{R}_x^{-1} = \begin{pmatrix} \cos \varphi_x & \sin \varphi_x \\ -\sin \varphi_x & \cos \varphi_x \end{pmatrix} \begin{pmatrix} \cos \varphi_x & -\sin \varphi_x \\ \sin \varphi_x & \cos \varphi_x \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \underline{\mathbb{1}} = \begin{pmatrix} \cos \varphi_x & -\sin \varphi_x \\ \sin \varphi_x & \cos \varphi_x \end{pmatrix} \begin{pmatrix} \cos \varphi_x & \sin \varphi_x \\ -\sin \varphi_x & \cos \varphi_x \end{pmatrix} = \underline{R}_x^{-1} \underline{R}_x$$

Graphically, the *inverse* $u \rightarrow x$ orthonormal transformation for a $\varphi_u = +45^\circ$ (CCW) rotation is shown by the red ellipse in the figure below:



The equation for the red ellipse, expressed in terms of the **independent** random variable $x_1 - x_2$ **orthonormal** basis vectors is given by:

$$\frac{x_1^2}{\sigma_{x_1}^2} + \frac{x_2^2}{\sigma_{x_2}^2} = 1 \Rightarrow (x_1 \ x_2) \begin{pmatrix} 1/\sigma_{x_1}^2 & 0 \\ 0 & 1/\sigma_{x_2}^2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 1$$

Note that the matrix $\begin{pmatrix} 1/\sigma_{x_1}^2 & 0 \\ 0 & 1/\sigma_{x_2}^2 \end{pmatrix}$ is the **inverse** of the \underline{x} -basis **variance** matrix $\hat{\underline{V}}_{\underline{x}} = \begin{pmatrix} \sigma_{x_1}^2 & 0 \\ 0 & \sigma_{x_2}^2 \end{pmatrix}$:

$$\begin{pmatrix} \sigma_{x_1}^2 & 0 \\ 0 & \sigma_{x_2}^2 \end{pmatrix} \begin{pmatrix} 1/\sigma_{x_1}^2 & 0 \\ 0 & 1/\sigma_{x_2}^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \underline{\mathbb{1}} = \begin{pmatrix} 1/\sigma_{x_1}^2 & 0 \\ 0 & 1/\sigma_{x_2}^2 \end{pmatrix} \begin{pmatrix} \sigma_{x_1}^2 & 0 \\ 0 & \sigma_{x_2}^2 \end{pmatrix}$$

Which can be written compactly as: $\hat{\underline{V}}_{\underline{x}} \hat{\underline{V}}_{\underline{x}}^{-1} = \underline{\mathbb{1}} = \hat{\underline{V}}_{\underline{x}}^{-1} \hat{\underline{V}}_{\underline{x}}$ where $\underline{\mathbb{1}}$ is the unit matrix, and thus we can also write the above \underline{x} -basis ellipse equation compactly as:

$$\frac{x_1^2}{\sigma_{x_1}^2} + \frac{x_2^2}{\sigma_{x_2}^2} = 1 \Rightarrow (x_1 \ x_2) \begin{pmatrix} 1/\sigma_{x_1}^2 & 0 \\ 0 & 1/\sigma_{x_2}^2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 1 \Rightarrow \underline{x}^T \hat{\underline{V}}_{\underline{x}}^{-1} \underline{x} = 1$$

The equation for the red ellipse, expressed in terms of the **non-independent** random variable $u_1 - u_2$ **orthonormal** basis vectors is given by:

$$\frac{u_1^2}{\sigma_{u_1}^2} + \frac{u_2^2}{\sigma_{u_2}^2} - \frac{2u_1u_2\rho(u_1, u_2)}{\sigma_{u_1}\sigma_{u_2}} = 1 \Rightarrow (u_1 \ u_2) \frac{1}{1-\rho^2(u_1, u_2)} \begin{pmatrix} \frac{1}{\sigma_{u_1}^2} & -\frac{\rho(u_1, u_2)}{\sigma_{u_1}\sigma_{u_2}} \\ -\frac{\rho(u_1, u_2)}{\sigma_{u_1}\sigma_{u_2}} & \frac{1}{\sigma_{u_2}^2} \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = 1$$

$$\text{where } \rho(u_1, u_2) \equiv \frac{\text{cov}(u_1, u_2)}{\sigma_{u_1}\sigma_{u_2}}$$

