

Statics - TAM TAM 211

Lecture 8

September 28, 2018

Announcements

- ❑ No classes September 29 – October 7 for National Day Holiday
 - ❑ Saturday Sept 29 make-up class cancelled to accommodate for Quiz 1
 - ❑ Sunday Sept 30 make-up class cancelled to accommodate for Quiz 2
 - ❑ Enjoy your vacation!
- ❑ Upcoming deadlines:
 - Friday (today)
 - Written Assignment 2
 - Tuesday (10/9)
 - Prairie Learn HW3
 - Friday (10/12)
 - Written Assignment 3

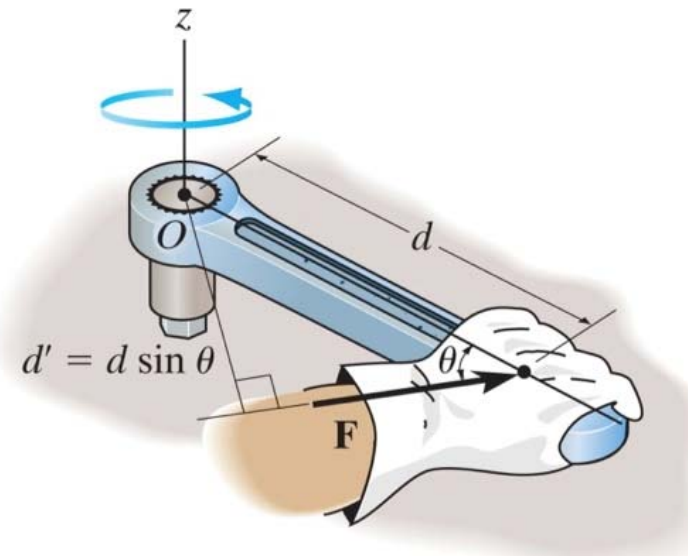
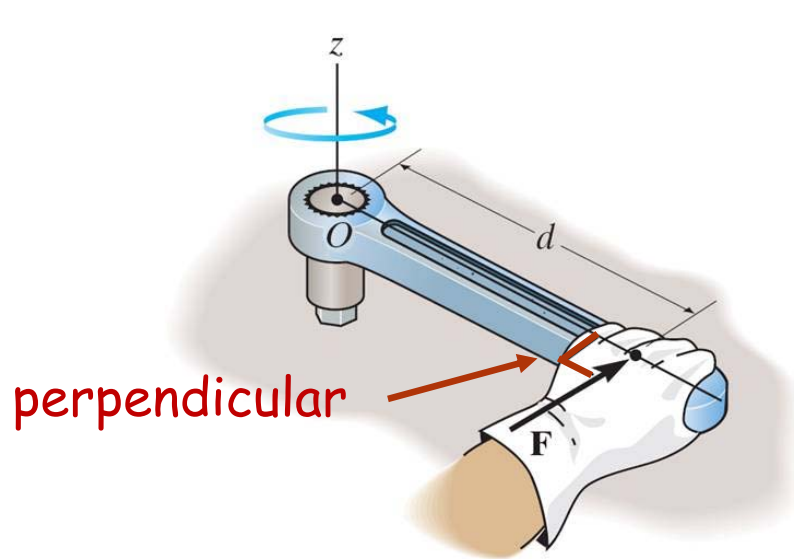


Chapter 4: Force System Resultants

Goals and Objectives

- Discuss the concept of the moment of a force and show how to calculate it in two and three dimensions
- How to find the moment about a specified axis (using Scalar Triple Product)
- Define the moment of a couple
- Finding equivalence force and moment systems
- Reduction of distributed loading

