

Statics - TAM 211

Lecture 12

October 15, 2018

Announcements

- ❑ As announced during discussion section, you are encouraged and allowed to use your Casio calculator during PrairieLearn HWs and Quizzes.
 - ❑ You should learn to solve a system of equations by hand using a calculator
- ❑ PrairieLearn incorrect software issues:
 - ❑ Negative sign symbol (- vs. —)
 - ❑ Space between negative sign (-12 vs. - 12)
 - ❑ Solutions:
 - ❑ Always type in the negative sign symbol (-) into your PL answers for HW or Quiz.
 - ❑ Do not add space between negative symbol and number
 - ❑ All students with these errors will be provided updated grades on Quiz 1. No credit for Quiz 2 and beyond.
- ❑ Upcoming deadlines:
 - Tuesday (10/16)
 - Prairie Learn HW4
 - Friday (10/19)
 - Written Assignment 4
 - Quiz 2
 - Week of Oct 22



Recap: General procedure for analysis

1. Read the problem carefully; write it down carefully.
2. MODEL THE PROBLEM: Draw given diagrams neatly and construct additional figures as necessary.
3. Apply principles needed.
4. Solve problem symbolically. Make sure equations are dimensionally homogeneous
5. Substitute numbers. Provide proper units *throughout*. Check significant figures. Box the final answer(s).
6. See if answer is reasonable.

Most effective way to learn engineering mechanics is to *solve problems!*

Chapter 4: Force System Resultants

Goals and Objectives

- Discuss the concept of the moment of a force and show how to calculate it in two and three dimensions
- How to find the moment about a specified axis
- Define the moment of a couple
- Finding equivalence force and moment systems
- Reduction of distributed loading

Recap: Resultant or Equivalent Force and Moment Systems

Reducing a force system to a single resultant force \vec{F}_R and a single resultant couple moment about point O $(\vec{M}_R)_O$:

$$\vec{F}_R = \Sigma F_x \hat{i} + \Sigma F_y \hat{j} + \Sigma F_z \hat{k}$$

$$\text{Magnitude: } |\vec{F}_R| = \sqrt{F_x^2 + F_y^2 + F_z^2}$$

Orientation in Cartesian coordinate system: x-direction (F_x), y-direction (F_y), z-direction (F_z),

Orientation in Cylindrical coordinate system: $\theta = \tan^{-1} \frac{F_{opp}}{F_{adj}}$

$$(\vec{M}_R)_O = \Sigma \mathbf{M}_O + \Sigma \mathbf{M}$$

\uparrow $\vec{r}_{oi} \times \vec{F}_i$ \leftarrow Sum (couple moments)

Recap: Distributed loads

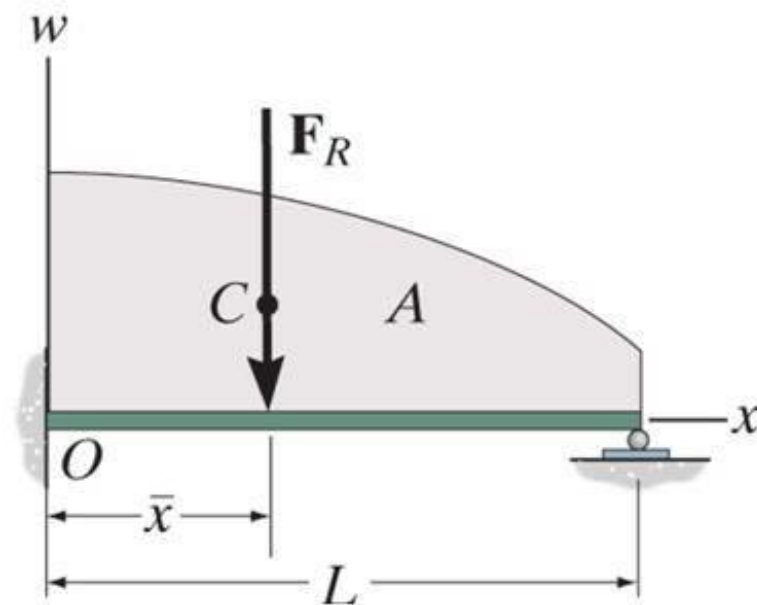
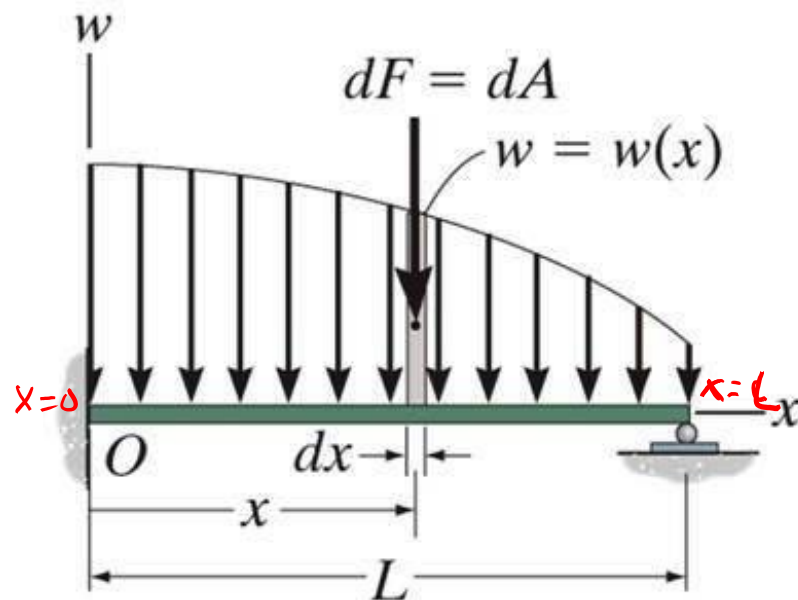
- Equivalent force system for distributed loading function $w(x)$ with units of $\frac{\text{force}}{\text{length}}$.
- Find magnitude F_R and location \bar{x} of the equivalent resultant force for $\overline{\mathbf{F}}_R$