Here, the matrix $\hat{\underline{V}}_{\underline{u}}^{-1} \equiv \frac{1}{1-\rho^2(u_1, u_2)} \begin{pmatrix} 1/\sigma_{u_1}^2 & -\rho(u_1, u_2)/\sigma_{u_1}\sigma_{u_2} \\ -\rho(u_1, u_2)/\sigma_{u_1}\sigma_{u_2} & 1/\sigma_{u_2}^2 \end{pmatrix}$ is the **inverse** of the

\underline{u} -basis **covariance** matrix $\hat{\underline{V}}_{\underline{u}} = \begin{pmatrix} \sigma_{u_1}^2 & \text{cov}(u_1, u_2) \\ \text{cov}(u_2, u_1) & \sigma_{u_2}^2 \end{pmatrix} = \begin{pmatrix} \sigma_{u_1}^2 & \sigma_{u_1}\sigma_{u_2}\rho(u_1, u_2) \\ \sigma_{u_2}\sigma_{u_1}\rho(u_2, u_1) & \sigma_{u_2}^2 \end{pmatrix}$:

$$\begin{aligned}
& \begin{pmatrix} \sigma_{u_1}^2 & \sigma_{u_1}\sigma_{u_2}\rho(u_1, u_2) \\ \sigma_{u_1}\sigma_{u_2}\rho(u_1, u_2) & \sigma_{u_2}^2 \end{pmatrix} \frac{1}{1-\rho^2(u_1, u_2)} \begin{pmatrix} 1/\sigma_{u_1}^2 & -\rho(u_1, u_2)/\sigma_{u_1}\sigma_{u_2} \\ -\rho(u_1, u_2)/\sigma_{u_1}\sigma_{u_2} & 1/\sigma_{u_2}^2 \end{pmatrix} \\
&= \frac{1}{1-\rho^2(u_1, u_2)} \begin{pmatrix} 1-\rho^2(u_1, u_2) & \cancel{-\sigma_{u_1}\rho(u_1, u_2)/\sigma_{u_2} + \sigma_{u_1}\rho(u_1, u_2)/\sigma_{u_2}} \\ \cancel{\sigma_{u_2}\rho(u_1, u_2)/\sigma_{u_1} - \sigma_{u_2}\rho(u_1, u_2)/\sigma_{u_1}} & 1-\rho^2(u_1, u_2) \end{pmatrix} \\
&= \frac{1}{1-\rho^2(u_1, u_2)} \begin{pmatrix} 1-\rho^2(u_1, u_2) & 0 \\ 0 & 1-\rho^2(u_1, u_2) \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \underline{\underline{1}}
\end{aligned}$$

