

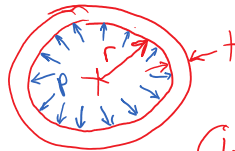
## Chapter 8: Combined Loading

### Chapter Objectives

- ✓ Determine stresses developed in thin-walled pressure vessels
- ✓ Determine stresses developed in a member's cross section when axial load, torsion, bending and shear occur simultaneously.

### Thin-walled pressure vessels

- Inner radius:  $r$
- Wall thickness:  $t$
- Thin walls:  $\frac{r}{t} \geq 10$
- Assume that stress distribution in thin wall is uniform
- Pressure vessel contains fluid under pressure  $p$



is valid when variables  $r_i, r_o, t$  are used in the thick-wall formulation

$p$  acts uniformly throughout the vessel



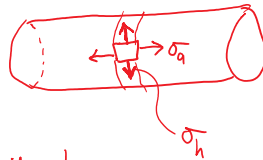
Cylindrical vessels



Spherical vessels

## Pressure vessel failures

fracture in cylindrical pressure vessels tends to happen along longitudinal lines



Hoop stress:  $\sigma_h$

Axial stress:  $\sigma_a$

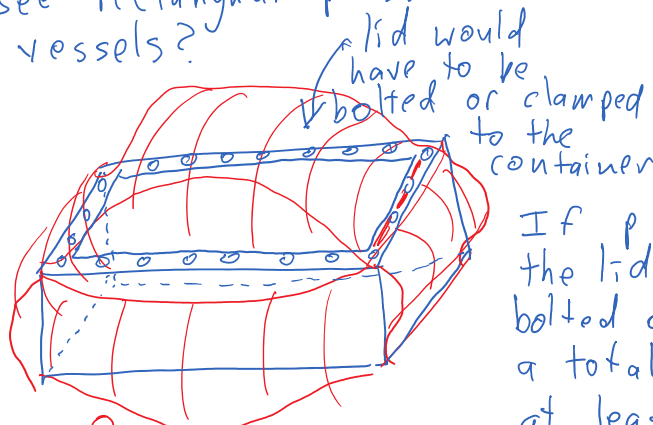
We will show

that  $\sigma_h \approx 2 \cdot \sigma_a \Rightarrow$  failure happens in this direction



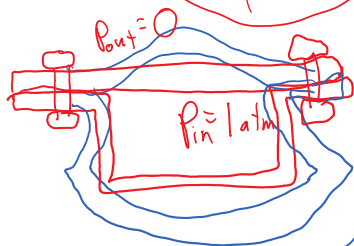
## ASIDE

Why do we rarely (never) see rectangular pressure vessels?



If  $p$  is high, the lid must be bolted on with a total force of at least  $p \times A$  (area of the lid)

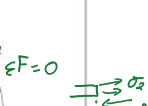
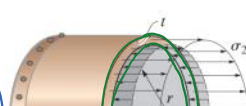
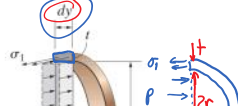
← this total force would be very large even for a small pressure



deformations would be LARGE!

leaks are unlikely to develop in cylindrical pressure vessels under pressure.

## Cylindrical vessels



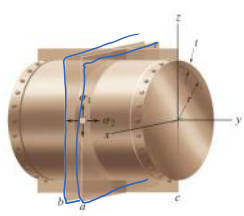


Figure 8B.31a

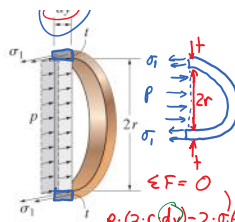


Figure 8B.31b

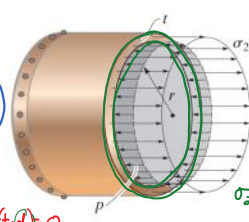


Figure 8B.31c

$[\sigma] = \text{stress} = \frac{\text{force}}{\text{area}}$   
 $[p] = \text{stress} = \frac{\text{force}}{\text{area}}$   
 $[\frac{r}{t}] = \text{dimensionless} = 1$   
 $[r] = \text{length}$   
 $[t] = \text{length}$