$$|\overline{\mathbf{F}}_R| = F_R = \int_0^L dF = \int_0^L w(x) dx = A$$

$$M_O = \int_0^L x w(x) dx = \bar{x} F_R$$

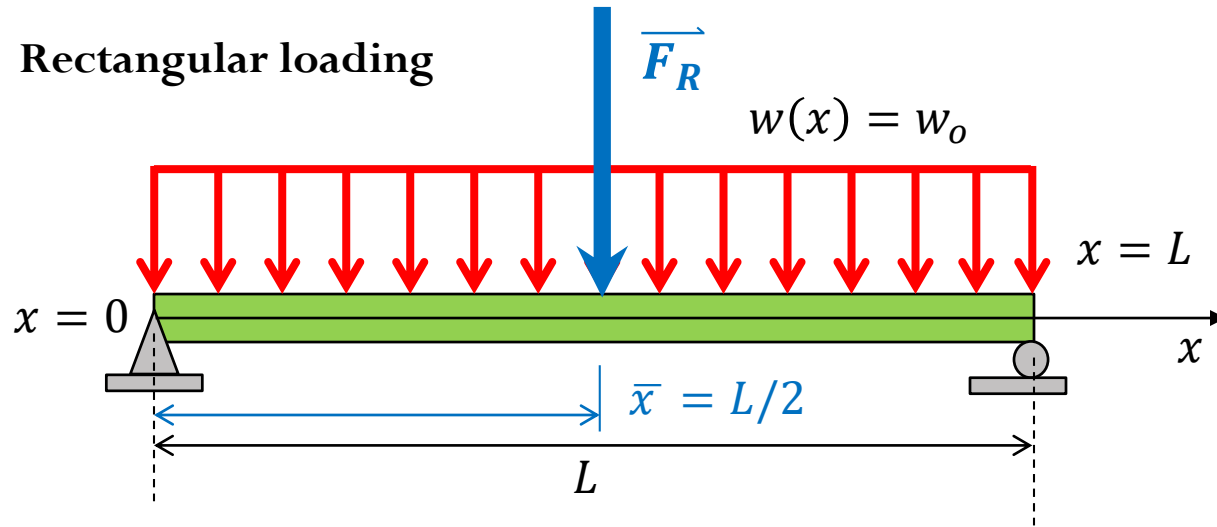
$$\bar{x} = \frac{M_O}{F_R} = \frac{\int_0^L x w(x) dx}{\int_0^L w(x) dx}$$

\bar{x} = **geometric center or centroid** of area A under loading curve $w(x)$.



