

# Statics - TAM 211

**Lecture 10**

**October 10, 2018**

# Announcements

## □ Upcoming deadlines:

- Friday (10/12)
  - Written Assignment 3
- Tuesday (10/16)
  - Prairie Learn HW4

Reminder:

Discussion Section

Absent > 5 minutes late



# Chapter 4: Force System Resultants

# Goals and Objectives

- ✓ Discuss the concept of the moment of a force and show how to calculate it in two and three dimensions
- ✓ How to find the moment about a specified axis
- ✓ Define the moment of a couple
- Finding equivalence force and moment systems
- Reduction of distributed loading

# Recap from lecture 9:

- **Moment of a force couple** ( $\vec{F}$  and  $-\vec{F}$ )
  - $\vec{M}_O = \vec{r} \times \vec{F}$ ,  $|\vec{M}_O| = Fd$  (where  $d \approx \perp$  dist btw  $\vec{F}$  and  $-\vec{F}$ )
  - Couple moment is a **free vector**, i.e. it is **independent** of the choice of location of O!
- **Equivalent couples**
  - $M_O = F_1 d_1 = F_2 d_2$
  - For example,  $M_O = 10 \text{ Nm}$  if  $F_1 = 5 \text{ N}$ ,  $d_1 = 2 \text{ m}$ , or  $F_2 = 2.5 \text{ N}$ ,  $d_2 = 4 \text{ m}$
- **Resultant couple moment**
  - $\vec{M}_R = \Sigma \vec{M}_i$

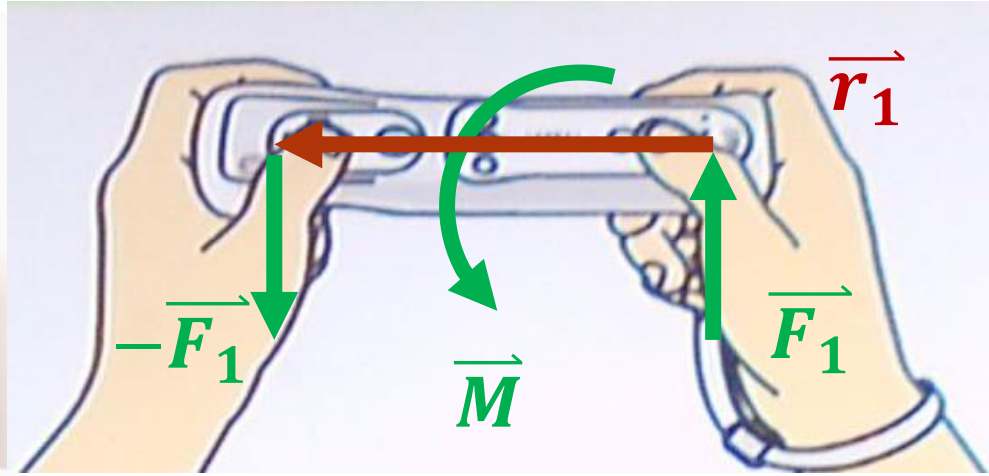
# Moment of a force



$\vec{M}$  is a free vector. It can be placed anywhere on the body, and still create a tendency for a rotation