Recap: Moment of a force



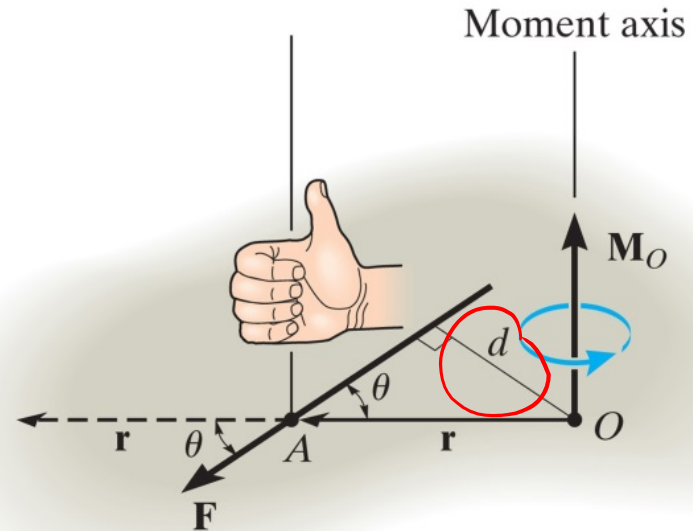
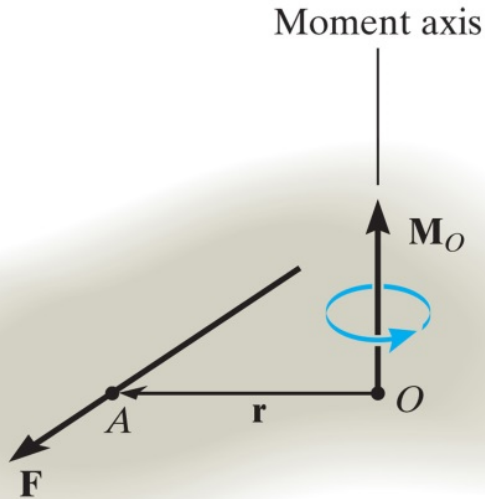
Scalar Formulation: $M_O = F d$

Scalar Formulation: $M_O = F d'$

Direction: Moment about point O \vec{M}_O is **perpendicular** to the plane that contains the force \vec{F} and its moment arm \vec{d} . The right-hand rule is used to define the sense.

Magnitude: In a 2D case (where \vec{F} is **perpendicular** to \vec{d}), the magnitude of the moment about point O is $M_O = F d$

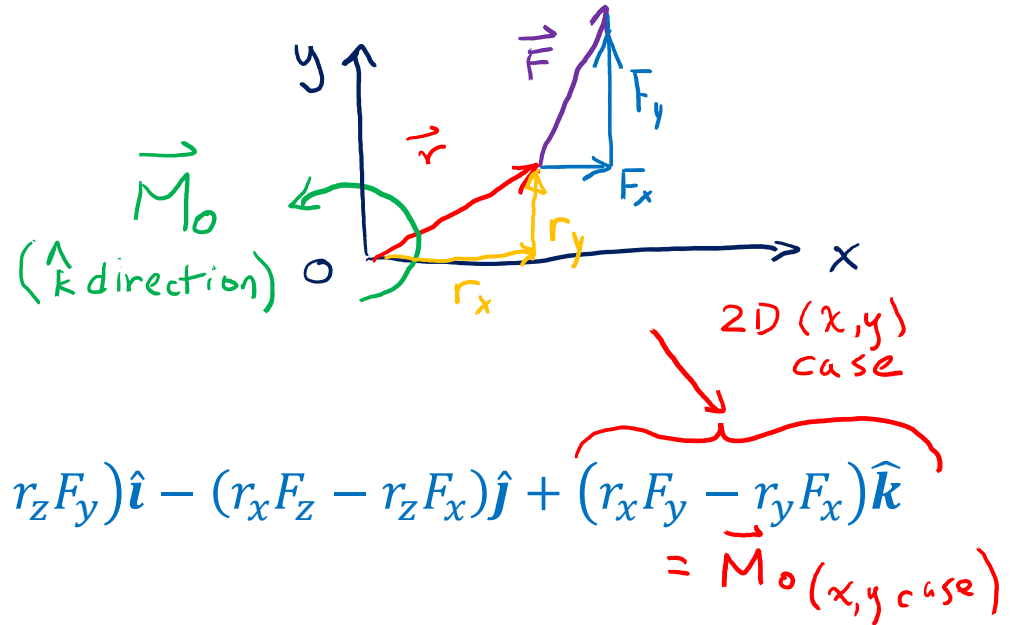
Recap: Moment of a force



Vector Formulation

Use cross product: $\vec{M}_O = \vec{r} \times \vec{F}$

Direction: Defined by right hand rule.



$$\vec{M}_O = \vec{r} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ r_x & r_y & r_z \\ F_x & F_y & F_z \end{vmatrix} = (r_y F_z - r_z F_y) \hat{i} - (r_x F_z - r_z F_x) \hat{j} + (r_x F_y - r_y F_x) \hat{k}$$

$= \vec{M}_O(x,y \text{ case})$

Magnitude: recall $|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin\theta$