Recap: Simple Shape Distributed loads

Rectangular loading

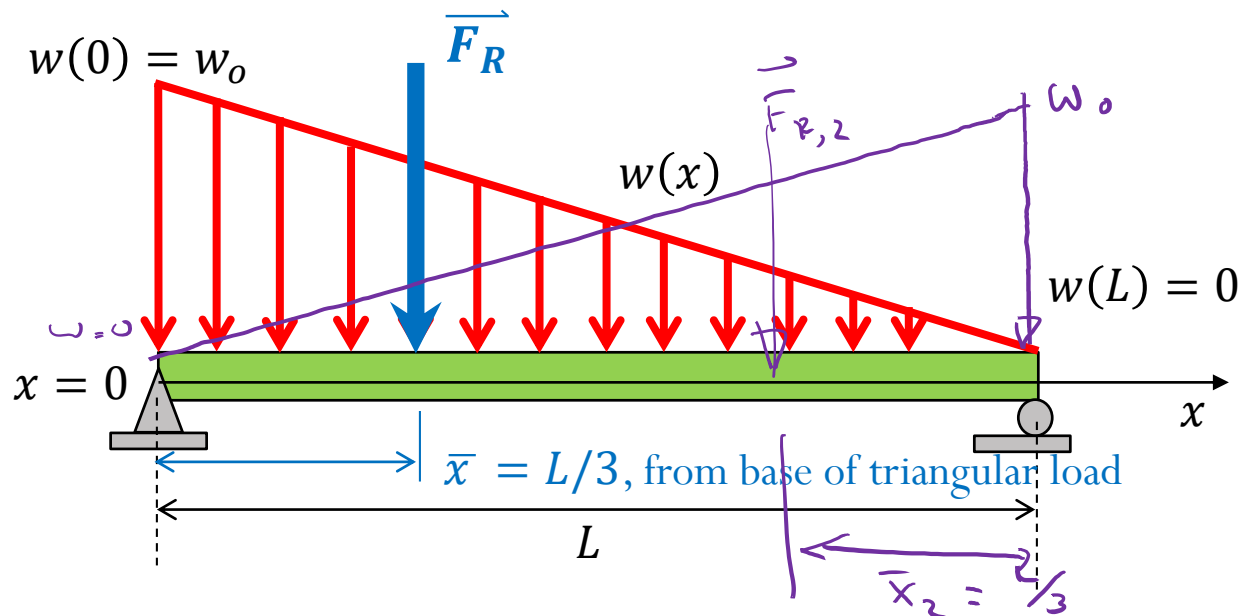


$$w(x) = w_0$$

$$|\vec{F}_R| = F_R = w_0 L$$

$$\bar{x} = \frac{L}{2}$$

Triangular loading

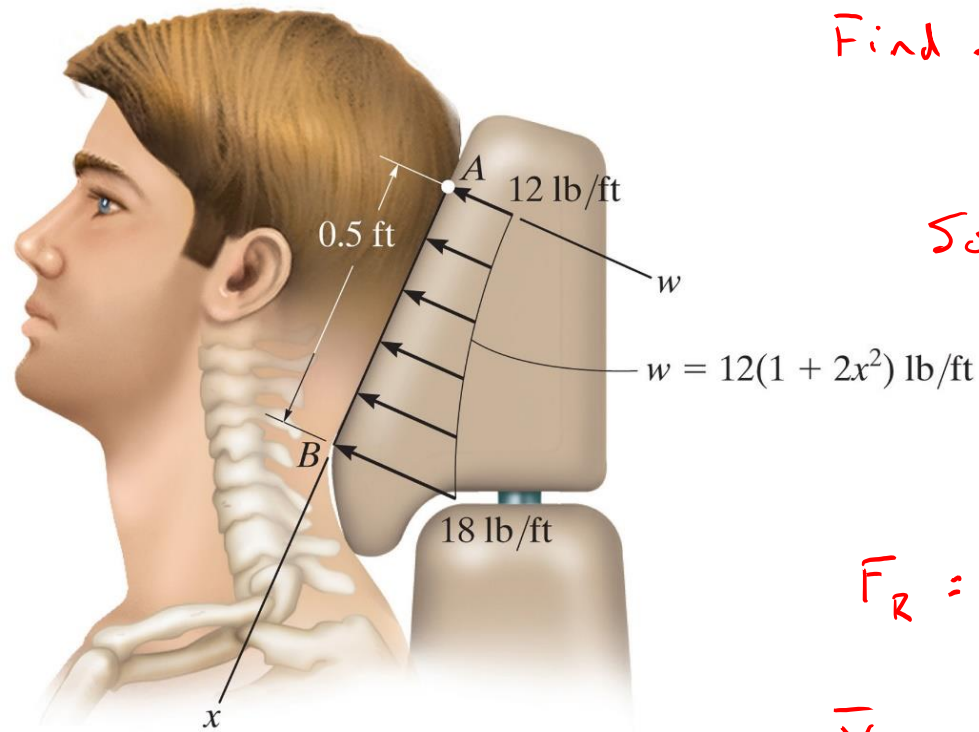


$$w(x) = w_0 - \frac{w_0 x}{L}$$

$$F_R = w_0 \frac{L}{2}$$

$$\bar{x} = \frac{L}{3}$$

Find equivalent force and its location from point A for loading on headrest.