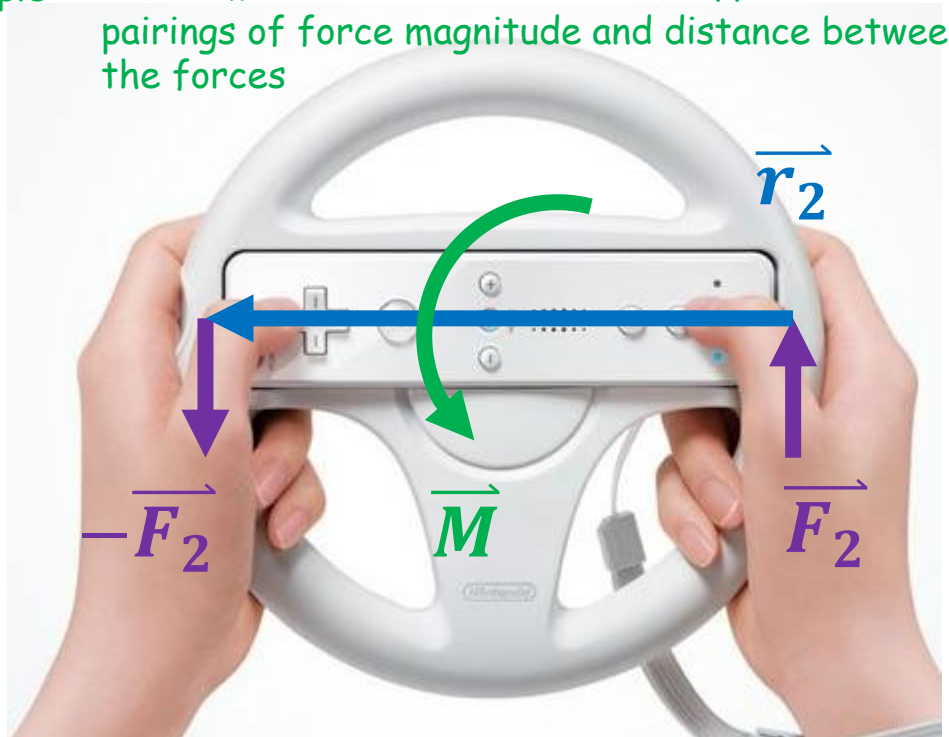


# Moment of a force couple and equivalent couples



$\vec{M}$  can be created with just one force or a force couple

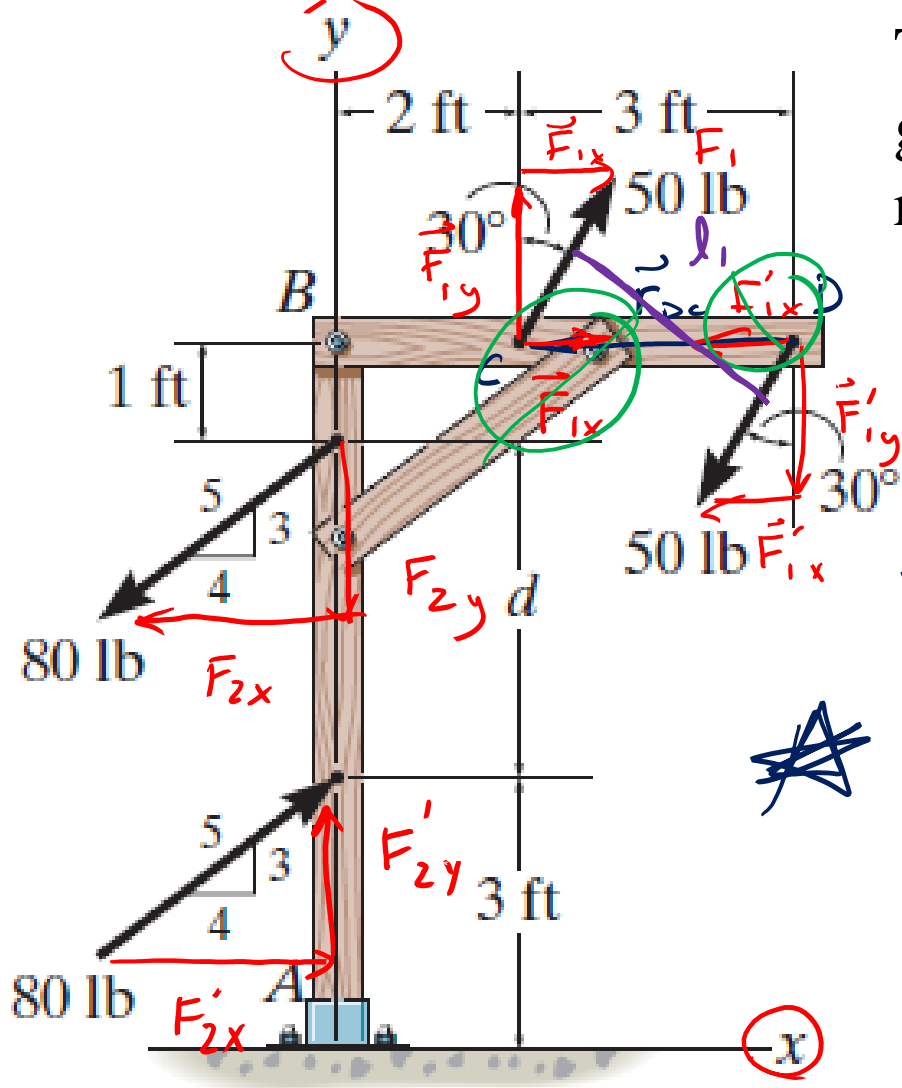
The same  $\vec{M}$  can be created with different pairings of force magnitude and distance between the forces



# Recap from lecture 9:

- **Moment of a force couple** ( $\vec{F}$  and  $-\vec{F}$ )
  - $\vec{M}_O = \vec{r} \times \vec{F}$ ,  $|\vec{M}_O| = Fd$  (where  $d \approx \perp$  dist btw  $\vec{F}$  and  $-\vec{F}$ )
  - Couple moment is a **free vector**, i.e. it is **independent** of the choice of location of O!
  - Rotate your i>clicker/phone: apply equal & opposite (not co-linear) forces by each index finger, with **same** small force magnitude & gap between fingers, change locations along i>clicker/phone. Does it have the same rotation?
- **Equivalent couples**
  - Rotate your i>clicker/phone: increase (or decrease) force magnitude and increase (or decrease) gap to get the same rotation.  $M_O = F d$
  - For example,  $M_O = 10 \text{ Nm}$  if  $F_1 = 5 \text{ N}$ ,  $d_1 = 2 \text{ m}$ , or  $F_2 = 2.5 \text{ N}$ ,  $d_2 = 4 \text{ m}$
- **Resultant couple moment**
  - $\vec{M}_R = \sum \vec{M}_i$





Two couples act on the beam with the geometry shown and  $d = 4$  ft. Find the resultant couple

Want  $\vec{M}_R = \sum \vec{M}_i$

Can any component of the applied forces be ignored when calculate couple moment?