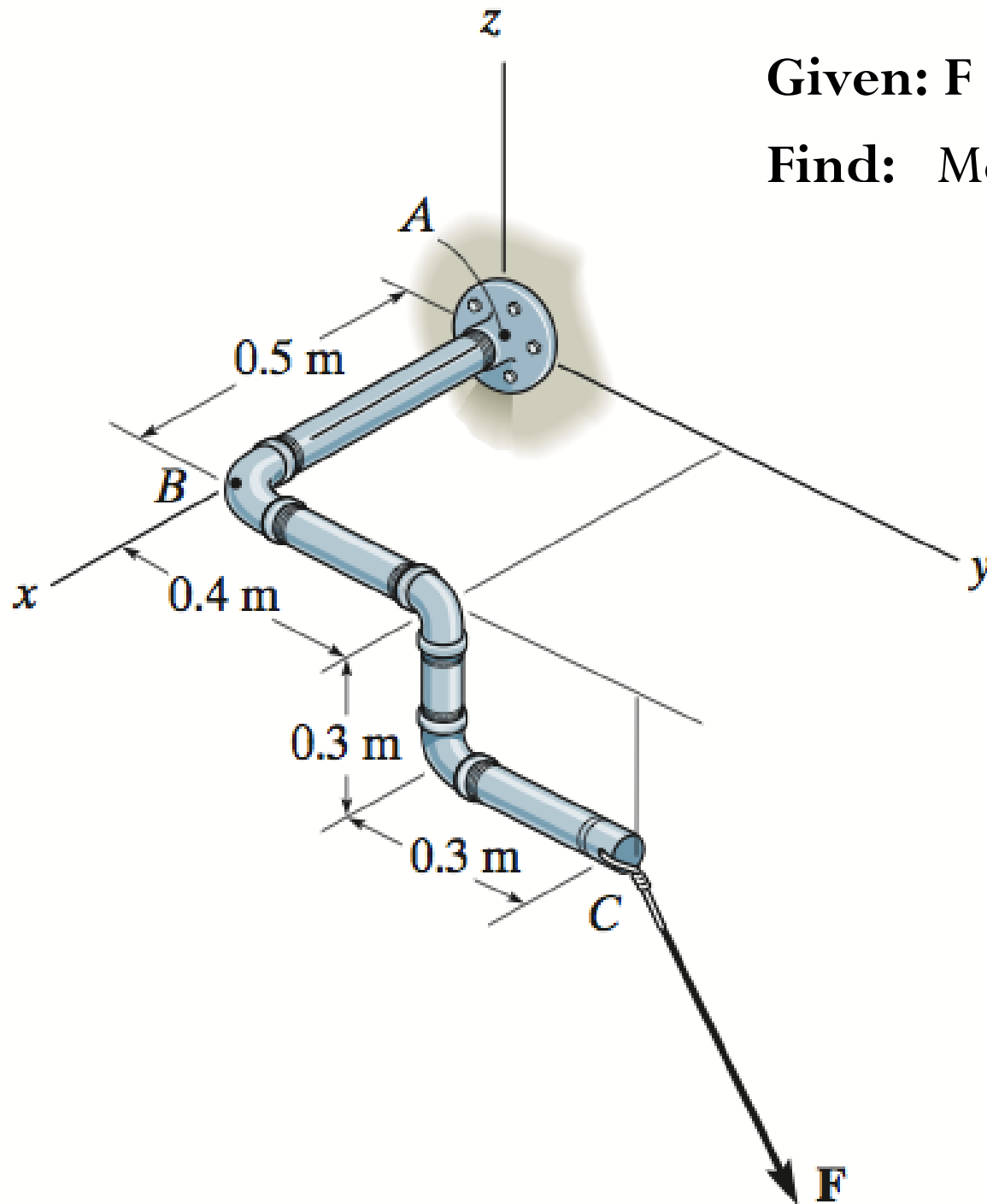
$$M_O = |\vec{M}_O| = |\vec{r}| |\vec{F}| \sin\theta = F(r \sin\theta) = Fd$$