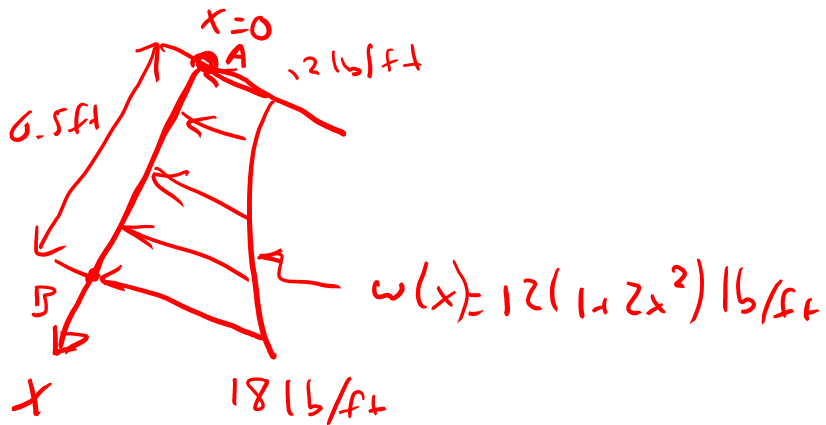
Find: \vec{F}_R & \bar{x} wrt pt. A
wrt: with respect to

$$\text{Soln: } F_R = \int_0^L w(x) dx$$

$$\bar{x} = \frac{M_0}{F_R} = \frac{\int_0^L x w(x) dx}{\int_0^L w(x) dx}$$

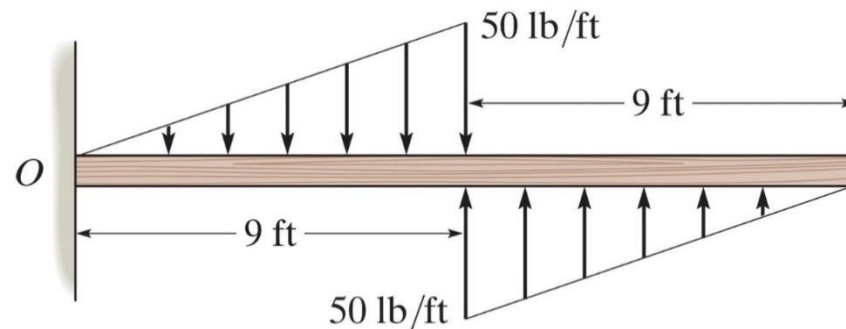
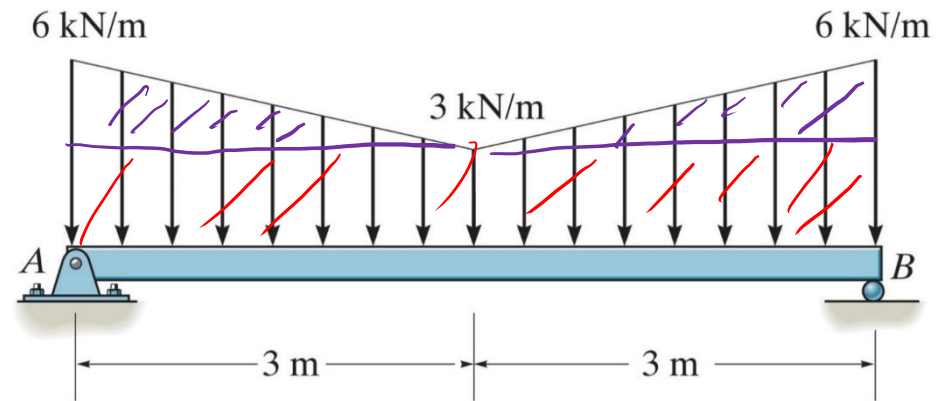
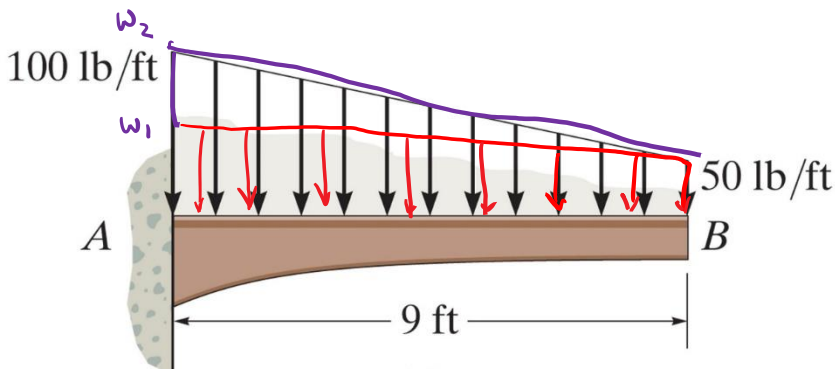
$$F_R = \int_0^{0.5 \text{ ft}} [12(1 + 2x^2) \text{ lb/ft}] dx$$

