

Statics - TAM 211

Lecture 5

September 19, 2018

Announcements

☐ Upcoming deadlines:

- Friday (Sept 21)
 - Written Assignment 1
 - Find on [Schedule](#)
 - You can SCAN your WA at RC
 - Submit on Blackboard
- Tuesday (9/26)
 - Prairie Learn HW2



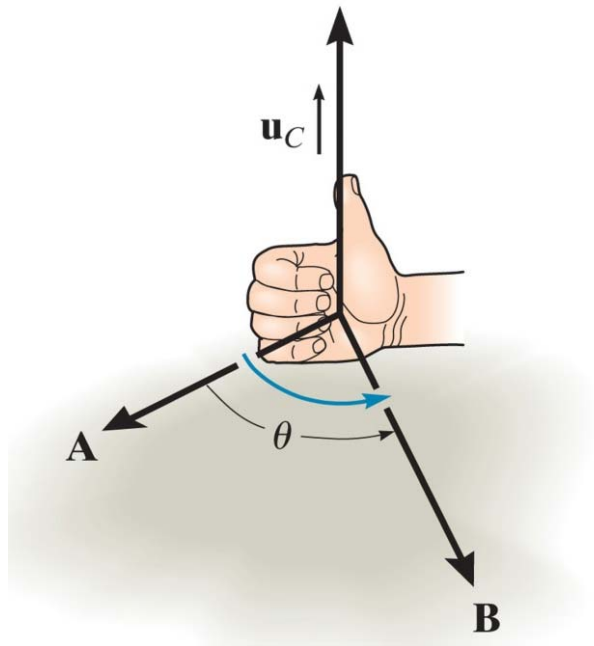
Recap of Lecture 4

- Position vectors
- Force vector directed along a line
- Dot (scalar) product

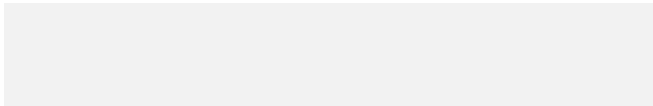
Cross (or vector) product

The cross product of vectors \mathbf{A} and \mathbf{B} yields the vector \mathbf{C} , which is written

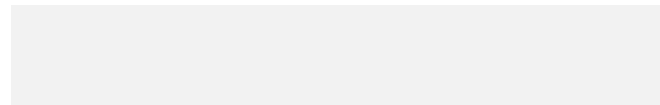
$$\mathbf{C} = \mathbf{A} \times \mathbf{B}$$



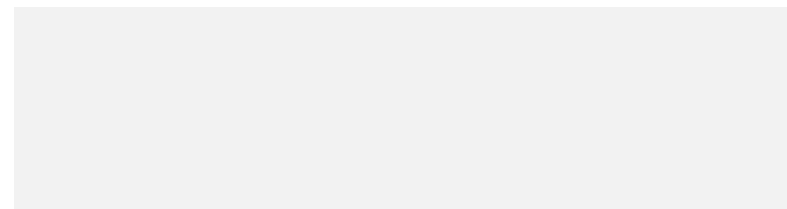
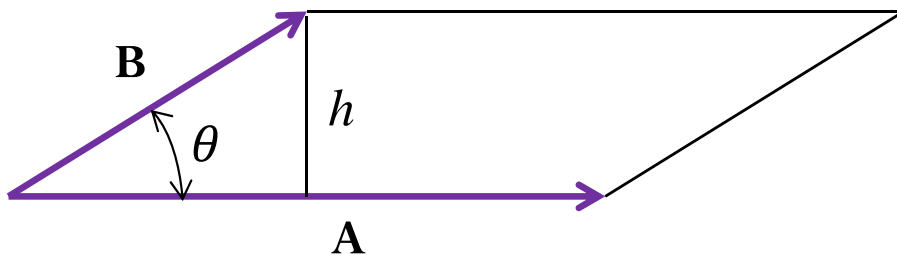
The magnitude of vector \mathbf{C} is given by:



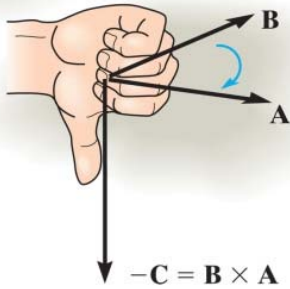
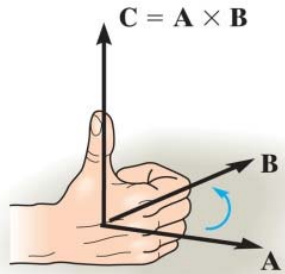
The vector \mathbf{C} is perpendicular to the plane containing \mathbf{A} and \mathbf{B} (specified by the **right-hand rule**). Hence,



Geometric definition of the cross product: the magnitude of the cross product is given by the area of a parallelogram



Cross (or vector) product



Laws of operation:

$$\mathbf{A} \times \mathbf{B} = -\mathbf{B} \times \mathbf{A}$$

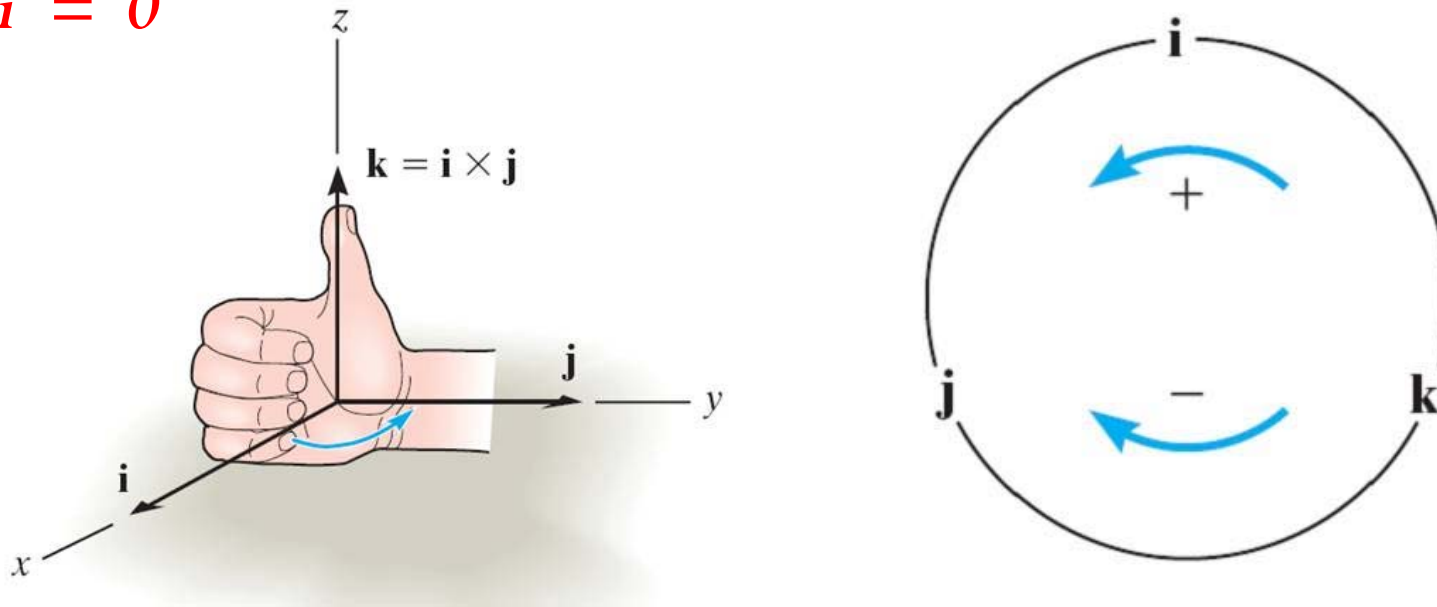
$$\alpha(\mathbf{A} \times \mathbf{B}) = (\alpha\mathbf{A}) \times \mathbf{B} = \mathbf{A} \times (\alpha\mathbf{B}) = (\mathbf{A} \times \mathbf{B})\alpha$$

$$\mathbf{A} \times (\mathbf{B} + \mathbf{D}) = \mathbf{A} \times \mathbf{B} + \mathbf{A} \times \mathbf{D}$$