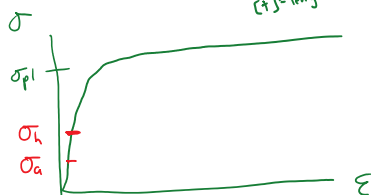
$\sigma_r = \frac{p \cdot r}{t} = \text{hoop stress, } \sigma_h$   
 $\sigma_h = \frac{p \cdot r}{t}$

$\sigma_a = \frac{p \cdot r}{2 \cdot t}$

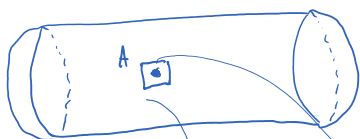
$[p] = \text{we know}$   
 $[\sigma_a] = \text{stress} = \frac{\text{force}}{\text{area}}$

$[\frac{r}{t}] = 1$

$[2] = 1 = \text{dimensionless}$



$\sigma_h = 2 \times \sigma_a$   
 = Why cylindrical vessels tend to fail longitudinally!

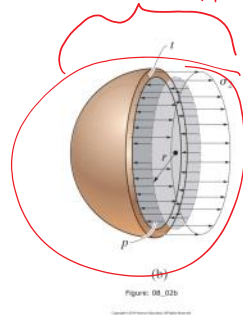
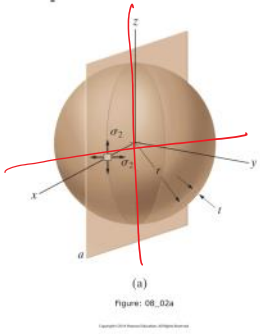


$\sigma_h = \frac{p \cdot r}{t}$   
 $\sigma_a = \frac{p \cdot r}{2 \cdot t}$

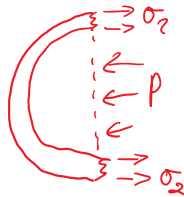
If we were to rotate our choice of material element, the values of the stresses in the thin wall would change.  
 (we won't do that yet, but we will in ch.9)

Side note  
 cylindrical pressure vessels often have hemispherical end caps. In the end caps, the spherical theory applies.

# Spherical vessels



No matter how you "cut" the vessel to derive the stress, you get the same F.B.D. as the axial stress case of the cylindrical vessel (see previous slide)