$$\bar{x} = \frac{\int_0^{0.5} x (12(1 + 2x^2)) dx}{\int_0^{0.5} (12(1 + 2x^2)) dx}$$

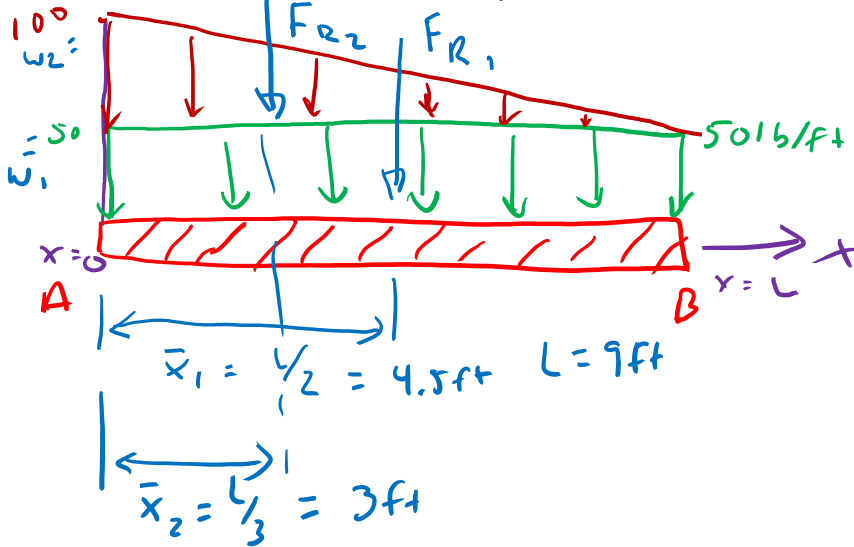
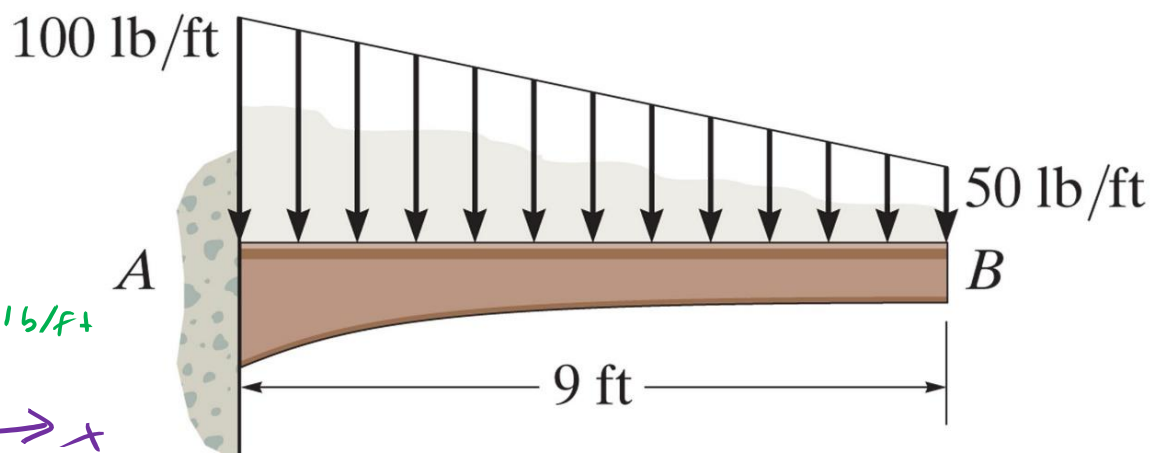


Superposition of simple shapes

- Divide complex distributed loads into multiple simple shapes of rectangles and/or triangles.
- Superimpose the resultant forces for each simple shape to determine the final composite resultant force.



Determine the magnitude and location of the equivalent resultant of this load.