d is the perpendicular distance from O to \vec{F}

Example – Vector Formulation

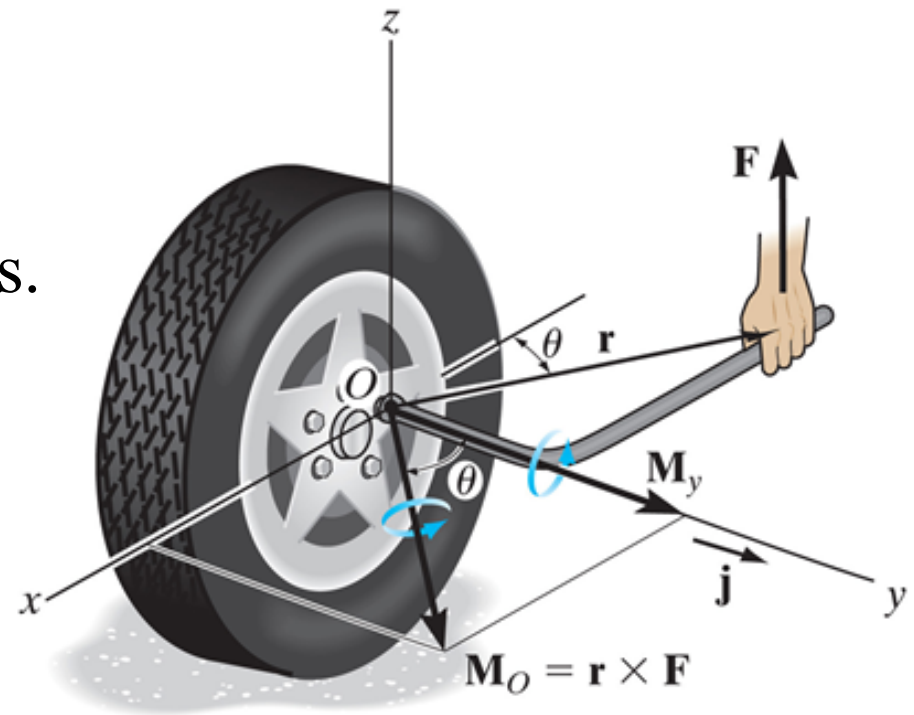
Given: $\mathbf{F} = \{600\mathbf{i} + 800\mathbf{j} - 500\mathbf{k}\}$ N

Find: Moment of the force about point B .



Moment of a force about a specified axis

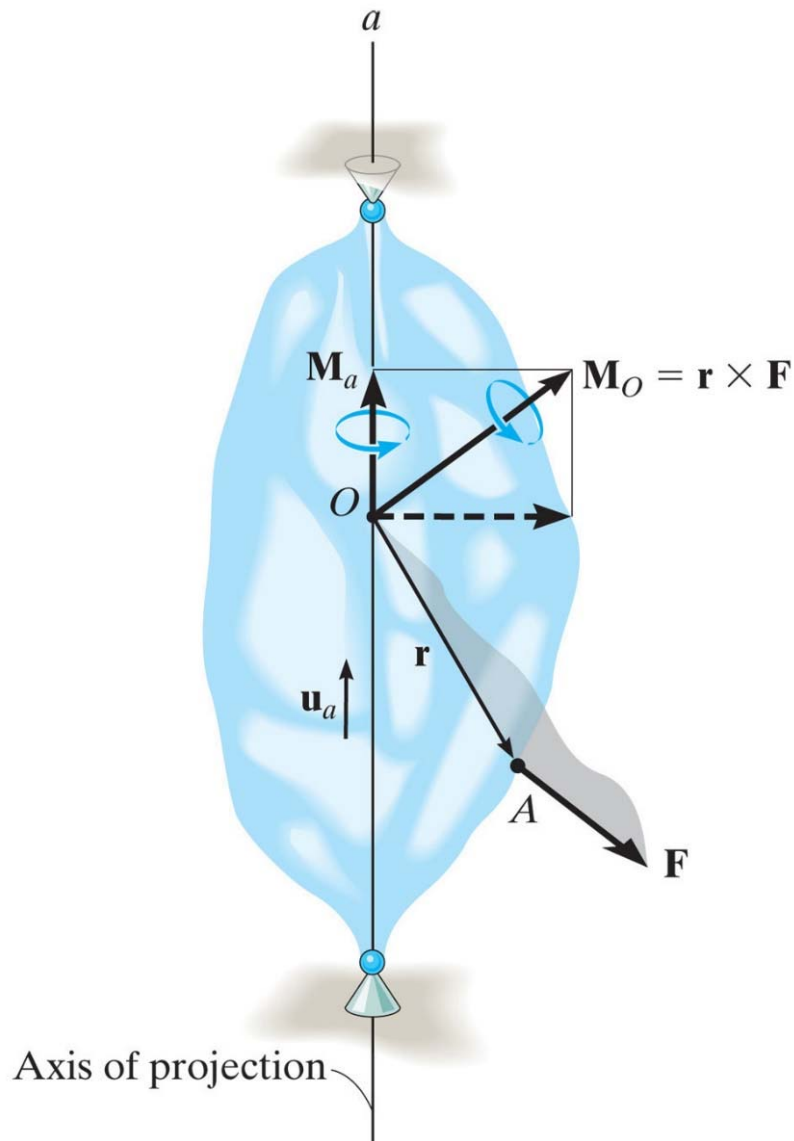
A force is applied to the tool as shown. Find the magnitude of the moment of this force about the y -axis.