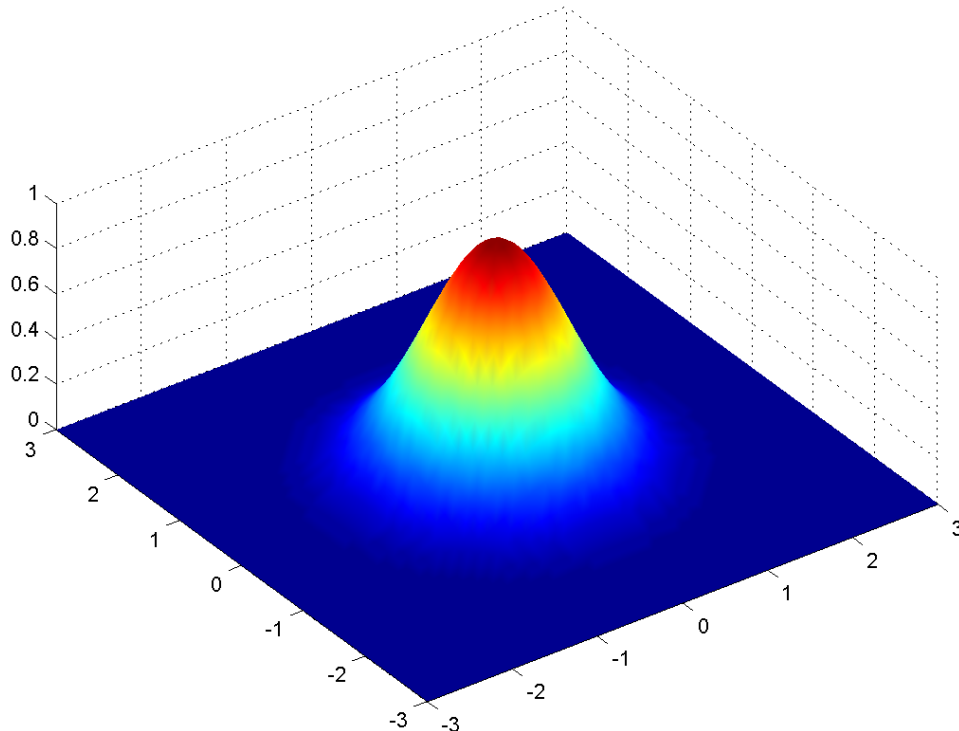
which can be written compactly as: $\hat{\underline{\underline{V}}}_{\underline{\underline{u}}} \hat{\underline{\underline{V}}}_{\underline{\underline{u}}}^{-1} = \underline{\underline{1}} = \hat{\underline{\underline{V}}}_{\underline{\underline{u}}}^{-1} \hat{\underline{\underline{V}}}_{\underline{\underline{u}}}$ and thus we can also write the above $\underline{\underline{u}}$ -basis ellipse equation compactly as:

$$\frac{u_1^2}{\sigma_{u_1}^2} + \frac{u_2^2}{\sigma_{u_2}^2} - \frac{2u_1u_2\rho(u_1, u_2)}{\sigma_{u_1}\sigma_{u_2}} = 1 \Rightarrow \underline{\underline{u}}^T \hat{\underline{\underline{V}}}_{\underline{\underline{u}}}^{-1} \underline{\underline{u}} = 1$$

If the P.D.F. associated with the *independent* random variables x_1 and x_2 is the Gaussian/normal distribution, *i.e.*

$$G(x_1, x_2) = G(x_1) \cdot G(x_2) = \frac{1}{\sqrt{2\pi} \sigma_{x_1}} e^{-\frac{x_1^2}{2\sigma_{x_1}^2}} \cdot \frac{1}{\sqrt{2\pi} \sigma_{x_2}} e^{-\frac{x_2^2}{2\sigma_{x_2}^2}} = \frac{1}{2\pi \sigma_{x_1} \sigma_{x_2}} e^{-\left[\frac{x_1^2}{2\sigma_{x_1}^2} + \frac{x_2^2}{2\sigma_{x_2}^2}\right]}$$

The 3-D surface associated with the 2-D Gaussian/normal probability distribution $G(x_1, x_2)$ is shown in the figure below (for the special/limiting case of $\sigma_{x_1} = \sigma_{x_2}$):



We see that contours of constant/equal probability density are (in general) ellipses in the 2-D $x_1 - x_2$ plane, where the argument of the exponential is equal to a constant, i.e.

$$\left[\frac{x_1^2}{2\sigma_{x_1}^2} + \frac{x_2^2}{2\sigma_{x_2}^2} \right] = \text{constant}$$