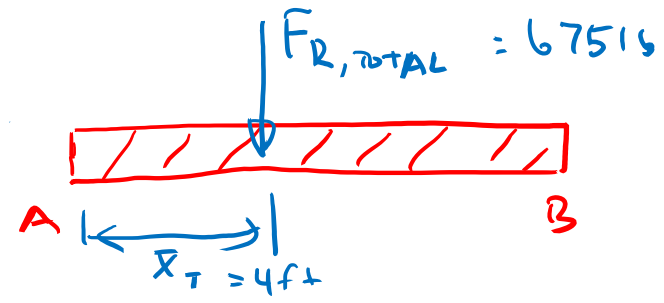
$$F_{R1} = w_1 L = 50 L = 450 \text{ lb}$$

$$F_{R2} = w_0 \frac{L}{2} = (100 - 50) \frac{L}{2} = 225 \text{ lb}$$

$$\bar{x}_T = ?$$

Sum Moments:

$$\bar{x}_1 F_{R1} + \bar{x}_2 F_{R2} = \bar{x}_T F_{RT} \Rightarrow \bar{x}_T =$$

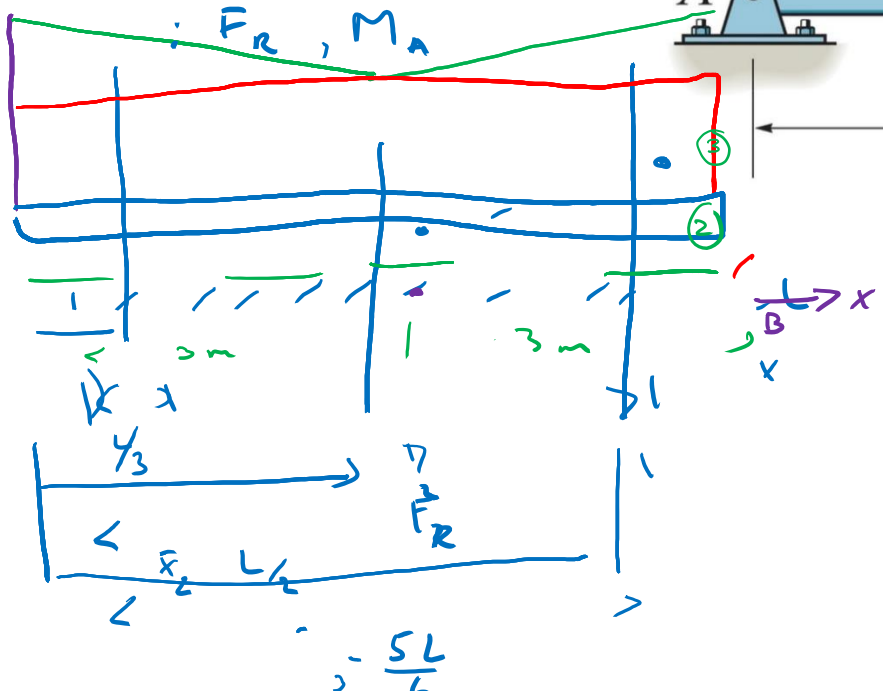
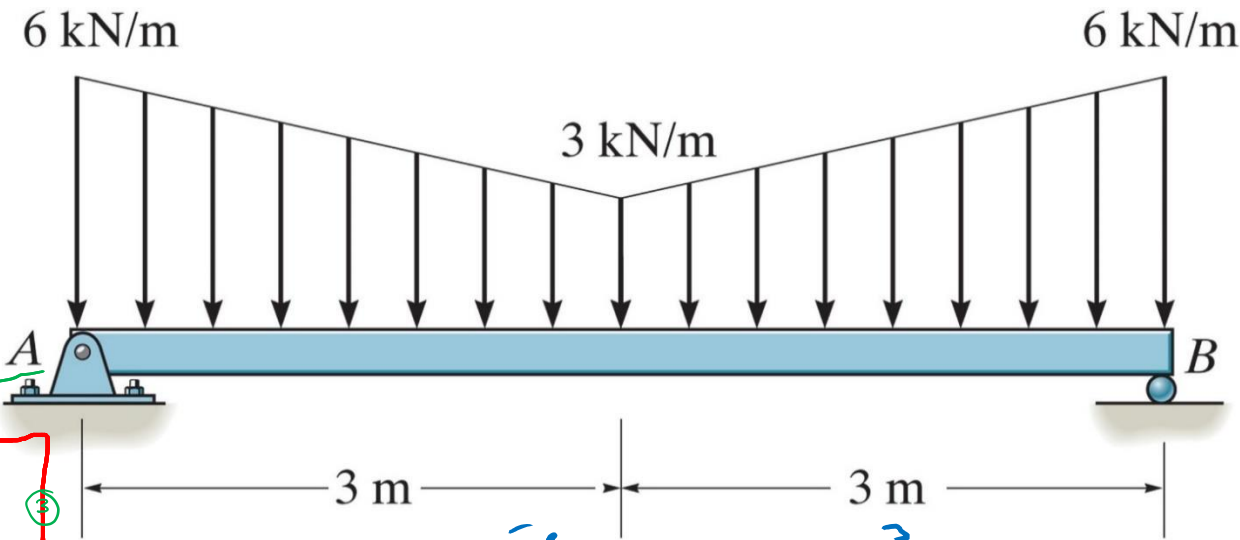


