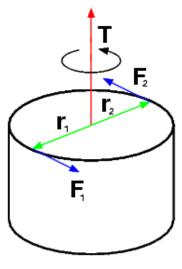
### Statics - TAM 210 & TAM 211

Lecture 9 February 5, 2018

### Announcements

- ☐ Upcoming deadlines:
- Tuesday (2/6)
  - PL Homework 3
- Quiz 2 (2/7-9)
  - Reserve testing time at CBTF
  - Lectures 5-9
- Friday (2/9)
  - Mastering Engineering Tutorial 5



https://fr.wikipedia.org/wiki/Couple\_(physique)



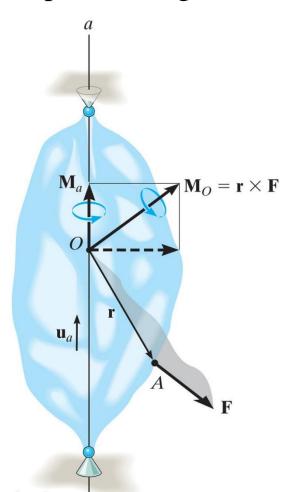
## Chapter 4: Force System Resultants

Goals and Objectives Moment being represented

- Discuss the concept of the moment of a force and show how to M = 7 x F calculate it in two and three dimensions
- How to find the moment about a specified axis  $M_{\alpha}$
- Define the moment of a couple
- Finding <u>equivalence force and moment systems</u>
- Reduction of <u>distributed loading</u>

# Recap: Moment of a force about a specified axis (Scalar Triple Product)

The <u>magnitude</u> of the projected moment about any generic axis *a* can be computed using the scalar triple product:



$$\left| \overrightarrow{\boldsymbol{M}_{a}} \right| = \overrightarrow{\boldsymbol{u}_{a}} \cdot \left( \overrightarrow{\boldsymbol{r}} \times \overrightarrow{\boldsymbol{F}} \right)$$

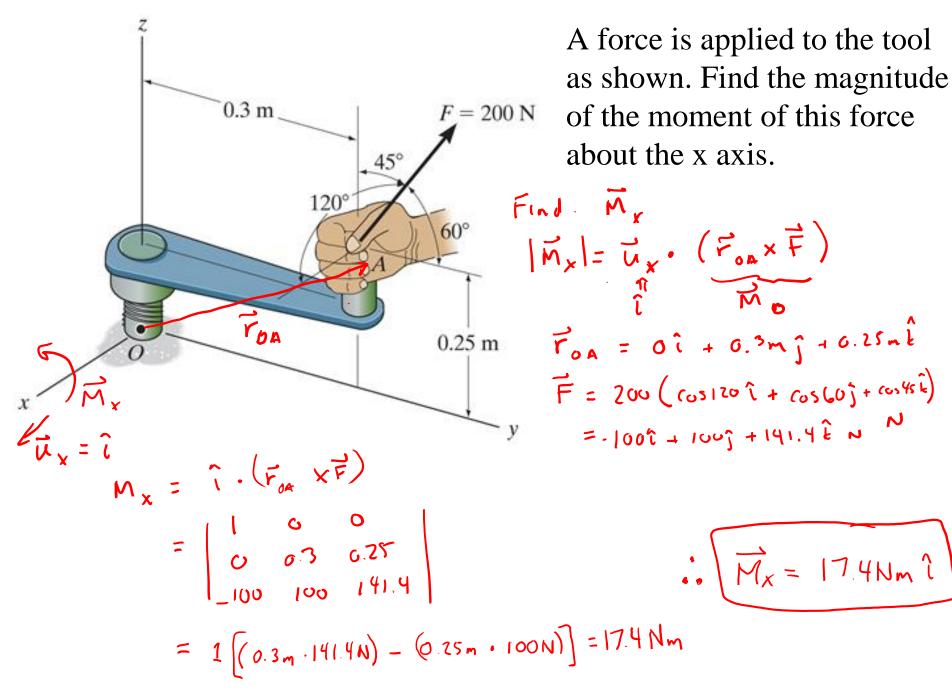
$$= \begin{vmatrix} u_{a_{x}} & u_{a_{y}} & u_{a_{z}} \\ r_{x} & r_{y} & r_{z} \\ F_{x} & F_{y} & F_{z} \end{vmatrix}$$

The <u>direction</u> of the projected moment about any generic axis *a* can be defined using :

$$\overline{M_a} = \left| \overline{M_a} \right| \overline{u_a}$$

where  $\overrightarrow{u_a}$  is the unit vector along axis a

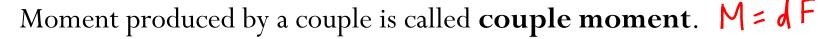
Axis of projection-



### Moment of a couple

**Couple:** two parallel forces that have same magnitude, but opposite directions, and are separated by a perpendicular distance *d*.