Cross (or vector) product

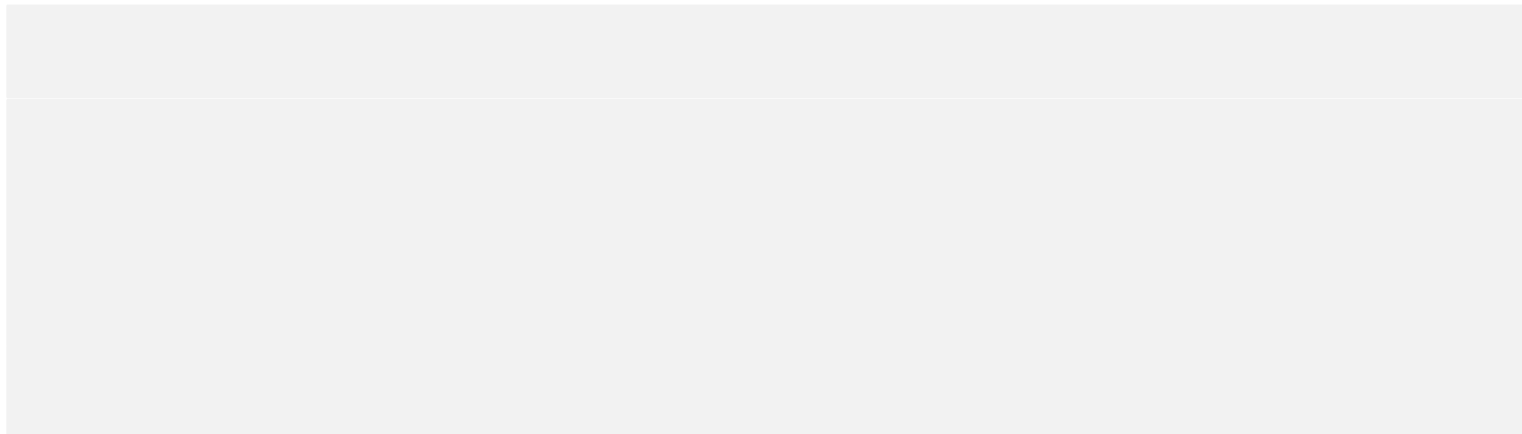
The right-hand rule is a useful tool for determining the direction of the vector resulting from a cross product. Note that a vector crossed into itself is zero, e.g., $\mathbf{i} \times \mathbf{i} = \mathbf{0}$

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Considering the cross product in Cartesian coordinates

$$\mathbf{A} \times \mathbf{B}$$

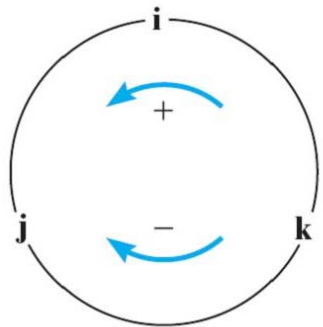


Cross (or vector) product

Also, the cross product can be written as a determinant.

$$\mathbf{A} \times \mathbf{B} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

Each component can be determined using 2×2 determinants.