$$F_{R,T} = F_{R1} + F_{R2}$$

$$F_{RT} = 675 \text{ lb} \downarrow$$

$$\frac{\bar{x}_1 F_{R1} + \bar{x}_2 F_{R2}}{F_{RT}} \Rightarrow \bar{x}_T = 4 \text{ ft}$$

Replace the distributed loading by an equivalent resultant force and couple moment acting at point A.



$$F_R = \int_0^L w(x) dx = \int_0^2 6 dx + \int_2^4 3 dx + \int_4^6 6 dx = 12 + 6 + 12 = 30 \text{ kN}$$

$$F_{R1} = 6 \times 2 = 12 \text{ kN}$$

$$F_{R2} = 3 \times 2 = 6 \text{ kN}$$

$$F_{R3} = 6 \times 2 = 12 \text{ kN}$$

$$M_A = - \left(12 \times \frac{2}{3} + 6 \times 2 + 12 \times \frac{2}{3} \right) = -81 \text{ kNm}$$

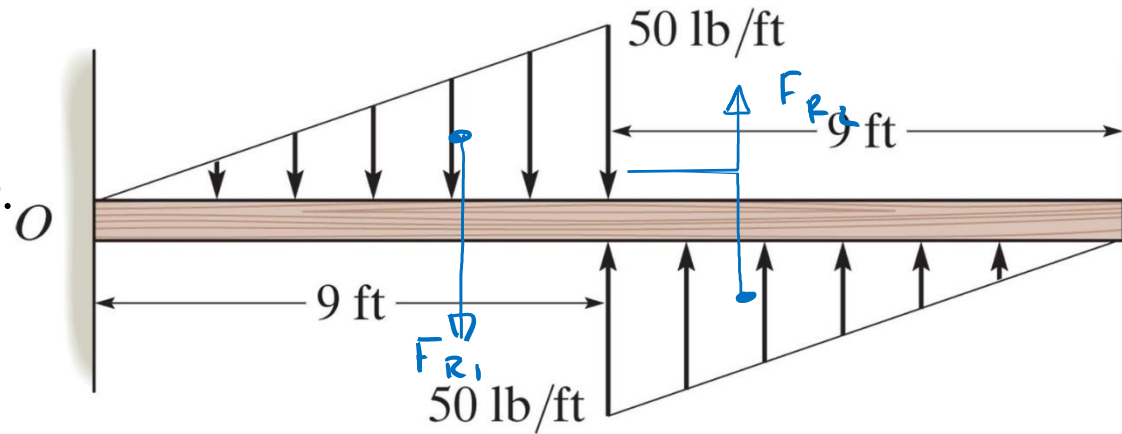
$$M_A = -81 \text{ kNm}$$

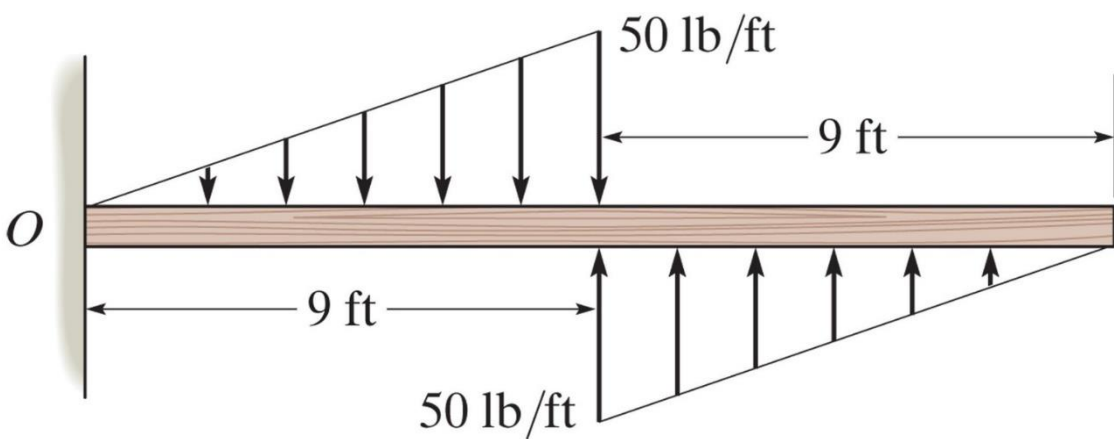
Replace the loading by an equivalent resultant force and couple moment acting at point O.