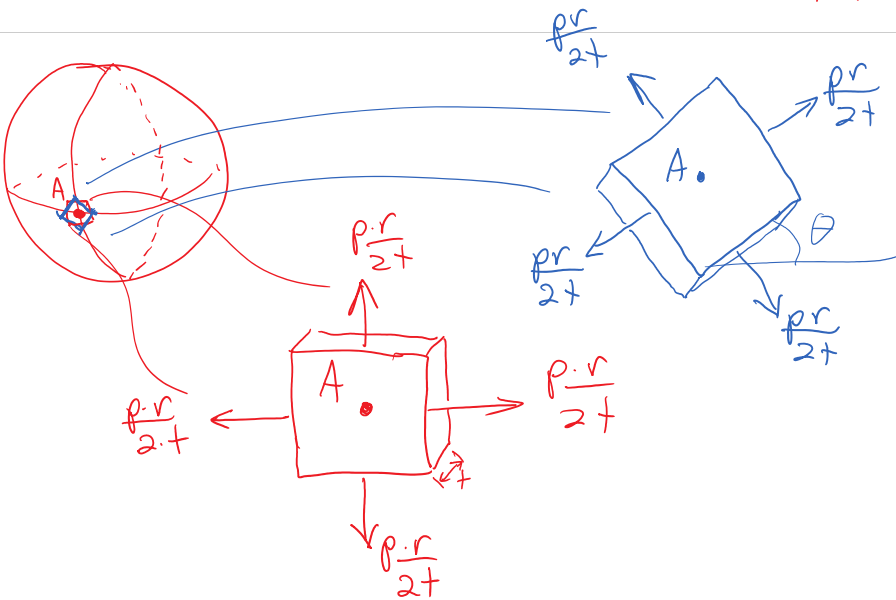


$$\sum F = 0$$

$$\sigma_2 \cdot (t \cdot 2\pi r) - p \cdot (\pi r^2) = 0$$

$$\sigma_2 = \frac{p \cdot r}{2 \cdot t}$$

acts in both directions of any stress element in the thin wall



No matter what value  $\theta$  has, the normal stresses in the thin wall will equal  $p \cdot r / 2 \cdot t$  only true for spherical pressure vessels

**Example:** A spherical pressure vessel of  $D = 900$ -mm outer diameter is to be fabricated from a steel having an ultimate tensile stress  $\sigma_u = 400$  MPa. Knowing that a factor of safety of  $FS=4.0$  is desired and that the gage pressure can reach  $p=3.5$  MPa, determine the smallest wall thickness that should be used.

$$p = p_{\text{gage}} = p_{\text{inner}} - p_{\text{outer}}$$

↑ usually atmospheric pressure

$$p_{\text{atm}} = 1 \text{ atm} \approx 100 \text{ kPa}$$

If  $p_{\text{outer}}$  is  $1 \text{ atm}$  (absolute)  $\approx 14.7 \text{ psi}$ , we usually just approximate  $p_{\text{outer}} = 0$

$$p \approx p_{\text{inner}}$$

$$\text{spherical: } \sigma_a = \frac{p \cdot r}{2 \cdot t} \quad \sigma_{\text{allow}} = \frac{\sigma_u}{F.S.}$$

$$\text{we want } \sigma_a \leq \sigma_{\text{allow}} \Rightarrow \frac{p \cdot r}{2 \cdot t} \leq \frac{\sigma_u}{F.S.}$$

$$r = r_o - t = \frac{D}{2} - t \Rightarrow \frac{p}{2 \cdot t} \left( \frac{D}{2} - t \right) \leq \frac{\sigma_u}{F.S.}$$

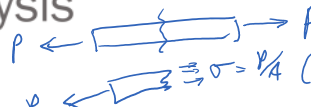
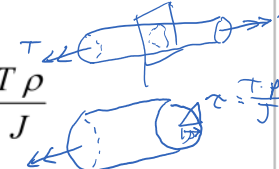

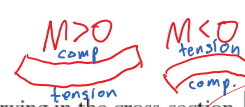
$$\frac{p \cdot D}{4t} - \frac{p}{2} \leq \frac{\sigma_u}{F.S.}$$

$$4t \left( \frac{p \cdot D}{4t} \right) \leq \left( \frac{\sigma_u}{F.S.} + \frac{p}{2} \right) 4t$$

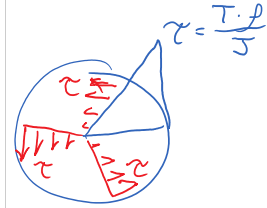
$$p \cdot D \leq \left( \frac{\sigma_u}{F.S.} + \frac{p}{2} \right) \cdot 4t$$

$$\Rightarrow t \geq \frac{p \cdot D}{4 \left( \frac{\sigma_u}{F.S.} + \frac{p}{2} \right)} \quad \therefore t \geq 7.7 \text{ mm}$$