For element \mathbf{i} :

$$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

For element \mathbf{j} :

$$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

For element \mathbf{k} :

$$\begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

$$\mathbf{A} \times \mathbf{B} = (A_y B_z - A_z B_y)\mathbf{i} - (A_x B_z - A_z B_x)\mathbf{j} + (A_x B_y - A_y B_x)\mathbf{k}$$

Chapter 3: Equilibrium of a particle

Goals and Objectives

- Practice following general procedure for analysis.
- Introduce the concept of a free-body diagram for an object modeled as a particle.
- Solve particle equilibrium problems using the equations of equilibrium.

General procedure for analysis

1. Read the problem carefully; write it down carefully.
2. **MODEL THE PROBLEM:** Draw given diagrams neatly and construct additional figures as necessary.
3. Apply principles needed.
4. Solve problem symbolically. Make sure equations are dimensionally homogeneous
5. Substitute numbers. Provide proper units *throughout*. Check significant figures. Box the final answer(s).
6. See if answer is reasonable.

Most effective way to learn engineering mechanics is to *solve problems!*

Equilibrium of a particle

According to Newton's first law of motion, a particle will be in **equilibrium** (that is, it will remain at rest or continue to move with constant velocity) if and only if

where \vec{F} is the resultant force vector of all forces acting on a particle.

3-Dimensional forces: equilibrium requires

Equilibrium of a particle (cont)

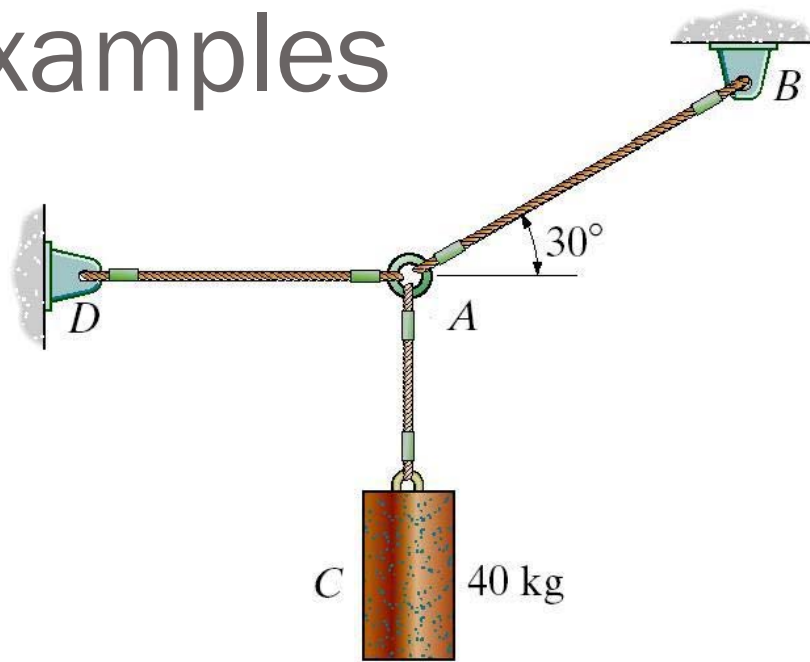
Coplanar forces: if all forces are acting in a single plane, such as the “xy” plane, then the equilibrium condition becomes

Free body diagram

Drawing of a body, or part of a body, on which all forces acting on the body are shown.

- Key to writing the equations of equilibrium.
 - Can draw for any object/subsystem of system. Pick the most appropriate object. (Equal & opposite forces on interacting bodies.)
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- Draw Outlined Shape: image object free of its surroundings
 - Sometimes may collapse large object into point mass
 - Establish x, y, z axes in any suitable orientation
 - Show positive directions for translation and rotation
 - Show all forces acting on the object at points of application
 - Label all known and unknown forces
 - Sense (“direction”) of unknown force can be assumed. If solution is negative, then the sense is reverse of that shown on FBD

Examples



Find the tension in the cables for a given mass.

- Draw Outlined Shape
- Establish x, y, z axes
- Show all forces acting on object
- Label known and unknown forces
- Assume sense of unknown force

Find the forces in cables AB and AC?