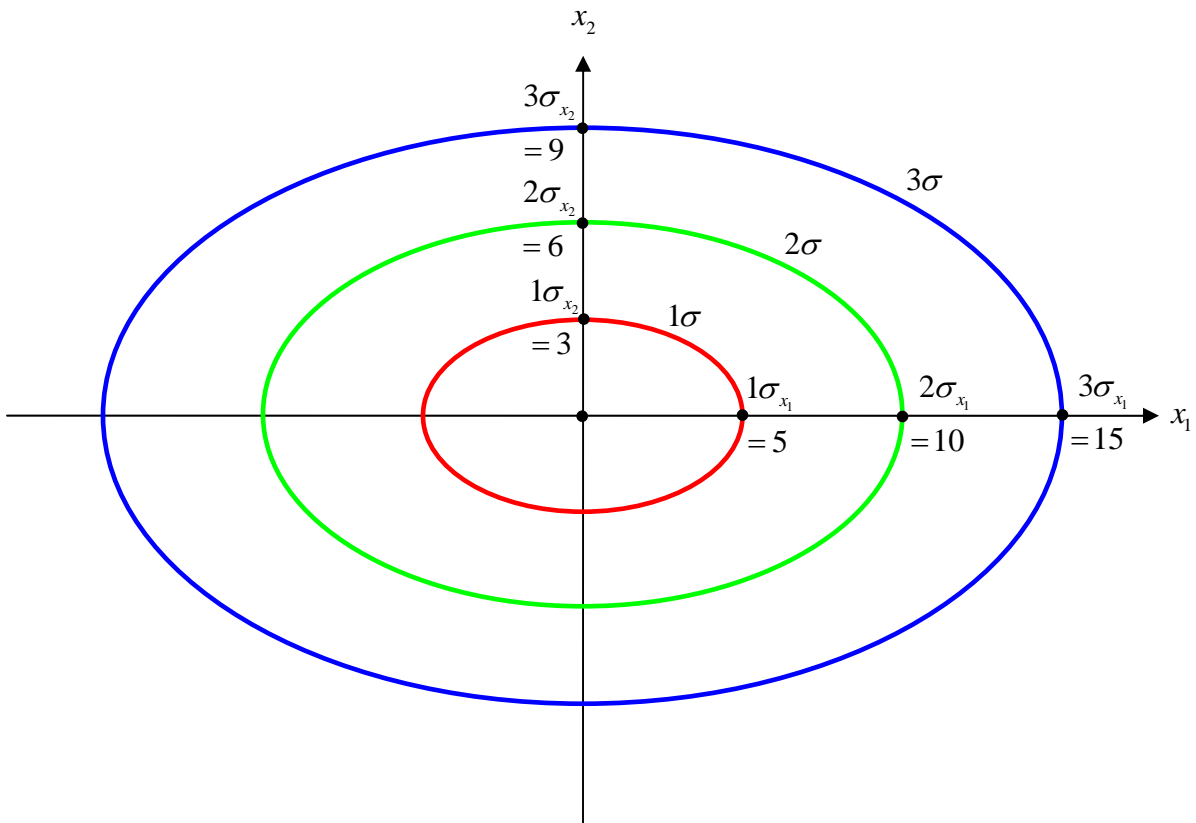
At the points $(x_1, x_2) = (\pm\sigma_{x_1}, 0)$ and/or $(x_1, x_2) = (0, \pm\sigma_{x_2})$ on the ellipse curve in the 2-D $x_1 - x_2$ plane, we see that constant = 1/2 (true for any value of (x_1, x_2) lying on this particular ellipse)

and thus we see that the equation of an ellipse for which $\left[\frac{x_1^2}{2\sigma_{x_1}^2} + \frac{x_2^2}{2\sigma_{x_2}^2} \right] = \frac{1}{2}$ associated with the above 2-D Gaussian/normal P.D.F. $G(x_1, x_2)$, corresponds to a 1-sigma (= 1 standard deviation) contour (*aka* 1-sigma “equipotential”) of constant/equal probability density.

Similarly, e.g. for an arbitrary # of (integer) sigma/standard deviations, i.e. $n_\sigma = 1, 2, 3, 4, 5, \dots$

this corresponds to contours associated with equation of ellipses for which $\left[\frac{x_1^2}{2\sigma_{x_1}^2} + \frac{x_2^2}{2\sigma_{x_2}^2} \right] = \frac{n_\sigma^2}{2}$

is satisfied, as shown in the figure below:



For the Gaussian/normal P.D.F. associated with the **dependent** random variables

$$u_1 \equiv \frac{1}{\sqrt{2}}(x_1 - x_2) \text{ and } u_2 \equiv \frac{1}{\sqrt{2}}(x_1 + x_2):$$

$$G(u_1, u_2) = \frac{1}{2\pi \sigma_{u_1} \sigma_{u_2}} \frac{1}{\sqrt{1 - \rho^2(u_1, u_2)}} e^{-\left[\frac{1}{2[1 - \rho^2(u_1, u_2)]} \left(\frac{u_1^2}{\sigma_{u_1}^2} + \frac{u_2^2}{\sigma_{u_2}^2} - \frac{2u_1 u_2 \rho(u_1, u_2)}{\sigma_{u_1} \sigma_{u_2}} \right) \right]} \text{ where } \rho(u_1, u_2) \equiv \frac{\text{cov}(u_1, u_2)}{\sigma_{u_1} \sigma_{u_2}}$$

{ This is the general form of a 2-D Gaussian distribution in two variables, including correlations }

Then we see that contours of constant/equal probability density are indeed ellipses in the 2-D $u_1 - u_2$ plane, where the argument of the exponential is equal to a constant, i.e.

$$\left[\frac{1}{2[1 - \rho^2(u_1, u_2)]} \left(\frac{u_1^2}{\sigma_{u_1}^2} + \frac{u_2^2}{\sigma_{u_2}^2} - \frac{2u_1 u_2 \rho(u_1, u_2)}{\sigma_{u_1} \sigma_{u_2}} \right) \right] = \text{constant}$$

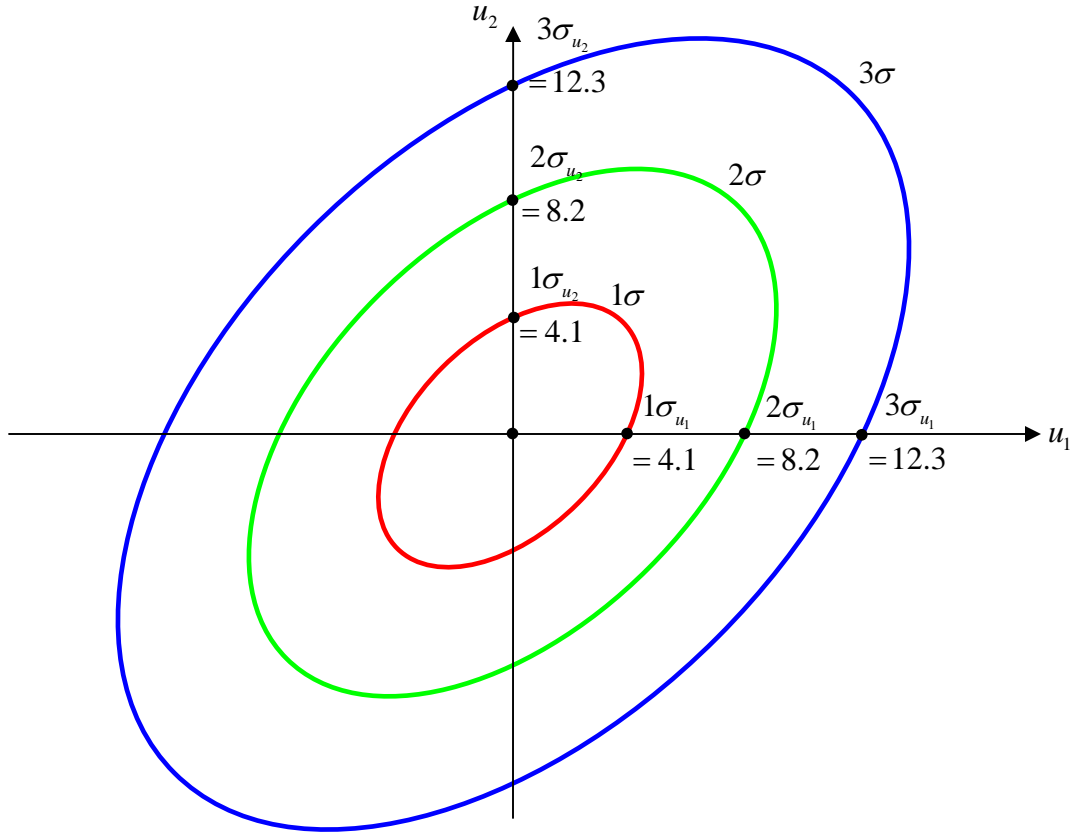
At the points $(u_1, u_2) = (\pm\sigma_{u_1}, 0)$ and/or $(u_1, u_2) = (0, \pm\sigma_{u_2})$ on the ellipse curve in the 2-D $u_1 - u_2$ plane, we see that constant = 1/2 (true for any value of (u_1, u_2) lying on this particular ellipse) and thus we see that the equation of an ellipse for which