FIND: F_R & \vec{M}_O

SOLN: $\vec{F}_R = 0$

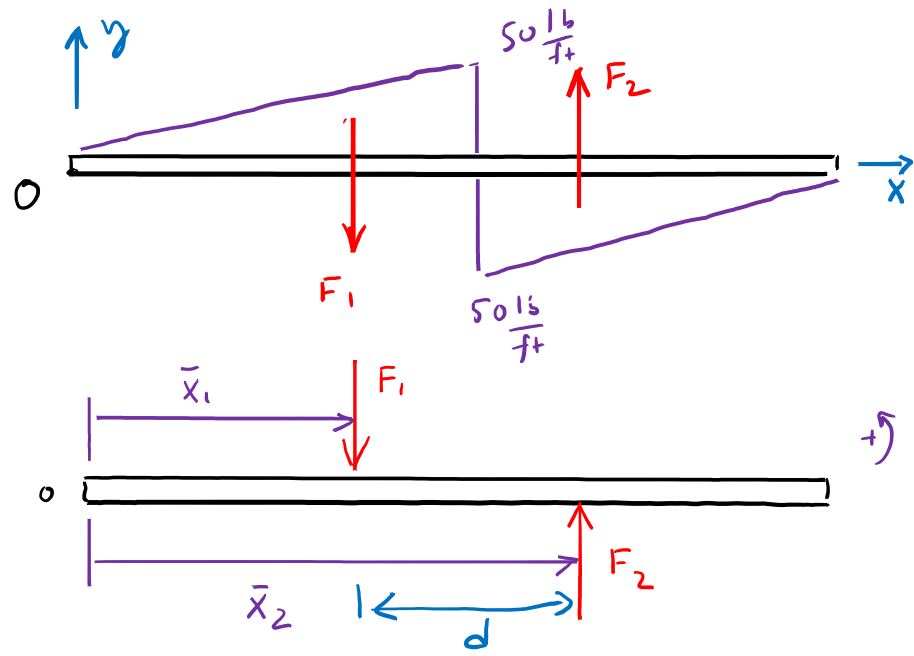
$\vec{M}_O = 1350 \text{ lb}\cdot\text{ft} + \hat{k} (+5)$





Replace the loading by an equivalent resultant force and couple moment acting at point O.

Find: \vec{F}_R , \vec{M}_O
 Soln: Draw FBD



Sum forces:

$$\vec{F}_R = \sum F_y = F_1 + F_2$$

$$= -\frac{9ft}{2} (50 \frac{lb}{ft}) \hat{j} + \frac{9ft}{2} (50 \frac{lb}{ft}) \hat{j}$$

$$\Rightarrow \vec{F}_R = 0$$

$$\Rightarrow \vec{F}_1 = -\vec{F}_2$$

$$\vec{M}_O = \vec{r} \times \vec{F} = -\bar{x}_1 F_1 + \bar{x}_2 F_2$$

$$= -(\frac{2}{3} 9ft) F_1 + (9ft + \frac{1}{3} 9ft) F_2$$

$$= -(6ft) F_1 + (12ft) F_2$$

But $\vec{F}_1 = -\vec{F}_2$, $|\vec{F}_1| = |\vec{F}_2| = F$

$$= (6ft) F = (6ft) (\frac{9ft}{2}) (50 \frac{lb}{ft}) = 1350 lbft \hat{k}$$

Or if note that \vec{F}_1 & \vec{F}_2 create a couple moment, then can say

$$\vec{M}_O = \vec{r} \times \vec{F} = d F, \text{ where } F = F_1 \text{ or } F_2$$

$$\therefore \vec{M}_O = (6ft) (\frac{9ft}{2}) (50 \frac{lb}{ft}) = 1350 lbft \hat{k} \checkmark_{\text{same}}$$