## Review of stress analysis

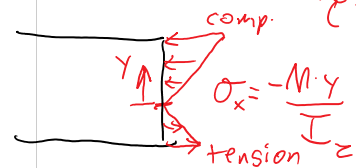
- **Normal force P** *ch. 4*  leads to uniform normal stress  $\sigma = \frac{P}{A}$   $\sigma = \frac{P}{A}$  (uniform)
- **Torsional moment T (circular shafts)**  leads to shear stress varying in the cross-section  $\tau = \frac{T \rho}{J}$
- **Shear force V (beams)**  leads to shear stress varying in the cross-section  $\tau = \frac{V Q(y)}{I t}$
- **Bending moment M**  leads to normal stress varying in the cross-section  $|\sigma| = \frac{M c}{I}$   $\sigma_x = -\frac{M \cdot y}{I_z}$
- **Internal pressure p in a spherical or cylindrical vessel** leads to hoop stress  $\sigma_h = \frac{p r}{t}$  and axial stress  $\sigma_a = \frac{p r}{2 t}$

*cylindrical only*



$$\tau = \frac{V \cdot Q}{I \cdot t}$$

$$\tau = \frac{V Q}{I \cdot t}$$

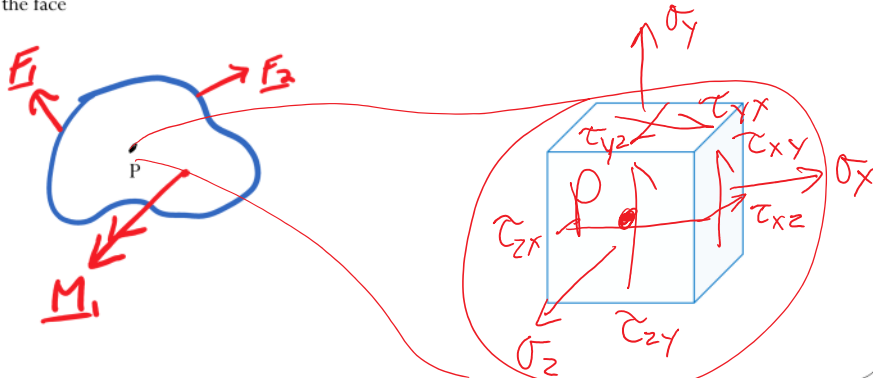


## State of stress in a solid

Consider a solid body subjected to externally applied loads

Suppose we wish to know about the stresses being caused at a particular point of interest, point P.

We can draw a small (infinitesimal) cube of material around the point of interest and note the infinitesimal forces that act on each face. In general, the force acting on each face can be broken into 3 vector components, one of which is normal to the face and two of which act in the plane of the face



$$\sigma_x$$

$$\sigma_y$$

$$\sigma_z$$

$$\tau_{xy} = \tau_{yx}$$

$$\tau_{xz} = \tau_{zx}$$

$$\tau_{yz} = \tau_{zy}$$

all of the stresses that may act at a point

## Stress in 2 and 3 dimensions

Normal stresses:  $\sigma_x, \sigma_y, \sigma_z$

Shear stresses:  $\tau_{xy} = \tau_{yx}, \tau_{yz} = \tau_{zy}, \tau_{xz} = \tau_{zx}$

→ equalities due to requirement of zero net moment in equilibrium

First index: indicates face normal direction

Second index: indicates force direction on that face

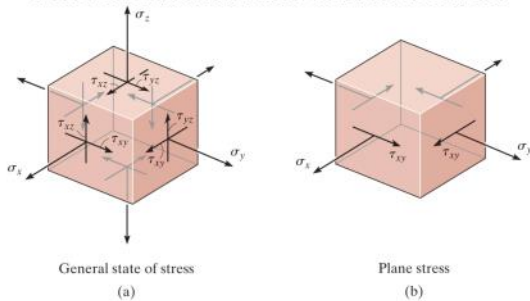
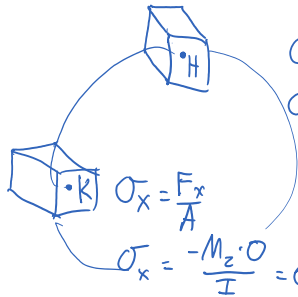
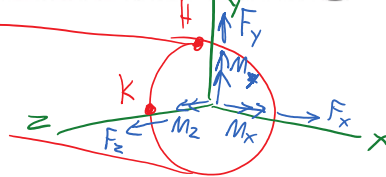
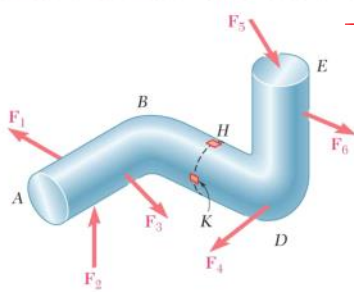


