Statics - TAM TAM 211

Lecture 6 September 21, 2018

Announcements

- □ Zhaoyu Xu (TA) has office hours on Fridays 1-3 pm in Library Cafe.
- □ Use the Blackboard Discussion Board if you have questions.
- Videos with more practice of resultant forces have been uploaded to Blackboard
- □ No class on Monday September 24 (Mid-Autumn Festival)

Upcoming deadlines:

- Friday (Sept 21)
 - Written Assignment 1
- Tuesday (9/26)
 - Prairie Learn HW2
- Thursday (9/28)
 - Note different day!
 - Quiz 1
 - 6-7 pm
 - Computer Lab
 - No personal calculator, must use computer





Chapter 3: Equilibrium of a particle

Goals and Objectives

- Practice following <u>general procedure for analysis</u>.
- Introduce the concept of a <u>free-body diagram</u> for an object modeled as a particle.
- Solve equilibrium problems using the <u>equations of equilibrium</u>.
 - 3D, 2D planar, idealizations (smooth surfaces, pulleys, springs)

Recap: General procedure for analysis

- 1. Read the problem carefully; write it down carefully.
- 2. MODELTHE PROBLEM: Draw given diagrams neatly and construct additional figures as necessary.
- 3. Apply principles needed.
- 4. Solve problem symbolically. Make sure equations are dimensionally homogeneous
- 5. Substitute numbers. Provide proper units *throughout*. Check significant figures. Box the final answer(s).
- 6. See if answer is reasonable.

Most effective way to learn engineering mechanics is to *solve problems!*

Recap: Equilibrium of a particle

3-Dimensional forces: equilibrium requires

$$\sum F_{x} = 0$$

$$\sum F_{x} i + \sum F_{y} j + \sum F_{z} k = 0$$

$$\sum F_{y} = 0$$

$$\sum F_{z} = 0$$

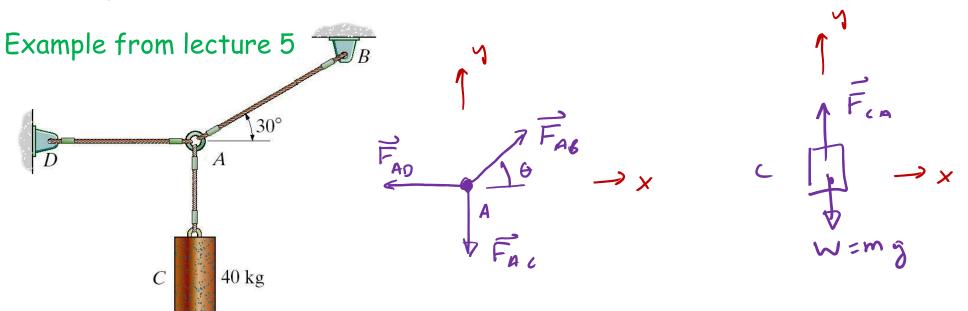
Planar forces: if all forces are acting in a single plane, such as the "xy" plane, then the equilibrium condition becomes $\sum E = 0$

$$\sum \mathbf{F} = \sum F_x \, \mathbf{i} + \sum F_y \, \mathbf{j} = \mathbf{0} \qquad \Longrightarrow \qquad \sum F_x = 0$$
$$\sum F_y = 0$$

Recap: Free body diagram

Drawing of a body, or part of a body, on which all forces acting on the body are shown.

- Draw Outlined Shape: image object free of its surroundings
- Establish x, y, z axes in any suitable orientation
 - $\hfill\square$ Show positive directions for translation and rotation
- □ Show all forces acting on the object at points of application
- □ Label all known and unknown forces
- □ Sense ("direction") of unknown force can be assumed. If solution is negative, then the sense is reverse of that shown on FBD



Recap: Equations of equilibrium

- □ Use FBD to write equilibrium equations in x, y, z directions
 □ ∑ F_x = 0, ∑ F_y = 0, and if 3D ∑ F_z = 0,
 □ If # equations ≥ # unknown forces, statically determinate (can solve for unknowns)
 - If # equations < # unknown forces, indeterminate (can NOT solve for unknowns), need more equations</p>
- Get more equations from FBD of other bodies in the problem

(a) Pt. A:
(a) Pt. A:
(a) Pt. C:

$$EF_{3} = 0$$

(b) $-F_{n3} + F_{n8}(0)0 \ge 0$
 $EF_{3} = 0$
(c) F_{cn} (c) $F_{cn} - mg = 0$
(c) F_{cn} (c) F_{cn} (c) $F_{cn} - mg = 0$
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(c) F_{cn} (c)

Find the forces in cables AB and AC?