- Resultant force is zero.  $\vec{F}_{\kappa} = \vec{F} + (-\vec{F}) = 0$
- Couple produces actual rotation, or if no movement is possible, tendency of rotation in a specified direction.



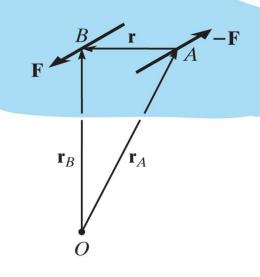
Sum of moments of both couple forces about **any** arbitrary point:

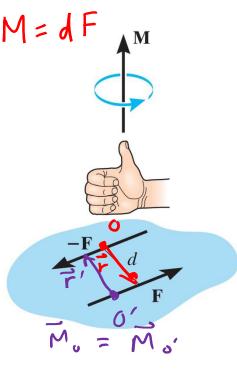
$$\overrightarrow{M} = (\overrightarrow{r_B} \times \overrightarrow{F}) + (\overrightarrow{r_A} \times (-\overrightarrow{F}))$$

$$= (\overrightarrow{r_B} - \overrightarrow{r_A}) \times \overrightarrow{F}$$

$$= \overrightarrow{r} \times \overrightarrow{F}$$

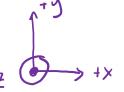
Couple moment is a **free vector**, i.e. is **independent** of the choice of O!



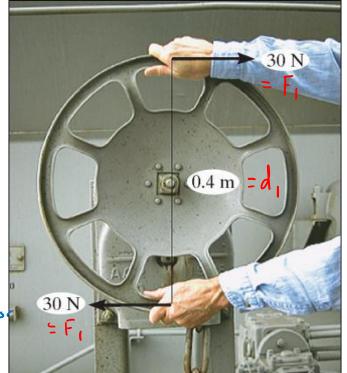


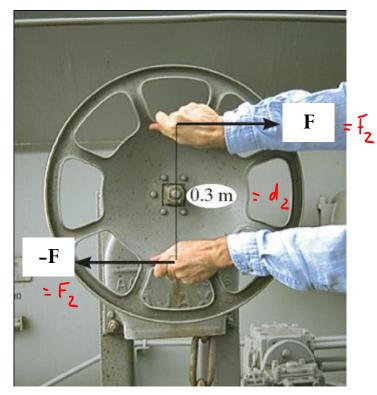
### Equivalent couples

Define (soldinate Frame



Notation for representing a vector pointing perpendicular (in or out of s (reen)





in Elike arrow

A torque or moment of 12 N·m is required to rotate the wheel.

Would F be greater or less than 30 N?

$$M_1 = d_1 F_1 = (0.4 \text{ m})(30 \text{ N})$$
 $M_2 = -12 \text{ Nm } \hat{k}$ 

$$M_2 = -12 \text{ Nm } \text{ M}_2 = d_2 \text{ F}$$
 $12 \text{ Nm} = 0.3 \text{ m} \text{ F}$ 
 $F = 40 \text{ N}$ 
 $F = 40 \text{ N}$ 

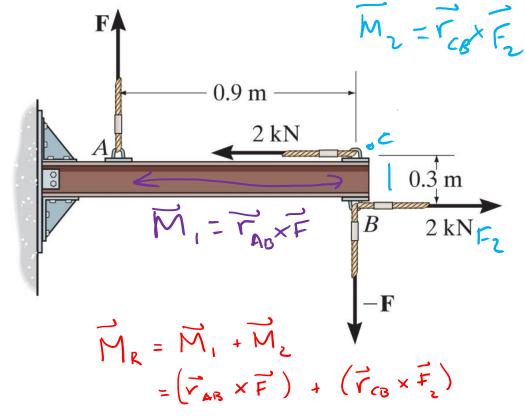
### Resultant Couple Moment

Since couple moments are vectors, their resultant is due to vector addition:

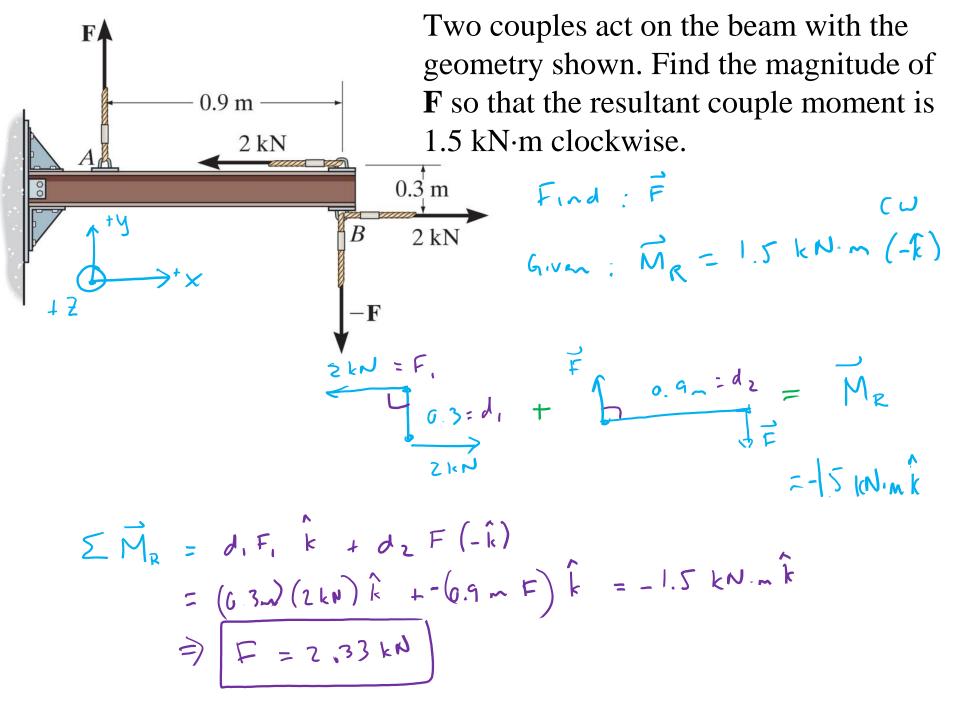
$$\overrightarrow{M_R} = \overrightarrow{M_1} + \overrightarrow{M_2} + \cdots$$

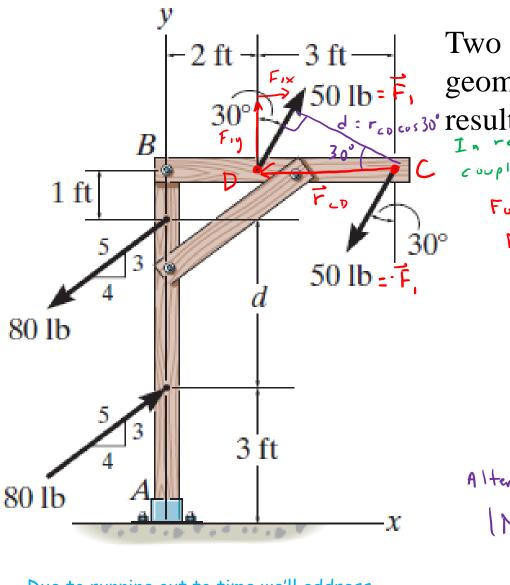
$$= \Sigma \overrightarrow{M_i}$$

$$= \Sigma \left(\overrightarrow{r} \times \overrightarrow{F}\right)$$



Note that MR, since it is a free vector, can be placed anywhere on the beam.





Due to running out to time, we'll address the typed problem statement in our next lecture. Hint to find  $M_R$ , need to also determine  $M_{lower}$ , such that  $M_R = M_{upper} + M_{lower}$ 

Two couples act on the beam with the geometry shown and d = 4 ft. Find the d: rco cos 30' resultant couple

In response to student question about couple moment when is not I to F: For upper beam, what is the Moment due to the solb force Couple? Find: Mupper Mupper = FXF = FCD XF,  $= (-3142) \times 50 (510,30)$ t < 0303 )16 = - 130 ft.15 k |Mupper| = dF where dis\_ distance Alternatively, =(|rcol cos 30° f1) (50 16) = (3 cos 30°) 50 ft.16 = 130 st. 16 ccu (-k) Mupper = - 130ft 16 k / same