$\vec{M}_1 = \vec{r}_{DC} \times \vec{F}_1$

$\vec{r}_{DC} = 3\hat{i} + (-\hat{j})$

$\vec{F}_1 = 50 \text{ lb} (\sin 30^\circ \hat{i} + \cos 30^\circ \hat{j})$

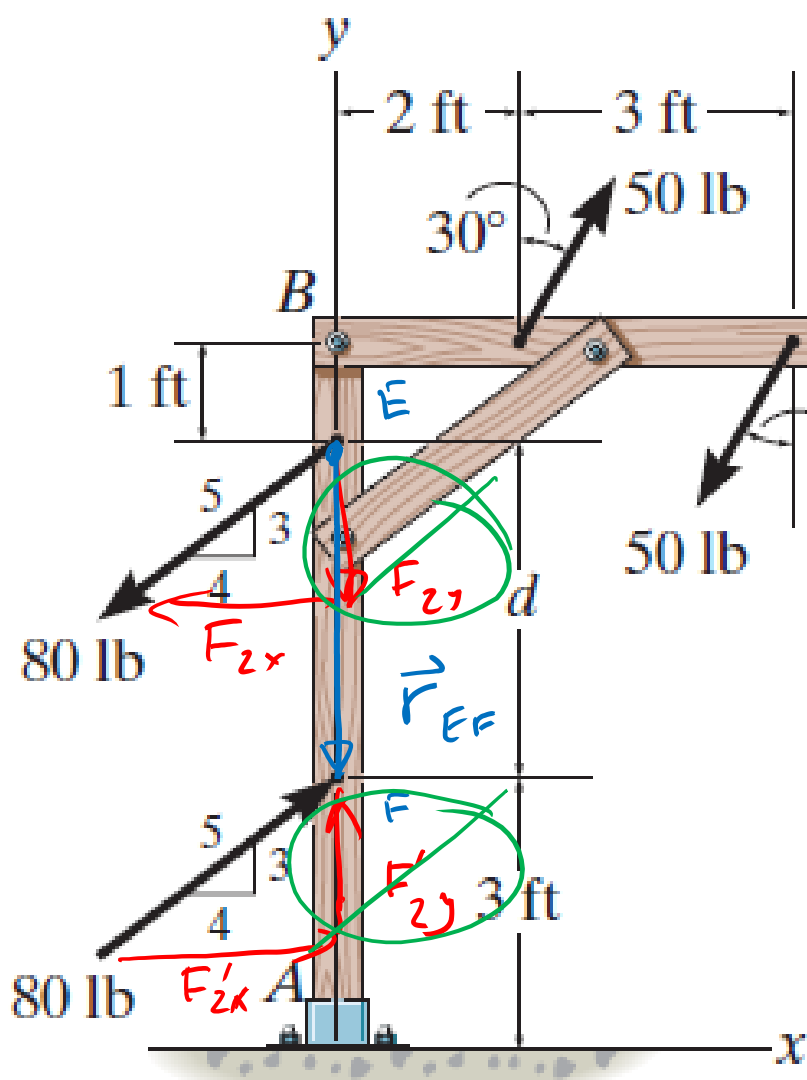
$\vec{M}_1 = -3\hat{i} \times (50 (\sin 30^\circ \hat{i} + \cos 30^\circ \hat{j}))$   
 $= -130 \text{ ft}\cdot\text{lb} \hat{k}$

$\Rightarrow F_{1x}$  components do NOT contribute to couple moment

$\hat{i} \times \hat{i} = 0$   
 $\Rightarrow \vec{M}_1 = -3\hat{i} \times 50 \cdot \cos 30^\circ \hat{j}$

$M_1 = d_1 F_{1y}$

$M_1 = l_1 F_1$   $l_1 = |\vec{r}_{DC}| \cos 30^\circ$   $F_1 = 50 \text{ lb}$   $M_1 = -130 \text{ ft}\cdot\text{lb}$



Lower beam:  $\vec{M}_2 = ?$

$$\vec{M} = \vec{r}_{EF} \times \vec{F}_2$$

$$\vec{r}_{EF} = d \hat{j}$$

$$\vec{F}_2 = 80 \left(\frac{4}{5}\right) \hat{i} + 80 \left(\frac{3}{5}\right) \hat{j}$$

$$+\curvearrowright \vec{M}_2 = 256 \text{ ft}\cdot\text{lb} \hat{k}$$

Resultant Moment

$$\vec{M}_R = \vec{M}_1 + \vec{M}_2$$

$$= -130 \hat{k} + 256 \hat{k}$$

$$\vec{M}_R = 126 \text{ ft}\cdot\text{lb} \hat{k} \quad \leftarrow + \text{ ccw}$$