Figure: 09\_01

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## Stresses under combined loading



$$\sigma_x = \frac{F_x}{A} \quad \tau_{xz} = \frac{M_x \cdot \rho}{J} \text{ (Torsion)}$$

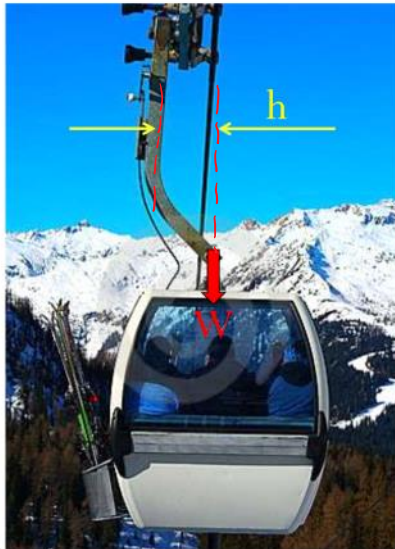
$$\sigma_x = -\frac{M_z \cdot y}{I} \text{ (Bending)} \quad \tau_{xz} = \frac{V \cdot Q}{I \cdot t} = 0 \text{ (shear)}$$

etc...

$$\tau_{xy} = \frac{M_x \cdot \rho}{J} \text{ (Torsion)}$$

$$\tau_{xy} = \frac{V \cdot Q}{I \cdot t} \neq 0 \text{ (on N.A.)}$$

## Jet Ski Gondola



A gondola on a ski lift is supported by a bent arm, as indicated in the figure. The arm has a square cross-sectional area with side length  $b$  and is offset by a distance  $h$  from the line of action of the weight force  $W$ . Find an expression for the minimum and maximum tensile stresses in the straight section of the arm.



Stresses in the cross-section

$$\sigma = \frac{W}{A} \quad \sigma = -\frac{(W \cdot h) \cdot y}{I}$$

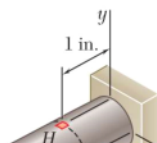


$$\sigma_{min} = \frac{W}{A} - \left| \frac{(W \cdot h) \cdot y_{max}}{I} \right|$$

$$\sigma_{max} = \frac{W}{A} + \left| \frac{(W \cdot h) \cdot y_{max}}{I} \right|$$

## Example

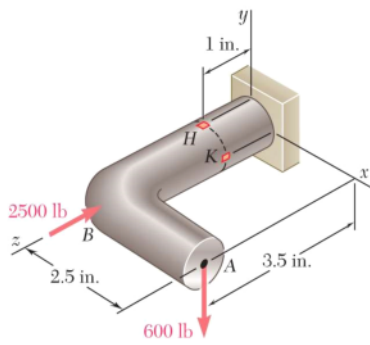
Find the state of stress at points H and K



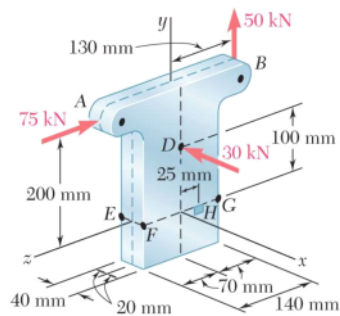


## Example

Find the state of stress at points H and K



## Example



Three forces are applied to a short steel post as shown. Determine the state of stress at point *H* on the outer surface of the post.