$$\left[\frac{1}{2[1 - \rho^2(u_1, u_2)]} \left(\frac{u_1^2}{\sigma_{u_1}^2} + \frac{u_2^2}{\sigma_{u_2}^2} - \frac{2u_1 u_2 \rho(u_1, u_2)}{\sigma_{u_1} \sigma_{u_2}} \right) \right] = \frac{1}{2} \text{ associated with the above 2-D}$$

Gaussian/normal P.D.F. $G(u_1, u_2)$, corresponds to a 1-sigma (= 1 standard deviation) contour (aka 1-sigma “equipotential”) of constant/equal probability density for this distribution.

Similarly, e.g. for an arbitrary # of (integer) sigma/standard deviations, i.e. $n_\sigma = 1, 2, 3, 4, 5, \dots$ this corresponds to contours associated with equation of ellipses for which

$$\left[\frac{1}{2[1 - \rho^2(u_1, u_2)]} \left(\frac{u_1^2}{\sigma_{u_1}^2} + \frac{u_2^2}{\sigma_{u_2}^2} - \frac{2u_1 u_2 \rho(u_1, u_2)}{\sigma_{u_1} \sigma_{u_2}} \right) \right] = \frac{n_\sigma^2}{2} \text{ is satisfied, as shown in the figure below:}$$



Note from the above discussion(s), for k **independent** random variables that we can also write the Gaussian P.D.F. in matrix notation as:

$$G(x_1, x_2, \dots, x_k) = G(x_1) \cdot G(x_2) \dots G(x_k) = \frac{1}{(2\pi)^{k/2} \prod_{i=1}^k \sigma_{x_i}} e^{-\frac{1}{2} \sum_{i=1}^k \frac{x_i^2}{\sigma_{x_i}^2}} = \frac{1}{(2\pi)^{k/2} |\underline{V}_x|^{1/2}} e^{-\frac{1}{2} \underline{x}^T \hat{\underline{V}}_x^{-1} \underline{x}}$$

For k **dependent** random variables, the Gaussian P.D.F. in matrix notation is:

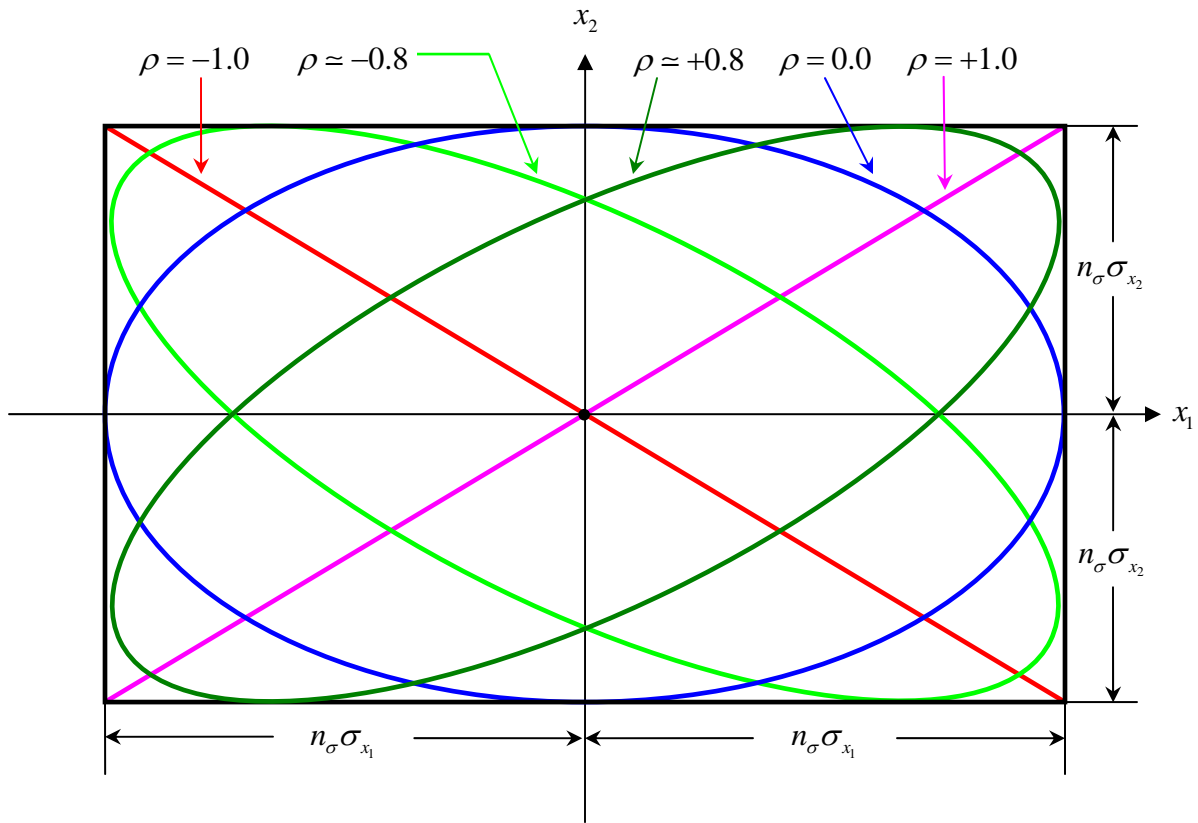
$$G(u_1, u_2, \dots, u_k) = \frac{1}{(2\pi)^{k/2} \prod_{i,j=1}^k \sigma_{u_i} \sigma_{u_j} \sqrt{1 - \rho^2(u_i, u_j)}} e^{-\frac{1}{2} \sum_{i,j=1}^k \left[\frac{1}{1 - \rho^2(u_i, u_j)} \left(\frac{u_i^2}{\sigma_{u_i}^2} + \frac{u_j^2}{\sigma_{u_j}^2} - \frac{2u_i u_j \rho(u_i, u_j)}{\sigma_{u_i} \sigma_{u_j}} \right) \right]} = \frac{1}{(2\pi)^{k/2} |\underline{V}_u|^{1/2}} e^{-\frac{1}{2} \underline{u}^T \hat{\underline{V}}_u^{-1} \underline{u}}$$

In the figure below, for a given n_σ ellipse contour, we show the effect of varying the correlation

coefficient $-1 \leq \rho(x_1, x_2) \equiv \frac{\text{cov}(x_1, x_2)}{\sigma_{u_1} \sigma_{u_2}} \leq +1$ between its upper/lower limits in the general n_σ

ellipse equation:
$$\left[\frac{1}{2} \frac{1}{1 - \rho^2(u_1, u_2)} \left(\frac{u_1^2}{\sigma_{u_1}^2} + \frac{u_2^2}{\sigma_{u_2}^2} - \frac{2u_1 u_2 \rho(u_1, u_2)}{\sigma_{u_1} \sigma_{u_2}} \right) \right] = \frac{n_\sigma^2}{2}$$

e.g. for the $G(x_1, x_2)$ P.D.F., when x_1 and x_2 in general are *dependent* random variables:



Note that *each* of the n_σ ellipses in the above figure touch/are tangent to the sides of an enclosing rectangular box of dimensions $2n_\sigma\sigma_{x_1} \times 2n_\sigma\sigma_{x_2}$. The above n_σ ellipse equation(s), used in conjunction with the 4 straight-line equations that describe each of the four sides of the enclosing rectangular box can be solved simultaneously to determine the tangent/intersection point(s) of a given ellipse with the enclosing rectangular box.