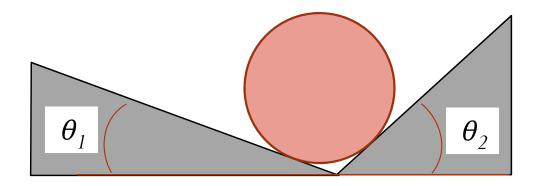
- Draw Outlined Shape
- \Box Establish x, y, z axes

- □ Label known and unknown forces
- Assume sense of unknown force
- □ Show all forces acting on object



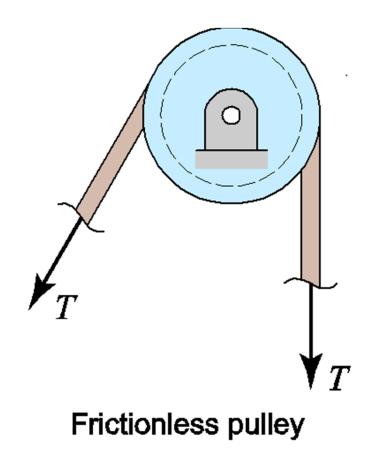
Idealizations

Contact force on a <u>smooth surface</u> (with no friction) will be a normal force (i.e., perpendicular to the surface at the point of contact.



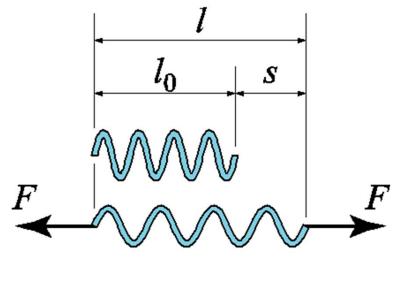
Idealizations

<u>**Pulleys</u>** are (usually) regarded as frictionless; then the tension in a rope or cord around the pulley is the same on either side.</u>



Idealizations

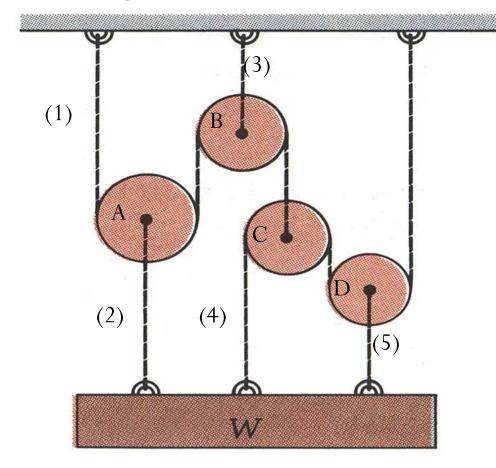
Springs are (usually) regarded as linearly elastic; then the tension is proportional to the *change* in length *s*.

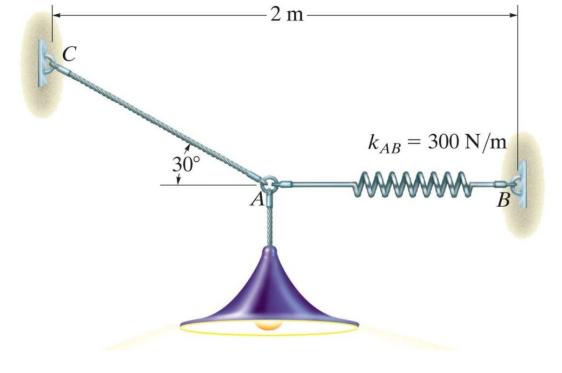


 $F = ks = k(l - l_0)$

Linearly elastic spring

The five ropes can each take 1500 N without breaking. How heavy can *W* be without breaking any?





Determine the required length of cord AC so that the 8-kg lamp can be suspended in the position shown. The undeformed spring length is 0.4 m and has a stiffness of 300 N/m.

3D force systems Use $\Sigma \overrightarrow{F_x} = 0, \Sigma \overrightarrow{F_y} = 0, \Sigma \overrightarrow{F_z} = 0$