Recall: the projected component of a vector, \vec{A} , along the direction of another, \vec{B} , can be determined using the dot product.

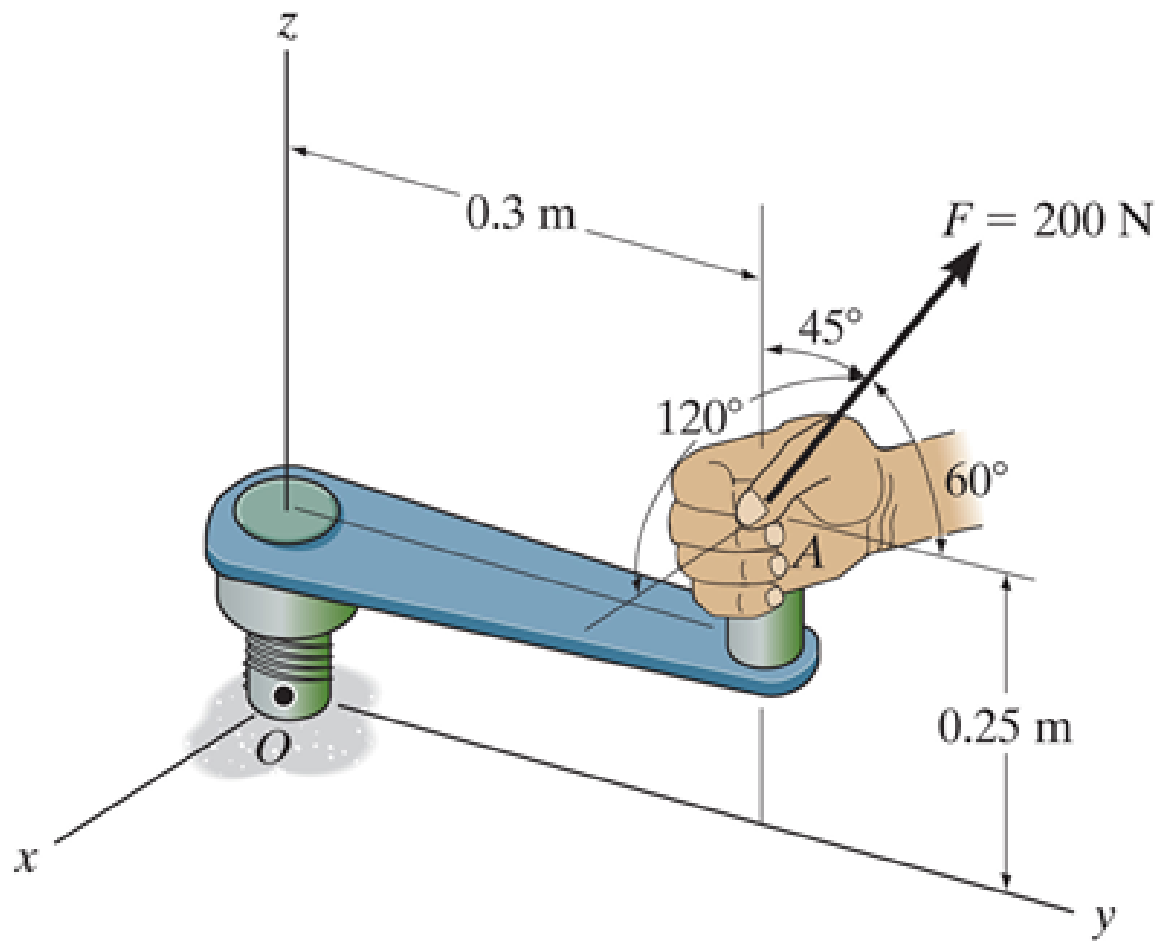
Moment of a force about a specified axis (Scalar Triple Product)

The magnitude of the projected moment about any generic axis a can be computed using the scalar triple product:



The direction of the projected moment about any generic axis a can be defined using :

where $\overline{\mathbf{u}}_a$ is the unit vector along axis a



A force is applied to the tool as shown. Find the magnitude of the moment of this force about the x axis.